Comparing C^r Values with Network Perturbation Results - Focal Species: Plants

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Contents

| 1 | Plant Notes and Generalized C^r | 1 | | | |
|---|---|---|--|--|--|
| 2 | Density Dependence in the Plant Population Baseline Simulation Perturbation Experiment - Perturbing Node Survival Rates | | | | |
| 3 | | | | | |
| 4 | | | | | |
| 5 | Plant Plots - June 2018 - to Match Pintail Outputs | | | | |
| | 5.1 Population weighted average C^r | 6 | | | |
| | 5.2 Population Distribution W^r | 7 | | | |
| | 5.3 Proportional Dependence D_s | 8 | | | |
| | 5.4 Criticality - NEW K^r | 9 | | | |

1 Plant Notes and Generalized C^r

We model a population of Buttercup plant building our model based on the formulation in A general modeling framework for describing spatially structured population dynamics by Sample et. al. We track the population at eight breeding nodes. The population is modeled through three times steps each year:

- Summer, seeds and plants at all nodes.
- Autumn/Winter, seeds and plants at all nodes.
- Spring, seeds and plants at all nodes.

We use a generalized network model formulation were we define one time step as

$$\vec{\mathbf{N}}_{t+1} = \mathbf{A}_t \vec{\mathbf{N}}_t \tag{1}$$

Where $\vec{\mathbf{N}}_t$ contains the population at each of the *n* nodes and *c* classes at time *t*. The matrix \mathbf{A}_t contains all of the demographic node update and migration data for time *t*. (Christine and Joanna have a draft of a paper with this construction).

Within the plant code we calculate the C^r values for both the origin and the intermediate nodes during each season. We use a generalized one equation definition of C^r in matrix form.

$$\vec{\mathbf{C}}_t = \left(\prod_{\tau=t}^{t+s-1} \mathbf{A}_{\tau}^T\right) \vec{\mathbf{1}}_{nc} \tag{2}$$

where s is the total number of seasons in one anual cycle, for the plants s = 3 and $\vec{\mathbf{C}}_t$ is a column vector that contains the C^r values at each node for each class for focal season, or time, t.

We note that because the code is run to equillibrium, the overall growth rate of the nework is equal to one. We can calculate the growth rate using:

$$\lambda_t = \frac{\vec{\mathbf{N}}_t^T}{N_t^{tot}} \vec{\mathbf{C}}_t \tag{3}$$

where N_t^{tot} is the sum of the equilibrium population values across all nodes and all classes in the network and is represented by the following summation

$$N_t^{tot} = \sum_{r=1}^n \sum_{x=1}^c N_{r,t}^x \tag{4}$$

2 Density Dependence in the Plant Population

The nodal update function f is density dependent. f is defined by:

$$f_{i,t}^{p} = \underbrace{s_{i,t}^{p} \cdot N_{i,t}^{p}}_{\text{plants that survive}} + \underbrace{\Psi_{i,t} \cdot T_{i,t} \cdot s_{i,t}^{s} \cdot N_{i,t}^{s}}_{\text{plants that survive}} + \underbrace{\Psi_{i,t} \cdot T_{i,t} \cdot s_{i,t}^{s} \cdot N_{i,t}^{s}}_{\text{plants that survive}}$$
(5)

 $s_{i,t}^p, T_{i,t}$, and $s_{i,t}^s$ are all constants. $\Psi_{i,t}$ is the density-dependent postgermination survival rate. $\Psi_{i,t}$ is given by:

$$\Psi_{i,t} = \psi_{i,t} \cdot e^{-(N_{i,t}^p + T_{i,t} \cdot s_{i,t}^s \cdot N_{i,t}^s)/K_i}$$
(6)

 K_i is the carying capacity at node i and $\psi_{i,t}$ is the maximum germination rate, which is constant, but varies by season.

3 Baseline Simulation

The baseline simulation gives us identical results to A general modeling framework for describing spatially structured population dynamics by Sample et. al. We find that the long term carrying capacity for each node during the nonbreeding season, including all classes, is

Total Network Population vs. Time Single Annual Survey (beginning of season 1 – nonbreeding) Output Output

Figure 1: Baseline results: population over time at nonbreeding node.

4 Perturbation Experiment - Perturbing Node Survival Rates

To investigate the utility of the metrics as an indicator of the change in carrying capacity K we consider the following perturbations to the survival rate at each node:

$$PERT = .9, .8, .7, .6, .5$$

Some notes about the simulations:

- All simulations are run to equillibrium with an error tollerance of within 1 plant, meaning the network growth rate $\lambda = 1$.
- We only cary out negative perturbations because positive perturbations will cause survival rates to exceed 1.

5 Plant Plots - June 2018 - to Match Pintail Outputs

We will consider metrics for the x-axis of our graph:

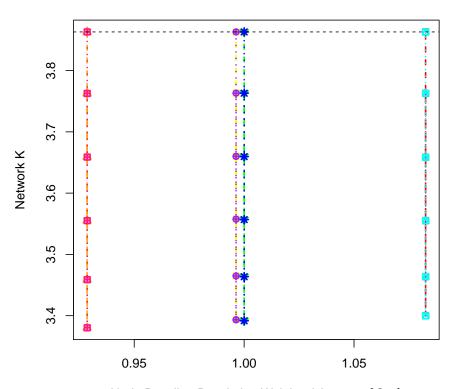
- Baseline C^r vs K perturbations this is the population weighted C^r value averaged across classes and seasons Figure 2
- \bullet Baseline W^r vs K perturbations the population proportions averaged across seasons Figure 3
- \bullet Baseline D_s vs K perturbations the proportional dependence as defined in Bagstad et al, generalizing to account for juveniles: Figure 4
- NEW Baseline Criticality KR_i vs K perturbations defined as the network growth rate in the absence of node i using a population weighted average across seasons: Figure 5. Note that because we are at equilibrium the baseline network growth rate is $\lambda = 1$.

5.1 Population weighted average C^r

In order to be consistent across case studies we decide to calculate C^r using a population weighted average. The general matrix form of C^r results in a C^r values for each node, class, and season. To combine these into a single full year network wide C^r value we first do a population weighted average by class within each node and then do a population weighted average across seasons. This results in a single C^r values for each node.

The plant model has three seasons (Summer, Autumn/Winter, Spring) and two classes (seeds and plants).

Range of Network Carying Capacities (K) vs Baseline CR



Node Baseline Population Weighted Average \$C^r\$

Figure 2: Perturbation results: Range of K values after perturbations to each node, X-axis represents baseline population weighted C^r values for each node

| Node 1 | | year-round |
|--------|----------|------------|
| Node 2 | Δ | year-round |
| Node 3 | × | year-round |
| Node 4 | ∇ | year-round |
| Node 5 | * | year-round |
| Node 6 | \oplus | year-round |
| Node 7 | | year-round |
| Node 8 | ∇ | year-round |

5.2 Population Distribution W^r

 W^r is calculated as the percent of the total population residing at a node. This calculation results in W^r values for each node during each seaons. To get a consistent value for the network, we average (not weighted) across the seasons. The final numbers should sum to one.

Range of Network Carying Capacities (K) vs Baseline \$W^r\$

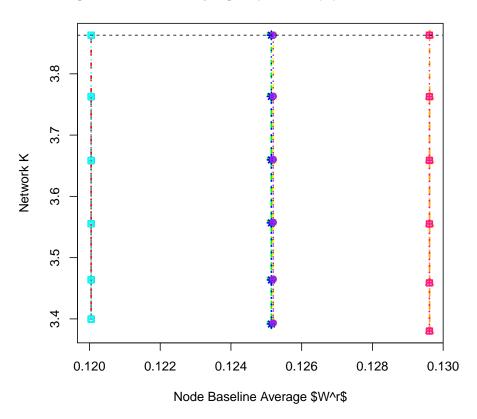


Figure 3: Perturbation results: Range of K values after perturbations to each node, X-axis represents baseline average W^r value for each node

| Node 1 | | year-round |
|--------|----------|------------|
| Node 2 | Δ | year-round |
| Node 3 | × | year-round |
| Node 4 | ∇ | year-round |
| Node 5 | * | year-round |
| Node 6 | \oplus | year-round |
| Node 7 | | year-round |
| Node 8 | ∇ | year-round |

5.3 Proportional Dependence D_s

 D_s is calculated following Bagstad et al. We first find the population weighted C^r values for each of the seasons and then average across the anual cycle.

Range of Network Carying Capacities (K) vs Baseline D_s

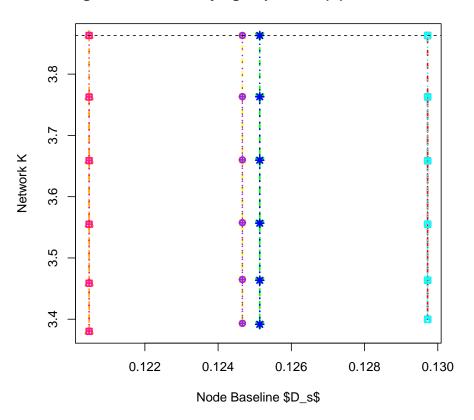


Figure 4: Perturbation results: Range of K values after perturbations to each node, X-axis represents baseline D_s value for each node

| Node 1 | | year-round |
|--------|----------|------------|
| Node 2 | Δ | year-round |
| Node 3 | × | year-round |
| Node 4 | ∇ | year-round |
| Node 5 | * | year-round |
| Node 6 | \oplus | year-round |
| Node 7 | | year-round |
| Node 8 | ∇ | year-round |

5.4 Criticality - NEW K^r

Criticality K^r is a new metric concieved of by Christine and her colleagues. The basic idea is that from C^r we can calculate the network growth rate λ . In the case of a population in equilibrium, like our simulations, $\lambda = 1$. Then one could also calculate a theoretical C^r value as if on of the nodes was removed. From this theoretical C^r value we could calulcate a new network growth rate γ . We define criticality as

$$K^r = \lambda - \gamma$$

In other words K^r represents the amount of the network growth rate that flows through the focal node r. In our equilibrium case is $K^r=1$ then all of the network growth rate must flow through r and removal of r reduces the new growth rate γ to zero. Alternatively, if $K^r=0$ then none of the original network growth rate flows through r and removal of r does not change the growth rate, $\lambda=\gamma=1$.

The K^r calculation results in criticality vales for each node during each season. To get a single yearly value we use a population weighted average.

Range of Network Carying Capacities (K) vs Baseline Criticalit

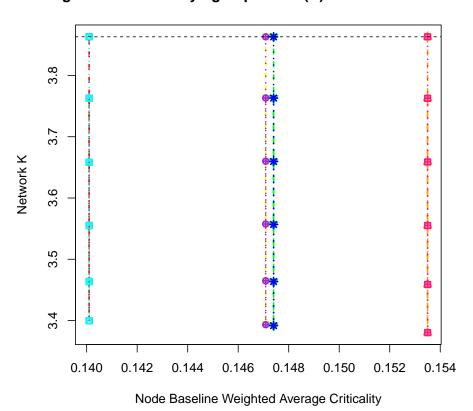


Figure 5: Perturbation results: Range of K values after perturbations to each node, X-axis represents baseline Criticality value for each node

| Node 1 | | year-round |
|--------|----------|------------|
| Node 2 | Δ | year-round |
| Node 3 | × | year-round |
| Node 4 | ∇ | year-round |
| Node 5 | * | year-round |
| Node 6 | \oplus | year-round |
| Node 7 | | year-round |
| Node 8 | ∇ | year-round |