Mathematics for Machine Learning

Probabilistic Modeling & Inference

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Credits for the resource

- The slides are based on the textbooks:
 - Marc Peter Deisenroth, A. Aldo Faisal, and Cheng Soon Ong: Mathematics for Machine Learning. Cambridge University Press. 2020.
 - Howard Anton, Chris Rorres, Anton Kaul: Elementary Linear Algebra. Wiley. 2019.
- We could partially refer to the monograph: Francesco Orabona: A Modern Introduction to Online Learning. https://arxiv.org/abs/1912.13213

Outline

Probabilistic Models & Bayesian Inference

2 Latent-Variable Models

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- Note: μ is unknown in advance and can never be observed directly.
- We need mechanisms to learn something about μ given observed outcomes of coin-flip.

Probabilistic Models

- The benefit of using probabilistic models:
 - A unified and consistent set of tools from probability theory for modeling, inference, prediction, and model selection.
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 - The prior and the likelihood.
 - The marginal likelihood p(x) (though integrating out the parameters is required.)
 - The posterior (obtained by dividing the joint by the marginal likelihood).
- Therefore, a probabilistic model is specified by the joint distribution of all its random variables.

- ullet We have already learnt two ways of estimating model parameters $oldsymbol{ heta}$:
 - Maximum likelihood estimation (MLE)
 - Maximum a posteriori estimation (MAP)
- We can then obtain a *single-best* value of θ (solving an optimization problem), then we can use them to make predictions.
- Note: These decision-making systems typically have different objective functions than the likelihood (e.g., squared-error loss or a mis-classification error).
- Having the full posterior distribution around can be useful and leads to more robust decisions.

- Bayesian inference: finding such a posterior distribution.
- For a dataset \mathcal{X} , a parameter prior $p(\theta)$, and a likelihood function, the posterior

$$p(\theta \mid \mathcal{X}) = \frac{p(\mathcal{X} \mid \theta)p(\theta)}{p(\mathcal{X})},$$

then by applying Bayes' theorem,

$$p(\mathcal{X}) = \int p(\mathcal{X} \mid \boldsymbol{\theta}) p(\boldsymbol{\theta}) d\boldsymbol{\theta}.$$

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- $oldsymbol{ ilde{ heta}}$ The prediction becomes an average over all plausible parameter values $oldsymbol{ heta}$.
 - The plausibility is encapsulated by the distribution $p(\theta)$.

Computational Issues

- ullet MLE or MAP yields a consistent point estimate $oldsymbol{ heta}^*$ of the parameters.
 - Key computational problem: optimization.
 - Prediction: straightforward.
- Bayesian inference yields a distribution.
 - Key computational problem: integration.
 - Prediction: solving another integration problem.

Outline

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2 Latent-Variable Models

Latent Variables

- ullet Sometimes it is useful to have additional variable (besides $oldsymbol{ heta}$) as part of the model.
 - We call them latent variables.
- Latent variables can
 - Describe the data-generation process.
 - Increase the interpretability of the model.
 - Simplify the structure of the model.

Denote data by \mathbf{x} , the model parameter by $\boldsymbol{\theta}$ and the latent variables by \mathbf{z} , we obtain the conditional distribution:

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A Two-Step Procedure

- **1** Compute the likelihood $p(\mathbf{x} \mid \boldsymbol{\theta})$ (not depending on \mathbf{z}).
- ② Use the likelihood for parameter estimation or Bayesian inference.

Likelihood in Terms of Marginal Distribution

What we already have: a conditional distribution

$$p(\mathbf{x} \mid \mathbf{z}, \boldsymbol{\theta}).$$

We need to marginalize out the latent variables to have the predictive distribution of the data given the model parameters θ :

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- \Rightarrow a posterior distribution over the model parameters given a dataset $\mathcal{X}.$
 - $p(X \mid \theta)$ requires the marginalization of latent variables **z**.

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• $p(\mathbf{z})$: the prior on \mathbf{z} ; $p(\mathcal{X} \mid \mathbf{z}, \boldsymbol{\theta})$: given.



Example

Consider the set of affine functions.

- Let $\mathbf{x}_i = [1, x_i^{(1)}, x_i^{(2)}, \dots, x_i^{(D)}]^{\top}$
- The corresponding parameter $\theta = [\theta_0, \theta_1, \dots, \theta_D]^{\top}$.
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which is equivalent to

$$f(\mathbf{x}_i, \boldsymbol{\theta}) = \theta_0 + \sum_{d=1}^{D} \theta_d x_i^{(d)}$$

Discussions