

# Randomized Algorithms

## Markov Chains and Random Walks

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# Outline

- Markov Chains: definitions and representations
- Application: Random Walk
- Classification of States
- Stationary Distribution

# Stochastic Process

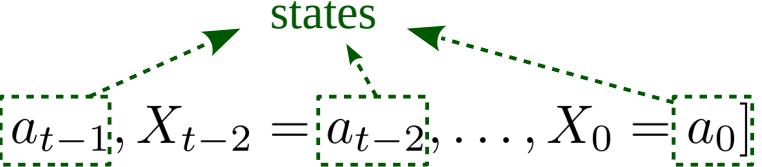
- A stochastic process  $\mathbf{X} = \{X(t) : t \in T\}$  is a collection of random variables.
  - $t$ : time
  - $X(t)$ : state of the process at time  $t$ .
- If  $T$  is a countably infinite set, we say  $\mathbf{X}$  is a discrete time process.

# Markov Chain

- A discrete time stochastic process  $X_0, X_1, X_2, \dots$  is a **Markov chain** if

$$\Pr[X_t = a_t \mid X_{t-1} = a_{t-1}, X_{t-2} = a_{t-2}, \dots, X_0 = a_0] = \Pr[X_t = a_t \mid X_{t-1} = a_{t-1}] = P_{a_{t-1}, a_t}.$$

states



- Markov property.

# Markov Chain

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- Markov property.
- ✓ This does **NOT** imply that  $X_t$  is **independent** of  $X_0, X_1, \dots, X_{t-2}$ ,
  - ✓ The dependency of  $X_t$  on the past is captured in  $X_{t-1}$ .

# Markov Chain

- Markov property implies:  
→ The Markov chain is uniquely defined by the one-step transition matrix.

$$\mathbf{P} = \left\{ \begin{array}{cccccc} P_{0,0} & P_{0,1} & \cdots & P_{0,j} & \cdots \\ P_{1,0} & P_{1,1} & \cdots & P_{1,j} & \cdots \\ \vdots & \vdots & \ddots & \vdots & \ddots \\ P_{i,0} & P_{i,1} & \cdots & P_{i,j} & \cdots \\ \vdots & \vdots & \ddots & \vdots & \ddots \end{array} \right\}$$

for all  $i$ ,  $\sum_{j \geq 0} P_{i,j} = 1$ .

# Transition Probabilities

- $\bar{p}(t) = (p_0(t), p_1(t), p_2(t), \dots)$ .
  - $p_i(t)$ : the probability that the process is at state  $i$  at time  $t$ .

$$p_i(t) = \sum_{j \geq 0} p_j(t-1) P_{j,i}.$$

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- $m$  step transition probability:

$$P_{i,j}^m = \Pr[X_{t+m} = j \mid X_t = i].$$

$$P_{i,j}^m = \sum_{k \geq 0} P_{i,k} P_{k,j}^{m-1}.$$

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$$\bar{p}(t) = \bar{p}(t-1) \mathbf{P}.$$

$$\mathbf{P}^{(m)} = \mathbf{P} \cdot \mathbf{P}^{(m-1)}$$

$\mathbf{P}^{(m)} = \mathbf{P}^m$  (by induction on  $m$ )

- $m$  step transition probability:

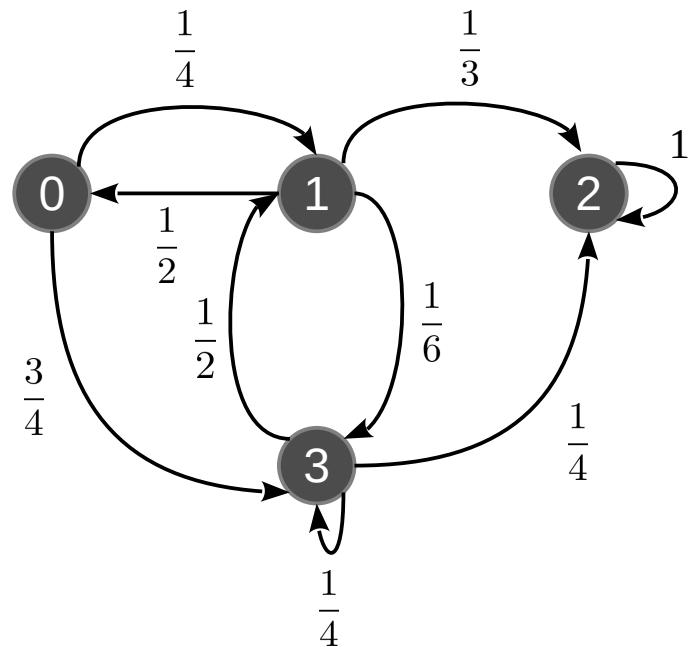
$$P_{i,j}^m = \Pr[X_{t+m} = j \mid X_t = i].$$

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for any  $t \geq 0$  and  $m \geq 1$ ,

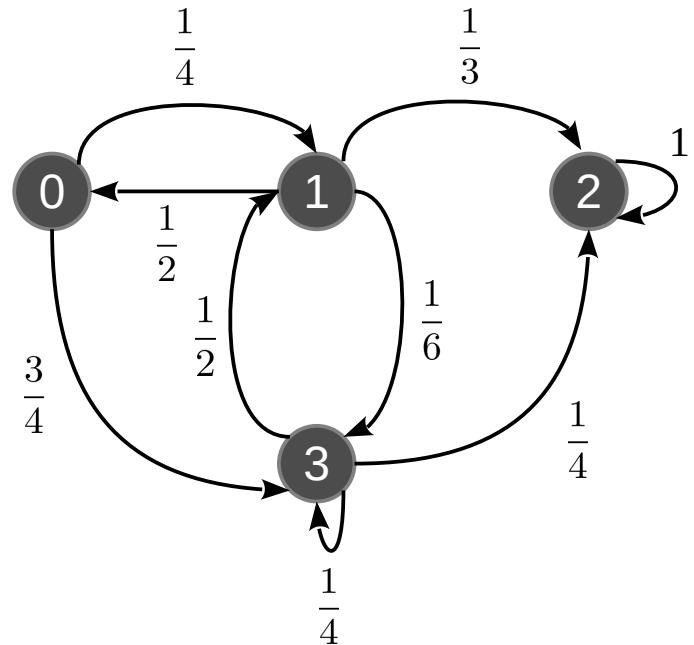
$$\bar{p}(t+m) = \bar{p}(t) \mathbf{P}^m.$$

# Transition Probabilities



$$\mathbf{P} = \begin{bmatrix} 0 & 1/4 & 0 & 3/4 \\ 1/2 & 0 & 1/3 & 1/6 \\ 0 & 0 & 1 & 0 \\ 0 & 1/2 & 1/4 & 1/4 \end{bmatrix}$$

# Transition Probabilities



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$$\mathbf{P}^3 = \begin{bmatrix} 3/16 & 7/48 & 29/64 & 41/192 \\ 5/48 & 5/24 & 79/144 & 5/36 \\ 0 & 0 & 1 & 0 \\ 1/16 & 13/96 & 107/192 & 47/192 \end{bmatrix}$$

# Transition Probabilities

- If we begin in a state chosen uniformly at random:  $(\frac{1}{4}, \frac{1}{4}, \frac{1}{4}, \frac{1}{4})$ , what is the probability distribution after three steps?

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$$(1/4, 1/4, 1/4, 1/4) \mathbf{P}^3 = (17/192, 47/384, 737/1152, 43/288).$$

$$\mathbf{P}^3 = \begin{bmatrix} 3/16 & 7/48 & 29/64 & 41/192 \\ 5/48 & 5/24 & 79/144 & 5/36 \\ 0 & 0 & 1 & 0 \\ 1/16 & 13/96 & 107/192 & 47/192 \end{bmatrix}$$

# Exercise

- Consider the two-state Markov chain with the following transition matrix. Find a simple expression for  $P_{0,0}^t$ .

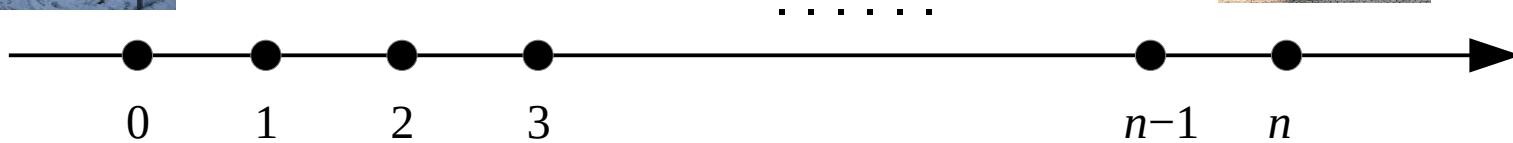
$$\mathbf{P} = \begin{bmatrix} p & 1-p \\ 1-p & p \end{bmatrix}$$

# Application: Random Walks

Steppenberglallee Aachen



Aachener Dom

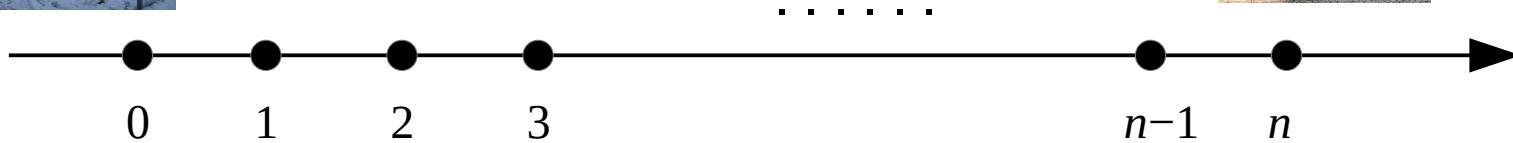


# Application: Random Walks

Steppenbergsallee Aachen



Aachener Dom



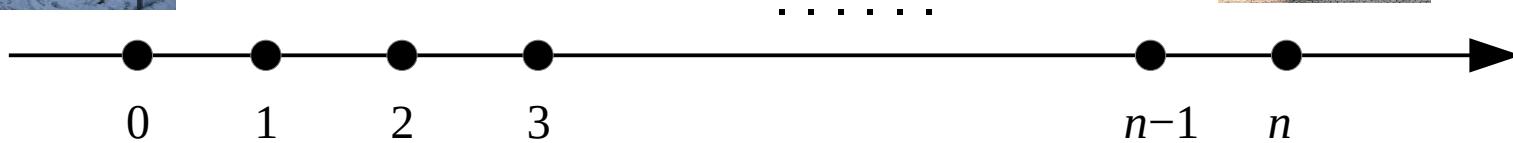
- $X_i$ : the position after the  $i$ th step you've walked.

# Application: Random Walks

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- Only at the position 0 (my home) we know how to make a right step towards the destination (cathedral).

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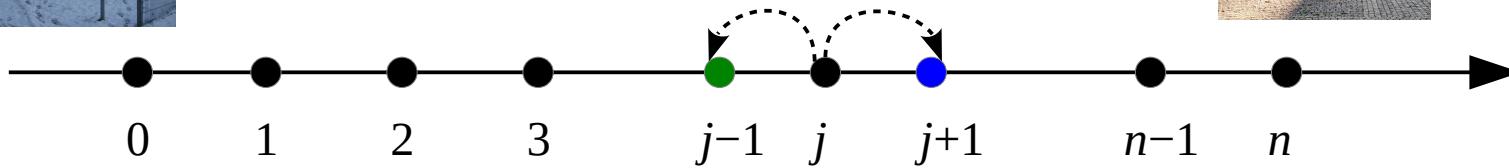
$$\Pr[X_{i+1} = 1 \mid X_i = 0] = 1.$$

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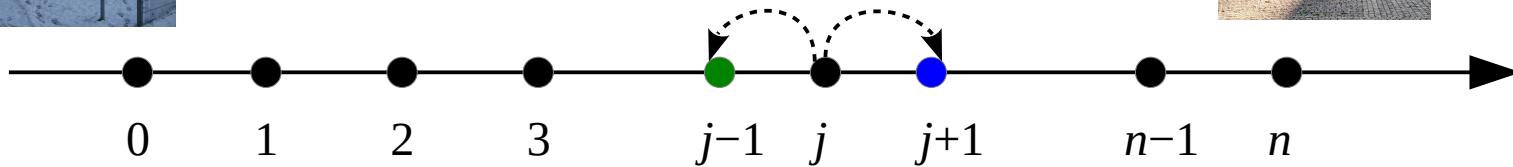
- If we are at positions  $1, 2, \dots, n-1$ , we have no idea about the direction to go.
- Suppose then we have chance of 50% to get one step **closer** to the destination and 50% to get one step **backward**...
- How many steps we expect to walk...?

# Application: Random Walks

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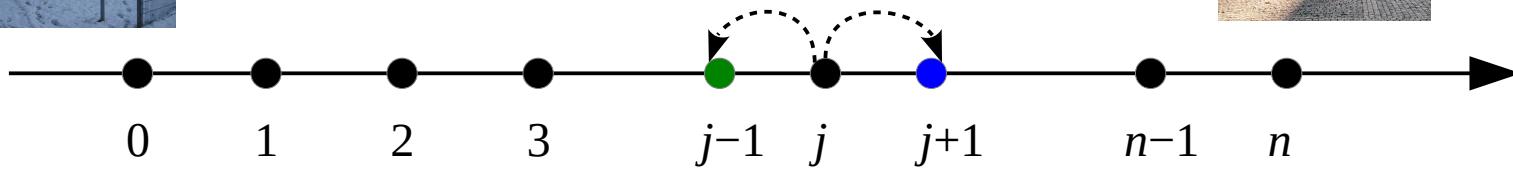
- Markov chain  $X_0, X_1, X_2, \dots$
- $Z_j$ : random variable; the number of steps to reach  $n$  from  $j$ .
- $h_j$ : the expected steps to reach  $n$  when starting from  $j$ .
  - $\mathbb{E}[Z_j] = h_j$ .
- $h_n = 0$ ,  $h_0 = h_1 + 1$ .

# Application: Random Walks

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- $\mathbf{E}[Z_j] = \mathbf{E} \left[ \frac{1}{2} \cdot (1 + Z_{j-1}) + \frac{1}{2} \cdot (1 + Z_{j+1}) \right].$

$$h_j = \frac{h_{j-1}}{2} + \frac{h_{j+1}}{2} = \frac{h_{j-1} + h_{j+1}}{2} + 1. \quad (\text{for } 1 \leq j \leq n-1)$$

# Application: Random Walks

$$h_{j+1} = 2h_j - h_{j-1} - 2$$

$$h_j = 2h_{j-1} - h_{j-2} - 2$$

$$h_{j-1} = 2h_{j-2} - h_{j-3} - 2$$

$$h_{j-2} = 2h_{j-3} - h_{j-4} - 2$$

...    ...    ...

$$h_2 = 2h_1 - h_0 - 2$$

$$h_1 = h_0 - 1$$

# Application: Random Walks

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$$h_{j-2} = 2h_{j-3} - h_{j-4} - 2$$

...

$$h_2 = 2h_1 - h_0 - 2$$

$$h_1 = h_0 - 1$$

$$\Rightarrow h_j = h_{j+1} + 2j + 1.$$

# Application: Random Walks

$$\begin{array}{lll} h_{j+1} & = 2h_j & -h_{j-1} - 2 \\ h_j & = 2h_{j-1} & -h_{j-2} - 2 \\ h_{j-1} & = 2h_{j-2} & -h_{j-3} - 2 \\ h_{j-2} & = 2h_{j-3} & -h_{j-4} - 2 \\ \dots & \dots & \dots \\ h_2 & = 2h_1 & -h_0 - 2 \\ h_1 & = h_0 & -1 \end{array}$$

$$h_0 = h_1 + 1 = h_2 + 1 + 3 = \dots = \sum_{i=0}^{n-1} (2i + 1) = n^2.$$

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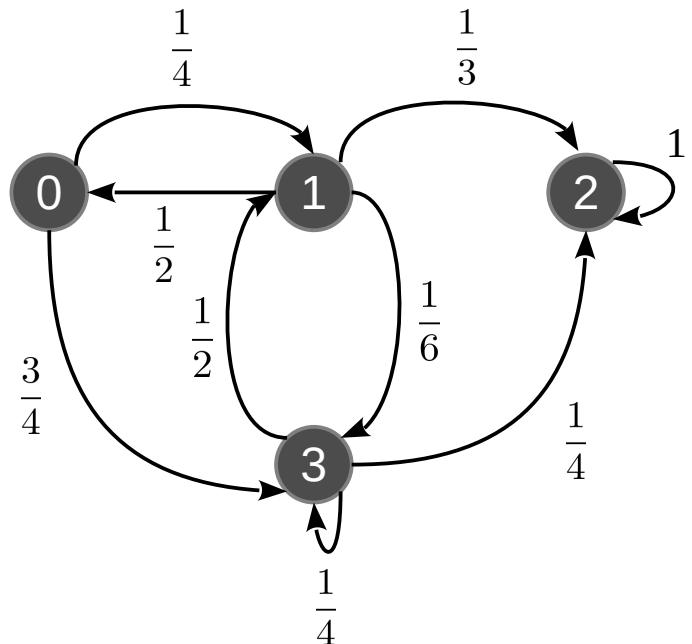
$$\Pr[\text{walking steps } > 2n^2] \leq \frac{n^2}{2n^2} = \frac{1}{2}.$$

$$\Rightarrow h_j = h_{j+1} + 2j + 1.$$

# Exercise

- Consider the random walk we just discussed. Now we assume that whenever position 0 is reached, with probability  $\frac{1}{2}$  the walk moves to position 1 and with probability  $\frac{1}{2}$  the walk stays at 0. What is the expected number of steps to reach  $n$  starting from position 0?

# Classification of States

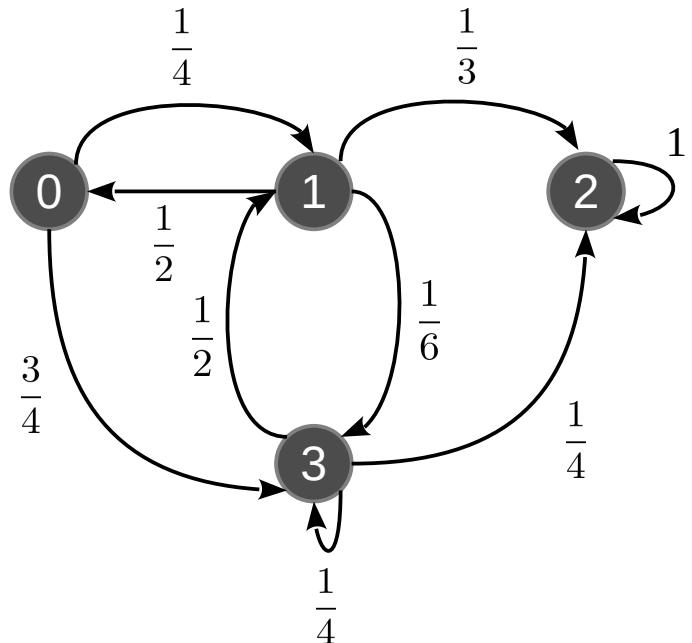


- $i \rightarrow j$  **accessible**:

For some integer  $n \geq 0$ ,  $P_{i,j}^n > 0$

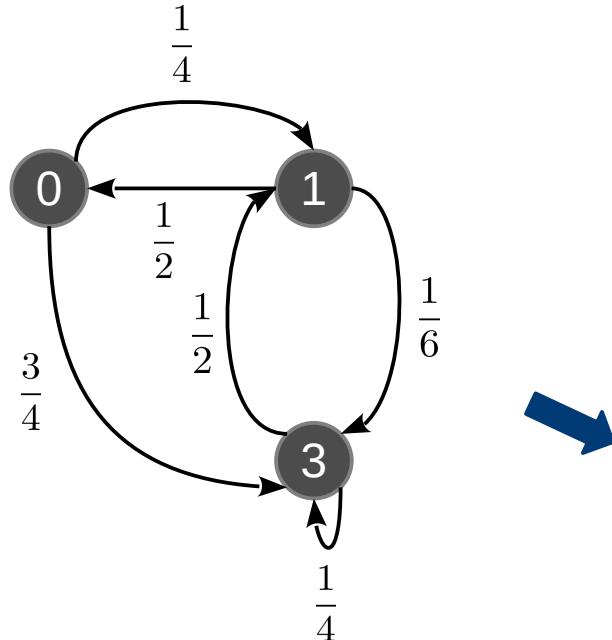
- How about  $2 \rightarrow 0$ ?  $2 \rightarrow 1$ ?

# Classification of States



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  - ◆ How about  $2 \rightarrow 0$ ?  $2 \rightarrow 1$ ?
- $i \leftrightarrow j$ :  $i$  and  $j$  **communicate**.

# Classification of States

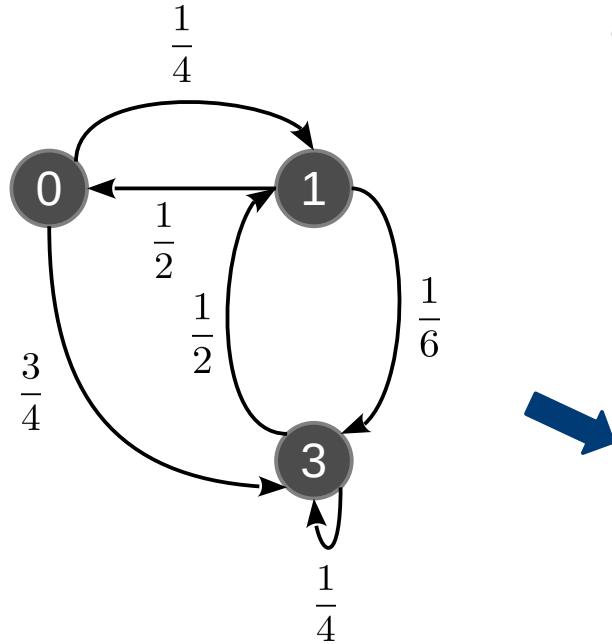


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  - ◆ How about  $2 \rightarrow 0$ ?  $2 \rightarrow 1$ ?
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The Markov chain is **irreducible**.

- Any two states communicate.

# Classification of States



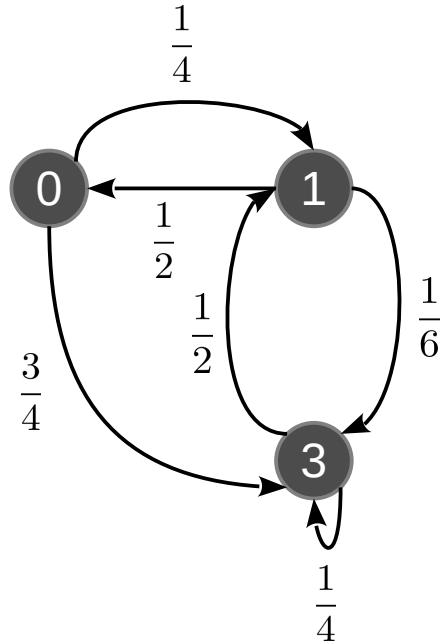
- $r_{i,j}^t$ : the probability that starting at state  $i$ , the first transition to state  $j$  occurs at time  $t$ .

$$r_{i,j}^t = \Pr[X_t = j \text{ and, for } 1 \leq s \leq t-1, X_s \neq j \mid X_0 = i]$$

The Markov chain is **recurrent**.

- $\sum_{t \geq 1} r_{i,i}^t = 1$  for every state  $i$

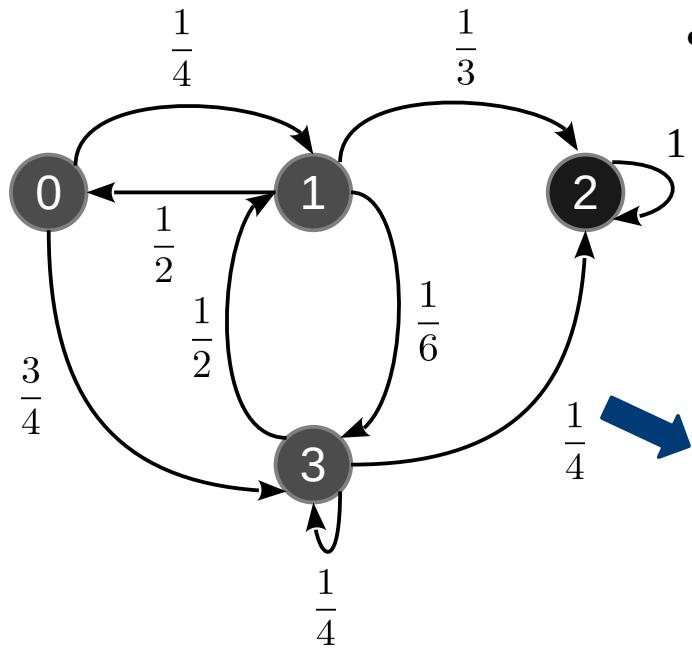
# Classification of States



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$$r_{i,j}^t = \Pr[X_t = j \text{ and, for } 1 \leq s \leq t-1, X_s \neq j \mid X_0 = i]$$
  - $h_{i,i}$ : the expected time to return state  $i$  when starting from state  $i$ .  
$$h_{i,i} = \sum_{t \geq 1} t \cdot r_{i,i}^t.$$
- The Markov chain is **recurrent**.
- $\sum_{t \geq 1} r_{i,i}^t = 1$  for every state  $i$
  - Each state  $i$  is **positive recurrent**.

$$h_{i,i} < \infty$$

# Classification of States



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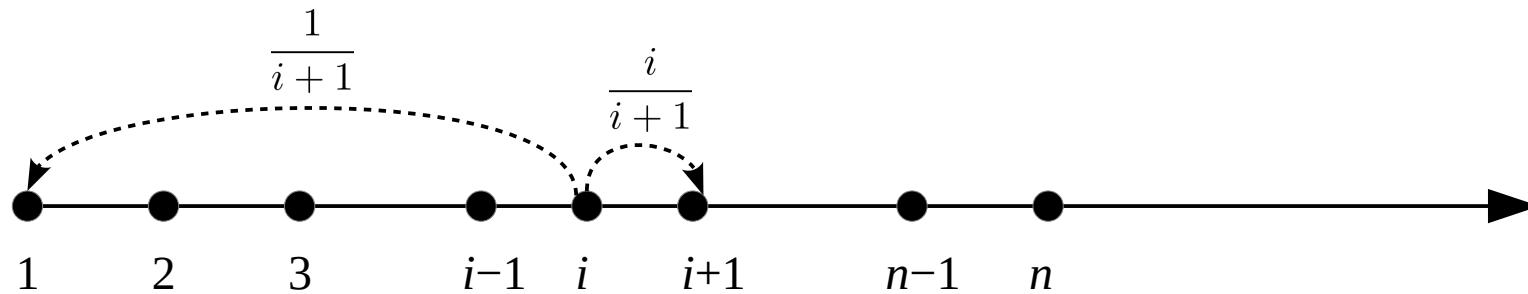
$$r_{i,j}^t = \Pr[X_t = j \text{ and, for } 1 \leq s \leq t-1, X_s \neq j \mid X_0 = i]$$

State 0, 1, 3 are **transient**.

- $\sum_{t \geq 1} r_{1,1}^t < 1$  for state  $i \in \{0, 1, 3\}$

# Classification of States

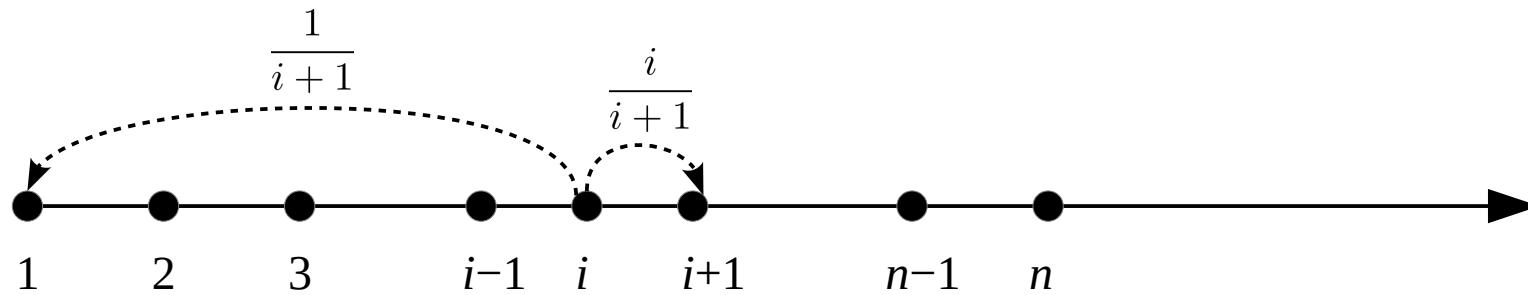
- An example of *null* recurrent:



$$r_{1,1}^t = \left( \prod_{j=1}^{t-1} \frac{j}{j+1} \right) \cdot \frac{1}{t+1} = \frac{1}{2} \cdot \frac{2}{3} \cdots \frac{t-1}{t} \cdot \frac{1}{t+1} = \frac{1}{t(t+1)}.$$

# Classification of States

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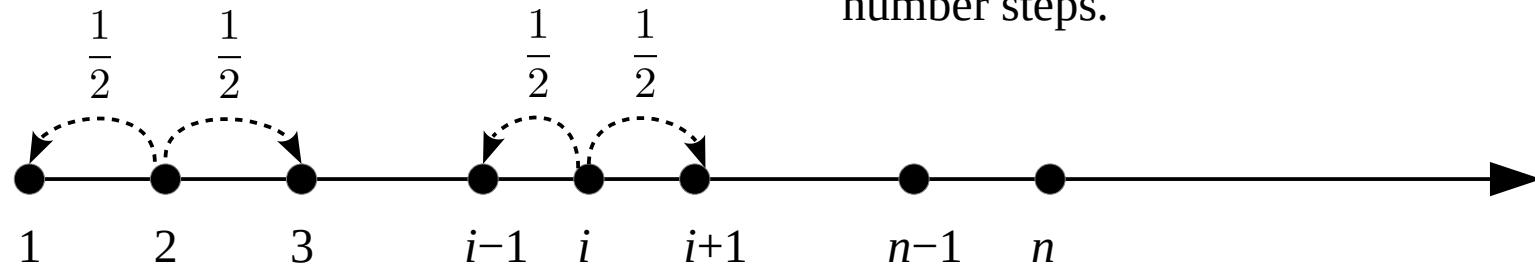


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$$h_{1,1} = \sum_{t \geq 1} t \cdot r_{1,1}^t = \sum_{t \geq 1} \frac{1}{t+1} \rightarrow \infty.$$

# Classification of States

- **periodic** states.
  - Suppose the chain starts at 2.
  - It can be at **even** number states only after **even** number steps.

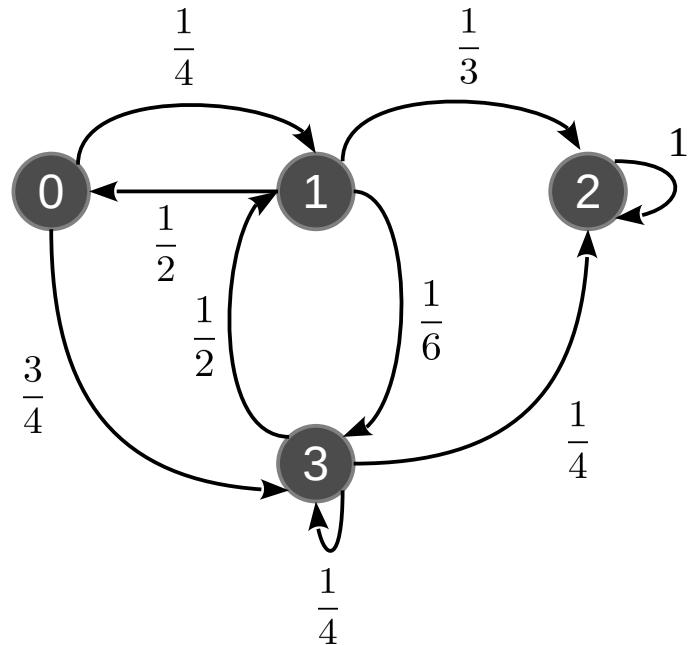


$j$  is **periodic** :

$\exists \Delta > 1$  such that  $\Pr[X_{t+s} = j \mid X_t = j] = 0$  unless  $s$  is divisible by  $\Delta$ .

- *aperiodic* = not periodic

# Classification of States



- An aperiodic, positive recurrent state is an **ergodic** state.
- **Ergodic Markov chain:** every state is ergodic.

# Stationary Distributions

- Recall that

$$\bar{p}(t) = \bar{p}(t-1)\mathbf{P}.$$

- Consider  $\bar{p}(t) = \bar{p}(t-1)$

That is,  $\bar{\pi} = \bar{\pi}\mathbf{P}$ .

$\bar{\pi}$  : a probability distribution over the states.

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That is,  $\bar{\pi} = \bar{\pi}\mathbf{P}$ .

$\bar{\pi}$  : a probability distribution over the states.

- We call it a **stationary distribution** of the Markov chain.

# Stationary Distributions

- **Theorem.** Any finite, irreducible, and ergodic Markov chain has the following properties:

1. The chain has a unique stationary distribution
2. for all  $j$  and  $i$ ,

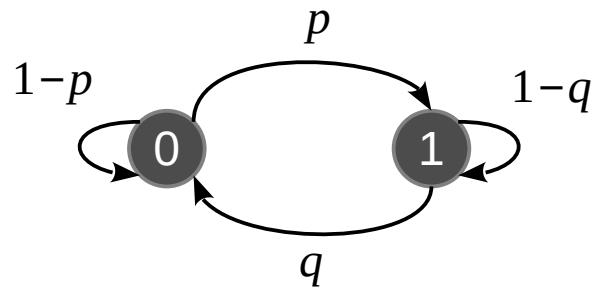
$$\lim_{t \rightarrow \infty} P_{j,i}^t \text{ exists and it's independent of } j$$

$$3. \pi_i = \lim_{t \rightarrow \infty} P_{j,i}^t = \frac{1}{h_{i,i}}.$$

# Computing the Stationary Distribution

- Method 1: Solve the system of linear equations.
- Example:

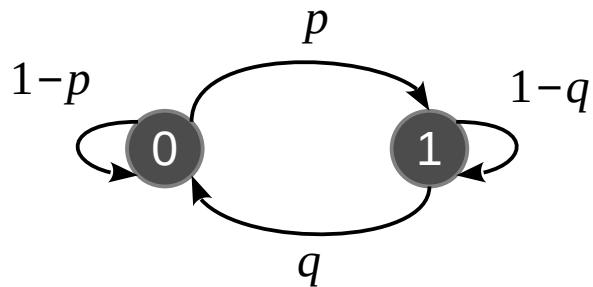
$$\mathbf{P} = \begin{bmatrix} 1-p & p \\ q & 1-q \end{bmatrix}.$$



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$$\bar{\pi}\mathbf{P} = \bar{\pi} \Leftrightarrow [\pi_0, \pi_1] \cdot \begin{bmatrix} 1-p & p \\ q & 1-q \end{bmatrix} = [\pi_0, \pi_1].$$

$$\pi_0(1-p) + \pi_1 q = \pi_0;$$

$$\pi_0 p + \pi_1(1-q) = \pi_1;$$

$$\pi_0 + \pi_1 = 1$$

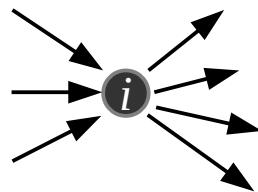
$$\pi_0 = \frac{q}{p+q}.$$

$$\pi_1 = \frac{p}{p+q}.$$

# Computing the Stationary Distribution

- Method 2: Cut-sets of the Markov chain.
- The idea:
  - For any state  $i$  of the chain,

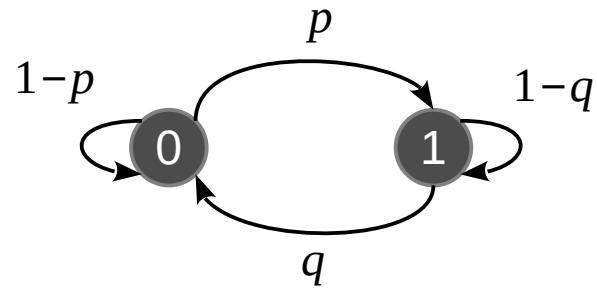
$$\sum_{j=0}^n \pi_j P_{j,i} = \pi_i = \pi_i \cdot \sum_{j=0}^n P_{i,j}$$



# Computing the Stationary Distribution

- Method 2: Cut-sets of the Markov chain.
- Example:

$$\mathbf{P} = \begin{bmatrix} 1-p & p \\ q & 1-q \end{bmatrix}.$$



The probability of leaving state 0 must equal the probability of entering state 0

$$\pi_0 p = \pi_1 q$$

$$\begin{aligned}\pi_0 &= \frac{q}{p+q}. \\ \pi_1 &= \frac{p}{p+q}.\end{aligned}$$

# Exercise

- Consider a Markov chain with state space  $\{0, 1, 2, 3\}$  and a transition matrix

$$\mathbf{P} = \begin{bmatrix} 0 & \frac{3}{10} & \frac{1}{10} & \frac{3}{5} \\ \frac{1}{10} & \frac{1}{10} & \frac{7}{10} & \frac{1}{10} \\ \frac{1}{10} & \frac{7}{10} & \frac{1}{10} & \frac{1}{10} \\ \frac{9}{10} & \frac{1}{10} & 0 & 0 \end{bmatrix}$$

Find the stationary distribution of the Markov chain.