

Mathematics for Machine Learning

— Probability & Distributions (Supplementary):

Sum Rule, Product Rule, Bayes' Theorem & Summary Statistics

Joseph Chuang-Chieh Lin

Department of Computer Science & Information Engineering,
Tamkang University

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Credits for the resource

- The slides are based on the textbooks:
 - *Marc Peter Deisenroth, A. Aldo Faisal, and Cheng Soon Ong: Mathematics for Machine Learning. Cambridge University Press. 2020.*
 - *Howard Anton, Chris Rorres, Anton Kaul: Elementary Linear Algebra. Wiley. 2019.*
- We could partially refer to the monograph:
Francesco Orabona: A Modern Introduction to Online Learning.
<https://arxiv.org/abs/1912.13213>

Outline

- 1 Sum & Product Rule
- 2 Bayes' Theorem
- 3 Means & Covariances
- 4 Sums & Transformations of Random Variables
- 5 Statistical Independence

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Sum Rule (1/2)

- \mathbf{x}, \mathbf{y} : random variables (vectors).
- $p(\mathbf{x}, \mathbf{y})$: joint distribution of \mathbf{x}, \mathbf{y} .
- $p(\mathbf{y} \mid \mathbf{x})$: conditional probability of \mathbf{y} given \mathbf{x} .

Sum Rule

$$p(\mathbf{x}) = \begin{cases} \sum_{\mathbf{y} \in \mathcal{Y}} p(\mathbf{x}, \mathbf{y}) & \text{if } \mathbf{y} \text{ is discrete} \\ \int_{\mathcal{Y}} p(\mathbf{x}, \mathbf{y}) d\mathbf{y} & \text{if } \mathbf{y} \text{ is continuous} \end{cases}$$

where \mathcal{Y} stands for the states of the target space of random variable Y .

- **Marginalization property.**

Sum Rule (2/2)

For $\mathbf{x} = [x_1, \dots, x_D]^\top$, the marginal

$$p(x_i) = \int p(x_1, \dots, x_D) d\mathbf{x}_{-i}$$

, where “ $-i$ ” means all except i .

Product Rule

Product Rule

$$p(\mathbf{x}, \mathbf{y}) = p(\mathbf{y} \mid \mathbf{x})p(\mathbf{x})$$

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Bayes' Theorem

Bayes' Theorem

$$\underbrace{p(\mathbf{x} | \mathbf{y})}_{\text{posterior}} = \frac{\overbrace{p(\mathbf{y} | \mathbf{x})}^{\text{likelihood}} \overbrace{p(\mathbf{x})}^{\text{prior}}}{\underbrace{p(\mathbf{y})}_{\text{evidence}}}.$$

- Prior: subjective prior knowledge (before observing data).
- Likelihood $p(\mathbf{y} | \mathbf{x})$: the probability of \mathbf{y} if we were to know the latent variable \mathbf{x} .
 - We call it “the likelihood of \mathbf{x} ”.
- Posterior $p(\mathbf{x} | \mathbf{y})$: the quantity that we know about \mathbf{x} after having observed \mathbf{y} .

Marginal Likelihood/Evidence

$$p(\mathbf{y}) := \sum_{\mathbf{x} \in \mathcal{X}} p(\mathbf{y} \mid \mathbf{x})p(\mathbf{x}) = \mathbb{E}_{\mathcal{X}}[p(\mathbf{y} \mid \mathbf{x})]$$

$$p(\mathbf{y}) := \int_{\mathbf{x} \in \mathcal{X}} p(\mathbf{y} \mid \mathbf{x})p(\mathbf{x})d\mathbf{x} = \mathbb{E}_{\mathcal{X}}[p(\mathbf{y} \mid \mathbf{x})].$$

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Expected Value

Expected value

The expected value of a function $g : \mathbb{R} \mapsto \mathbb{R}$ of a random variable $X \sim p(x)$ is

$$\mathbb{E}_X[g(x)] = \int_{\mathcal{X}} g(x)p(x)dx,$$

or

$$\mathbb{E}_X[g(x)] = \sum_{x \in \mathcal{X}} g(x)p(x).$$

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Multivariate $X = [X_1, \dots, X_D]^\top$

$$\mathbb{E}_X[g(\mathbf{x})] = \begin{bmatrix} \mathbb{E}_{X_1}[g(x_1)] \\ \vdots \\ \mathbb{E}_{X_D}[g(x_D)] \end{bmatrix} \in \mathbb{R}^D,$$

where \mathbb{E}_{X_d} : taking the expectation w.r.t. the x_d .

Expected Value (contd.)

Mean

For $\mathbf{x} \in \mathbb{R}^D$,

$$\mathbb{E}_X[\mathbf{x}] = \begin{bmatrix} \mathbb{E}_{X_1}[x_1] \\ \vdots \\ \mathbb{E}_{X_D}[x_D] \end{bmatrix} \in \mathbb{R}^D,$$

where

- $\mathbb{E}_{X_d}[x_d] = \int_{\mathcal{X}} x_d p(x_d) dx_d$ if X is continuous ;
- $\mathbb{E}_{X_d}[x_d] = \sum_{x_i \in \mathcal{X}} x_i p(x_d = x_i) dx_d$ if X is discrete.

Linearity of Expectation

Let $f(\mathbf{x}) = ag(\mathbf{x}) + bh(\mathbf{x})$ for $a, b \in \mathbb{R}$ and $\mathbf{x} \in \mathbb{R}^D$.

$$\begin{aligned}\mathbb{E}_X[f(\mathbf{x})] &= \int f(\mathbf{x})p(\mathbf{x})d\mathbf{x} \\ &= \int [ag(\mathbf{x}) + bh(\mathbf{x})]d\mathbf{x} \\ &= a \int g(\mathbf{x})p(\mathbf{x})d\mathbf{x} + b \int h(\mathbf{x})p(\mathbf{x})d\mathbf{x} \\ &= a\mathbb{E}_X[g(\mathbf{x})] + b\mathbb{E}_X[h(\mathbf{x})].\end{aligned}$$

Linearity of Expectation (Discrete Case)

Let $f(\mathbf{x}) = ag(\mathbf{x}) + bh(\mathbf{x})$ for $a, b \in \mathbb{R}$ and $\mathbf{x} \in \mathcal{X}$.

$$\begin{aligned}\mathbb{E}_{\mathcal{X}}[f(\mathbf{x})] &= \sum_{\mathbf{x} \in \mathcal{X}} f(\mathbf{x})p(\mathbf{x}) \\ &= \sum_{\mathbf{x} \in \mathcal{X}} [ag(\mathbf{x}) + bh(\mathbf{x})]p(\mathbf{x}) \\ &= a \sum_{\mathbf{x} \in \mathcal{X}} g(\mathbf{x})p(\mathbf{x}) + b \sum_{\mathbf{x} \in \mathcal{X}} h(\mathbf{x})p(\mathbf{x}) \\ &= a\mathbb{E}_{\mathcal{X}}[g(\mathbf{x})] + b\mathbb{E}_{\mathcal{X}}[h(\mathbf{x})].\end{aligned}$$

Covariance

The (univariate) covariance between two univariate random variables $X, Y \in \mathbb{R}$ is

$$\text{Cov}_{X,Y}[x, y] := \mathbb{E}_{X,Y}[(x - \mathbb{E}_X[x])(y - \mathbb{E}_Y[y])].$$

Omit the subscript.

$$\text{Cov}[x, y] := \mathbb{E}[xy] - \mathbb{E}[x]\mathbb{E}[y].$$

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$$\text{Cov}[x, y] := \mathbb{E}[xy] - \mathbb{E}[x]\mathbb{E}[y].$$

Note that

$$\text{Cov}[x, x] := \mathbb{E}[x^2] - (\mathbb{E}[x])^2$$

is the **variance** and denoted by $\mathbb{V}_X[x]$ and $\sqrt{\text{Cov}[x, x]}$ denoted by $\sigma(x)$ is called the **standard deviation**.

Covariance of Multivariate R.V.'s

Covariance (Multivariate)

Consider random variables X and Y with states $\mathbf{x} \in \mathbb{R}^D$ and $\mathbf{y} \in \mathbb{R}^E$. The covariance between X and Y :

$$\text{Cov}[\mathbf{x}, \mathbf{y}] =$$

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$$\text{Cov}[\mathbf{x}, \mathbf{y}] = \mathbb{E}[\mathbf{x}\mathbf{y}^\top] - \mathbb{E}[\mathbf{x}]\mathbb{E}[\mathbf{y}]^\top = \text{Cov}[\mathbf{y}, \mathbf{x}]^\top \in \mathbb{R}^{D \times E}.$$

Variance (Multivariate)

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The variance of a random variables X with states $\mathbf{x} \in \mathbb{R}^D$ and mean $\boldsymbol{\mu} \in \mathbb{R}^D$ is

$$\mathbb{V}_X[\mathbf{x}] = \text{Cov}_X[\mathbf{x}, \mathbf{x}] = \mathbb{E}_X[(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^\top]$$

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$$\begin{aligned} \mathbb{V}_X[\mathbf{x}] &= \text{Cov}_X[\mathbf{x}, \mathbf{x}] = \mathbb{E}_X[(\mathbf{x} - \boldsymbol{\mu})(\mathbf{x} - \boldsymbol{\mu})^\top] = \mathbb{E}_X[\mathbf{x}\mathbf{x}^\top] - \mathbb{E}_X[\mathbf{x}]\mathbb{E}_X[\mathbf{x}]^\top \\ &= \begin{bmatrix} \text{Cov}[x_1, x_1] & \text{Cov}[x_1, x_2] & \cdots & \text{Cov}[x_1, x_D] \\ \text{Cov}[x_2, x_1] & \text{Cov}[x_2, x_2] & \cdots & \text{Cov}[x_2, x_D] \\ \vdots & \vdots & \ddots & \vdots \\ \text{Cov}[x_D, x_1] & \text{Cov}[x_D, x_2] & \cdots & \text{Cov}[x_D, x_D] \end{bmatrix}. \end{aligned}$$

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- The **covariance matrix** of the multivariate X .

Correlation

Correlation

The correlation between two random variables X, Y is

$$\text{corr}[x, y] = \frac{\text{Cov}[x, y]}{\sqrt{\mathbb{V}[x]\mathbb{V}[y]}} \in [-1, 1].$$

Empirical Means & Covariances

In machine learning, we need to learn from empirical observations of data.

Empirical Mean & Covariance

The **empirical mean** vector: arithmetic average of the observations for each variable:

$$\bar{\mathbf{x}} := \frac{1}{N} \sum_{i=1}^N \mathbf{x}_i,$$

for $\mathbf{x}_i \in \mathbb{R}^D$. The **empirical covariance** matrix is a $D \times D$ matrix

$$\Sigma := \frac{1}{N} \sum_{i=1}^N (\mathbf{x}_i - \bar{\mathbf{x}})(\mathbf{x}_i - \bar{\mathbf{x}})^\top.$$

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$$\Sigma := \frac{1}{N} \sum_{i=1}^N (\mathbf{x}_i - \bar{\mathbf{x}})(\mathbf{x}_i - \bar{\mathbf{x}})^\top.$$

- Σ is symmetric, positive semidefinite.

Computing the Empirical Variance

Approaches:

- 1 $\mathbb{V}_X[x] := \mathbb{E}_X[(x - \mu)^2]$.
- 2 $\mathbb{V}_X[x] = \mathbb{E}_X[x^2] - (\mathbb{E}_X[x])^2$.
 - One-pass; more efficient
- 3 Averaging pairwise differences between all pairs of observations.

$$\frac{1}{N^2} \sum_{i,j=1}^N (x_i - x_j)^2 = \textcolor{red}{2} \left[\frac{1}{N} \sum_{i=1}^N x_i^2 - \left(\frac{1}{N} \sum_{i=1}^N x_i \right)^2 \right].$$

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- 2 $\mathbb{V}_X[x] = \mathbb{E}_X[x^2] - (\mathbb{E}_X[x])^2$.
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$$\frac{1}{N^2} \sum_{i,j=1}^N (x_i - x_j)^2 = 2 \left[\frac{1}{N} \sum_{i=1}^N x_i^2 - \left(\frac{1}{N} \sum_{i=1}^N x_i \right)^2 \right].$$

- Twice of the 2nd approach.
- Interesting perspective to compute the left-hand side target.

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Basic Rules

Simple Rules & Exercise

Consider two random variables X, Y with states $\mathbf{x}, \mathbf{y} \in \mathbb{R}^D$. Then,

$$\mathbb{E}[\mathbf{x} \pm \mathbf{y}] = \mathbb{E}[\mathbf{x}] \pm \mathbb{E}[\mathbf{y}]$$

$$\mathbb{V}[\mathbf{x} \pm \mathbf{y}] = \mathbb{V}[\mathbf{x}] + \mathbb{V}[\mathbf{y}] \pm \text{Cov}[\mathbf{x}, \mathbf{y}] \pm \text{Cov}[\mathbf{y}, \mathbf{x}] \quad (\text{Exercise}).$$

- **Note:** For a constant vector $\mathbf{b} \in \mathbb{R}^D$, $\mathbb{V}(\mathbf{x} \pm \mathbf{b}) = \mathbb{V}[\mathbf{x}]$ because $\mathbb{V}[\mathbf{b}] = \mathbb{E}[\mathbf{b}\mathbf{b}^\top] - \mathbb{E}[\mathbf{b}]\mathbb{E}[\mathbf{b}]^\top = \mathbf{b}\mathbf{b}^\top - \mathbf{b}\mathbf{b}^\top = \mathbf{0}$ and

$$\text{Cov}(\mathbf{x}, \mathbf{b})$$

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- **Note:** For a constant vector $\mathbf{b} \in \mathbb{R}^D$, $\mathbb{V}(\mathbf{x} \pm \mathbf{b}) = \mathbb{V}[\mathbf{x}]$ because $\mathbb{V}[\mathbf{b}] = \mathbb{E}[\mathbf{b}\mathbf{b}^\top] - \mathbb{E}[\mathbf{b}]\mathbb{E}[\mathbf{b}]^\top = \mathbf{b}\mathbf{b}^\top - \mathbf{b}\mathbf{b}^\top = \mathbf{0}$ and

$$\text{Cov}(\mathbf{x}, \mathbf{b}) = \mathbb{E}[\mathbf{x}\mathbf{b}^\top] - \mathbb{E}[\mathbf{x}]\mathbb{E}[\mathbf{b}]^\top$$

Basic Rules

Simple Rules & Exercise

Consider two random variables X, Y with states $\mathbf{x}, \mathbf{y} \in \mathbb{R}^D$. Then,

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- **Note:** For a constant vector $\mathbf{b} \in \mathbb{R}^D$, $\mathbb{V}(\mathbf{x} \pm \mathbf{b}) = \mathbb{V}[\mathbf{x}]$ because $\mathbb{V}[\mathbf{b}] = \mathbb{E}[\mathbf{b}\mathbf{b}^\top] - \mathbb{E}[\mathbf{b}]\mathbb{E}[\mathbf{b}]^\top = \mathbf{b}\mathbf{b}^\top - \mathbf{b}\mathbf{b}^\top = \mathbf{0}$ and

$$\text{Cov}(\mathbf{x}, \mathbf{b}) = \mathbb{E}[\mathbf{x}\mathbf{b}^\top] - \mathbb{E}[\mathbf{x}]\mathbb{E}[\mathbf{b}]^\top = \mathbb{E}[\mathbf{x}]\mathbf{b}^\top - \mathbb{E}[\mathbf{x}]\mathbf{b}^\top = \mathbf{0}.$$

- **Question:** Why does the second equality hold?

Consider $\mathbf{y} = \mathbf{A}\mathbf{x} + \mathbf{b}$ and let $\Sigma := \mathbb{V}_X[\mathbf{x}]$.

$$\mathbb{E}_Y[\mathbf{y}] = \mathbb{E}_X[\mathbf{Ax} + \mathbf{b}] = \mathbf{A}\mathbb{E}_X[\mathbf{x}] + \mathbf{b}$$

$$\mathbb{V}_Y[\mathbf{y}] = \mathbb{V}_X[\mathbf{A}\mathbf{x} + \mathbf{b}] = \mathbb{V}_X[\mathbf{A}\mathbf{x}] = \mathbf{A}\mathbb{V}_X[\mathbf{x}]\mathbf{A}^\top = \mathbf{A}\Sigma\mathbf{A}^\top.$$

A set of small navigation icons typically found in Beamer presentations, including symbols for back, forward, search, and other slide controls.

Affine Transformation of r.v.'s (2/2)

Furthermore, let $\boldsymbol{\mu} := \mathbb{E}_X[\mathbf{x}]$ and $\boldsymbol{\Sigma} := \mathbb{V}_X[\mathbf{x}]$.

$$\begin{aligned}\text{Cov}[\mathbf{x}, \mathbf{y}] &= \mathbb{E}[\mathbf{x}(\mathbf{Ax} + \mathbf{b})^\top] - \mathbb{E}[\mathbf{x}]\mathbb{E}[\mathbf{Ax} + \mathbf{b}]^\top \\ &= \boldsymbol{\mu}\mathbf{b}^\top + \mathbb{E}[\mathbf{xx}^\top]\mathbf{A}^\top - \boldsymbol{\mu}\mathbf{b}^\top - \boldsymbol{\mu}\boldsymbol{\mu}^\top\mathbf{A}^\top \\ &= (\mathbb{E}[\mathbf{xx}^\top] - \boldsymbol{\mu}\boldsymbol{\mu}^\top)\mathbf{A}^\top \\ &= \boldsymbol{\Sigma}\mathbf{A}^\top.\end{aligned}$$

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(Statistically) Independent

Two random variables X, Y are statistically independent if and only if

$$p(\mathbf{x}, \mathbf{y}) = p(\mathbf{x})p(\mathbf{y}).$$

If X, Y are independent, then

- $p(\mathbf{y} \mid \mathbf{x}) = p(\mathbf{y})$.
- $p(\mathbf{x} \mid \mathbf{y}) = p(\mathbf{x})$.
- $\mathbb{V}_{X,Y}[\mathbf{x} + \mathbf{y}] = \mathbb{V}_X[\mathbf{x}] + \mathbb{V}_Y[\mathbf{y}]$.
- $\text{Cov}_{X,Y}(\mathbf{x}, \mathbf{y}) = \mathbf{0}$.

Note that $\text{Cov}_{X,Y}(\mathbf{x}, \mathbf{y}) = \mathbf{0}$ does NOT necessarily imply that X and Y are independent.

See Example (6.5).

Conditional Independence

Two random variables X, Y are conditionally independent given Z if and only if

$$p(\mathbf{x}, \mathbf{y} \mid \mathbf{z}) = p(\mathbf{x} \mid \mathbf{z})p(\mathbf{y} \mid \mathbf{z}).$$

for all $\mathbf{z} \in \mathcal{Z}$.

By the product rule, we can have

$$p(\mathbf{x}, \mathbf{y} \mid \mathbf{z}) = p(\mathbf{x} \mid \mathbf{y}, \mathbf{z})p(\mathbf{y} \mid \mathbf{z}).$$

Thus,

$$p(\mathbf{x} \mid \mathbf{y}, \mathbf{z}) = p(\mathbf{x} \mid \mathbf{z}).$$

Heads Up

If X, Y are independent, then $\mathbb{V}_{X,Y}[\mathbf{x} + \mathbf{y}] = \mathbb{V}_X[\mathbf{x}] + \mathbb{V}_Y[\mathbf{y}]$.

$$\therefore \text{Cov}_{X,Y}(\mathbf{x}, \mathbf{y}) = \mathbf{0}$$

Discussions