

Existence of Pure-Strategy Nash Equilibria in a Two-Party Policy Competition Game Extending to the General Case

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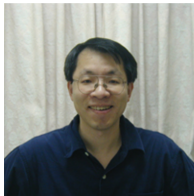
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Outline

- 1 Motivations
- 2 The Setting
- 3 Our Contribution
- 4 Concluding Remarks

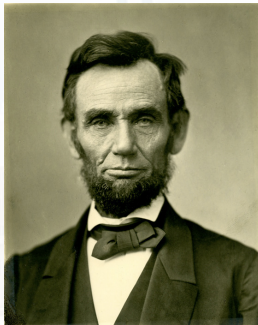


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The Inspiration (an EC'17 paper)

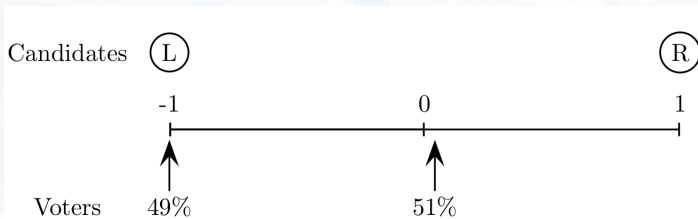


"[...] and that government of the people, by the people, for the people, shall not perish from the earth."

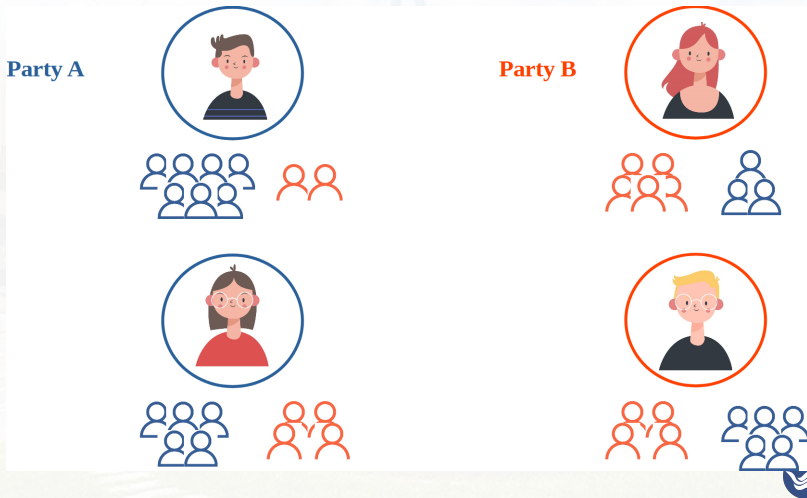
— Abraham Lincoln, 1863.



Previous Work (I): Distortion of Social Choice Rules



Previous Work (II): Two-Party Election Game



Previous Work (II): Two-Party Election Game

- Parties are players.
- Strategies: their candidates (or policies).
- A candidate beats the other candidates from other candidates of other parties with **uncertainty**.
- The payoff of each party: **expected utility** its supporters can get.



Previous Work (II): Two-Party Election Game (contd.)

- Party A : m candidates, party B : n candidates.
- Candidate A_i can bring social utility $u(A_i) = u_A(A_i) + u_B(A_i) \in [0, \beta]$ for some real $\beta \geq 0$.
- $p_{i,j}$: $\Pr[A_i \text{ wins over } B_j]$.
 - E.g., **Linear**: $p_{i,j} := (1 + (u(A_i) - u(B_j))/\beta)/2$
- Payoff (reward) $r_A = p_{i,j}u_A(A_i) + (1 - p_{i,j})u_A(B_j)$.



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- $p_{i,j}$: $\Pr[A_i \text{ wins over } B_j]$. more utility for all the people, more likely to win
 - E.g., **Linear**: $p_{i,j} := (1 + (u(A_i) - u(B_j))/\beta)/2$
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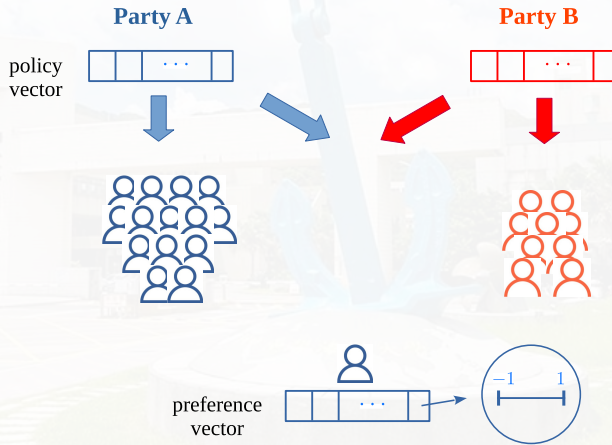


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Policies and Preferences



The Setting

- Policy vectors: $\mathbf{z}_A, \mathbf{z}_B \in S \subset \mathbb{R}^k$.
 - $\|\mathbf{z}_A\| \leq 1$ and $\|\mathbf{z}_B\| \leq 1$.
 - State (or profile): $\mathbf{z} := (\mathbf{z}_A, \mathbf{z}_B)$.

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- V_A and V_B : the supporters of A and B .
 - $V := V_A \dot{\cup} V_B, |V| = n$.
- Preference vector of a voter $v \in V$: \mathbf{q}_v .
- $Q_A := \sum_{v \in V_A} \mathbf{q}_v, Q_B := \sum_{v \in V_B} \mathbf{q}_v, Q := Q_A + Q_B,$
 $\|Q_A\|, \|Q_B\| \leq 1$.



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 $\|Q_A\|, \|Q_B\| \leq 1$.
- The utility

$$u_A(\mathbf{z}_A) = \sum_{v \in V_A} \mathbf{z}_A^\top \mathbf{q}_v = \mathbf{z}_A^\top Q_A, \quad u_B(\mathbf{z}_A) = \sum_{v \in V_B} \mathbf{z}_A^\top \mathbf{q}_v = \mathbf{z}_A^\top Q_B.$$

$$u_A(\mathbf{z}_B) = \sum_{v \in V_A} \mathbf{z}_B^\top \mathbf{q}_v = \mathbf{z}_B^\top Q_A, \quad u_B(\mathbf{z}_B) = \sum_{v \in V_B} \mathbf{z}_B^\top \mathbf{q}_v = \mathbf{z}_B^\top Q_B.$$



The Setting (Winning Prob. & Payoff)

- Winning probability:

$$\begin{aligned}p_{A \succ B} &= \frac{1}{2} + \frac{1}{4}(\mathbf{z}_A - \mathbf{z}_B)^\top \mathbf{Q}, \\p_{B \succ A} &= \frac{1}{2} + \frac{1}{4}(\mathbf{z}_B - \mathbf{z}_A)^\top \mathbf{Q}.\end{aligned}$$

- 1/4: a normalization factor.
- The payoffs:

$$\begin{aligned}R_A(\mathbf{z}) &= p_{A \succ B} \cdot \mathbf{z}_A^\top \mathbf{Q}_A + p_{B \succ A} \cdot \mathbf{z}_B^\top \mathbf{Q}_A, \\R_B(\mathbf{z}) &= p_{B \succ A} \cdot \mathbf{z}_B^\top \mathbf{Q}_B + p_{A \succ B} \cdot \mathbf{z}_A^\top \mathbf{Q}_B.\end{aligned}$$



So, we can compute the gradients and Hessian...

$$\frac{\partial R_A(\mathbf{z})}{\partial \mathbf{z}_A} = \frac{1}{2}Q_A + \frac{(\mathbf{z}_A - \mathbf{z}_B)^\top Q}{4kn}Q_A + \frac{(\mathbf{z}_A - \mathbf{z}_B)^\top Q_A}{4kn}Q.$$

$$\frac{\partial R_B(\mathbf{z})}{\partial \mathbf{z}_B} = \frac{1}{2}Q_B + \frac{(\mathbf{z}_B - \mathbf{z}_A)^\top Q}{4kn}Q_B + \frac{(\mathbf{z}_B - \mathbf{z}_A)^\top Q_B}{4kn}Q.$$

$$\frac{\partial^2 R_A(\mathbf{z})}{\partial \mathbf{z}_A^2}[i, j] = \frac{1}{4}(Q[i]Q_A[j] + Q[j]Q_A[i]),$$

$$\frac{\partial^2 R_B(\mathbf{z})}{\partial \mathbf{z}_B^2}[i, j] = \frac{1}{4}(Q[i]Q_B[j] + Q[j]Q_B[i]).$$



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Previous Contributions

[Nash 1950]

Every FINITE game has a **mixed-strategy** Nash equilibrium.

Our Contribution

In this work, we show that there **exists** a **pure-strategy Nash equilibrium (PSNE)** in the two-party policy competition game for

- the degenerate case: $k = 1$
- the general case $k \geq 1$ under the **consensus-reachable** condition
- The two-party policy competition game is NOT a finite game.
- The above PSNE consists of dominant-strategies.



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- the degenerate case: $k = 1$
 - the general case $k \geq 1$ under the **consensus-reachable** condition
 - the general case $k \geq 1$ for **non-consensus-reachable condition yet under a mild assumption.**
-
- The two-party policy competition game is NOT a finite game.
 - The above PSNE consists of dominant-strategies.



Claim of the Egoistic Property

Claim

The egoistic property must hold in the two-party policy competition game.

- $\mathbf{z}_A^\top Q_A \geq \mathbf{z}_B^\top Q_A$ and $\mathbf{z}_B^\top Q_B \geq \mathbf{z}_A^\top Q_B$.



The General Case: $k \geq 1$ — Simplification by Polar Coordinates

- It is sufficient for party A and B to consider the space $\text{span}(\{Q_A, Q_B\})$.
- Represent \mathbf{z}_A (resp., \mathbf{z}_B) in terms of **polar coordinates** (r_A, θ_A) (resp., (r_B, θ_B)).
 - $r_A = \|\mathbf{z}_A\|, r_B = \|\mathbf{z}_B\|$
 - θ_A (resp., θ_B) is the angle b/w Q_A and \mathbf{z}_A (resp., Q_B and \mathbf{z}_B).

For any two vectors $\mathbf{u}, \mathbf{v} \in \mathbb{R}^k, k \geq 1$,

$$\langle \mathbf{u}, \mathbf{v} \rangle = \|\mathbf{u}\| \|\mathbf{v}\| \cos(\theta),$$

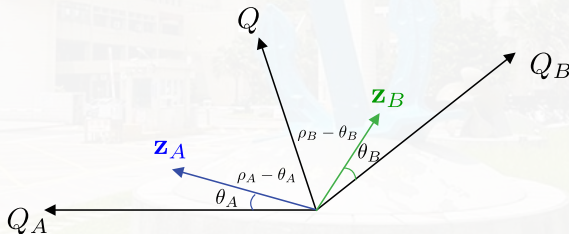
where θ is the angle b/w \mathbf{u} and \mathbf{v} .



A Good Condition

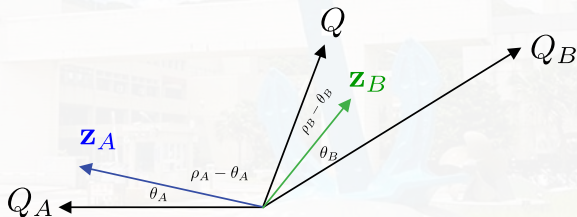
Consensus-Reachable

A two-party policy competition game is *consensus-reachable* if $Q_A^\top Q \geq 0$ and $Q_B^\top Q \geq 0$.



An Example of Not Consensus-Reachable

$$\rho_A > \pi/2.$$



About the Norms r_A, r_B

- A mild assumption: $\theta_A, \theta_B \leq \pi/2$.

Lemma

For the nonconsensus-reachable case where $\rho_A > \pi/2$ and $\theta_A, \theta_B \in [0, \pi/2]$, the best responses of the two players always set $r_A = r_B = 1$.

Sketch of the proof:

- Show that $\frac{\partial R_A(\mathbf{r}, \theta)}{\partial r_A} \big|_{\theta_A = \rho_A - \pi/2} \geq 0$.
- For $\theta \in [0, \rho_A - \theta_A]$, we can show that $\frac{\partial^2 R_A(\mathbf{r}, \theta)}{\partial r_A^2} \leq 0$.
- Hence, it follows that $\frac{\partial R_A(\mathbf{r}, \theta)}{\partial r_A} \geq 0$ for $\theta_A \in [0, \rho_A - \pi/2]$.
- Combining $\frac{\partial^2 R_A(\mathbf{r}, \theta)}{\partial r_A^2} \geq 0$ for $\theta_A \in [\rho_A - \pi/2, \pi/2]$, we have $\frac{\partial R_A(\mathbf{r}, \theta)}{\partial r_A} \geq 0$ for $\theta_A \in [0, \pi/2]$.



About the angles: θ_A, θ_B

- Set $x := \cos(\theta_A)$ and $y := \cos(\theta_B)$.
- Let $f(x) := R_A(r_A = 1, \theta_A)$ and $g(y) := R_B(r_B = 1, \theta_B)$, $x, y \in [0, 1]$.

$$\begin{aligned}
 f(x) &= \left(\frac{1}{2} + D_0(C_1 x + \sqrt{1 - C_1^2} \sqrt{1 - x^2} - C_3) \right) D_1 x \\
 &\quad + \left(\frac{1}{2} - D_0(C_1 x + \sqrt{1 - C_1^2} \sqrt{1 - x^2} - C_3) \right) D_1 C_4, \\
 g(y) &= \left(\frac{1}{2} + D_0(C_2 y + \sqrt{1 - C_2^2} \sqrt{1 - y^2} - C'_3) \right) D_2 y \\
 &\quad + \left(\frac{1}{2} - D_0(C_2 y + \sqrt{1 - C_2^2} \sqrt{1 - y^2} - C'_3) \right) D_2 C'_4,
 \end{aligned}$$

$$\begin{aligned}
 \text{subject to: } & 0 \leq D_0 \leq \frac{1}{2}, \quad 0 \leq D_1 \leq 1, \quad -1 \leq C_1 < 0, \quad 0 \leq C_2 \leq 1, \\
 & 0 \leq C_3 \leq 1, \quad -1 \leq C_4 < 0, \quad -1 \leq C'_3 \leq 1, \quad -1 \leq C'_4 \leq 1, \\
 & C_4 \leq C_1, \quad 0 \leq D_2 \leq 1, \quad D_0 \leq D_2 \text{ and } C'_4 \leq C_2,
 \end{aligned}$$

where $D_0 := \|Q\|/4$, $D_1 := \|Q_A\|$, $D_2 := \|Q_B\|$, $C_1 := \cos \rho_A$, $C_2 := \cos \rho_B$,
 $C_3 := \cos(\rho_B - \theta_B)$, $C'_3 := \cos(\rho_A - \theta_A)$, $C_4 := \cos(\rho_A + \rho_B - \theta_B)$,
 $C'_4 := \cos(\rho_A + \rho_B - \theta_A)$.



About the angles: θ_A, θ_B (contd.)

Lemma

$f(x)$ is concave and $g(y)$ is unimodal (quasi-concave).

- Therefore, Kakutani's Fixed-Point Theorem can be applied to guarantee the existence of a PSNE of the game even when it is NOT consensus-reachable.

Theorem

Under the mild condition that $\mathbf{z}_A^\top Q_A \geq 0$ and $\mathbf{z}_B^\top Q_B \geq 0$, the two-party policy competition game has at least one PSNE even when the game is not consensus-reachable.



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Future and Ongoing Work (1/3)

Monotone Game

A pseudo-gradient mapping of the game

$$F : \mathcal{D} \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

is said to be *monotone* if for all $\mathbf{u} = (x_1, y_1)$ and $\mathbf{v} = (x_2, y_2)$ in the domain one has

$$(F(\mathbf{u}) - F(\mathbf{v}))^\top (\mathbf{u} - \mathbf{v}) \geq 0.$$



Future and Ongoing Work (2/3)

Cocoercivity

A pseudo-gradient mapping of the game

$$F : \mathcal{D} \subseteq \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

is said to be λ -cocoercive (for some $\lambda > 0$) if for all $\mathbf{u} = (x_1, y_1)$ and $\mathbf{v} = (x_2, y_2)$ in the domain one has

$$(F(\mathbf{u}) - F(\mathbf{v}))^\top (\mathbf{u} - \mathbf{v}) \geq \lambda \|F(\mathbf{u}) - F(\mathbf{v})\|^2.$$



A Special Case for Further Progress

Counterexample of Monotonicity

The two-party policy competition game is NOT monotone in general, and hence not cocoercive for any $\lambda \leq 1$.

Theorem

The two-party policy competition game is λ -cocoercive for $\lambda = 1/\|Q_A\|^2$ if it is voter-symmetric.

- Voter-symmetric: $Q_A = Q_B$.
- E.g., Pre-Election within-in the party.



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- Voter-symmetric: $Q_A = Q_B$.
- E.g., Pre-Election within-in the party.
- One can apply gradient-based algorithms to find a PSNE with convergence rate $O(1/T)$ in this case.



Thanks for your attention!

Q & A

