

Minimum Cost Spanning Trees (MSTs)

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Outline

1 Introduction

2 Kruskal's algorithm

3 Prim's algorithm

4 Sollin's algorithm

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Cost & Minimum-Cost Spanning Tree

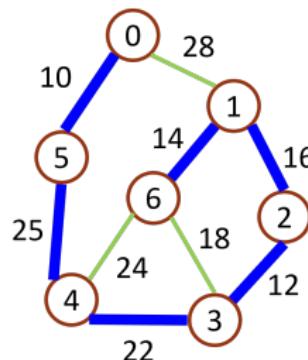
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$$\text{cost} = 10 + 25 + 22 + 12 + 16 + 14 = 99.$$

$$\text{cost} = 28 + 16 + 12 + 22 + 24 + 25 = 127.$$

Greedy Methods

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 - Kruskal's algorithm
 - Prim's algorithm
 - Sollin's algorithm
- ★ Further reading: Greedy Algorithms & Matroids [[link](#)]

Greedy Method (1/2)

- Construct an optimal solution in stages.
- A feasible solution is one which works within the constraints specified by the problem.
- At each stage, we make a decision that is **the best decision at that time**.
- Typically, The selection of an item at each stage is based on either **a least cost** or **a highest profit** criterion.

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 - We must use only edges within the graph.
 - Exactly $n - 1$ edges are used.
 - Never use edges that would produce a cycle.

TBD

```
void transpose(term a[], term b[]) { // b is set to the transpose of a
    int n, i, j, currentb;
    n = a[0].value; // total number of elements
    b[0].row = a[0].col; // rows in b = columns in a
    b[0].col = a[0].row; // columns in b = rows in a
    b[0].value = n;
    if (n > 0) { // dealing with a nonzero matrix
        currentb = 1;
        for (i=0; i<a[0].col; i++) // transpose by the columns in a
            for (j=1; j<=n; j++) // find elements from the current column
                if (a[j].col == i) { // element is in current column, add it to b
                    b[currentb].row = a[j].col;
                    b[currentb].col = a[j].row;
                    b[currentb].value = a[j].value;
                    currentb++;
                }
    }
}
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 - How to do this? \Rightarrow Union-Find Operations!
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- Time complexity: $O(e \log e)$.

Illustration of Kruskal's Algorithm

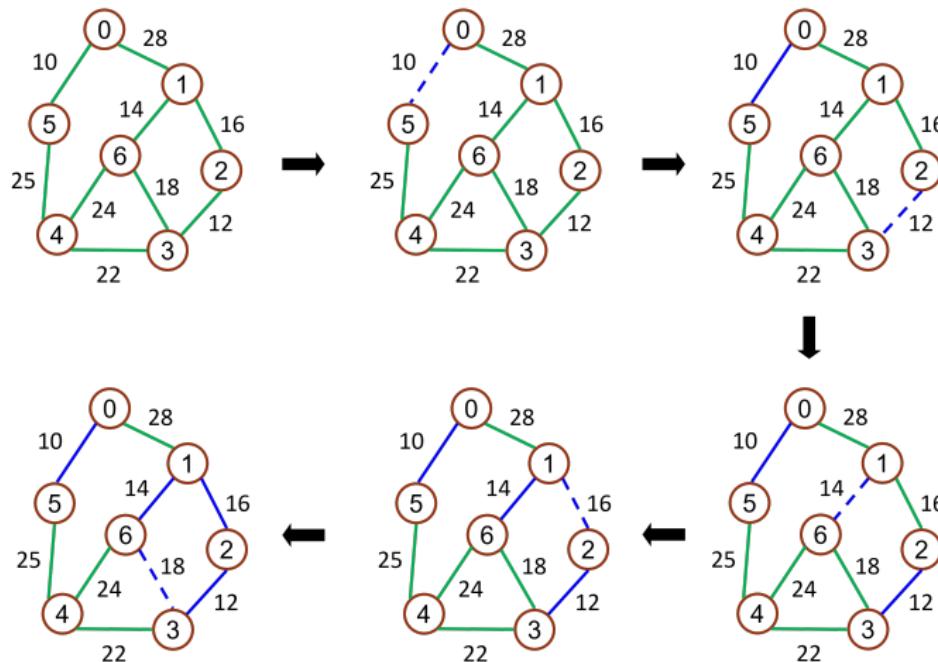
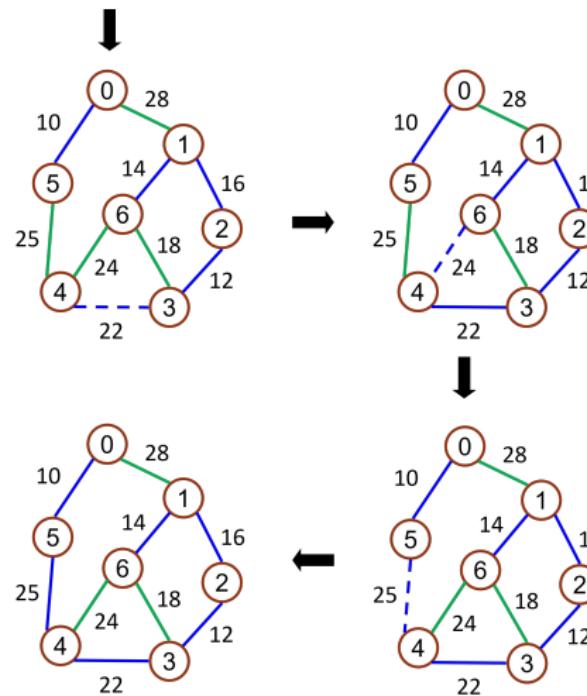


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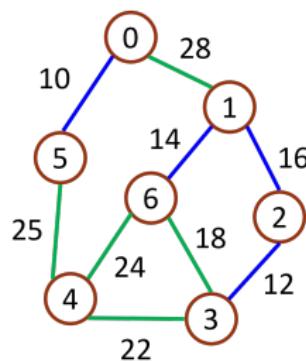


Union-Find Operations

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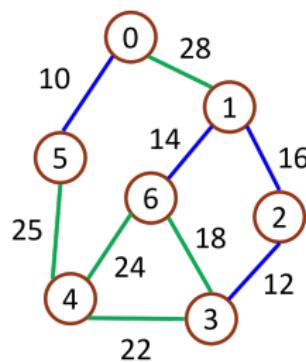
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- $\{0, 5\}, \{1, 2, 3, 6\}, \{4\}$: the sets corresponding to existing subtrees.
- Vertex 3 and 6 are already in the same set \Rightarrow edge $(3, 6)$ is rejected!

The Pseudo-code of Kruskal's Algorithm

```
T = { };
while (T contains fewer than n-1 edges && E is not empty) {
    choose a least cost edge (v,w) from E;
    delete (v,w) from E;
    if ((v,w) does not create a cycle in T)
        add (v,w) to T
    else
        discard (v,w);
}
if (T contains fewer than n-1 edges)
    printf("No spanning tree\n");
```

- How could “No spanning tree” happen?
- e union-find takes $O(e \log^* e)$ time ([supplementary](#))

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- The main difference:
 - The set of selected edges forms a **tree at all times** in Prim's algorithm.
 - The set of selected edges in Kruskal's algorithm forms a *forest at each stage*.

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- Repeat this edge addition until T contains $n - 1$ edges.

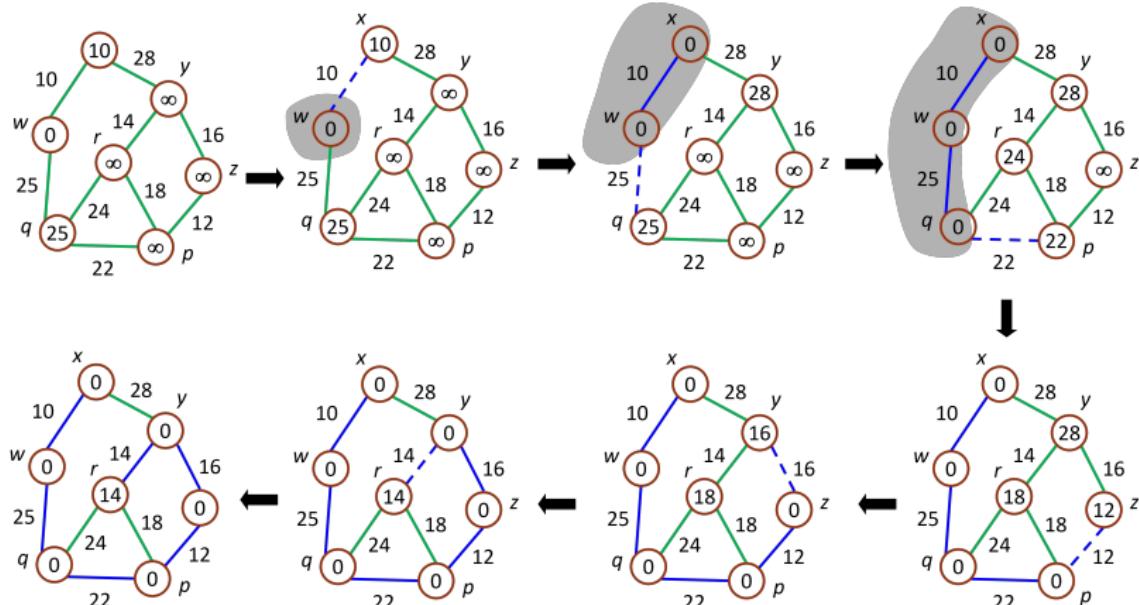
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Time complexity: $O(n^2)$.



Illustration of Prim's Algorithm



Prim's Algorithm (3/3)

```
T = {};
TV = {0};

while (T contains fewer than n-1 edges) {
    let (u,v) be a least cost edge such that u is in TV and
    v is not in TV;
    if (there is no such edge )
        break;
    add v to TV;
    add (u,v) to T;
}
if (T contains fewer than n-1 edges)
    printf("No spanning tree\n");
```

- Each vertex $v \notin TV$ has a companion vertex “ $\text{near}(v)$ ” such that $\text{near}(v) \in TV$ and $\text{cost}(\text{near}(v), v)$ is minimum over all such choices for $\text{near}(v)$.
- Therefore, it takes $O(n)$ time to choose an edge.
- We can implement Prim's algorithm in $O(n^2)$ time.

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Sollin's Algorithm (1/2)

- Sollin's algorithm selects several edges for inclusion in T at each stage.
- At the start of a stage, the selected edges, together with all the n vertices, form a spanning forest.
- During each stage, we select one edge for each tree in the forest.
 - This edge is a minimum cost edge that has exactly one vertex in the tree.

Sollin's Algorithm (2/2)

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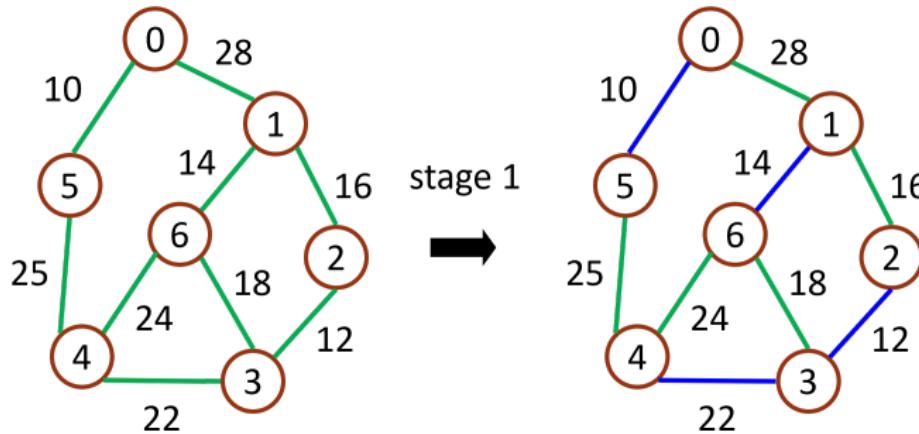
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- **Note:** two trees in the forest could select the same edge.
 - We need to **eliminate duplicate edges**.
- At the start of the first stage the set of selected edges is empty.
- The algorithm terminates when there is **only one tree at the end of a stage** or **no edges remain for selection**.

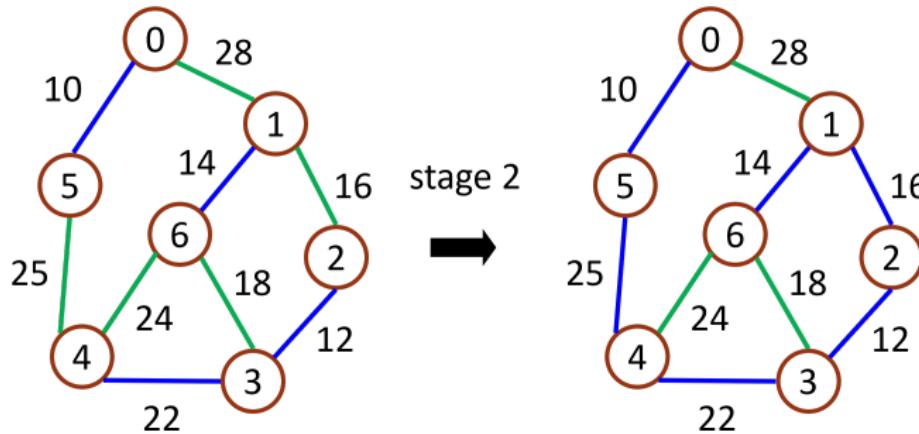
We can implement Sollin's algorithm in
 $O(e \log v)$ time.

Illustration of Sollin's Algorithm



- Stage 1: $(0,5), (1,6), (2,3), (3,2), (4,3), (5,0)$, and $(6,1)$ are selected, and then duplicates are removed.

Illustration of Sollin's Algorithm



- Stage 2: $(5, 4), (1, 2)$, and $(2, 1)$ are selected, and then duplicates are removed.

Discussions