

# Threaded Binary Tree & Heaps

Joseph Chuang-Chieh Lin (林莊傑)

Department of Computer Science & Engineering,  
National Taiwan Ocean University

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# Outline

- ① Threaded Binary Trees (引線二元樹)
- ② Heaps

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1 Threaded Binary Trees (引線二元樹)

2 Heaps

# Threaded Binary Trees

## Issue

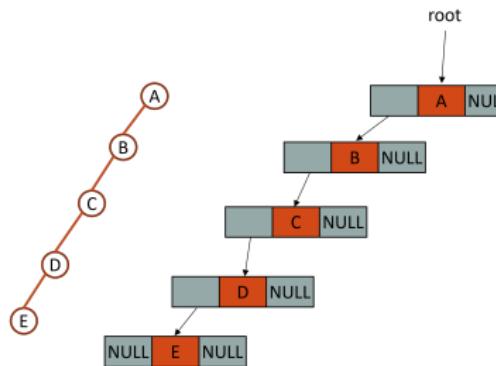
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# Threaded Binary Trees

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- Number of nodes:  $n$ .
- Number of null non-null links:  $n - 1$ .
- Number of null links:  $n + 1$ .

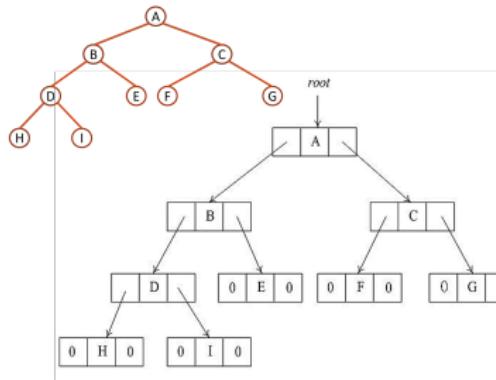


# Threaded Binary Trees

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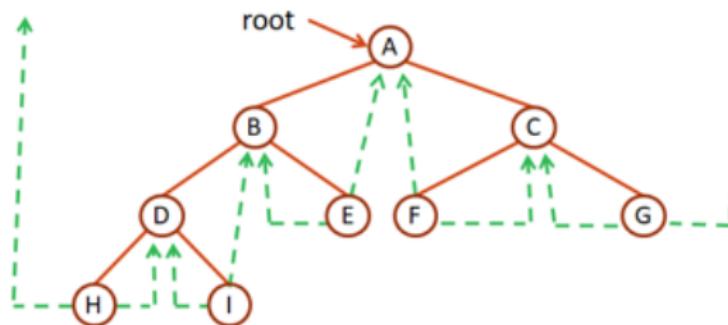
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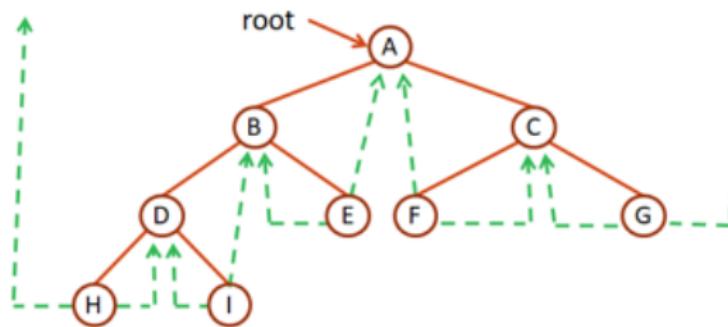
# Solution

Replace the NULL Links by pointers, **threads**, pointing to other nodes.



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## Threading Rules

- if  $\text{ptr} \rightarrow \text{leftChild}$  is NULL, then  $\text{ptr} \rightarrow \text{leftChild} = \text{inorder predecessor}$  (中序前行者) of  $\text{ptr}$ .
- if  $\text{ptr} \rightarrow \text{rightChild}$  is NULL, then  $\text{ptr} \rightarrow \text{rightChild} = \text{inorder successor}$  (中序後續者) of  $\text{ptr}$ .

# To distinguish between normal pointers and threads

- Two **additional** fields of the node structure: **left-thread**, **right-thread**.

```
typedef struct threadedTree *threadedPointer;

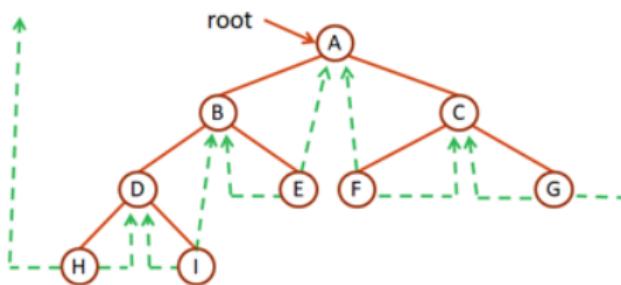
typedef struct threadedTree {
    short int leftThread;
    threadedPointer leftChild;
    char data;
    threadedPointer rightChild;
    short int rightThread;
};
```

leftThread	leftChild	data	rightChild	rightThread
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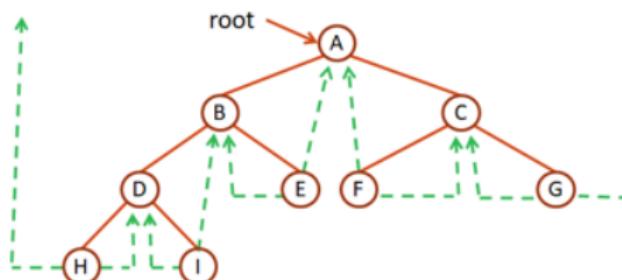
# Rules of the Threading Fields

- If  $\text{ptr} \rightarrow \text{leftThread} == \text{TRUE}$ ,  $\text{ptr} \rightarrow \text{leftChild}$  contains a thread; Otherwise, the node contains a pointer to the left child.
- If  $\text{ptr} \rightarrow \text{rightThread} == \text{TRUE}$ ,  $\text{ptr} \rightarrow \text{rightChild}$  contains a thread; Otherwise, the node contains a pointer to the right child.



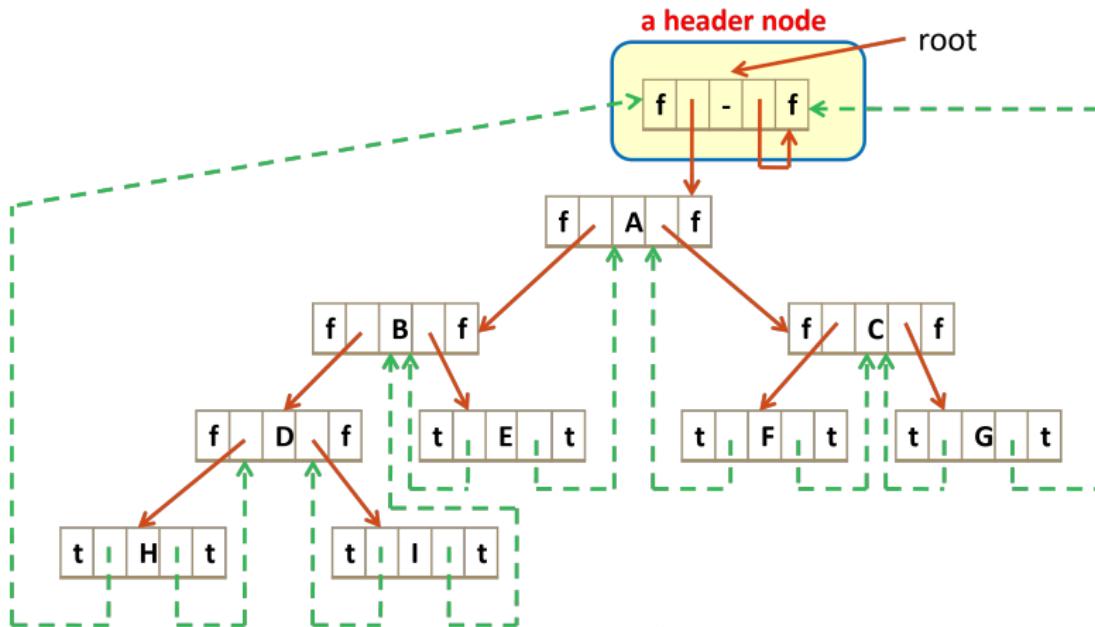
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- Two **dangling** threads at node  $H$  and  $G$ .  
 ⇒ Use a header node to collect them!

- The original tree becomes the left subtree of the head node.



Inorder sequence: H D I B E A F C G



# Representing an Empty Binary Tree

leftThread	leftChild	data	rightChild	rightThread
true	:	-	.	false

```
graph LR; LT1[true] --- LC1[::]; LC1 --- D1[-]; D1 --- RC1[.]; RC1 --- RT1[false];
```

# Finding the Inorder Successor of Node

```
threadedPointer insucc(threadedPointer tree) {  
    /* find the inorder successor of tree in a threaded  
       binary tree */  
    threadedPointer temp;  
    temp = tree->rightChild;  
    if (!tree->rightThread) // rightChild exists!  
        while (!temp->leftThread)  
            temp = temp->leftChild;  
    return temp;  
}
```

To perform an inorder traversal, we can simply make repeated calls to insucc!



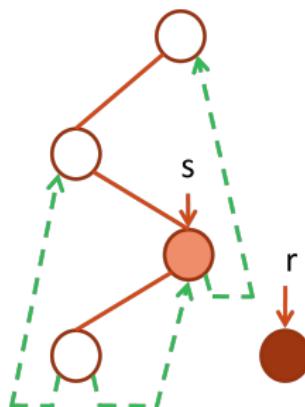
# Inorder Traversal of a Threaded Binary Tree

```
void traverseInorder(threadedPointer tree) {
    /* traverse the threaded binary tree inorder */
    threadedPointer temp = tree;
    while (1) {
        temp = insucc(temp);
        if (temp == tree)
            break;
        printf("%3c", temp->data);
    }
}
```

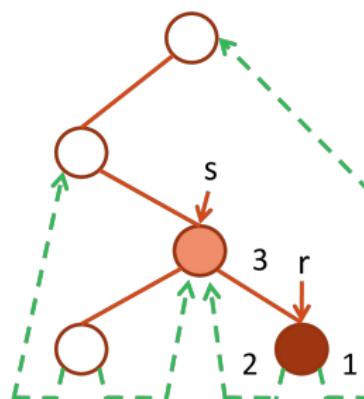


# Inserting $r$ as the rightChild of a node $s$

- Case I:  $s \rightarrow \text{rightThread} == \text{False}$



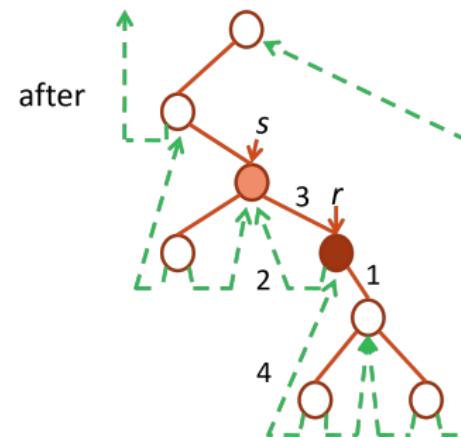
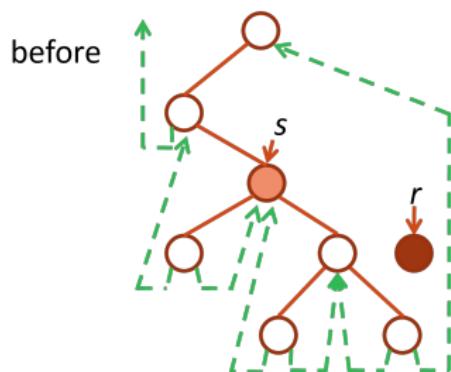
before



after

# Inserting $r$ as the rightChild of a node $s$

- Case II:  $s \rightarrow \text{rightThread} \neq \text{False}$

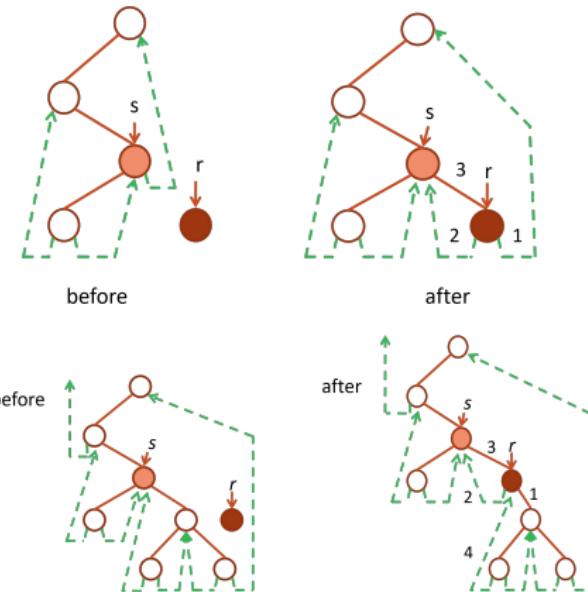


# The Code for the Insertion

```

void insertRight (threadedPointer s,
                  threadedPointer r) {
/* insert r as the right child of s */
    threadedPointer temp;
    r->rightChild = s->rightChild;
    r->rightThread = s->rightThread;
    r->leftChild = s;
    r->leftThread = TRUE;
    s->rightChild = r;
    s->rightThread = FALSE;
    if (!r->rightThread){ // step 4
        temp = insucc(r);
        temp->leftChild = r;
    }
}

```



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1 Threaded Binary Trees (引線二元樹)

2 Heaps

# Heaps

## Max Tree

A **max tree** is a tree in which

- the key value in each node  $\geq$  the key values in its children.

# Heaps

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A **max tree** is a tree in which

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## Min Tree

A **min tree** is a tree in which

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# Heaps

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A **min tree** is a tree in which

- the key value in each node  $\leq$  the key values in its children.

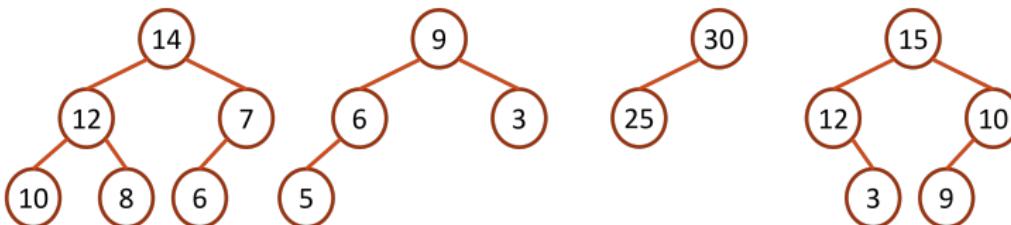
## Max Heap

A complete binary tree that is also a max tree.

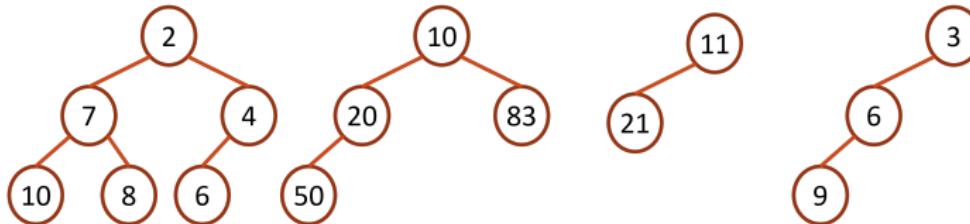
## Min Heap

A complete binary tree that is also a min tree.

# Examples: Max & Min Trees

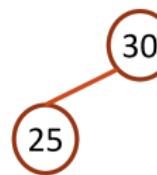
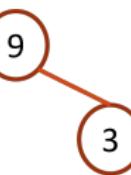
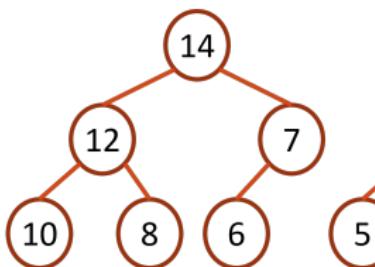


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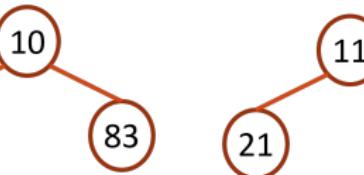
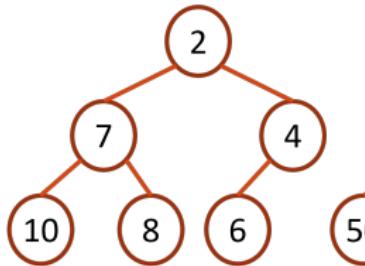


Min Trees

# Examples: Max & Min Heaps



Max Heaps



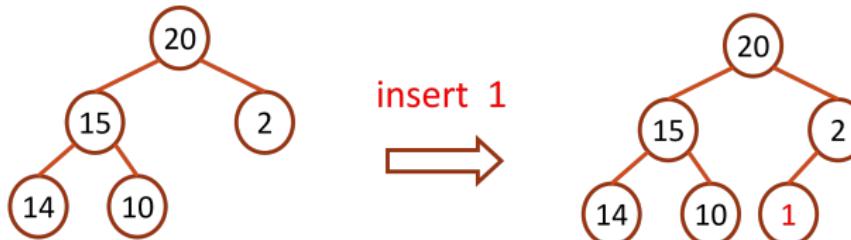
Min Heaps

# The Key Application: Priority Queues

- Heaps are frequently used to implement **priority queues**.
- In this kind of queue,
  - the element to be **deleted** is the one with **highest** (or **lowest**) priority.
  - at **any time**, an element with **arbitrary priority** can be **inserted** into the queue.

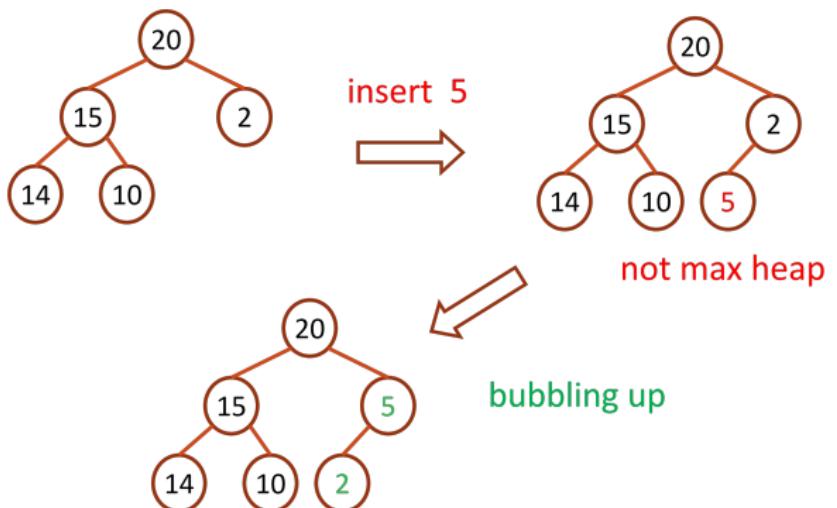
# Insertion into a Max Heap

- The **bubbling process**.
  - It begins at the new node of the tree and moves toward the root.



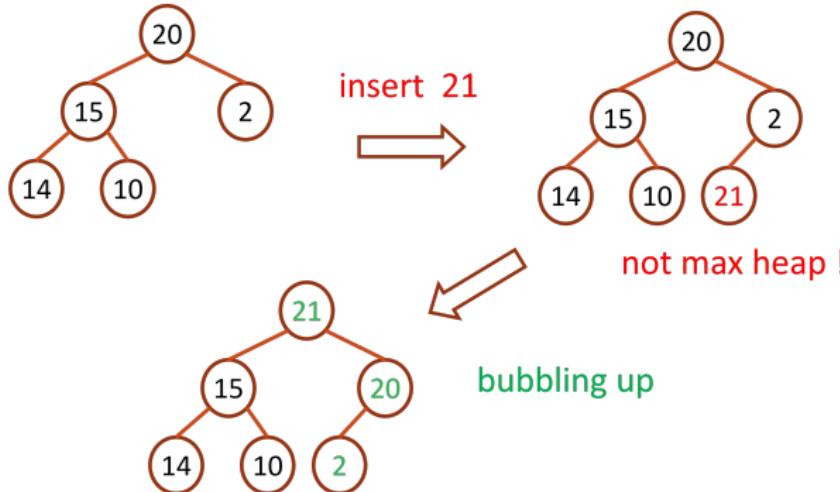
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# The Code for Insertion into a Max Heap

- Consider the following declarations:

```
#define MAX_ELEMENTS 200 /* maximum heap size+1 */  
#define HEAP_FULL (n) (n == MAX_ELEMENTS -1)  
#define HEAP_EMPTY (n) (!n)  
typedef struct {  
    int key;  
    /* other fields */  
} element;  
element heap[MAX_ELEMENTS];  
int n = 0;
```

# The Code for Insertion into a Max Heap

```
void push (element item, int *n) {
    /* insert item into a max heap of current size *n */
    int i;
    if (HEAP_FULL(*n)) {
        printf("The heap is full.\n");
        exit(EXIT_FAILURE);
    } // O(1) time
    i = ++(*n);
    while ((i != 1) && (item.key > heap[i/2].key)) {
        heap[i] = heap[i/2];
        i /= 2;
    } // O(lg n) time
    heap[i] = item; // O(1) time
}
```

- The time complexity of the insertion:  $O(\lg n)$ .



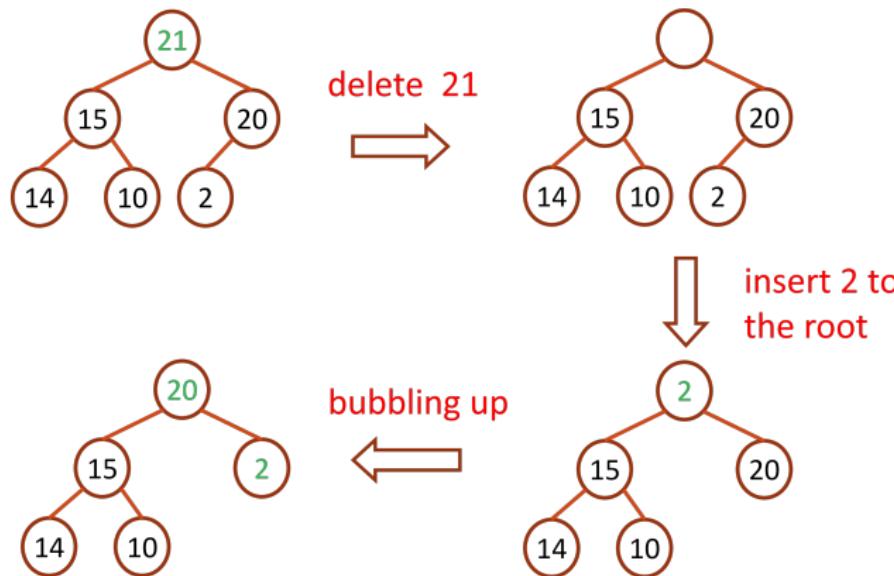
# Deletion from a Max Heap

- When an element is to be deleted from a max heap, it is **ALWAYS** taken from the root of the heap.

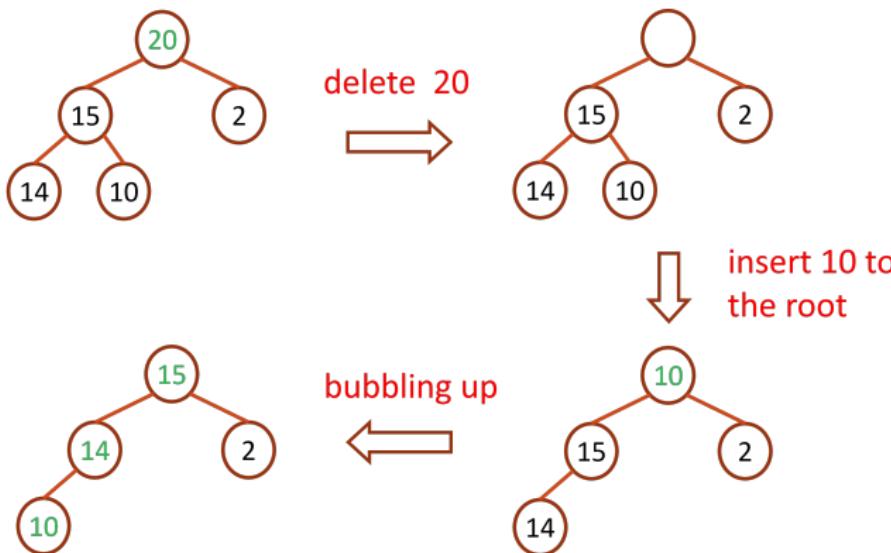
# Deletion from a Max Heap

- When an element is to be deleted from a max heap, it is **ALWAYS** taken from the root of the heap.
- The steps of deletion from a Max heap:
  - delete the root node.
  - insert the last node into the root.
  - use the **bubbling up process** to ensure that the resulting heap remains a max heap.

# Illustration of Deletion from a Max Heap



# Illustration of Deletion from a Max Heap



# The Code for Deletion from a Max Heap

```
element pop(int *n) {
    /* delete element with the highest key from the heap */
    int parent, child;
    element item, temp;
    if (HEAP_EMPTY(*n)) {
        fprintf(stderr, "The heap is empty\n");
        exit(EXIT_FAILURE);
    }
    /* save value of the element with the highest key */
    item = heap[1];
    /* use last element in heap to adjust heap */
    temp = heap[(*n)--];
    parent = 1;
    child = 2;
    while (child <= *n) { // O(lg n) time
        /* find the larger child of the current parent */
        if ((child < *n) && (heap[child].key < heap[child+1].key))
            child++;
        if (temp.key >= heap[child].key) break;
        /* move to the next lower level */
        heap[parent] = heap[child];
        parent = child;
        child *= 2;
    }
    heap[parent] = temp;
    return item;
}
```

# Time Complexity of the Deletion from a Max Heap

- Delete the root node:  $O(1)$ .
- Insert the last node to the root:  $O(1)$ .
- Since the height of the heap is  $\lceil \lg(n + 1) \rceil$ , the while loop is iterated for  $O(\lg n)$  times.
- Thus, the overall time complexity: the time complexity of the deletion:  $O(\log n)$ .

# Discussions

