

# Mathematics for Machine Learning

## — Linear Algebra: Projections & Gram-Schmidt Orthogonalization

Joseph Chuang-Chieh Lin

Department of Computer Science & Engineering,  
National Taiwan Ocean University

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## Credits for the resource

- The slides are based on the textbooks:
  - *Marc Peter Deisenroth, A. Aldo Faisal, and Cheng Soon Ong: Mathematics for Machine Learning. Cambridge University Press. 2020.*
  - *Howard Anton, Chris Rorres, Anton Kaul: Elementary Linear Algebra. Wiley. 2019.*
- We could partially refer to the monograph:  
*Francesco Orabona: A Modern Introduction to Online Learning.*  
<https://arxiv.org/abs/1912.13213>

# Outline

- 1 Orthogonal Projections
- 2 Gram-Schmidt Orthogonalization
- 3 Rotations

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- Sometimes, only a few dimensions contain most information.
- We might try to project the original high-dimensional data onto a lower-dimensional space and work on it.
- Note: When we compress or visualize high-dimensional data, we will lose information.

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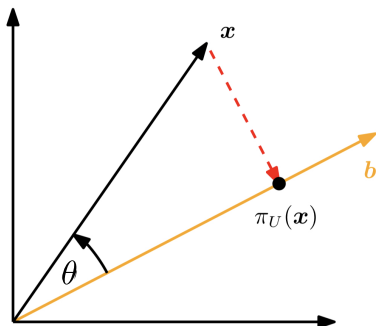
- Principal Component Analysis (PCA)
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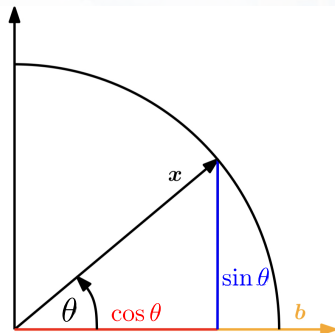
Examples (dimensionality reduction)

- Principal Component Analysis (PCA)
- Deep Neural Networks
- Classification
- Linear Regression

## Projection from 2D to 1D



(a) Projection of  $x \in \mathbb{R}^2$  onto a subspace  $U$  with basis vector  $b$ .



(b) Projection of a two-dimensional vector  $x$  with  $\|x\| = 1$  onto a one-dimensional subspace spanned by  $b$ .

# Projection

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- Recall that linear mappings can be expressed by transformation matrices.



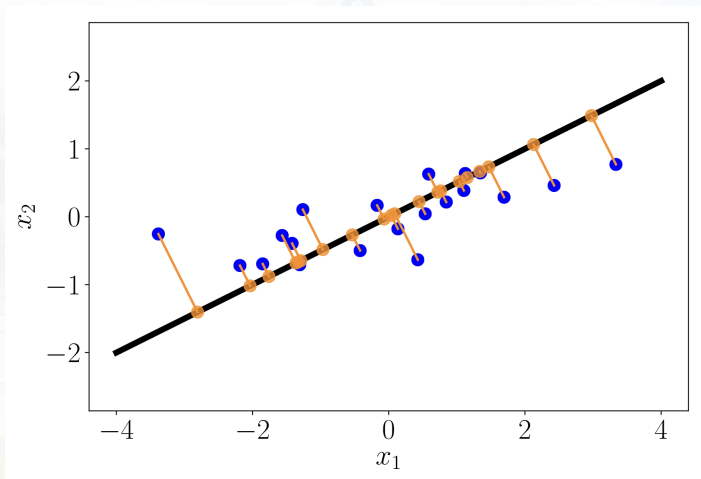
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- The projection matrices  $\mathbf{P}_\pi$  exhibit the property that  $\mathbf{P}_\pi^2 = \mathbf{P}_\pi$ .

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- Finding the projection  $\pi_U(\mathbf{x}) \in U$ :

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- If we use the dot product as the inner product and let  $\theta$  be the angle between  $\mathbf{x}$  and  $\mathbf{b}$ :

$$\|\pi_U(\mathbf{x})\| = \frac{|\mathbf{b}^\top \mathbf{x}|}{\|\mathbf{b}\|^2} \|\mathbf{b}\| = |\cos \theta| \|\mathbf{x}\| \|\mathbf{b}\| \frac{\|\mathbf{b}\|}{\|\mathbf{b}\|^2} = |\cos \theta| \|\mathbf{x}\|.$$

- Finding the projection matrix  $P_\pi$ :
  - Recall: projection is a linear mapping.
  - With the dot product as the inner product,

$$\|\pi_U(\mathbf{x})\| = \lambda \mathbf{b} = \mathbf{b} \lambda = \mathbf{b} \frac{\mathbf{b}^\top \mathbf{x}}{\|\mathbf{b}\|^2} = \frac{\mathbf{b} \mathbf{b}^\top}{\|\mathbf{b}\|^2} \mathbf{x}.$$

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Find the projection matrix  $\mathbf{P}_\pi$  onto the line  $U$  through the origin spanned by  $\mathbf{b} = [1 \ 2 \ 2]^\top$  and the projection of  $\mathbf{x} = [1 \ 1 \ 1]^\top$ .

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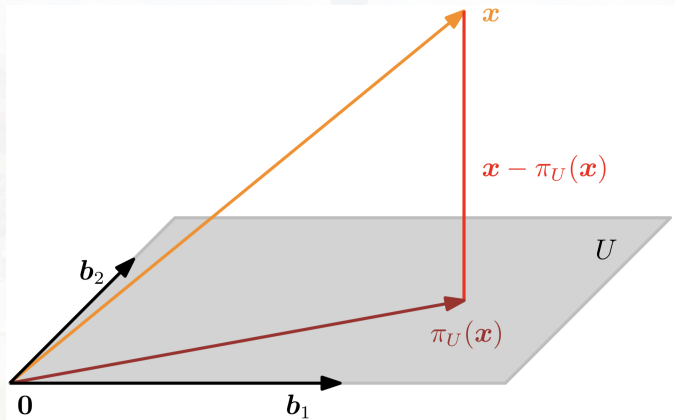
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## Projection onto General Subspaces (1/4)

Orthogonal projections of  $\mathbf{x} \in \mathbb{R}^n$  onto  $U \subseteq \mathbb{R}^n$  with  $\dim(U) = m \geq 1$ .



## Projection onto General Subspaces (2/4)

- Any projection can be represented as a linear combination of the basis vectors  $\mathbf{b}_1, \dots, \mathbf{b}_m$  of  $U$ .
  - $\pi_U(\mathbf{x}) = \sum_{i=1}^m \lambda_i \mathbf{b}_i$ .
- Find the coordinates  $\lambda_1, \dots, \lambda_m$ :

$$\pi_U(\mathbf{x}) = \sum_{i=1}^m \lambda_i \mathbf{b}_i = \mathbf{B}\boldsymbol{\lambda}$$

for  $\mathbf{B} = [\mathbf{b}_1, \dots, \mathbf{b}_m] \in \mathbb{R}^{n \times m}$ ,  $\boldsymbol{\lambda} = [\lambda_1, \dots, \lambda_m]^\top \in \mathbb{R}^m$ .

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Note:  $\mathbf{x} \perp \{\mathbf{b}_1, \dots, \mathbf{b}_m\}$  ( $\because$  minimum distance)

$$\begin{aligned} \langle \mathbf{b}_1, \mathbf{x} - \pi_U(\mathbf{x}) \rangle &= \mathbf{b}_1^\top (\mathbf{x} - \pi_U(\mathbf{x})) = 0 \\ &\vdots \\ \langle \mathbf{b}_m, \mathbf{x} - \pi_U(\mathbf{x}) \rangle &= \mathbf{b}_m^\top (\mathbf{x} - \pi_U(\mathbf{x})) = 0 \end{aligned}$$

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( $\Rightarrow$ ):  $\mathbf{Ax} = \mathbf{0} \Rightarrow \mathbf{A}^\top \mathbf{Ax} = \mathbf{0}$ .

( $\Leftarrow$ ):  $\mathbf{A}^\top \mathbf{Ax} = \mathbf{0} \Rightarrow \mathbf{x}^\top \mathbf{A}^\top \mathbf{Ax} = (\mathbf{Ax})^\top (\mathbf{Ax}) = \|\mathbf{Ax}\|^2 = 0 \Rightarrow \mathbf{Ax} = \mathbf{0}$

But wait a minute ...

Why  $\mathbf{B}^\top \mathbf{B}$  is invertible?

Fact

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- $\text{rank}(\mathbf{A}) = \text{rank}(\mathbf{A}^\top \mathbf{A})$  ( $\because$  the Dimension Theorem).

## Example

### Example

For a subspace  $U = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix} \right\} \subseteq \mathbb{R}^3$  and  $\mathbf{x} = \begin{bmatrix} 6 \\ 0 \\ 0 \end{bmatrix} \in \mathbb{R}^3$ .

Find

- the coordinates  $\lambda$  of  $\mathbf{x}$  in terms of  $U$
- the projection point  $\pi_U(\mathbf{x})$
- the projection matrix  $\mathbf{P}_\pi$ .

- First, we find that the spanning set of  $U$  is a basis (check its linear independence!).

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$$\mathbf{B}^\top \mathbf{B} = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 1 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} 3 & 3 \\ 3 & 5 \end{bmatrix},$$

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- Then, solve  $\mathbf{B}^\top \mathbf{B} \boldsymbol{\lambda} = \mathbf{B}^\top \mathbf{x}$  to find  $\boldsymbol{\lambda}$ :

$$\begin{bmatrix} 3 & 3 \\ 5 & 5 \end{bmatrix} \begin{bmatrix} \lambda_1 \\ \lambda_2 \end{bmatrix} = \begin{bmatrix} 6 \\ 0 \end{bmatrix}$$

So  $\boldsymbol{\lambda} = \begin{bmatrix} 5 \\ -3 \end{bmatrix}$ .

- The projection of  $\mathbf{x}$ :

$$\pi_U(\mathbf{x}) = \mathbf{B} \boldsymbol{\lambda} = \begin{bmatrix} 5 \\ 2 \\ -1 \end{bmatrix}.$$

- The **projection error**:

$$\|\mathbf{x} - \pi_U(\mathbf{x})\| = \|[1 \quad -2 \quad 1]^T\|$$

- The **projection error**:

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- Finally, the projection matrix:

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- The **projection error**:

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- Finally, the projection matrix:

$$\mathbf{P}_\pi = \mathbf{B}(\mathbf{B}^\top \mathbf{B})^{-1} \mathbf{B}^\top = \frac{1}{6} \begin{bmatrix} 5 & 2 & -1 \\ 2 & 2 & 2 \\ -1 & 2 & 5 \end{bmatrix}.$$

What if  $B = (\mathbf{b}_1, \dots, \mathbf{b}_m)$  is orthonormal?

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What if  $B = (\mathbf{b}_1, \dots, \mathbf{b}_m)$  is orthonormal?

- $\pi_U(\mathbf{x}) = \mathbf{B}(\mathbf{B}^\top \mathbf{B})^{-1} \mathbf{B}^\top \mathbf{x} \Rightarrow \pi_U(\mathbf{x}) = \mathbf{B} \mathbf{B}^\top \mathbf{x}.$ 
  - $\because \mathbf{B}^\top \mathbf{B} = \mathbf{I}.$
- Coordinates:  $\lambda = (\mathbf{B}^\top \mathbf{B})^{-1} \mathbf{B}^\top \mathbf{x} = \mathbf{B}^\top \mathbf{x}.$

# Outline

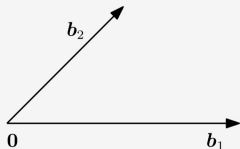
- 1 Orthogonal Projections
- 2 Gram-Schmidt Orthogonalization
- 3 Rotations

# Illustration of Gram-Schmidt Orthogonalization

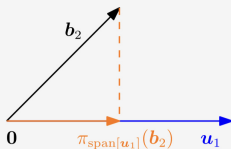
- **Goal:** Transform any basis  $(\mathbf{b}_1, \dots, \mathbf{b}_n)$  of an  $n$ -dimensional vector space  $V$  into an orthogonal/orthonormal basis of  $V$ .

$$\mathbf{u}_1 := \mathbf{b}_1$$

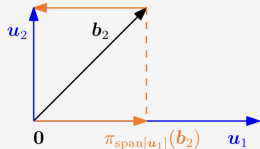
$$\mathbf{u}_k := \mathbf{b}_k - \pi_{\text{span}(\{\mathbf{u}_1, \dots, \mathbf{u}_{k-1}\})}(\mathbf{b}_k), \quad k = 2, \dots, n.$$



(a) Original non-orthogonal basis vectors  $\mathbf{b}_1, \mathbf{b}_2$ .



(b) First new basis vector  $\mathbf{u}_1 = \mathbf{b}_1$  and projection of  $\mathbf{b}_2$  onto the subspace spanned by  $\mathbf{u}_1$ .



(c) Orthogonal basis vectors  $\mathbf{u}_1$  and  $\mathbf{u}_2 = \mathbf{b}_2 - \pi_{\text{span}[\mathbf{u}_1]}(\mathbf{b}_2)$ .

## Example

### Example

Consider a basis  $(\mathbf{b}_1, \mathbf{b}_2)$  of  $\mathbb{R}^2$ , where  $\mathbf{b}_1 = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$ ,  $\mathbf{b}_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ .

Apply the Gram-Schmidt method to construct an orthonormal basis  $(\mathbf{u}_1, \mathbf{u}_2)$  of  $\mathbb{R}^2$  (assuming the dot product as the inner product).

$$\mathbf{u}_1 := \mathbf{b}_1 = \begin{bmatrix} 2 \\ 0 \end{bmatrix},$$

$$\mathbf{u}_2 := \mathbf{b}_2 - \pi_{\text{span}(\mathbf{u}_1)}(\mathbf{b}_2)$$

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$$\begin{aligned} \mathbf{u}_2 &:= \mathbf{b}_2 - \pi_{\text{span}(\mathbf{u}_1)}(\mathbf{b}_2) = \mathbf{b}_2 - \frac{\mathbf{u}_1 \mathbf{u}_1^\top}{\|\mathbf{u}_1\|^2} \mathbf{b}_2 \\ &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \end{aligned}$$

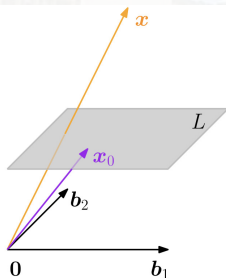


$$\mathbf{u}_1 := \mathbf{b}_1 = \begin{bmatrix} 2 \\ 0 \end{bmatrix},$$

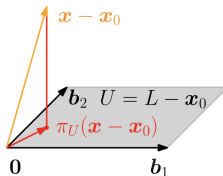
$$\begin{aligned} \mathbf{u}_2 &:= \mathbf{b}_2 - \pi_{\text{span}(\mathbf{u}_1)}(\mathbf{b}_2) = \mathbf{b}_2 - \frac{\mathbf{u}_1 \mathbf{u}_1^\top}{\|\mathbf{u}_1\|^2} \mathbf{b}_2 \\ &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{aligned}$$

# Projection onto Affine Spaces

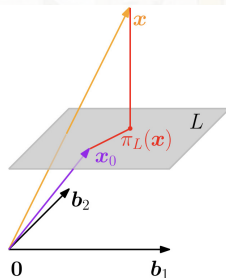
- Given an affine space  $L = \mathbf{x}_0 + U$ .
  - $U$  is a low-dimensional subspace of  $V$ .
- $\pi_L(\mathbf{x}) = \mathbf{x}_0 + \pi_U(\mathbf{x} - \mathbf{x}_0)$



(a) Setting.



(b) Reduce problem to projection  $\pi_U$  onto vector subspace.

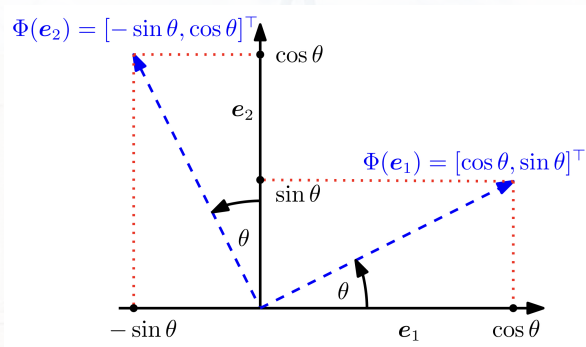


(c) Add support point back in to get affine projection  $\pi_L$ .

# Outline

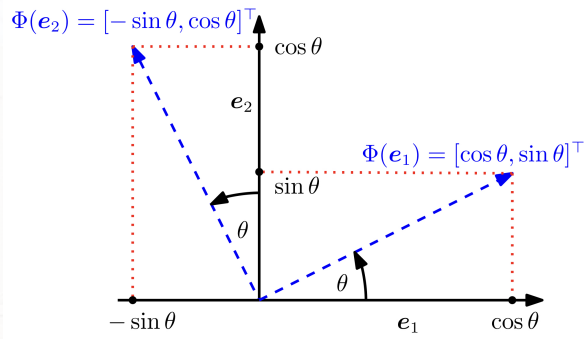
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# Rotations in $\mathbb{R}^2$ as An Example



- Standard basis  $\mathbf{e} = \{\mathbf{e}_1 = [1 \ 0]^\top, \ \mathbf{e}_2 = [0 \ 1]^\top\}$ .
- $\mathbf{R}(\theta) = [\Phi(\mathbf{e}_1) \ \Phi(\mathbf{e}_2)]$

# Rotations in $\mathbb{R}^2$ as An Example



- Standard basis  $\mathbf{e} = \{\mathbf{e}_1 = [1 \ 0]^\top, \ \mathbf{e}_2 = [0 \ 1]^\top\}$ .
- $\mathbf{R}(\theta) = [\Phi(\mathbf{e}_1) \ \Phi(\mathbf{e}_2)] = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ .

# Discussions