

# Breadth-First Search (BFS)

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# Outline

## 1 Breadth-First Search (BFS)



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# Breadth First Search (BFS) (1/2)

- The algorithm starts at vertex  $v$  and marks it as visited.
- Then visiting each of the vertices on  $v$ 's adjacency list.
- When we have visited all the vertices on  $v$ 's adjacency list, we visit all the unvisited vertices that are adjacent to the first vertex on  $v$ 's adjacency list.
- To implement this scheme, as we visit each vertex we place the vertex in a **queue**.



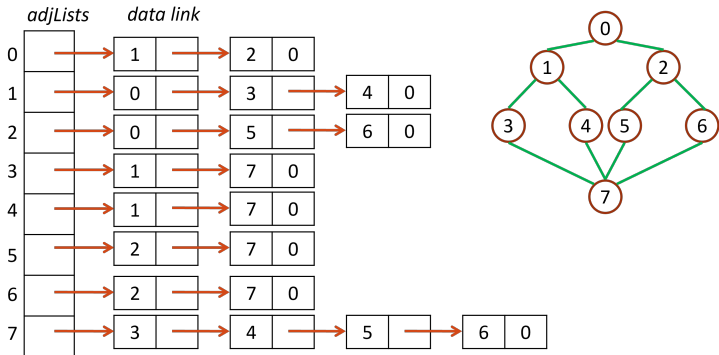
## Breadth-First Search (BFS) (2/2)

- When we have exhausted an adjacency list, we remove a vertex from the queue and proceed by examining each of the vertices on its adjacency list.
- Unvisited vertices are visited and placed on the queue; visited are ignored.
- Finish the search when the queue is empty.



# BFS Example

- Using a queue and recursion.
  - It resembles the level-order tree traversal.



- The DFS order:  $v_0 \rightarrow v_1 \rightarrow v_2 \rightarrow v_3 \rightarrow v_4 \rightarrow v_5 \rightarrow v_6 \rightarrow v_7$ .

# The Pseudocode of DFS

```
DFS(G, u) {  
    u.visited = True  
    for each v in G.Adj[u]  
        if v.visited == False  
            DFS(G, v)  
}  
  
driving main () {  
    for each u in G  
        u.visited = false  
    for each u in G  
        DFS(G, u)  
}
```



# DFS in C

```
#define FALSE 0
#define TRUE 1
short int visited[MAX_VERTICES];
/* intializing to be FALSE for all */

void DFS(int v) {
    /* DFS beginning at vertex v */
    nodePointer w;
    visited[v] = true;
    printf("%5d",v);
    for(w = graph[v]; w; w = w->link)
        if (!visited[w->vertex])
            DFS(w->vertex);
}
```





# Analysis of DFS

- For  $G = (V, E)$  represented by an **adjacency list**, vertices adjacent to  $v$  can be determined in  $|N(v)|$ , where  $N(v)$  denotes the set of vertices adjacent to  $v$  in  $G$ .



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  - Follow the chain of links,  $O(1)$  for deriving each neighbor of  $v$ .
- DFS examines each node in the adjacency lists at most **once**, the time cost for the search is  $O(e)$ , where  $e = |E|$ .



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- For  $G = (V, E)$  represented by an **adjacency matrix**, vertices adjacent to  $v$  can be determined in  $O(n)$  time, where  $n = |V|$ .
    - One needs to scan the corresponding row of the adjacency matrix.
  - Total time:  $O(n^2)$ .



# Discussions

