

Mathematics for Machine Learning

— When Models Meet Data

Empirical Risk Minimization

Joseph Chuang-Chieh Lin

Department of Computer Science & Engineering,
National Taiwan Ocean University

Fall 2025

Credits for the resource

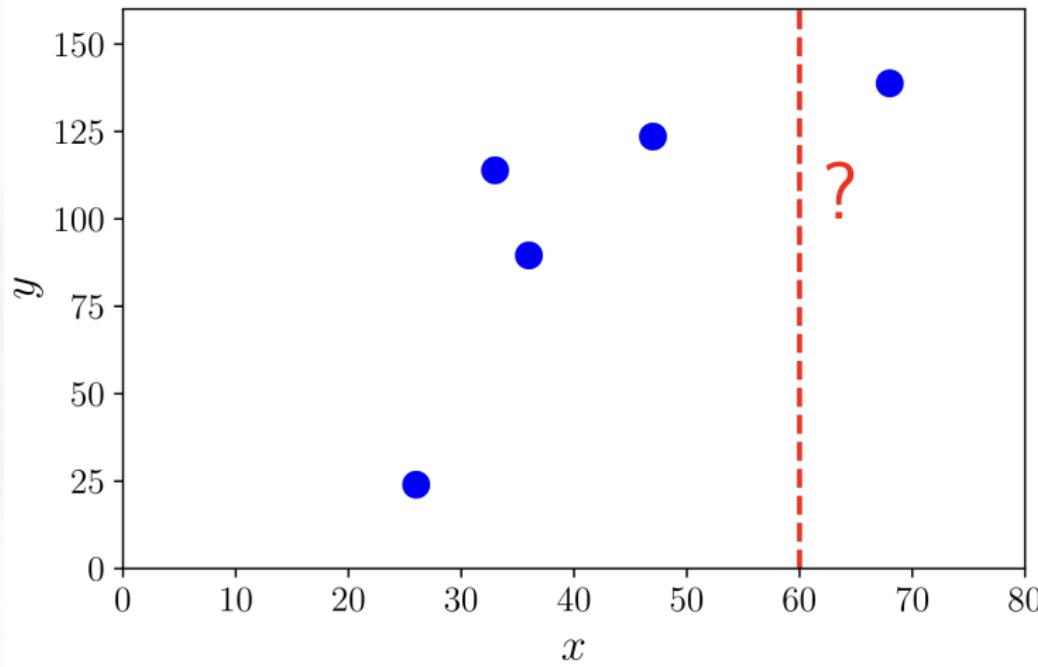
- The slides are based on the textbooks:
 - *Marc Peter Deisenroth, A. Aldo Faisal, and Cheng Soon Ong: Mathematics for Machine Learning. Cambridge University Press. 2020.*
 - *Arnold J. Insel, Lawrence E. Spence, Stephen H. Friedberg: Linear Algebra, 4th Edition. Prentice Hall. 2013.*
 - *Howard Anton, Chris Rorres, Anton Kaul: Elementary Linear Algebra, 12th Edition. Wiley. 2019.*
- We could partially refer to the monograph:
Francesco Orabona: A Modern Introduction to Online Learning.
<https://arxiv.org/abs/1912.13213>

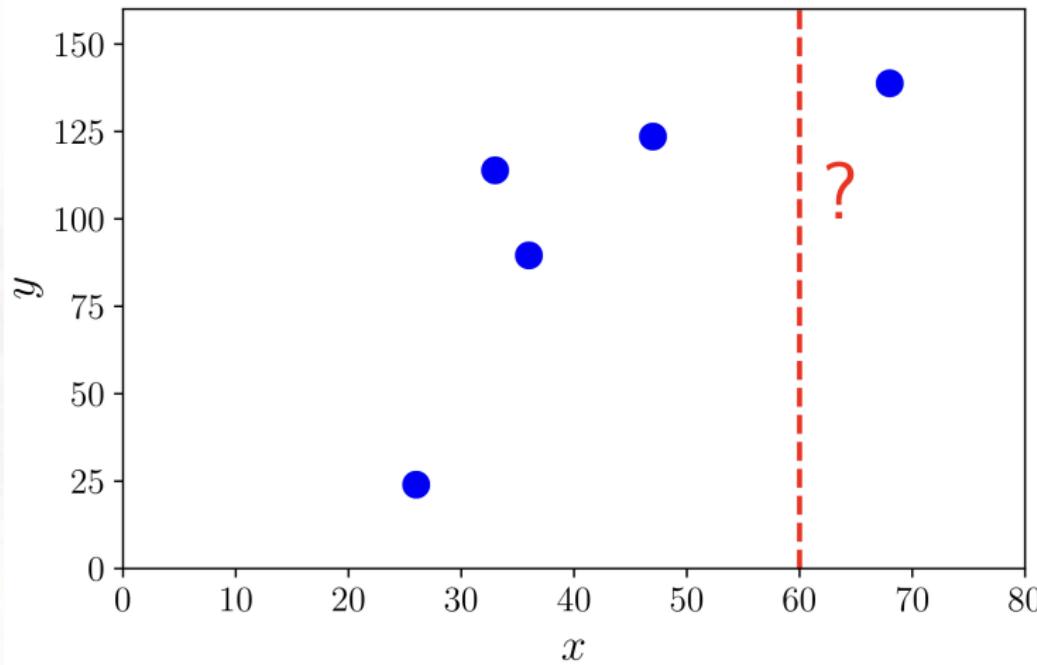
Outline

- 1 Data, Models, and Learning
- 2 Empirical Risk Minimization

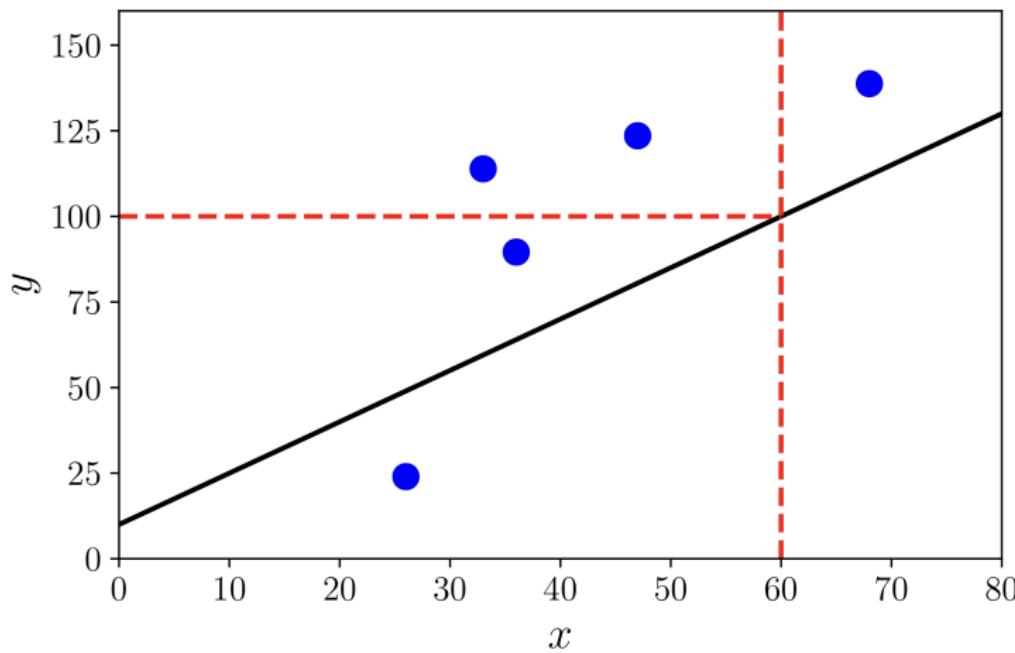
Motivation

- It's time to consider a problem that a ML algorithm is designed to solve.
- We will see some performance metrics to speak for what a "good" model is.
- As before, we assume that the data is represented as vectors.
- Denote by N the number of examples (or data points, examples, etc.) in a dataset.
- The data has D features, hence a vector is of D -dimensional here.





- We are interested in the salary of a person aged 60.



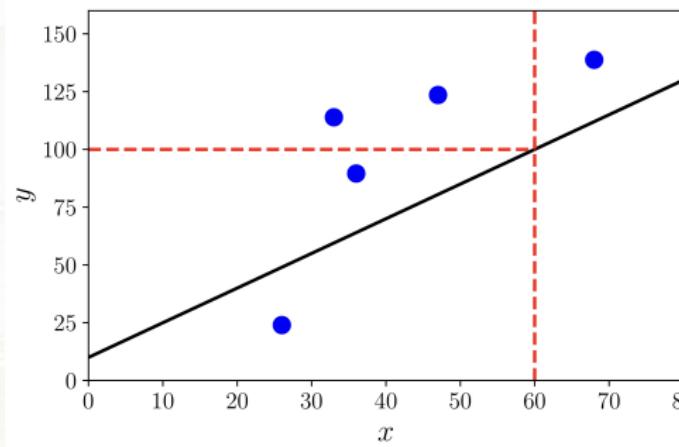
- We are interested in the salary of a person aged 60.

Models as Functions

For example, consider the linear function $f: \mathbb{R}^D \rightarrow \mathbb{R}$,

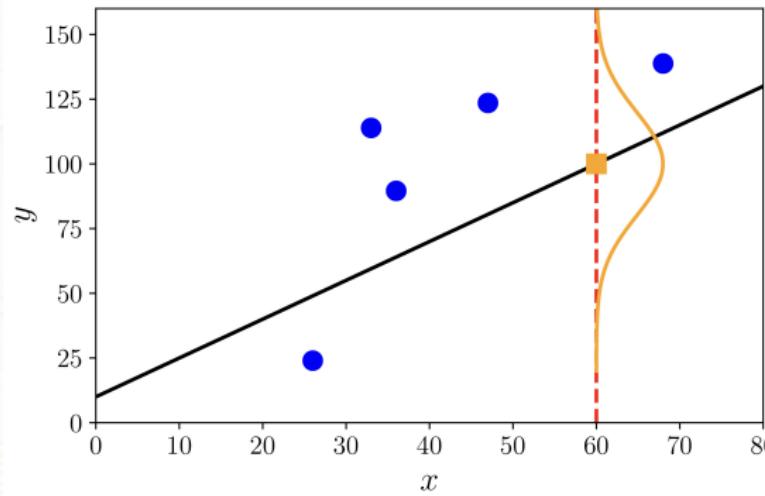
$$f(\mathbf{x}) = \boldsymbol{\theta}^\top \mathbf{x} + \theta_0$$

for unknown $\boldsymbol{\theta}$ and θ_0 .



Models as Probability Distributions

We can also consider predictors as probabilistic models (e.g., distribution of possible functions).



Goal of Learning

- Find a model and its **corresponding parameters** such that the predictor performs well on **unseen** data.
- Three algorithmic phases:
 - Prediction or inference
 - Non-probabilistic: prediction (e.g., Empirical risk minimization (ERM)).
 - Probabilistic: inference (e.g., maximum likelihood, Bayesian inference).
 - Training or parameter estimation.
 - Hyperparameter tuning or model selection.

Outline

1 Data, Models, and Learning

2 Empirical Risk Minimization

Hypothesis Class of Functions

Given N examples $\mathbf{x}_i \in \mathbb{R}^D$, $i = 1, \dots, N$ and corresponding labels $y_i \in \mathbb{R}$.

Goal: Estimate a predictor $f(\cdot, \theta) : \mathbb{R}^D \rightarrow \mathbb{R}$, parametrized by θ

$$f(\mathbf{x}_i, \theta^*) \approx y_i \text{ for all } i \in \{1, \dots, N\},$$

where θ^* is a good parameter we aim to find.

Let $\hat{y}_i = f(\mathbf{x}_i, \theta^*)$ represent the output of the predictor.

Example

Consider the set of **affine functions**.

- Let $\mathbf{x}_i = [1, x_i^{(1)}, x_i^{(2)}, \dots, x_i^{(D)}]^\top$
- The corresponding parameter $\boldsymbol{\theta} = [\theta_0, \theta_1, \dots, \theta_D]^\top$.
- Consider a more compact form as below:

$$f(\mathbf{x}_i, \boldsymbol{\theta}) = \boldsymbol{\theta}^\top \mathbf{x}_i.$$

Example

Consider the set of **affine functions**.

- Let $\mathbf{x}_i = [1, x_i^{(1)}, x_i^{(2)}, \dots, x_i^{(D)}]^\top$
- The corresponding parameter $\boldsymbol{\theta} = [\theta_0, \theta_1, \dots, \theta_D]^\top$.
- Consider a more compact form as below:

$$f(\mathbf{x}_i, \boldsymbol{\theta}) = \boldsymbol{\theta}^\top \mathbf{x}_i.$$

which is equivalent to

$$f(\mathbf{x}_i, \boldsymbol{\theta}) = \theta_0 + \sum_{d=1}^D \theta_d x_i^{(d)}$$

Loss Functions for Training & Empirical Risk

We specify a **loss function** $\ell(y_n, \hat{y}_n)$ to say how *bad* a model fits the data.

Goal: Loss Minimization

Find a good parameter θ^* such that the average loss on the set of N training examples is minimized.

Assumptions

A given training set $\{(\mathbf{x}_1, y_1), (\mathbf{x}_2, y_2), \dots, (\mathbf{x}_N, y_N)\}$ is independently and identically distributed (i.i.d.).

- $\mathbf{X} := [\mathbf{x}_1, \dots, \mathbf{x}_N]^\top \in \mathbb{R}^{N \times D}$, label vector $\mathbf{y} := [y_1, \dots, y_N]^\top \in \mathbb{R}^N$.
- The average loss:

$$R_{\text{emp}}(f, \mathbf{X}, \mathbf{y}) = \frac{1}{N} \sum_{i=1}^N \ell(y_i, \hat{y}_i).$$

Example

Consider the squared loss $\ell(y_i, \hat{y}_i) = (y_i - \hat{y}_i)^2$. So we wish to solve

Example

Consider the squared loss $\ell(y_i, \hat{y}_i) = (y_i - \hat{y}_i)^2$. So we wish to solve

$$\min_{\theta \in \mathbb{R}^D} \frac{1}{N} \sum_{i=1}^N (y_i - f(\mathbf{x}_i, \theta))^2,$$

that is,

$$\min_{\theta \in \mathbb{R}^D} \frac{1}{N} \sum_{i=1}^N (y_i - \theta^\top \mathbf{x}_i)^2$$

Example

Consider the squared loss $\ell(y_i, \hat{y}_i) = (y_i - \hat{y}_i)^2$. So we wish to solve

$$\min_{\theta \in \mathbb{R}^D} \frac{1}{N} \sum_{i=1}^N (y_i - f(\mathbf{x}_i, \theta))^2,$$

that is,

$$\min_{\theta \in \mathbb{R}^D} \frac{1}{N} \sum_{i=1}^N (y_i - \theta^\top \mathbf{x}_i)^2 \iff \min_{\theta \in \mathbb{R}^D} \frac{1}{N} \|\mathbf{y} - \mathbf{X}\theta\|^2.$$

- ★ The least-squares problem.

Remark: True Risk in Terms of Expected Risk (1/2)

- We are NOT interested in a predictor that ONLY performs well on the training data.
- We seek a predictor that performs well on **unseen** test data.

Remark: True Risk in Terms of Expected Risk (1/2)

- We are NOT interested in a predictor that ONLY performs well on the training data.
- We seek a predictor that performs well on **unseen** test data.
- Formally, we are interested in finding f that minimizes the **expected risk**:

$$\mathbf{R}_{\text{true}}(f) = \mathbb{E}_{\mathbf{x}, y}[\ell(y, f(\mathbf{x}))],$$

where y is the label and $f(\mathbf{x})$ is the prediction based on \mathbf{x} .

- ★ $\mathbf{R}_{\text{true}}(f)$: the true risk if we had access to an infinite amount of data.

Remark: True Risk in Terms of Expected Risk (2/2)

Questions arising from minimizing expected risk:

- How should we change the training procedure to generalize well?
- How do we estimate expected risk from finite data?

Regularization: An Approach to Reduce Overfitting

Key: Bias the search for the minimizer of empirical risk by introducing a **penalty** term which is referred to as **regularization**.

Example

Revisit the least-squares problem. By adding a penalty term involving θ we have:

$$\min_{\theta \in \mathbb{R}^D} \frac{1}{N} \|\mathbf{y} - \mathbf{X}\theta\|^2 + \lambda \|\theta\|^2.$$

Cross-Validation: Assess the Generalization Performance (1/2)

Partition the dataset into two sets $\mathcal{D} = \mathcal{R} \cup \mathcal{V}$ s.t. $\mathcal{R} \cap \mathcal{V} = \emptyset$.

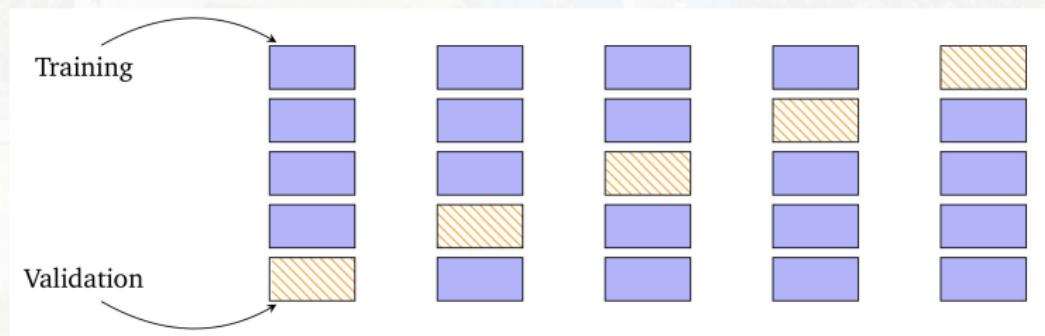
- \mathcal{R} : the training set.
- \mathcal{V} : the validation set.

Cross-Validation: Assess the Generalization Performance (1/2)

Partition the dataset into two sets $\mathcal{D} = \mathcal{R} \cup \mathcal{V}$ s.t. $\mathcal{R} \cap \mathcal{V} = \emptyset$.

- \mathcal{R} : the training set.
- \mathcal{V} : the validation set.

K -fold cross-validation: partition the data into K chunks ($K - 1$ of them: \mathcal{R} ; the rest one of them: \mathcal{V}).



Cross-Validation: Assess the Generalization Performance (2/2)

Cross-validation approximates the expected generalization error:

$$\mathbb{E}_{\mathcal{V}}[R(f, \mathcal{V})] \approx \frac{1}{K} \sum_{k=1}^K R(f^{(k)}, \mathcal{V}^{(k)}),$$

where $R(f^{(k)}, \mathcal{V}^{(k)})$ is the risk (e.g., RMSE) on the validation set $\mathcal{V}^{(k)}$ for predictor $f^{(k)}$.

- A potential computational cost of training the model K times, which can be burdensome (except we can do it in parallel).

Discussions