

Mathematics for Machine Learning

— When Models Meet Data

Parameter Estimation

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Credits for the resource

- The slides are based on the textbooks:
 - *Marc Peter Deisenroth, A. Aldo Faisal, and Cheng Soon Ong: Mathematics for Machine Learning. Cambridge University Press. 2020.*
 - *Arnold J. Insel, Lawrence E. Spence, Stephen H. Friedberg: Linear Algebra, 4th Edition. Prentice Hall. 2013.*
 - *Howard Anton, Chris Rorres, Anton Kaul: Elementary Linear Algebra, 12th Edition. Wiley. 2019.*
- We could partially refer to the monograph:
Francesco Orabona: A Modern Introduction to Online Learning.
<https://arxiv.org/abs/1912.13213>

Outline

1 Maximum Likelihood Estimation

2 Maximum A Posteriori Estimation

Goal

- Use probabilistic distributions to model our uncertainty due to:
 - the observation process.
 - the uncertainty in the parameters of the predictor.

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Maximum Likelihood Estimation (MLE)

For data represented by a random variable \mathbf{x} and for a family of probability densities $p(\mathbf{x} | \theta)$ parameterized by θ , we aim at the **negative log-likelihood**:

$$\mathcal{L}_{\mathbf{x}}(\theta) = -\log p(\mathbf{x} | \theta).$$

- **Note:** The parameter θ is varying and the data \mathbf{x} is fixed.
- $\mathcal{L}_{\mathbf{x}}(\theta)$: a function of θ .

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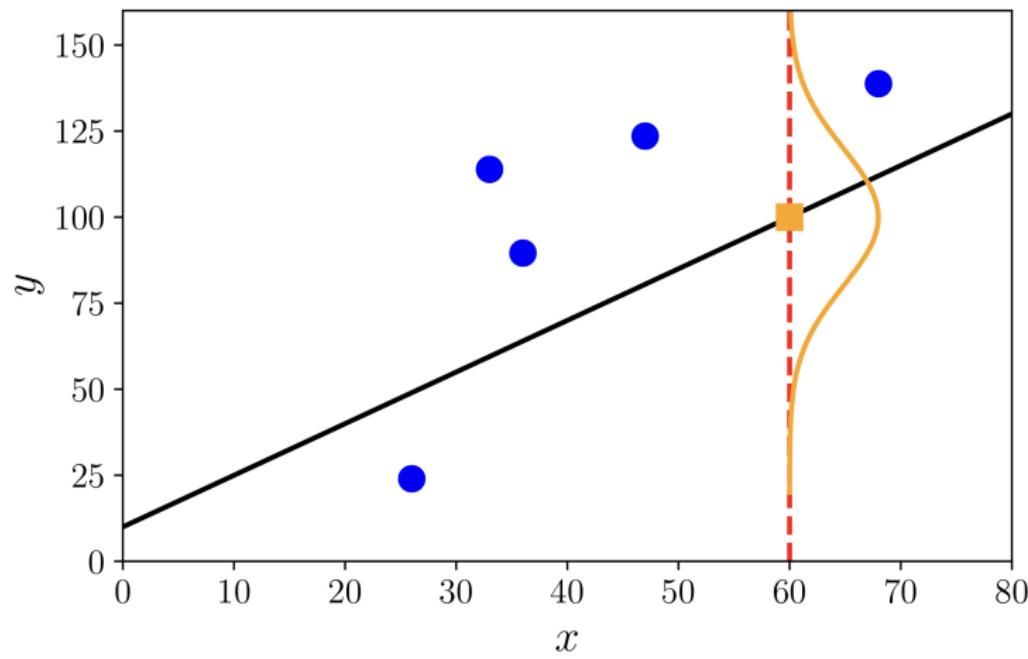
For a given dataset \mathbf{x} , the likelihood allows us choose the settings of θ that more “likely” has generated the data or how “likely” θ is for the observations \mathbf{x} .

Example

- Specify that the conditional probability of the labels given the examples is a Gaussian distribution.
- Assume that we can explain our observation uncertainty by independent Gaussian noise $\varepsilon \sim \mathcal{N}(0, \sigma^2)$.
- We assume the linear model $\mathbf{x}_i^\top \boldsymbol{\theta}$ is used for prediction.

For each example-label pair (\mathbf{x}_i, y_i) ,

$$p(y_i \mid \mathbf{x}_i, \boldsymbol{\theta}) = \mathcal{N}(y_i \mid \mathbf{x}_i^\top \boldsymbol{\theta}, \sigma^2).$$



MLE for i.i.d. examples

- Assume that $(\mathbf{x}_1, y_1), \dots, (\mathbf{x}_N, y_N)$ are i.i.d.
- The likelihood factorizes into a product of likelihoods of each individual example

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Note: Do not forget that $\mathcal{L}(\theta)$ is a function of θ .

Example (contd.)

$$\begin{aligned}
 \mathcal{L}(\boldsymbol{\theta}) &= -\sum_{i=1}^N \log p(y_i \mid \mathbf{x}_i, \boldsymbol{\theta}) = -\sum_{i=1}^N \log \mathcal{N}(y_i \mid \mathbf{x}_i^\top \boldsymbol{\theta}, \sigma^2) \\
 &= -\sum_{i=1}^N \log \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(y_i - \mathbf{x}_i^\top \boldsymbol{\theta})^2}{2\sigma^2}\right) \\
 &= -\sum_{i=1}^N \log \exp\left(-\frac{(y_i - \mathbf{x}_i^\top \boldsymbol{\theta})^2}{2\sigma^2}\right) - \sum_{i=1}^N \log \frac{1}{\sqrt{2\pi\sigma^2}} \\
 &= \frac{1}{2\sigma^2} \sum_{i=1}^N (y_i - \mathbf{x}_i^\top \boldsymbol{\theta})^2 - \sum_{i=1}^N \log \frac{1}{\sqrt{2\pi\sigma^2}}.
 \end{aligned}$$

⇒ minimizing $\mathcal{L}(\boldsymbol{\theta})$

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The second term is **constant**.

\Rightarrow minimizing $\mathcal{L}(\boldsymbol{\theta}) \Rightarrow$ solving the least-squares problem.

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Motivation (1/2)

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We can multiply an additional term (i.e., $p(\theta)$) to the likelihood.

Motivation (2/2)

- For a given prior, after observing some data \mathbf{x} , how should we update $p(\theta)$?
 - ⇒ Bayes's theorem.
 - ★ Compute a posterior distribution $p(\theta | \mathbf{x})$.

$$p(\theta | \mathbf{x}) = \frac{p(\mathbf{x} | \theta)p(\theta)}{p(\mathbf{x})}.$$

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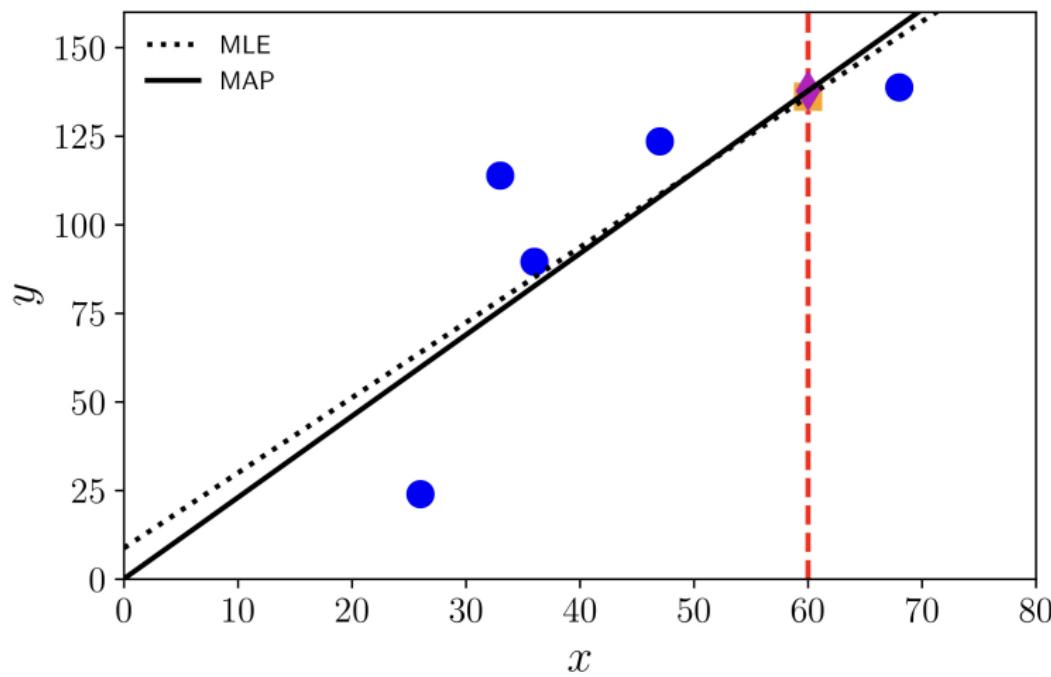
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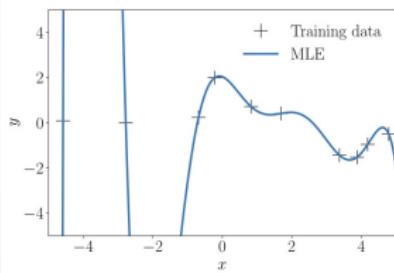
So,

$$p(\theta | \mathbf{x}) \propto p(\mathbf{x} | \theta)p(\theta).$$

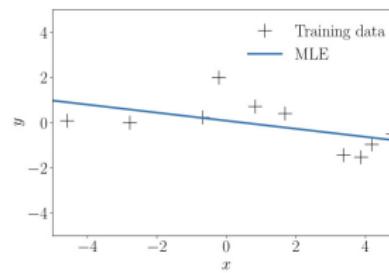
MLE vs. MAP



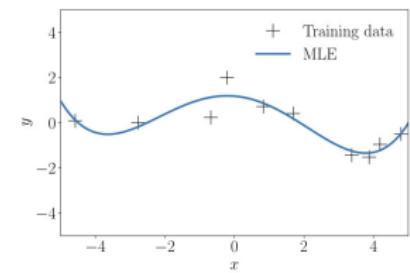
Maximum A Posteriori Estimation



(a) Overfitting



(b) Underfitting.



(c) Fitting well.

Discussions