

Sp '06 Exam 2 Solns

1) Shape functions are

$$N = \begin{bmatrix} \frac{1}{2}\xi(\xi-1) & 1-\xi^2 & \frac{1}{2}\xi(\xi+1) \end{bmatrix}$$

For a rod element

$$K = \int_{x_1}^{x_3} \frac{\partial}{\partial x} N^T EA \frac{\partial}{\partial x} N dx$$

Since $x = N \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$ and $x_2 = \frac{x_1 + x_3}{2}$

$$\begin{aligned} x &= \frac{1}{2}\xi^2 \overset{\textcircled{1}}{x_1} - \frac{1}{2}\xi x_1 + \frac{x_1 + x_3}{2} - \xi^2 \frac{x_1 + x_3}{2} + \frac{1}{2}\xi^2 \overset{\textcircled{1}}{x_3} + \frac{1}{2}\xi x_3 \\ &= \frac{x_1 + x_3}{2} + \left(\frac{x_3 - x_1}{2} \right) \xi \end{aligned}$$

$$\therefore J = \frac{dx}{d\xi} = \frac{x_3 - x_1}{2} = \frac{l}{2}$$

$$K = \int_{-1}^1 \frac{\partial}{\partial \xi} N^T EA \frac{\partial}{\partial \xi} N \frac{1}{2} d\xi$$

$$B = \frac{1}{J} \frac{\partial}{\partial \xi} N = \begin{bmatrix} \xi - \frac{1}{2} & -2\xi & \xi + \frac{1}{2} \end{bmatrix} \frac{1}{l}$$

see script

$$K = \frac{2EA}{l} \begin{bmatrix} 1.67 & -1.33 & .167 \\ & 2.67 & -1.33 \\ & & 1.67 \end{bmatrix}$$

```

% Problem 1
disp('Problem 1')
K=zeros(3,3);
Xi=[-1 1]/sqrt(3);
for i=1:2
    xi=Xi(i)
    B=[xi-1/2 -2*xi xi+1/2]
    K=K+B'*B
end
disp('Problem 2')

evalpoly= [-1 1 -1 1; %poly evaluated at -1
           3 -2 1 0; %poly derivative evaluated at -1
           1 1 1 1; %poly evaluated at 1
           3 2 1 0]; %poly dervative evaluated at 1
disp('Shape function 1 coefficients')
N1=evalpoly\ [1 0 0 0]'

disp('Shape function 1 coefficients')
N2=evalpoly\ [0 1 0 0]'

disp('Shape function 1 coefficients')
N3=evalpoly\ [0 0 1 0]'

disp('Shape function 1 coefficients')
N4=evalpoly\ [0 0 0 1]'
gset key
xi=-1:.01:1;
grid on
plot(xi,polyval(N1,xi),'-;N1;',xi,polyval(N2,xi),'-;N2;',xi,polyval(N3,xi),'-;N3;',xi,polyval(N4,xi),'-;N4;')

B1=polyderiv(polyderiv(N1))
B2=polyderiv(polyderiv(N2))
B3=polyderiv(polyderiv(N3))
B4=polyderiv(polyderiv(N4))

disp("Don't forget that terms need to be multiplied ordivided by J as shown in the written soluti
on.")

```

2) Shape functions are derived in script

$$K_{14} = \int_{-1}^1 B^T E I(\xi) B T d\xi$$

$$N_1 = \frac{\xi^3}{4} - \frac{3\xi}{4} + \frac{1}{2}$$

$$N_2 = \frac{1}{4}(\xi^3 - \xi^2 - \xi + 1) J$$

$$N_3 = \frac{1}{4}(\xi^3 + 3\xi + 2)$$

$$N_4 = \frac{1}{4}(\xi^3 - \xi^2 - \xi - 1) J$$

$$I = \frac{I_1}{2}(1-\xi) + \frac{I_2}{2}(1+\xi)$$

$$T = \frac{1}{J}$$

$$B = \frac{1}{J^2} \frac{d^2}{d\xi^2} N$$

$$= \frac{4}{L^2} \begin{bmatrix} \frac{3}{2}\xi & (\frac{3}{2}\xi - \frac{1}{2})\frac{1}{2} & -\frac{3}{2}\xi & (\frac{3}{2}\xi + \frac{1}{2})\frac{1}{2} \end{bmatrix}$$

Polynomial to be integrated is 3rd order

$2n-1 = 3$, $n=2$. 2 points are sufficient

$$K_{14} = \frac{4}{L^2} \sum_{\xi_1 = -\frac{1}{\sqrt{3}}, \xi_2 = \frac{1}{\sqrt{3}}}^2 \frac{3}{2}\xi \left(\frac{3}{2}\xi + \frac{1}{2} \right) \left(\frac{I_1}{2}(1-\xi) + \frac{I_2}{2}(1+\xi) \right)$$

$$= \frac{2I_1 + 4I_2}{L^2} E$$

Condition for N_2 is $\theta = 1 @ x_1$
 $\left. \frac{d}{dx} v(x) \right|_{x=x_1} = 1$

Usage shape functions in natural coordinates

$$\left. \frac{d}{d\xi} v(\xi) \right|_{\xi=-1} = \frac{dx}{d\xi} \left. \frac{d}{dx} v(x) \right|_{x=x_1}$$

$$= J \left. \frac{d}{dx} v(x) \right|_{x=x_1}$$

So since $\left. \frac{d}{dx} v(x) \right|_{x=x_1} = 1$, then

$$\left. \frac{d}{d\xi} v(\xi) \right|_{\xi=-1} = J. \text{ For computational}$$

purposes, we set then to 1, then

scale the coefficients by J

3) There is an error in the problem. The equation given for \bar{x} actually gives \bar{y} . \bar{x} is given by $\frac{S \times \partial t}{S \partial A}$

Since the polynomial is 1st order, one point should be sufficient. Let's see

$$y = N[y]$$

$$x = N[x]$$

$$= 2S - rS - S^2$$

$$= r$$

$$J = \begin{bmatrix} \frac{\partial y}{\partial r} & \frac{\partial y}{\partial S} \\ \frac{\partial x}{\partial r} & \frac{\partial x}{\partial S} \end{bmatrix} = \begin{bmatrix} 1 & -S \\ 0 & 2-r-2S \end{bmatrix}$$

$$\det[J] = \overset{\text{very important}}{2J} = 2-r-2S$$

$$\text{So } \int_0^1 \int_0^1 y J dr ds = \int_0^1 \int_0^1 (2S - rS - S^2)(2-r-2S) dr ds$$

is a 3rd order polynomial and requires 4 points.

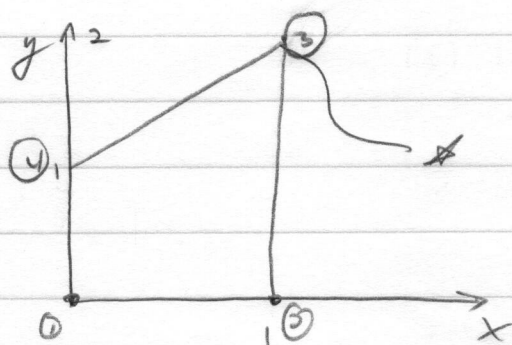
For exam, one loop makes the most sense

See script for solution.

$\bar{x} = \frac{1}{3}$, $\bar{y} = \frac{1}{3}$. You should be able to do these by hand (you should have them memorized.)

```
%Problem 3
A=0;
Qx=0;
Qy=0;
weights=[-27/48 25/48 25/48 25/48];
r=[1/3 3/5 1/5 1/5]
s=[1/3 1/5 1/5 3/5]
for i=1:4
    w=weights(i)
    x=r(i);
    y=2*s(i)-r(i)*s(i)-s(i)^2
    J=1/2*(2-r(i)-2*s(i))
    A=A+w*J
    Qx=Qx+w*y*J
    Qy=Qy+w*x*J
end
Qx/A
Qy/A
```

4)



Find Stresses @ ③

presuming only $u_3, v_3 \neq 0$ We need $\frac{\partial u}{\partial x}, \frac{\partial v}{\partial x}, \frac{\partial u}{\partial y}, \frac{\partial v}{\partial y}$.To get them, we need J and $\frac{\partial u}{\partial \xi}, \frac{\partial u}{\partial \eta}, \frac{\partial v}{\partial \xi}, \frac{\partial v}{\partial \eta}$

$$u = \sum N_i u_i, \quad v = \sum N_i v_i$$

We can evaluate these where we need them

$$\frac{\partial u}{\partial \xi} = \frac{\partial N_3}{\partial \xi} u_3, \quad \frac{\partial u}{\partial \eta} = \frac{\partial N_3}{\partial \eta} u_3, \quad \frac{\partial v}{\partial \xi} = \frac{\partial N_3}{\partial \xi} v_3, \quad \frac{\partial v}{\partial \eta} = \frac{\partial N_3}{\partial \eta} v_3$$

$$= \frac{1}{2} u_3, \quad = \frac{1}{2} u_3, \quad = \frac{1}{2} v_3, \quad = \frac{1}{2} v_3$$

$$J = \frac{1}{4} \begin{bmatrix} 0 & 0 & 2 & -2 \\ 0 & -2 & 2 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 1 & 0 \\ 1 & 2 \\ 0 & 1 \end{bmatrix}$$

$$= \frac{1}{4} \begin{bmatrix} 2 & 2 \\ 0 & 4 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} \frac{\partial u}{\partial x} \\ \frac{\partial u}{\partial y} \end{bmatrix} = J^{-1} \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \end{bmatrix} u_3 = \frac{1}{2} u_3 \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \text{likewise} \quad \begin{bmatrix} \frac{\partial v}{\partial x} \\ \frac{\partial v}{\partial y} \end{bmatrix} = \frac{1}{2} v_3 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$S \cdot \begin{bmatrix} \epsilon_{xx} \\ \epsilon_{xy} \\ \gamma_{xy} \end{bmatrix} = \begin{bmatrix} \frac{1}{2} u_3 \\ \frac{1}{2} v_3 \\ \frac{1}{2} (u_3 + v_3) \end{bmatrix}$$

We need more information to determine what $[E]$ to use.