1)
$$E_{x} = \frac{\partial U}{\partial x} = \Omega_{3} + \Omega_{4} y$$

Ex may have $\Omega_{5} = \alpha_{4} = 0$ in one clean!

Read $\alpha_{3} \neq 0$ with $\alpha_{4} = 0$ in an algorithm of strain is whitely.

2) $E = \int_{0}^{2\pi} \frac{\partial^{2}}{\partial x^{2}} N^{T} E I \frac{\partial^{2}}{\partial x^{2}} N dx$

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$$= \int_{0}^{2\pi} \frac{\partial^{2}}{\partial x^{2}} \left(\frac{1}{2} + \frac{12}{2} \frac{1}{2} \right) \left(\frac{1}{2} + \frac{12}{2} \frac{1}{2} \right) x \cdot \left(\frac{32L}{25} - \frac{60L}{25} \right) x^{2}$$

$$+ \left(\frac{72L_{2}}{26} - \frac{72L_{1}}{26} \right) x^{3} dx$$

$$= \frac{2E}{2} \left(\frac{1}{2} + 2L_{2} \right)$$

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3) N: (1- 5) N: 7 u(x)= u, N, + u, N2 u' = u, N, + u, N' = = = = = = [u,] There is a type chearly the 1st term should be I character Also, for the potential field V'= [-1 | 1] [V]

Integrating over the element, taking the variation of things that can vary. SU-SUS N'EAN'DX U- SYSN'EAN'DXU - SUSN'EAN' dx V - SU SN'EA N' dx V Factoring coefficients and performing integrals EA[,] u - eA[,] V = 0 and $eA \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} y - \frac{eA}{e} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} y = 0$

Assembled

$$V$$
 C_0
 C_0

5) Plane stran is the state under which no strain is allowed out at the plane.

An example is any object of uniform cross section constrained between to rigid boundaries and subject to