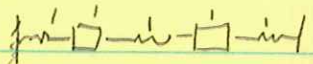


- 1) By observation, this system is 
 Mode shapes are $\frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$, $\frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

$$\omega_1^2 = \frac{1}{2} \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = 1, \omega_1 = 1 \text{ rad/s}$$

$$\omega_2^2 = \frac{1}{2} \begin{bmatrix} 1 & -1 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \end{bmatrix} \begin{bmatrix} 3 \\ -3 \end{bmatrix} = 3, \omega_2 = 1.73$$

For perturbation, $A_0 = \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$

$$A = \begin{bmatrix} 1.1 & 0 \\ 0 & 1 \end{bmatrix}^{-1/2} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 1.1 & 0 \\ 0 & 1 \end{bmatrix}^{-1/2} = \begin{bmatrix} 1.82 & -0.95 \\ -0.95 & 2 \end{bmatrix}$$

While we are here, $\omega_1 = 0.98 \text{ rad/s}$, $\omega_2 = 1.69 \text{ rad/s}$

So, $\epsilon A_1 = \begin{bmatrix} -0.18 & 0.05 \\ 0.05 & 0 \end{bmatrix}$, If we choose $\epsilon = 0.1$,

$A_1 = \begin{bmatrix} -1.8 & 0.5 \\ 0.5 & 0 \end{bmatrix}$, so this is a small change

So, using perturbation, $\omega_1^2 = 1 + (0.1) \frac{1}{2} \begin{bmatrix} 1 & 1 \end{bmatrix} \begin{bmatrix} -1.8 & 0.5 \\ 0.5 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

$$= 1 + 0.05(-0.8) = 0.96, \omega_1 = 0.98$$

$$\omega_2^2 = 2.86, \omega_2 = 1.69 \text{ rad/s}$$

There is no error to two places.

$$2) \quad T = \int_0^l \rho A \dot{w}^2 dx + \frac{1}{2} m \dot{w}^2 \Big|_{x=0}$$

$$U = \int_0^l EI \left(\frac{\partial^2 w}{\partial x^2} \right)^2 dx + \frac{1}{2} K w^2 \Big|_{x=0}$$

$$\delta \int_{t_1}^{t_2} \int_0^l T - U \, dx \, dt = 0$$

Considering T , $\delta \int_{t_1}^{t_2} \int_0^l T \, dx \, dt = \delta \int_{t_1}^{t_2} \int_0^l \rho A \dot{w} \, \delta w \, dx + m \dot{w} \, \delta w \Big|_{x=0} \, dt$

Considering δU , $\int_{t_1}^{t_2} \int_0^l EI \frac{\partial^4 w}{\partial x^4} \, \delta w \, dx - EI \frac{\partial^3 w}{\partial x^3} \, \delta w \Big|_0^l + EI \frac{\partial^2 w}{\partial x^2} \, \delta w' \Big|_0^l + K w \, \delta w \Big|_{x=0} \, dt$

Collecting coeffs of δx inside integral over x

$$\text{EOM: } +EI \frac{\partial^4 w}{\partial x^4} + \rho A \ddot{w} = 0$$

At left end ($x=0$): $m \ddot{w} + EI \frac{\partial^3 w}{\partial x^3} - K w = 0$
and $EI \frac{\partial^2 w}{\partial x^2} = 0$

At right end, $w=0, w'=0$.

$$3) \quad EI w'''' + PA \ddot{w} = 0$$

Subst

$$w(x,t) = u(x,t) + a \sin \omega t$$

$$EI u'''' + PA \ddot{u} = -PA a \omega^2 \sin \omega t$$

Mass normalized modes are

$$U(x) = \sqrt{\frac{2}{PA}} \sin \frac{n\pi x}{l}$$

linear undamped, sine in
sine out

$$u_n(x,t) = A_n \sin \omega t U_n(x)$$

$$\int_0^l \frac{1}{2PA} \cdot PA \sin^2 \frac{n\pi x}{l} dx$$

$$= \frac{1}{2} \int_0^l \sin^2 \frac{n\pi x}{l} dx = \frac{1}{4}$$

should have been $\sqrt{\frac{2}{PA}}$

Subst

$$\sum_{n=1}^{\infty} \left[EI \left(\frac{n\pi}{l} \right)^4 \sqrt{\frac{2}{PA}} \sin \frac{n\pi x}{l} \sin \omega t - PA \sqrt{\frac{2}{PA}} \omega^2 \sin \omega t \right] = -PA a \omega^2 \sin \omega t$$

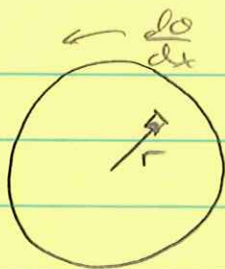
Mult by $\sqrt{\frac{2}{PA}} \sin \frac{m\pi x}{l}$ and integrate over domain

$$A_n \left[EI \left(\frac{m\pi}{l} \right)^2 \frac{1}{PA} \sin \omega t - \omega^2 \sin \omega t \right] = -PA a \omega^2 \sin \omega t \sqrt{\frac{2}{PA}} (1 - \cos m\pi)$$

$$A_n = \frac{-a \omega^2 PA \sqrt{\frac{2}{PA}} (1 - \cos m\pi)}{\left(\frac{m\pi}{l} \right)^2 \frac{EI}{PA} - \omega^2}$$

$$\text{So, } w(x,t) = \sum_{m=1}^{\infty} \frac{-a \omega^2 (1 - \cos m\pi)}{\left(\frac{m\pi}{l} \right)^2 \frac{EI}{PA} - \omega^2} 2 \sin \frac{m\pi x}{l} \sin \omega t - a \sin \omega t$$

4)



Shear strain at point r is $r \frac{d\theta}{dx}$

Shear stress is $G r \frac{d\theta}{dx}$

Moment of stress about center is $G r^2 \frac{d\theta}{dx}$

Total moment is

$$\int_A G r^2 \frac{d\theta}{dx} dA$$

$$= G \frac{d\theta}{dx} \underbrace{\int_A r^2 dA}_{\text{definition of } J}$$

$$= G J \frac{d\theta}{dx}$$