

Short answers

1) It works. Piezoceramic based linear strain gauge to quickly for low freq use.

- 2) a) real eigenvalues
 b) real eigenvectors
 c) orthogonal eigenvectors
 d) $\frac{1}{2}$ the storage space

3) $m\omega_n = .1 \quad \omega_d = .9 = \omega_n \sqrt{1-s^2} \quad s\omega_n = .01$

$$\frac{.01}{.9} = \frac{s\omega_n}{\omega_n \sqrt{1-s^2}} = \frac{s}{\sqrt{1-s^2}}$$

$$.95 = .01 \sqrt{1-s^2}$$

$$.81s^2 = .0001(1-s^2)$$

$$.8101s^2 = .0001$$

$$s = \sqrt{\frac{.0001}{.8101}} = .011 \quad (\text{or } s = \frac{.01}{.9})$$

$$\omega_n = \frac{.01}{.011} = .9 \text{ rad/s}$$

$$m = \frac{.01}{\omega_n} = 0.11 \text{ units} \quad (\text{I didn't give this})$$

$$m=0.11, C=250 \text{ N/m}, K=m\omega_n^2$$

$$0.11 \ddot{x} + 0.002 \dot{x} + 0.09x = F(t)$$

4) Energy Method doesn't allow inclusion of

- a) energy dissipation
 b) external forces

5) Easier to handle geometric nonlinearities

6) Yes, through the mass and stiffness matrices

7) K is symmetric and Positive semi-definite
(all eigenvalues ≥ 0)

M is symmetric and Positive definite.

8) In addition to orthogonality through K and M

$$\underline{u}_i^T K \underline{u}_i = \omega_i^2 \quad \underline{u}_i^T M \underline{u}_i = 1$$

when they are mass normalized

9) Orthogonality of \underline{v}_i (eigenvectors of \tilde{K})

10) Numerical simulation

Long Problems

1) a) i) $y_t = \frac{-mg}{k} \cos \sqrt{\frac{k}{m}} t$

ii) Equation one has no transient response given the initial deflection.

b) i) $y_{ss} = \frac{mg}{k}$, ii) $y_{ss} = 0$ for eqn 1

c) $y_s = \frac{mg}{k} (1 - \cos \sqrt{\frac{k}{m}} t)$

d) Max is $\frac{2mg}{k}$. Min is zero. Max is twice static deflection.

$$2) \quad a_0 = t$$

Real form $\frac{1}{T/2}$ easiest for this problem

$$a_n = \frac{2}{T} \left(\int_0^{\frac{T}{2}} 2 \cos \frac{2\pi n t}{T} dt + \int_{\frac{T}{2}}^T -1 \cos \frac{2\pi n t}{T} dt \right)$$

$$= \frac{2}{T} \left(\frac{2T}{2\pi n} \sin \frac{2\pi n t}{T} \Big|_0^{\frac{T}{2}} - \frac{T}{2\pi n} \sin \frac{2\pi n t}{T} \Big|_{\frac{T}{2}}^T \right)$$

$$= \frac{2}{T} \left(\frac{T}{\pi n} \left(\sin \frac{\pi n}{2} - 0 \right) - \frac{T}{2\pi n} \left(\sin 2\pi n - \sin \frac{\pi n}{2} \right) \right)$$

$$= 0$$

$$b_n = \frac{2}{T} \left(\int_0^{\frac{T}{2}} 2 \sin \frac{2\pi n t}{T} dt + \int_{\frac{T}{2}}^T -1 \cos \frac{2\pi n t}{T} dt \right)$$

$$= \frac{2}{T} \left(\frac{-2T}{2\pi n} \cos \frac{2\pi n t}{T} \Big|_0^{\frac{T}{2}} + \frac{T}{2\pi n} \cos \frac{2\pi n t}{T} \Big|_{\frac{T}{2}}^T \right)$$

$$= \frac{-1}{\pi n} \left[2(\cos \pi n - \cos 0) - (\cos 2\pi n - \cos \pi n) \right]$$

1/-1 even/odd 1/-1 even/odd

For n odd

$$b_n = \frac{-1}{\pi n} (2(-1 - 1) - (1 + 1)) \\ = \frac{6}{\pi n}$$

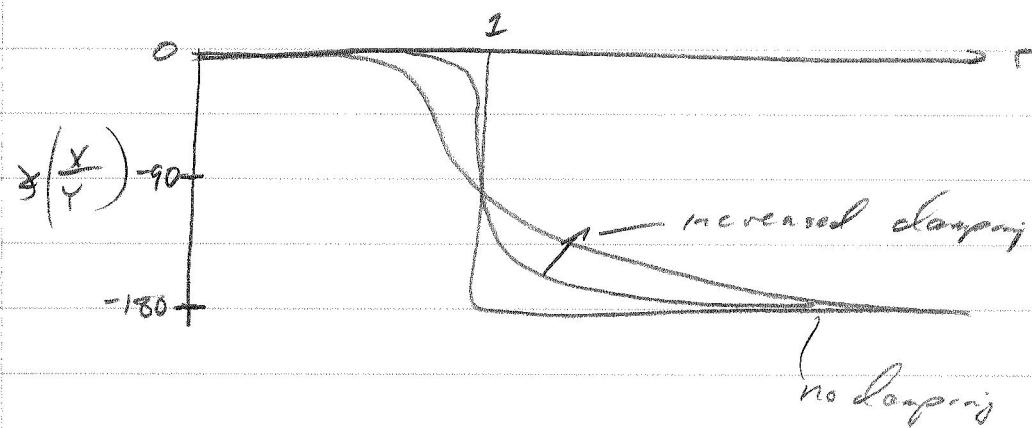
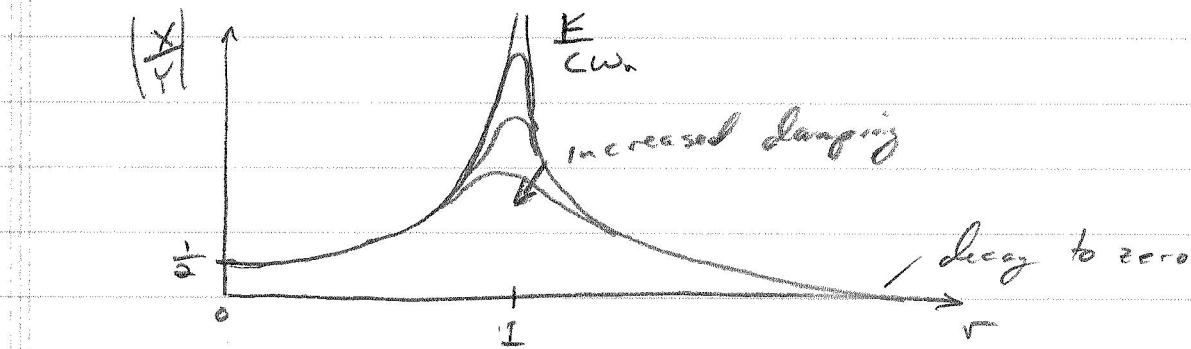
For n even

$$b_n = \frac{-1}{\pi n} (0) = \boxed{0}$$

$$F(t) = \frac{1}{2} + \sum_{n=1}^{\infty} \frac{6}{n\pi} \sin \frac{2\pi n t}{T}$$

3)

$$\ddot{y} = \frac{-K}{2K - m\omega^2 + c_J w} \quad \omega_n = \sqrt{\frac{2K}{m}}$$



$$e) F = S^T E = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} s(t) \\ 0 \end{bmatrix}$$

(note \$S\$ is orthonormal, conveniently making \$S^T = S^{-1}\$)

$$F = \frac{1}{\sqrt{2}} \begin{bmatrix} s(t) \\ s(t) \end{bmatrix}$$

$$h(t) = \frac{1}{\sqrt{2}} e^{-i\omega_n t} \sin \omega_n t \quad S=0, w_0=w_n$$

$$r(t) = F(t) h(t)$$

$$r(t) = \frac{1}{\sqrt{2}} \frac{1}{3} \sin 3t \quad \text{Model mass is always 2}$$

$$s(t) = \frac{1}{\sqrt{2}} \frac{1}{10} \sin 10t$$

$$x(t) = S r(t) = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} \frac{1}{3} \sin 3t \\ \frac{1}{10} \sin 10t \end{bmatrix}$$

$$= \begin{bmatrix} \frac{1}{6} \sin 3t + \frac{1}{20} \sin 10t \\ \frac{1}{6} \sin 3t - \frac{1}{20} \sin 10t \end{bmatrix}$$

$$3) dt (K - M\omega^2) = 0$$

$$(35 - 2\lambda)(35 - 3\lambda) - 35^2 = 0$$

$$35^2 - 5 \cdot 35\lambda + 6\lambda^2 - 35^2 = 0$$

$$6\lambda^2 = 175\lambda$$

$$\lambda = 0, \frac{175}{6} (29.17)$$

$$\omega = 0, 5.4 \text{ rad/s}$$

$$u_1 = 0:$$

$$\begin{bmatrix} 35 & -35 \\ -35 & 35 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$u_1 = u_2, \quad u_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$u_2 = 5.4$$

$$\begin{bmatrix} 35 - 58.3 & -35 \\ -35 & 35 - 87.5 \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$-23.3u_1 + -35u_2 = 0$$

$$-35u_1 - 52.5u_2 = 0$$

$$u_1 = \begin{bmatrix} 1 \\ -0.666 \end{bmatrix}$$

You should check using orthogonality if true remains.

$$6) U = \frac{1}{2} k_1 x_1^2 + \frac{1}{2} k_2 (x_2 - x_1)^2 + \frac{1}{2} k_3 x_2^2$$

$$T = \frac{1}{2} m_1 \dot{x}_1^2 + \frac{1}{2} J_1 \dot{\theta}_1^2 + \frac{1}{2} m_2 \dot{x}_2^2 + \frac{1}{2} J_2 \dot{\theta}_2^2$$

These are clocks, so $\dot{\theta} = \frac{\dot{x}}{r}$

$$T = \frac{1}{2} \left(m_1 + \frac{J_1}{r_1^2} \right) \dot{x}_1^2 + \frac{1}{2} \left(m_2 + \frac{J_2}{r_2^2} \right) \dot{x}_2^2$$

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_1} \right) = \left(m_1 + \frac{J_1}{r_1^2} \right) \ddot{x}_1$$

$$\frac{\partial U}{\partial x_1} = k_1 x_1 + k_2 (x_2 - x_1)$$

Eqn 1 is

$$\boxed{\left(m_1 + \frac{J_1}{r_1^2} \right) \ddot{x}_1 + (k_1 + k_2) x_1 - k_2 x_2 = 0}$$

$$\frac{d}{dt} \left(\frac{\partial T}{\partial \dot{x}_2} \right) = \left(m_2 + \frac{J_2}{r_2^2} \right) \ddot{x}_2$$

$$\frac{\partial U}{\partial x_2} = k_2 (x_2 - x_1) + k_3 x_2$$

Eqn 2 is

$$\boxed{\left(m_2 + \frac{J_2}{r_2^2} \right) \ddot{x}_2 + (k_2 + k_3) x_2 - k_2 x_1 = 0}$$

→ (Grd Problem)

$$W_0 = C^2 W_{\text{ax}}$$

$$-w_n^2 X(x) = C^2 \overset{\omega^2}{X''(x)}$$

$$X''(x) + \frac{w_n^2}{C^2} X(x) = 0$$

$$X(x) = A \sin \omega x + B \cos \omega x$$

Free-Free conditions mean

$$x'|_{x=0} = A\omega \cos(\omega 0) - B\omega \sin(\omega 0) \quad (1)$$

$$x'|_{x=l} = A\omega \cos(\omega l) - B\omega \sin(\omega l) \quad (2)$$

From (1), $A=0$

From (2) $\sin \omega l = 0$

$$\omega_n = \frac{n\pi}{l} \quad n=0, 1, 2, \dots \quad (\text{Yes, zero})$$

Mode shapes are

$$X_n(x) = B_n \cos \frac{n\pi x}{l}$$

$$\text{Then, } \omega_n = \sqrt{\omega_n^2 C^2} = \frac{n\pi}{l} \sqrt{\frac{E}{\rho}}$$

To normalize then $B_n = \sqrt{\frac{2}{l}}$, except $B_0 = \frac{1}{l}$

$$w(t) = \sum_{n=1}^{\infty} T_n(t) X_n(t)$$

Subst into EOM, multiply over domain, gives

$$\left(\ddot{T}_n + \underbrace{C^2 \omega^2}_{\omega_n^2} T \right) = B_n 100 \cos \frac{n\pi}{2} \delta(t)$$

$$F = B_n 100 \cos \frac{n\pi}{2}$$

$$h(t) = \frac{1}{\omega_n} \sin \omega_n t$$

$$T(t) = 100 B_n \cos \frac{n\pi}{2} \frac{1}{\omega_n} \sin \omega_n t$$

$$\cos \frac{n\pi}{2} = \begin{cases} 0 & n \text{ odd} \\ 1 & n=0, 4, 8, \dots \\ -1 & n=2, 6, 10, \dots \end{cases}$$

Except for $n=0$. For $n=0$, impulse is initial velocity of a free system, so

$$T_n = 100 \frac{1}{\omega_0}, \quad T_n = 100 \frac{1}{\omega_0} t$$

$$w(x,t) = \frac{100}{t} t + \sum_{n=1}^{\infty} \frac{200}{\omega_n} \frac{(\cos \frac{n\pi}{2})}{\tan(X(\frac{t}{2}))} \cos \frac{n\pi x}{l} \sin \left(\frac{n\pi}{l} \sqrt{\frac{I}{\rho}} t \right)$$

$$\text{where } \omega_n = \frac{n\pi}{l} \sqrt{\frac{I}{\rho}}$$