

ME 464/664 Solns, Exam 1 2006

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```
t=(0:.1:.6)';  
T=[300 150 75 35 12 5 2]';
```

```
semilogy(t,T,'*')
```

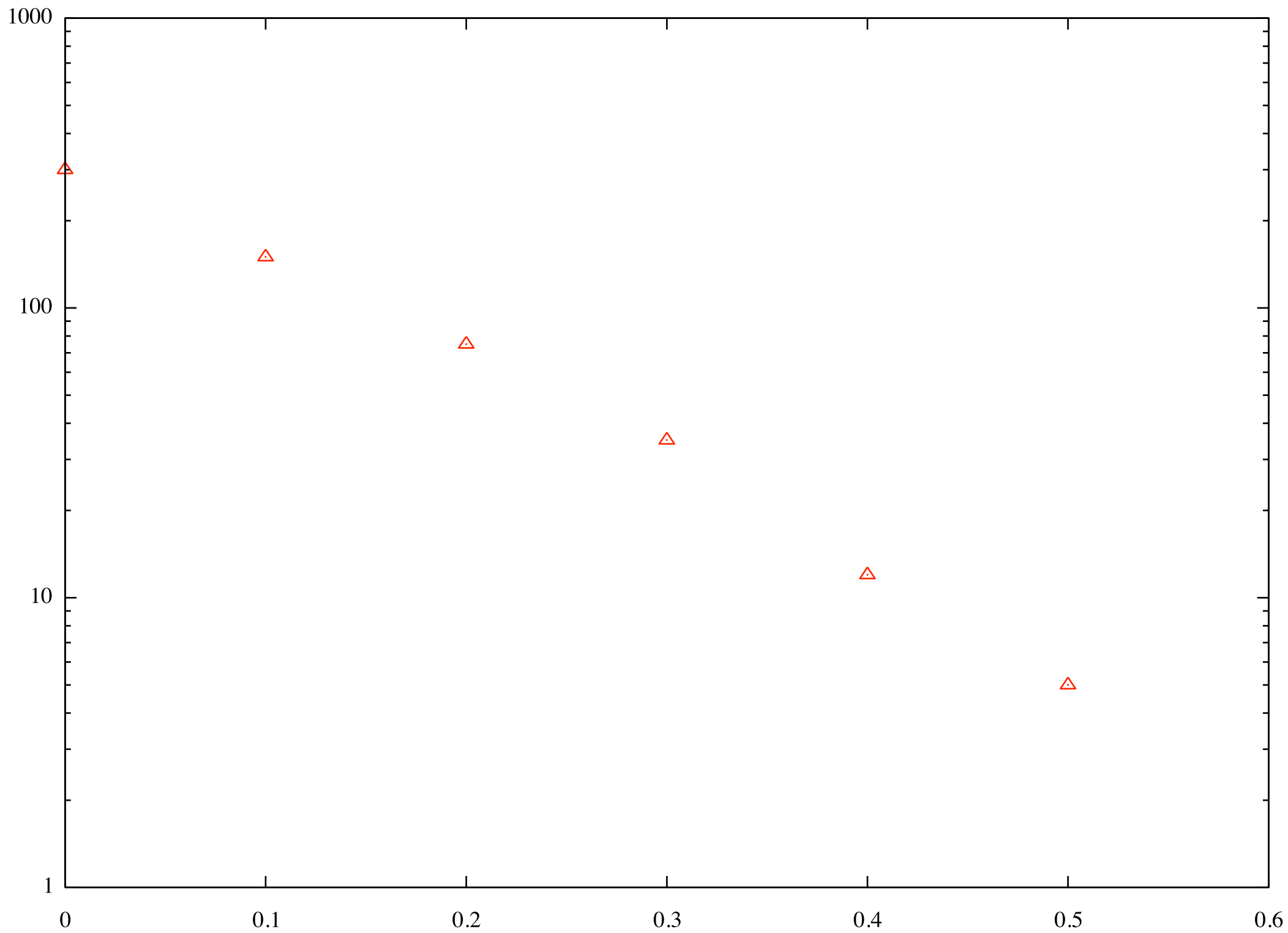
```
logT=log(T);
```

```
p=polyfit(t,logT,1)
```

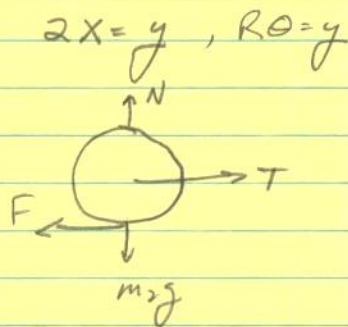
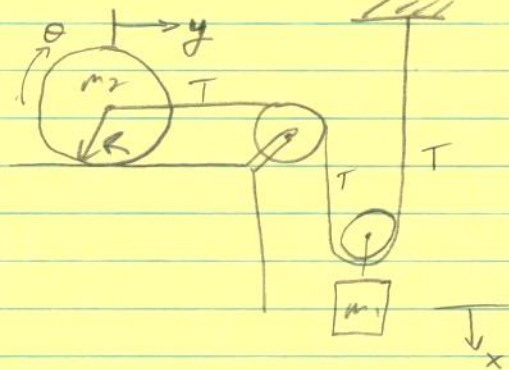
```
m=p(1)
```

```
b=exp(p(2))
```

```
disp(['solution is ' num2str(b) 'e^' num2str(m) 'T'])
```



2)



$$① \quad m_1 \ddot{x} = m_1 g - 2T$$

$$② \quad m_2 \ddot{y} = T - F$$

$$③ \quad I \ddot{\theta} = FR, \quad F = \frac{I}{R} \ddot{\theta}$$

$$③ \text{ into } ② \quad m_2 \ddot{y} = T - \frac{I}{R} \ddot{\theta}$$

$$\text{simplify} \quad m_2 \ddot{y} = T - \frac{I}{R^2} \ddot{y}$$

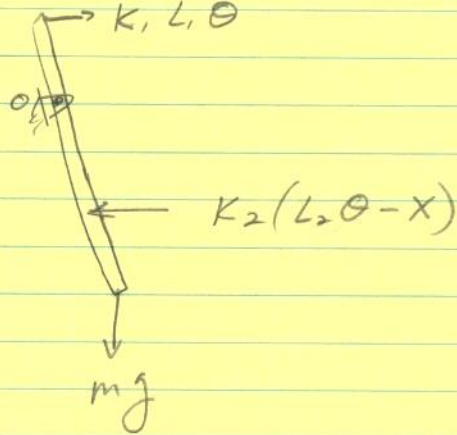
$$\text{simplify} \quad T = \left(m_2 + \frac{I}{R^2}\right) \ddot{y}$$

Subst into ①

$$m_1 \ddot{x} = m_1 g - 2\left(m_2 + \frac{I}{R^2}\right) \ddot{y}$$

$$\left[m_1 + 4\left(m_2 + \frac{I}{R^2}\right)\right] \ddot{x} = m_1 g$$

3)



$$\sum M_o = I \ddot{\theta} = -K_1 L_1 \theta (L_1 \cos \theta) - K_2 (L_2 \theta - x) L_2 \cos \theta - mg L_3 \sin \theta$$

$\sin \theta \approx \theta$ for small θ , $\cos \theta \approx 1$ for small θ

$$\underline{I \ddot{\theta} + (K_1 L_1^2 + K_2 L_2^2) \theta = mg L_3 \sin \theta + K_2 L_2 x}$$

4) Linear: 2, 3

Autonomous: 1, 2, 4