

Fall 2008 ME 460 Final Exam Solas

1)  $\frac{X(j\omega)}{r(j\omega)} = \frac{K}{K - m\omega^2 + c j\omega}$

n	$\omega$	$ H(j\omega) $	$\angle H(j\omega)$	$X_n$
0	0	$\frac{1}{2}$	0	$\frac{1}{2}$
1	$\pi$	1.01	$-0.018^\circ$	0.32
2	$2\pi$	1.04	$-0.037^\circ$	0.17
3	$3\pi$	1.10	$-0.059^\circ$	0.12

$$X(t) = \frac{1}{2} - 0.32 \sin(\pi t - 0.018^\circ) - 0.17 \sin(2\pi t - 0.037^\circ) - 0.12 \sin(3\pi t - 0.06^\circ)$$

Phases in rad  
 $-3 \times 10^{-4}$   
 $-6.5 \times 10^{-4}$   
 $-1 \times 10^{-3}$

Note: Excitations are far from resonance. However, this means they are all nearly quasi-static excitations. Such an assumption only leads to a 10% error in the 3<sup>rd</sup> term. A quasi static excitation solution would give

$$x(t) = \frac{1}{2} - 0.32 \sin \pi t - 0.16 \sin 2\pi t - 0.11 \sin 3\pi t$$

2) See solution to problem 2, on Fall '08 Exam # 2. This uses convolution integral, 2 times. (but the simplification doesn't happen)

3)  $\underline{r}(0) = S \underline{x}(0)$

a) I gave formula for inverting matrix

b) Columns of  $S$  are orthogonal, so its inverse is its transpose

$$\underline{r}(0) = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\underline{v}(0) = \underline{0}$$

$$\text{so } r_1(t) = \frac{1}{\sqrt{2}} \cos 3t, \quad r_2(t) = \frac{1}{\sqrt{2}} \cos 10t$$

$$\begin{aligned} \underline{x}(t) &= S \underline{r} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} \cos 3t \\ \cos 10t \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{2} \cos 3t + \frac{1}{2} \cos 10t \\ \frac{1}{2} \cos 3t - \frac{1}{2} \cos 10t \end{bmatrix} \end{aligned}$$

4)  $U = \frac{1}{2} k x_{\text{spring}}^2 - mgx$   $x_{\text{spring}} = \frac{1}{2} x$   
 $= \frac{1}{2} \frac{k}{4} x^2 - mgx$

$$T = \frac{1}{2} m \dot{x}^2 + \frac{1}{2} I \dot{\theta}^2$$

subst for  $I$  and  $\dot{\theta}$

$$I = \frac{1}{2} m_{\text{disk}} R^2$$

$$\dot{\theta} = \frac{\dot{x}}{R^2}$$

$$T = \frac{1}{2} \left( m + \frac{m_{\text{disk}}}{2} \right) \dot{x}^2$$

Using Lagrange's Eqn  $\frac{d}{dt} \left( \frac{\partial T}{\partial \dot{x}} \right) = \left( m + \frac{m_{\text{disk}}}{2} \right) \ddot{x}$

$$\frac{\partial U}{\partial x} = \frac{k}{4} x - mg, \text{ so}$$

$$\boxed{\left( m + \frac{m_{\text{disk}}}{2} \right) \ddot{x} + \frac{k}{4} x - mg = 0}$$

5)  $w_{tt} - c^2 w_{xx} = 0$

If ends are fixed, we can solve for mode shapes as (see prev exams/book)

$$X(x) = \sin \frac{n\pi x}{l}$$

$$S. \quad w(x, t) = \sum_{n=1}^{\infty} T_n(t) \sin \frac{n\pi x}{l}$$

Substituting

$$\left( \ddot{T} + \underbrace{c^2 \left( \frac{n\pi}{l} \right)^2}_{\omega_n^2} T \right) \sin \frac{n\pi x}{l} = 100 \delta(x - \frac{l}{3}) \delta(t)$$

Multiplying by  $\sin \frac{n\pi x}{l}$  and integrating over  $0 < x < l$

$$\ddot{T}_n + c^2 \left( \frac{n\pi}{l} \right)^2 T_n = \frac{2}{l} 100 \sin \frac{n\pi}{3} \delta(t)$$

The impulse response is (for undamped system)

$$\begin{aligned} T_n(t) &= \frac{\hat{F}}{m \omega_n} \sin \omega_n t \\ &= 200 \sin\left(\frac{n\pi}{3}\right) \frac{l}{n\pi} \sqrt{\frac{P}{E}} \sin\left(\frac{n\pi}{l} \sqrt{\frac{E}{P}} t\right) \end{aligned}$$

$$w(x, t) = \sum_{n=1}^{\infty} 200 \frac{l}{n\pi} \sqrt{\frac{P}{E}} \sin \frac{n\pi}{3} \sin\left(\frac{n\pi}{l} \sqrt{\frac{E}{P}} t\right) \sin \frac{n\pi x}{l}$$