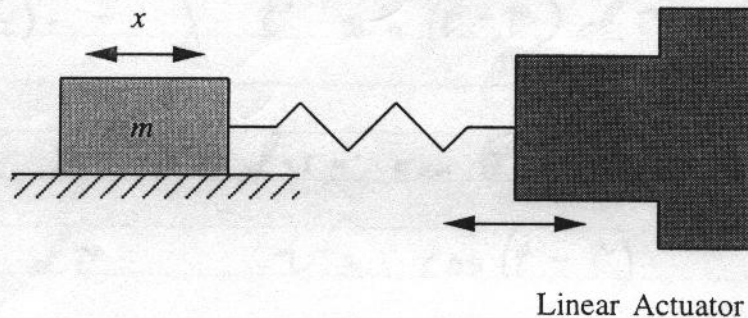


## ME 460/660 Exam 2, Spring '95

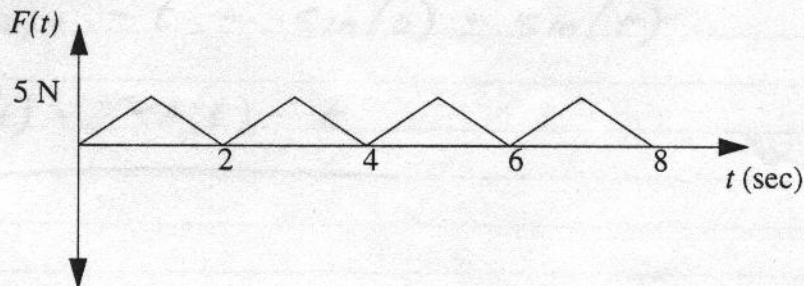
- 1) Find the response of an undamped system with  $m = 1$  kg and  $k = 1$  N to a force  $F(t) = -t$  using the convolution integral.
- 2) a) It is desired to position a mass of 1 kg within  $\pm 0.01$  mm using a linear actuator. The dynamic and static coefficients of friction between the mass and the surface are  $\mu = 0.07$ . Knowing that stiction occurs below  $x = \mu N/k$ , find the minimum stiffness allowable in the arm connecting the mass to the actuator. Use  $g = 9.81$  m/s<sup>2</sup>.  
b) If the actuator moves a distance of 1 cm, how long will it take for the position of the mass to meet the design specification? Assume the motion of the actuator is instantaneous.



- 3) Find the eigenvectors and eigenvalues of the following matrix. Normalize the eigenvalues and determine if they form an orthonormal set.

$$A = \begin{bmatrix} 2 & -1 \\ -2 & 4 \end{bmatrix}$$

- 4) Find the steady state response of a SDOF system with  $m = 5$  kg,  $c = 0.01$  Ns/m, and  $k = 20\pi^2$  N/m to the following force:



Which term in the Fourier series of the force is the most important one?

ME 460/660 Exam 2 Sp' 95, Solutions

- 1) Find the response of an undamped system with  $m=1 \text{ kg}$ ,  $k=1 \text{ N/m}$  to a force  $F(t)=-t$  using the convolution integral.

$$h(t) = \sin(t-\tau)$$

$$x(t) = \int_0^t F(\tau) h(t-\tau) d\tau$$

$$x(t) = - \int_0^t \tau \sin(t-\tau) d\tau$$

$$u = \tau \quad dv = \sin(t-\tau) d\tau$$

$$du = d\tau \quad v = \cos(t-\tau)$$

$$x(t) = - \left[ \tau \cos(t-\tau) \Big|_0^t - \int_0^t \cos(t-\tau) d\tau \right]$$

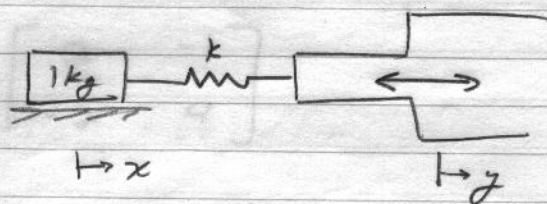
$$x(t) = - \left[ t + \sin(t-\tau) \Big|_0^t \right]$$

$$x(t) = -t - \sin(0) + \sin(t)$$

$$\underline{x(t) = \sin(t) - t}$$



2)



a) If  $|x-y| < \frac{\mu N}{k}$  when the actuator is at rest, the mass will not slip.

$$10^{-5} > \frac{.07 \cdot 9.81 \cdot 1}{k}$$

$$k > 6.867 \times 10^4 \text{ N/m}$$

b)  $x_0 = .01 \text{ m}$

The decay envelope is

$$x = x_0 - \frac{2\mu N \omega}{\pi k} t$$

$$10^{-5} = .01 - \frac{2 \cdot .07 \cdot 9.81}{\pi \sqrt{6.867 \times 10^4}} t_s$$

$$t_s = 5.99 \text{ sec}$$

$$\begin{bmatrix} -2.732 & -1 \\ 2.732 & -2.732 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$2.732 v_1 = -v_2$$

$$v_1 = \begin{bmatrix} 1 \\ -2.732 \end{bmatrix} \quad \text{normalized } v_1 = \begin{bmatrix} .341 \\ -.939 \end{bmatrix}$$

$v_1 \cdot v_2 = .277$  so they are not on orthogonal sets.

$$3) \quad A = \begin{bmatrix} 2 & -1 \\ -2 & 4 \end{bmatrix}$$

$$\det(A - \lambda I) = 0$$

$$(2 - \lambda)(4 - \lambda) - 2 = 0$$

$$8 - 6\lambda + \lambda^2 - 2 = 0$$

$$\lambda^2 - 6\lambda + 6 = 0$$

$$\lambda_{1,2} = 1.268, 4.732$$

$$(A - \lambda I) \underline{v} = \underline{0}$$

For  $\lambda_1 = 1.268$

$$\begin{bmatrix} .732 & -1 \\ -2 & 2.732 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$.732 v_1 = v_2$$

$$\underline{v}_1 = \begin{bmatrix} 1 \\ .732 \end{bmatrix} \quad \text{normalized} \quad \underline{v}_1 = \begin{bmatrix} .807 \\ .591 \end{bmatrix}$$

For  $\lambda_2 = 4.732$ :

$$\begin{bmatrix} -2.732 & -1 \\ -2 & -.732 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$2.732 v_1 = -v_2$$

$$\underline{v}_2 = \begin{bmatrix} 1 \\ -2.732 \end{bmatrix} \quad \text{normalized} \quad \underline{v}_2 = \begin{bmatrix} .344 \\ -.939 \end{bmatrix}$$

$$\underline{v}_1' \underline{v}_2 = .277 \quad \text{so they are not an orthonormal set.}$$



4)

$$\begin{aligned}
 a_0 &= \frac{2}{T} \int_0^T f(t) dt \\
 &= 1 + \int_0^1 5t dt + 7 \int_1^2 5(2-t) dt \\
 &= 1 \left( 2.5t^2 \Big|_0^1 + (10t - 2.5t^2) \Big|_1^2 \right) \\
 &= 1 (2.5 + (20 - 10) - (10 - 2.5)) \\
 &= 1 (2.5 + 10 - 7.5) = 5
 \end{aligned}$$

$b_n = 0$  because the function is even

$$a_n = \int_0^1 5t \cos \frac{2\pi nt}{2} dt + \int_1^2 5(2-t) \cos \frac{2\pi nt}{2} dt$$

$$a_n = \int_0^1 5t \cos \frac{2\pi nt}{2} dt$$

$$u = 5t \quad dv = \cos \frac{2\pi nt}{2} dt$$

$$du = 5 dt \quad v = \frac{1}{\pi n} \sin \pi nt$$

$$\int_0^1 5t \cos \frac{2\pi nt}{2} dt = \frac{5t}{\pi n} \sin \pi nt \Big|_0^1 - 5 \int_0^1 \frac{1}{\pi n} \sin \pi nt dt$$

$$= \frac{-5}{\pi n} + \frac{-1}{\pi n} \cos \pi nt \Big|_0^1$$

$$= \frac{5}{\pi^2 n^2} (\cos \pi n - 1)$$

Since the series is the Fourier series of the system at resonance the most significant term is the one with the largest coefficient, or term 1.

# ME 460/660 Exam 2, Spring '95

$$\int_1^2 10 \cos \pi n t \, dt$$

1) Find the response of an undamped system with  $m = 1$  kg and  $k = 1$  N to a force  $F(t) = -t$  using the convolution integral.

$$= \frac{10}{\pi n} \sin \pi n t \Big|_1^2$$

2) a) It is desired to position a mass of 1 kg within  $\pm 0.1$  mm using a linear actuator. The dynamic and static coefficients of friction between the mass and the surface are  $\mu = 0.7$ . Knowing that slippage occurs below  $x = \mu/k$ , find the minimum stiffness allowable in the arm connecting the mass to the actuator. Use  $g = 9.81$  m/s<sup>2</sup>.

$$= 0$$

b) If the actuator moves a distance of 1 cm, how long will it take for the position of the mass to meet the design specification? Assume the motion of the actuator is instantaneous.

$$\int_1^2 -5t \cos \pi n t \, dt$$

$$= \frac{-5}{\pi^2 n^2} \cos \pi n t \Big|_1^2$$

$$= \frac{+5}{\pi^2 n^2} (-\cos 2\pi n + \cos \pi n)$$

$$A_n = \frac{5}{\pi^2 n^2} (\cos \pi n - 1 - \cos 2\pi n + \cos \pi n)$$

$$A_n = \frac{5}{\pi^2 n^2} (2 \cos \pi n - 2)$$

$$A_n = \frac{5}{\pi^2 n^2} (\cos \pi n - 1) \begin{cases} \frac{-10}{\pi^2 n^2} & n = 1, 3, 5, \dots \\ 0 & n = 2, 4, 6, \dots \end{cases}$$

The Fourier series is then

$$F(t) = 2.5 - \frac{10}{\pi^2} \cos \pi t - \frac{10}{9\pi^2} \cos 3\pi t - \dots$$

Since none of the terms drive the system at resonance, the most significant term is the one with the largest coefficient, or term 1.  $n = 2$