

$$1) \quad T = T(\dot{q}_i) \quad V = V(q_i, \dot{q}_i)$$

$$L = T - V = L(q_i, \dot{q}_i)$$

Hamilton's principle

$$\delta \int_{t_1}^{t_2} L + W_{nc} dt = 0$$

$$= \int_{t_1}^{t_2} \delta L(q_i, \dot{q}_i) + \sum_{i=1}^n Q_i \delta q_i dt$$

$$= \int_{t_1}^{t_2} \sum_{i=1}^n \left[\frac{\partial L}{\partial q_i} \delta q_i + \frac{\partial L}{\partial \dot{q}_i} \delta \dot{q}_i + Q_i \delta q_i \right] dt$$

$$= \sum_{i=1}^n \int_{t_1}^{t_2} \left(\frac{\partial L}{\partial q_i} \delta q_i + \frac{\partial L}{\partial \dot{q}_i} \delta \dot{q}_i + Q_i \delta q_i \right) dt$$

Integrating the second term

$$\int_{t_1}^{t_2} \frac{\partial L}{\partial \dot{q}_i} \delta \dot{q}_i dt = \underbrace{\frac{\partial L}{\partial \dot{q}_i} \delta q_i}_{0} \Big|_{t_1}^{t_2} - \int_{t_1}^{t_2} \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} \delta q_i dt$$

since q_i are assumed to be known at t_1 and t_2

Substituting

$$= \sum_{i=1}^n \int_{t_1}^{t_2} \underbrace{\left(\frac{\partial L}{\partial q_i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} + Q_i \right)}_{=0} \delta q_i dt$$

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} - \frac{\partial L}{\partial q_i} = Q_i$$

Q.E.D

$$2) \quad L = \frac{d^2}{dx^2} \left(EI \frac{d^2}{dx^2} \right)$$

$$w(0) = 0, \quad w'(0) = 0$$

$$\left. \frac{\partial^2 w}{\partial x^2} \right|_{x=L} = 0, \quad \left. \frac{\partial}{\partial x} \left(EI \frac{\partial^2 w}{\partial x^2} \right) \right|_{x=L} = m \left. \frac{\partial^2 w}{\partial t^2} \right|_{x=L}$$

$(u, L v) = (v, L u)$ for self adjointness
where u and v are comparison functions.

$$\begin{aligned} & \int_0^L u \frac{\partial^2}{\partial x^2} \left(EI \frac{\partial^2 v}{\partial x^2} \right) dx \\ &= u \left. \frac{\partial}{\partial x} \left(EI \frac{\partial^2 v}{\partial x^2} \right) \right|_0^L - \int_0^L \frac{\partial u}{\partial x} \frac{\partial}{\partial x} \left(EI \frac{\partial^2 v}{\partial x^2} \right) dx \\ &= \overset{=0 @ x=0}{u \left. \frac{\partial}{\partial x} \left(EI \frac{\partial^2 v}{\partial x^2} \right) \right|_0} - \overset{=0 @ x=0}{\frac{\partial u}{\partial x} EI \left. \frac{\partial^2 v}{\partial x^2} \right|_0} + \overset{=0 @ x=L}{\int_0^L \frac{\partial^2 u}{\partial x^2} EI \frac{\partial^2 v}{\partial x^2} dx} \end{aligned}$$

$$\left. \frac{\partial}{\partial x} \left(EI \frac{\partial^2 v}{\partial x^2} \right) \right|_L = m \left. \frac{\partial^2 v}{\partial t^2} \right|_L$$

Assuming a solution of the form $\frac{\partial^2 v}{\partial t^2} = \lambda v$

$$= u m \lambda v \Big|_L + \int_0^L \frac{\partial^2 u}{\partial x^2} EI \frac{\partial^2 v}{\partial x^2} dx$$

which is symmetrical in u and v .
Thus, the operator L is self-adjoint with respect to the given B.C.s.

To be positive definite, (u, Lu) must be positive for any non-zero comparison function.

$$(u, Lu) = m\lambda u^2 \Big|_{x=L} + \int_0^L \left(\frac{\partial^2 u}{\partial x^2} \right)^2 EI \, dx$$

The first term is ≥ 0

The second term is > 0 for any non-zero u assuming EI is always positive.

Thus, the operator is also positive definite.

$$3) \quad V = \frac{1}{2} \int_0^L EI \left(\frac{\partial^2 W}{\partial x^2} \right)^2 + GJ \left(\frac{\partial \theta}{\partial x} \right)^2 dx$$

$$T = \frac{1}{2} \int_0^L (\rho A \dot{W}^2 + \rho I_p \dot{\theta}^2) dx$$

$$+ \frac{1}{2} m v^2$$

where v is the velocity of the mass m .

For small motion, $v = e \dot{\theta} \Big|_{x=L} + \dot{W} \Big|_{x=L}$

Hamilton's principle states

$$\delta \int_{t_1}^{t_2} (T - V + W_{nc}) dt = 0$$

$W_{nc} = 0$ here

Let's work by term

The first term of T yields

$$\int_{t_1}^{t_2} \int_0^L \rho A \dot{W} \delta \dot{W} dx dt$$

Integrating by parts with respect to time yields

$$\int_0^L \delta W \dot{w} \Big|_{t_1}^{t_2} - \int_{t_1}^{t_2} \dot{w} P A \delta w dt dx$$

Likewise, the second term of T yields

$$\int_0^L \delta \dot{w} \dot{w} \Big|_{t_1}^{t_2} - \int_{t_1}^{t_2} \ddot{w} P I_p \delta \dot{w} dt dx$$

Taking the variation of the first term of the Potential energy yields

$$\int_{t_1}^{t_2} \int_0^L EI \frac{\partial^2 w}{\partial x^2} \delta \left(\frac{\partial^2 w}{\partial x^2} \right) dx dt$$

Integrating by parts twice yields

$$\begin{aligned} & \int_{t_1}^{t_2} EI \frac{\partial^2 w}{\partial x^2} \delta \frac{\partial w}{\partial x} \Big|_0^L - \int_0^L EI \frac{\partial^3 w}{\partial x^3} \delta \frac{\partial w}{\partial x} dx dt \\ &= \int_{t_1}^{t_2} EI \frac{\partial^2 w}{\partial x^2} \delta \frac{\partial w}{\partial x} \Big|_0^L - EI \frac{\partial^3 w}{\partial x^3} \delta w \Big|_0^L + \int_0^L EI \frac{\partial^4 w}{\partial x^4} \delta w dx dt \end{aligned}$$

Taking the variation of the second term of the potential energy and integrating by parts yields

$$\int_{t_1}^{t_2} \frac{\partial \phi}{\partial x} \delta \phi \Big|_0^L - \int_0^L \frac{\partial^2 \phi}{\partial x^2} \delta \phi dx dt$$

The third term of the kinetic energy is

$$T_3 = \frac{1}{2} m v^2 = \frac{1}{2} m (\dot{e}\theta_L + \dot{w}_L)^2$$

$$\delta T_3 = m (e \delta \dot{\theta}_L + \delta \dot{w}_L) (\dot{e}\theta_L + \dot{w}_L)$$

$$= m e \delta \dot{\theta}_L (\dot{e}\theta_L + \dot{w}_L) + m \delta \dot{w}_L (\dot{e}\theta_L + \dot{w}_L)$$

Integrating T_3 by parts with respect to time yields

$$\begin{aligned} &= m e (\dot{e}\theta_L + \dot{w}_L) \delta \theta_L \Big|_{t_1}^{t_2} - \int_{t_1}^{t_2} m e (\ddot{e}\theta_L + \ddot{w}_L) \delta \theta_L dt \\ &+ m (\dot{e}\theta_L + \dot{w}_L) \delta w_L \Big|_{t_1}^{t_2} - \int_{t_1}^{t_2} m (\ddot{e}\theta_L + \ddot{w}_L) \delta w_L dt \end{aligned}$$

Combining these 5 results yields

$$EI \frac{\partial^4 W}{\partial x^4} + PA \frac{\partial^2 W}{\partial t^2} = 0$$

$$GJ \frac{\partial^2 \theta}{\partial x^2} - PJ_p \frac{\partial^2 \theta}{\partial t^2} = 0$$

With the 6 boundary conditions

→	$W(0) = 0$	or	$\frac{\partial^3 W}{\partial x^3} \Big _{x=0} = 0$
→	$W'(0) = 0$	or	$\frac{\partial^2 W}{\partial x^2} \Big _{x=0} = 0$
→	$\theta(0) = 0$	or	$\theta'(0) = 0$
→	$\theta(l) = 0$	or	$\frac{\partial \theta}{\partial x} \Big _{x=l} = -m c (c \ddot{\theta} + \ddot{W}) \Big _{x=l}$
→	$W(l) = 0$	or	$\frac{\partial^3 W}{\partial x^3} \Big _{x=l} = +m (c \ddot{\theta} + \ddot{W}) \Big _{x=l}$
→	$W'(l) = 0$	or	$\frac{\partial^2 W}{\partial x^2} \Big _{x=l} = 0$