

Introduction to algorithms

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IFT2125-6001

TA: Maëlle Zimmermann

Demonstration 6

1

Question: Run the Prim algorithm on the following graph:

Solution: By running the algorithm, we get:

1

Iteration (u, v)	B
0	- {1}
1	(1,2) {1,2}
2	(2,3) {1,2,3}
3	(1,4) {1,2,3,4}
4	(4,5) {1,2,3,4,5}
5	(4,7) {1,2,3,4,5,7}
6	(7,6) {1,2,3,4,5,7,6}

Thus the underweight shaft of minimum weight is of weight 17.

2

Question: Show that the Prim algorithm can, like Kruskal's, be implemented using piles. Show that it then takes a time in $\Theta(\log n)$.

Solution: Let us first consider the Prim algorithm naively implemented without monceaux:

```
def Prim (V, E)
    def weight ((u, v, c)): return c
    F = sorted (E, key = weight)
    T = []
    Set B = (V [1])

    # as long as all vertices are not covered
    while len (B) != len (V)
        for (u, v, _) in F:
            if (! u in B) = (v in B)
                break
        T.append ((u, v))
        B.update ([u, v])
    return T
```

In the worst case, this algorithm takes a time in $O(n^2)$ (while execution loop exactly $n-1$ times and path of F in integer which contains a edges). But there is a better implementation. Here is the algorithm of Prim implemented with heaps:

```
def Prim_heap (V, E)
    if len (V) == 0:
        return []
    x = V [0] # current top
```

2

```
T = [] # minimum partial tree
B = Set (V [1]) # summits covered by T
H = [] # empty heap

# build neighbors of vertices
neighbors = [[] for v in V]
for (u, v, c) in E:
```

```

neighbors[u].append((v, c))
neighbors[v].append((u, c))

# calculation of the tree
while len(T) < len(V) - 1:
    # sets all neighbors of x in the heap
    for (y, c) in neighboring[x]:
        heappush(H, (c, (x, y)))

    # remove the edge to the minimum weight c
    (c, (u, v)) = heappop(H)

    # continues to withdraw until the edge passes through B and V \ B
    while (u in B) == (v in B):
        (c, (u, v)) = heappop(H)

    # update x, T and B
    x = u if u not in B else v
    T.append((u, v))
    B.add(x)
return T

```

In a heap, the push and pop operations take a time in $\Theta(\log k)$ and $\Theta(\log k)$ respectively (where k is the number of elements in the pile). Let $n = |V|$ and $a = |E|$, then:

- The loop that builds neighbors is executed a times so takes a long time in $\Theta(a)$.
- Each edge (u, v) is added at most 2 times in the heap either via u or via v . There are thus at most $2a$ push operations which each require a time of $\Theta(\log a)$. So the total time of the additions is in $\Theta(a \log a)$.
- Similarly, there are at most $2a$ pop operations that each require a time of $\Theta(\log a)$. So the total withdrawal time is in $\Theta(a \log a)$.
- The append and add operations are executed as many times as there are iterations of the algorithm, therefore at most $n - 1$ times.

The execution time of the algorithm is thus in $\Theta(a \log a)$, which is also written $\Theta(a \log n)$ for the same reasons as for the Kruskal algorithm.

