#### **Question one**

$$A(x, y, z) = \sum (1, 2, 4, 6)$$

$$B(x, y, z) = \sum (0, 1, 6, 7)$$

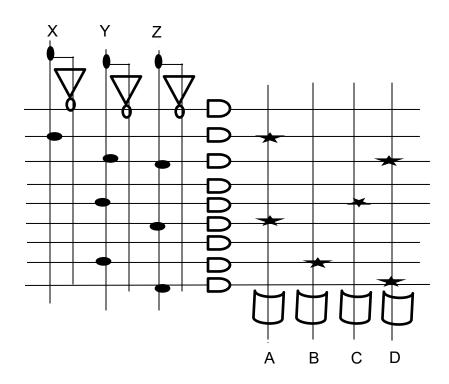
$$C(x, y, z) = \sum (2, 6)$$

A 
$$(x, y, z) = \sum (1, 2, 4, 6)$$
  
B  $(x, y, z) = \sum (0, 1, 6, 7)$   
C  $(x, y, z) = \sum (2, 6)$   
D  $(x, y, z) = \sum (1, 2, 3, 5, 7)$ 

#### Programming table

Products	AND Inputs				Outputs	
terms	X	Y	Z	D		
1	1	-	-	-	w = A + BC + BD	
2	-	1	1	-		
3	-	1	-	1		
4	-	0	1		x = B'C + B'D +	
5	-	0		1	BC'D'	
6	-	1	0	0		
7	-		1	1	y = CD + C'D'	
8	-	-	0	0		
9	-	-	-	-		
10	-	-	-	0	z = D'	
11				-		
12	-	-	-	-		

## Circuit diagram



# **Question Two** a)

<u>u</u> )					
X	Y	Z	A	В	C
0	0	0	0	1	0
0	0	1	0	1	1
0	1	0	1	0	0
0	1	1	1	0	1
1	0	0	0	0	1
1	0	1	0	1	0
1	1	0	0	1	1
1	1	1	1	0	0

b)

x\yz	00	01	11	10
0		1	1	

Υz	1		1

$$C = x' z + x z'$$
  
 $C=x+z$ 

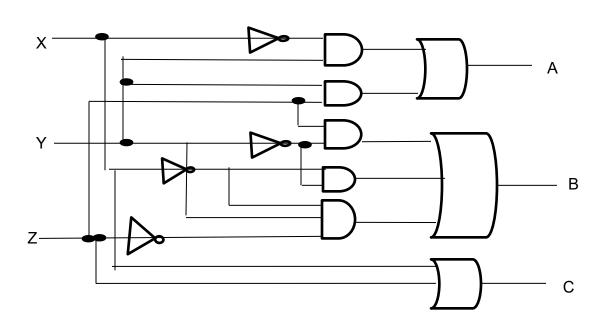
X

x\yz	00	01	11	10
0		1		
1		1		1

$$B = y' z + x' y' + x y z'$$

x\yz	00	01	11	10
0			1	1
1			1	

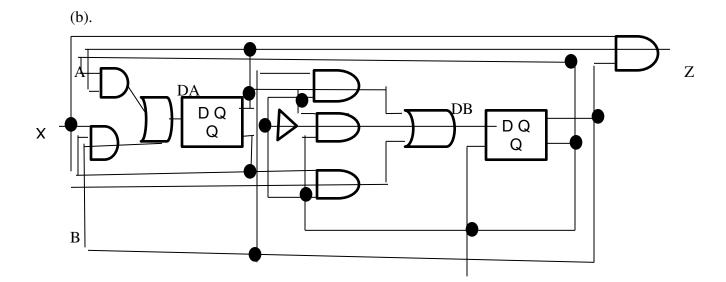
$$A = x' y + y z$$

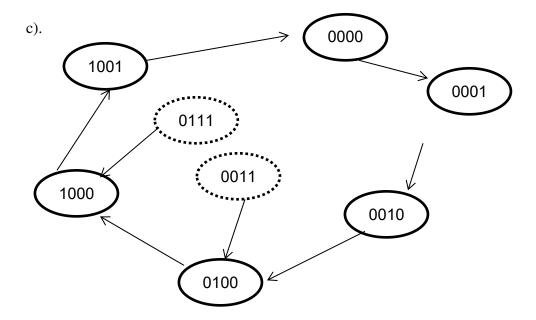


## **Question Three**

(a).

Prese	resent state Next state					Y		
Q4	Q3	Q2	Q1	$D_4=Q_4(t+1)$	$D_3=Q_3(t+1)$	$D_2=Q_2(t+1)$	$D_1 = Q_1(t+1)$	0
0	0	0	0	0	0	0	1	0
0	0	0	1	0	0	1	0	0
0	0	1	0	0	0	1	1	0
0	0	1	1	0	1	0	0	0
0	1	0	0	0	1	0	1	0
0	1	0	1	0	1	1	0	0
0	1	1	0	0	1	1	1	0
0	1	1	1	1	0	0	0	0
1	0	0	0	1	0	0	1	0
1	0	0	1	0	0	0	0	1





d). Yes, it is self-correcting because it is able to transit from invalid state to next valid state after a finite number of transitions