

Coding of bounded solutions of equation
 $u_{xx} - u + \eta(x)u^3 = 0$ with periodic piecewise
constant function $\eta(x)$

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Objective & Motivation

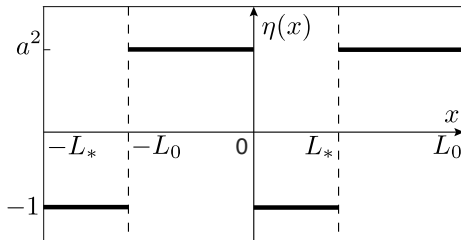
Our objective is an equation

$$u_{xx} - u + \eta(x)u^3 = 0, \quad (1)$$

$\eta(x)$ is a periodic piecewise-constant function of period $L = L_* + L_0$,

$$\eta(x) = \begin{cases} -1, & x \in [0; L_*]; \\ a^2, & x \in [L_*; L_* + L_0], \end{cases}$$

where $a \in \mathbb{R}$.



Our motivation is a GPE equation:

$$i\Psi_t + \Psi_{xx} + P(x)|\Psi|^2\Psi = 0, \quad (2)$$

$P(x) \in \mathbb{R}$ is a periodic function that changes its sign on the period.

Stationary states equation:

$$u_{xx} + \omega u + P(x)u^3 = 0, \quad \omega < 0.$$

We wrote a paper!

CHAOS 26, 073110 (2016)



Stable dipole solitons and soliton complexes in the nonlinear Schrödinger equation with periodically modulated nonlinearity

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Many localised stationary states was found (numerically).

Part I.

Common sense

Phase portraits

\mathcal{P}_* mapping:

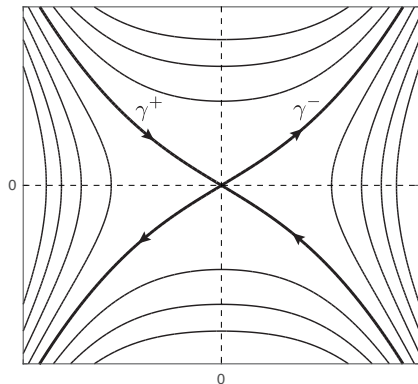


Figure 1: Phase portrait for the equation $u_{xx} - u - u^3 = 0$.

Poincaré map $\mathcal{P}(u_0, u'_0) = (u(L), u'(L))$, $u(x)$ is a solution of (1) with initial conditions (u_0, u'_0) ; $\mathcal{P} = \mathcal{P}_0 \mathcal{P}_*$.

\mathcal{P}_0 mapping:

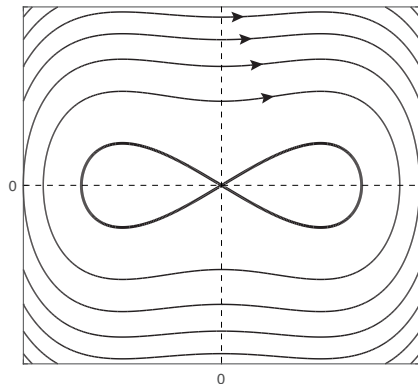


Figure 2: Phase portrait for the equation $u_{xx} - u + u^3 = 0$.

Part II.

Poincaré map

$$\text{dom}(\mathcal{P}_*) = \mathcal{U}_{L_*}^+$$

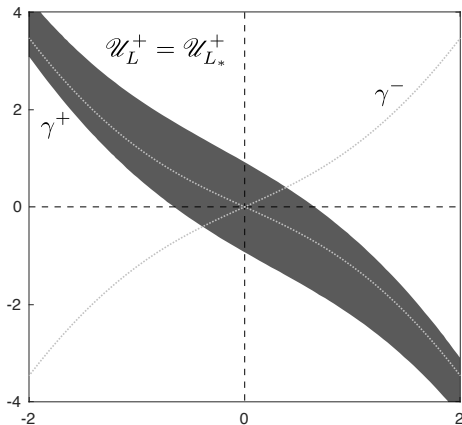


Figure 3: Domain of \mathcal{P} for the parameters $(L_*, L_0, a) = (2, 1, 1)$; γ^\pm are separatrices for the equation $u_{xx} - u - u^3 = 0$.

Theorem 1

$\forall L_*, 0 < L_* < +\infty$, set $\mathcal{U}_{L_*}^+$ is an infinite curvilinear open strip, that

- (a) $\mathcal{U}_{L_*}^+$ is symmetric with respect to the origin and contains γ^+ ;
- (b) $\mathcal{U}_{L_*}^+$ is bounded by two symmetric monotonically decreasing curves (which are C^1 functions);
- (c) vertical dimension of the $\mathcal{U}_{L_*}^+$ tends to zero exponentially when $L_* \rightarrow +\infty$.

$$\begin{aligned} \mathcal{U}_L^+ &\equiv \text{dom}(\mathcal{P}) = \text{dom}(\mathcal{P}_0 \mathcal{P}_*) \\ &= \text{dom}(\mathcal{P}_*) \equiv \mathcal{U}_{L_*}^+. \end{aligned}$$

$$\mathcal{P}_*(\mathcal{U}_L^+) = \mathcal{U}_{L_*}^-$$

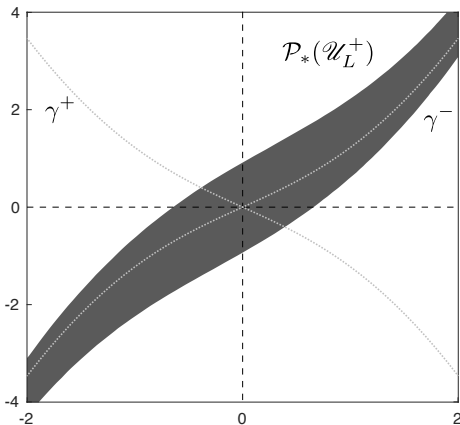


Figure 4: \mathcal{P}_* -image of \mathcal{U}_L^+ for the parameters $(L_*, L_0, a) = (2, 1, 1)$.

Theorem 2

$\forall L_*, 0 < L_* < +\infty$, set $\mathcal{U}_{L_*}^-$ is an infinite curvilinear open strip, that

- (a) $\mathcal{U}_{L_*}^-$ is symmetric with respect to the origin and contains γ^- ;
- (b) $\mathcal{U}_{L_*}^-$ is bounded by two symmetric monotonically increasing curves (which are C^1 functions);
- (c) vertical dimension of the $\mathcal{U}_{L_*}^-$ tends to zero exponentially when $L_* \rightarrow +\infty$.

$$\mathcal{P}_*(\mathcal{U}_L^+) = I\mathcal{U}_L^+,$$

where I is a reflection with respect to the u axis on the phase plane (u, u') .

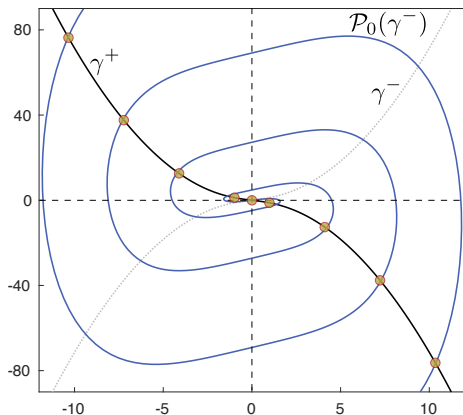


Figure 5: $\mathcal{P}_0(\gamma^-)$ (solid blue line) is an infinite spiral; yellow dots are the points of intersections $\mathcal{P}_0(\gamma^-) \cap \gamma^+$ predicted by the equation (3).

Theorem 3

\mathcal{P}_0 -image of the curve γ^- is an infinite spiral, it intersects γ^+ infinitely many times at the points $\{0\} \cup \{u_{\pm n}\}$, where

$$u_{\pm n} = \pm \frac{2a^{3/2}x_{n-1}}{\sqrt[4]{a^2+1}} L_0^{-1} + O(L_0); \quad (3)$$

$L_0 \rightarrow 0$, and x_n are determined as

$$x_n = cn^{-1} \left(\frac{\sqrt{a}}{\sqrt[4]{a^2+1}}, k \right) + K(k)n,$$

where $k = 1/\sqrt{2}$, $n \in \mathbb{N}$.

Here $K(\cdot)$ is the complete elliptic integral of the 1st kind, cn^{-1} is an inverse elliptic cosine.

$$\mathcal{P}_0(\mathcal{U}_{L_*}^-) = \mathcal{U}_L^-$$

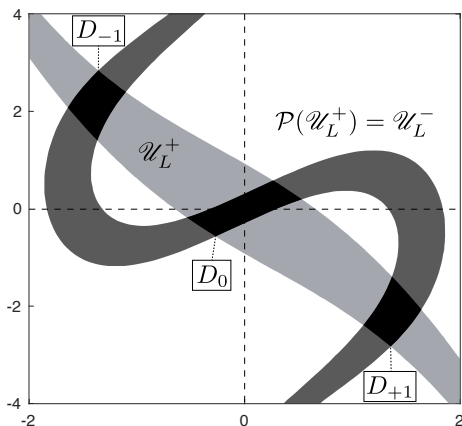


Figure 6: Three components D_{-1} , D_0 , D_{+1} (black) of the set $\mathcal{U}_L = \mathcal{U}_L^+ \cap \mathcal{U}_L^-$.

$$\mathcal{U}_L^- \equiv \text{dom}(\mathcal{P}^{-1}) = \mathcal{P}_0(\mathcal{U}_{L_*}^-) = \mathcal{P}(\mathcal{U}_L^-).$$

- Both \mathcal{P} and \mathcal{P}^{-1} are defined on $\mathcal{U}_L = \mathcal{U}_L^+ \cap \mathcal{U}_L^-$.
- \mathcal{U}_L consists of infinite number of components $\mathcal{U}_L = \bigcup_{i \in S} D_i$.
- Each component except of the central one (D_0) is a curvilinear quadrangle with monotonic borders (*island*).
- D_0 can be made an *island* by varying parameters (L_*, L_0, a) .

$$\mathcal{P}(\mathcal{U}_L) = \bigcup_{i \in S} \mathcal{P}(D_i)$$

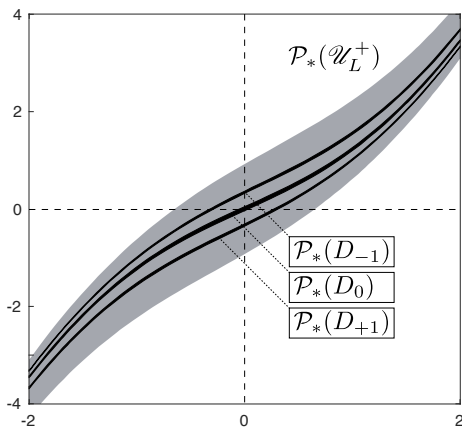


Figure 7: \mathcal{P}_* -image of the components D_{-1} , D_0 , D_{+1} of \mathcal{U}_L .

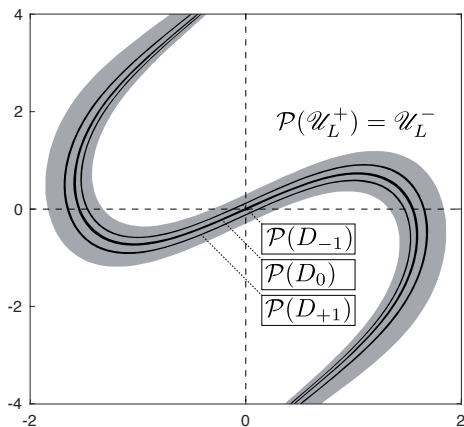


Figure 8: \mathcal{P} -image of the components D_{-1} , D_0 , D_{+1} of \mathcal{U}_L .

$$\bigcup_{i \in S} \mathcal{P}(D_i) \cap \mathcal{U}_L$$

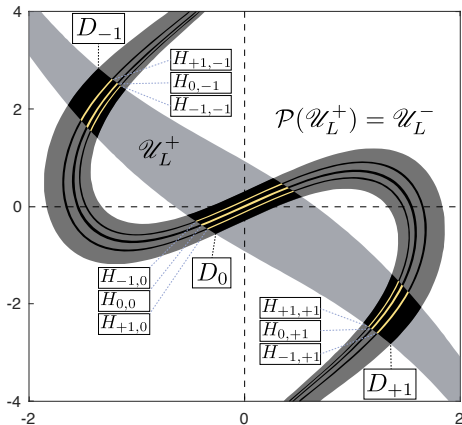


Figure 9: h -strips (yellow) as a result of intersections of $\mathcal{P}(D_i)$ and \mathcal{U}_L sets for the components D_{-1} , D_0 , D_{+1} .

$$\forall i, j, H_{i,j} = \mathcal{P}(D_i) \cap D_j \neq \emptyset.$$

- We call such sets as h -strips.
- Here h -strips consist of points where both \mathcal{P} and \mathcal{P}^{-2} are defined.
- This process can be continued, one can get points of initial condition where higher order of \mathcal{P}^{-k} are defined.
- Continuation of the process results in sets of nested h -strips.

$$\bigcup_{i \in S} \mathcal{P}^{-1}(D_i) \cap \mathcal{U}_L$$

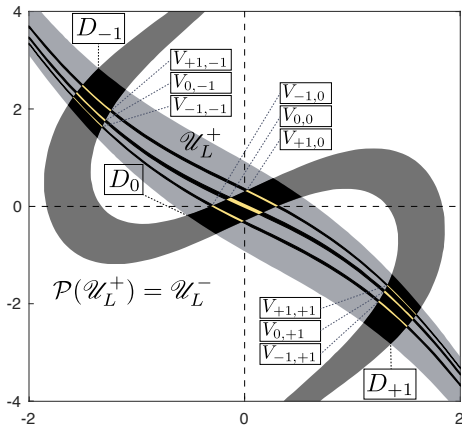


Figure 10: v -strips (yellow) as a result of intersections of $\mathcal{P}^{-1}(D_i)$ and \mathcal{U}_L sets for the components D_{-1} , D_0 , D_{+1} .

$$\forall i, j, V_{i,j} = \mathcal{P}^{-1}(D_i) \cap D_j \neq \emptyset.$$

- We call such sets as v -strips.
- Here v -strips consist of points where both \mathcal{P}^2 and \mathcal{P}^{-1} are defined.
- This process can be continued, one can get points of initial condition where higher order of \mathcal{P}^k are defined.
- Continuation of the process results in sets of nested v -strips.

All together

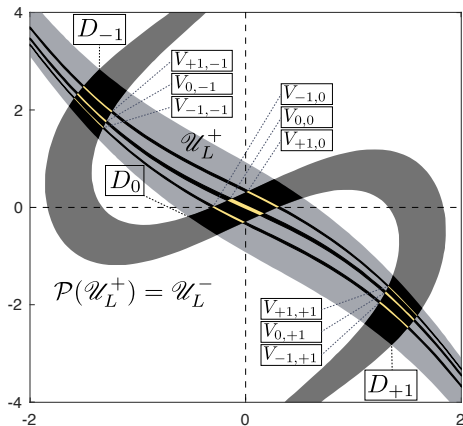


Figure 11: v -strips (yellow) as a result of intersections of $\mathcal{P}^{-1}(D_i)$ and \mathcal{U}_L sets for the components D_{-1} , D_0 , D_{+1} .

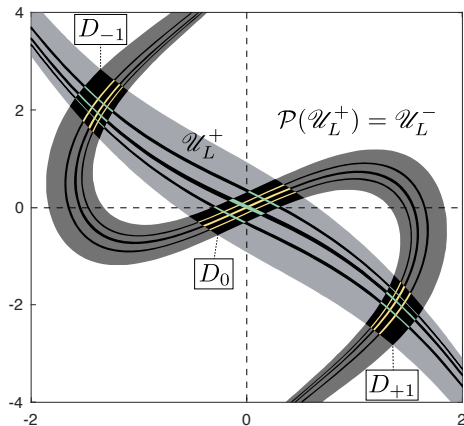


Figure 12: Intersections of h and v -strips (yellow and green) consist of points where both \mathcal{P}^2 and \mathcal{P}^{-2} are defined.

Part III.

Solutions coding

$$\mathcal{O} \rightarrow \mathcal{S}_\infty$$

Orbit is a sequence of points $\{p_n\}$, that

$$\mathcal{P}(p_n) = p_{n+1}.$$

\mathcal{O} – set of orbits of *regular* solution for the equation (1).

\mathcal{S} – set of bi-infinite sequences over the infinite alphabet

$$\{\dots, i_{-1}, i_0, i_1, \dots\},$$

where each symbol corresponds to the connected component $D_i \in \mathcal{U}_L$.

It's easy to assign a *code* to the solution!

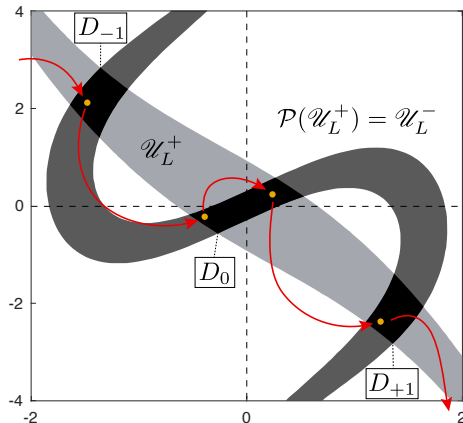


Figure 13: Sketch of an orbit of a *regular* solution (yellow dots) that corresponds to the code sequence $\{\dots, -1, 0, 0, +1, \dots\}$.

Solutions and their codes

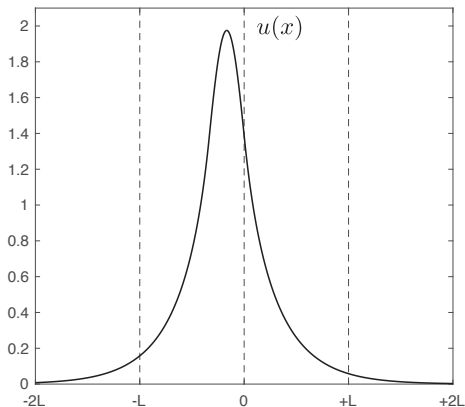


Figure 14: Solution of the code $\{\dots, 0, 0, +1, 0, 0, \dots\}$.

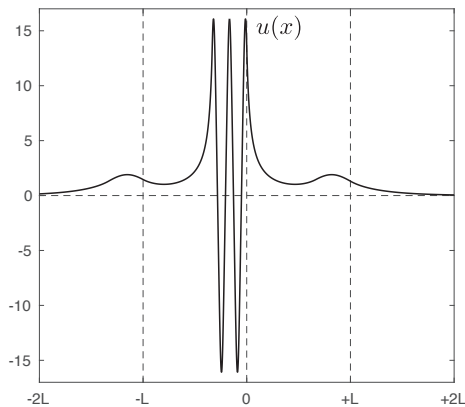


Figure 15: Solution of the code $\{\dots, 0, +1, +3, +1, 0, \dots\}$.

Solutions and their codes

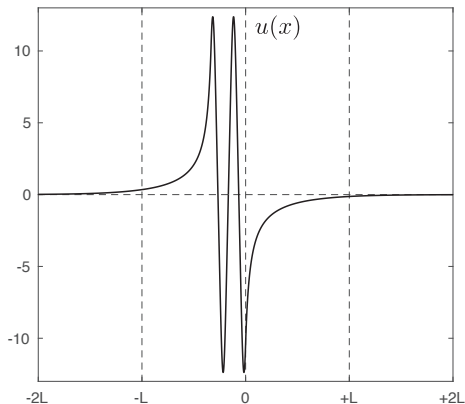


Figure 16: Solution of the code $\{\dots, 0, 0, -3, 0, 0, \dots\}$.

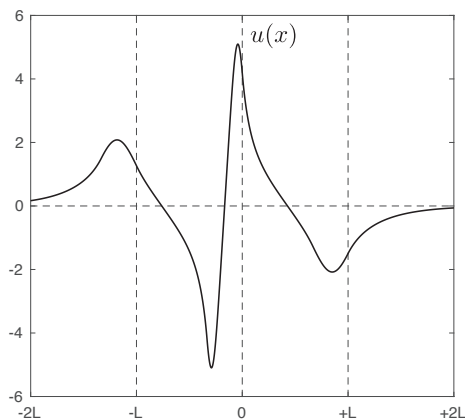


Figure 17: Solution of the code $\{\dots, 0, +1, +2, -1, 0, \dots\}$.

$$\mathcal{S}_\infty \rightarrow \mathcal{O}?$$

By code $\{\dots, i_{-1}, i_0, i_1, \dots\}$ find initial conditions for the equation (1) whose orbit visit components of \mathcal{U}_L in a right order ($X \xrightarrow{\mathcal{P}} Y = \mathcal{P}(X) \cap Y$).

$$D_{i_0} \supseteq H_{i_0} = D_{i_0};$$

$$D_{i_0} \supseteq V_{i_0} = D_{i_0};$$

$$D_{i_0} \supseteq H_{i_{-1}, i_0} = D_{i_{-1}} \xrightarrow{\mathcal{P}} D_{i_0};$$

$$D_{i_0} \supseteq V_{i_1, i_0} = D_{i_1} \xrightarrow{\mathcal{P}^{-1}} D_{i_0};$$

$$D_{i_0} \supseteq H_{i_{-2}, i_{-1}, i_0} = D_{i_{-2}} \xrightarrow{\mathcal{P}} D_{i_{-1}} \xrightarrow{\mathcal{P}} D_{i_0}; \quad D_{i_0} \supseteq V_{i_2, i_1, i_0} = D_{i_2} \xrightarrow{\mathcal{P}^{-1}} D_{i_1} \xrightarrow{\mathcal{P}^{-1}} D_{i_0};$$

.....

.....

Nested h -strips $\{H_n\}$:

Nested v -strips $\{V_n\}$:

$$\dots \subseteq H_{i_{-2}, i_{-1}, i_0} \subseteq H_{i_{-1}, i_0} \subseteq H_{i_0} = D_{i_0}.$$

$$\dots \subseteq V_{i_2, i_1, i_0} \subseteq V_{i_1, i_0} \subseteq V_{i_0} = D_{i_0}$$

$$\{H_n\} \xrightarrow{n \rightarrow \infty} h?$$

$$\{V_n\} \xrightarrow{n \rightarrow \infty} v?$$

Initial conditions in D_{i_0} should belongs to the intersection $h \cap v$.

Part IV.

Uniqueness

What is $h \cap v$?

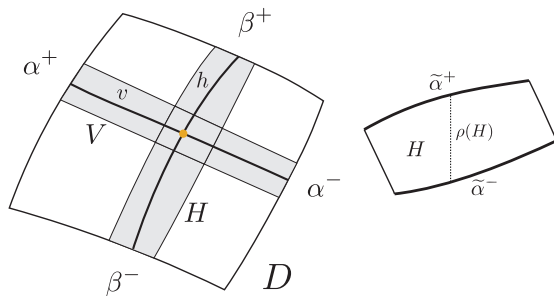
Theorem 4

Let

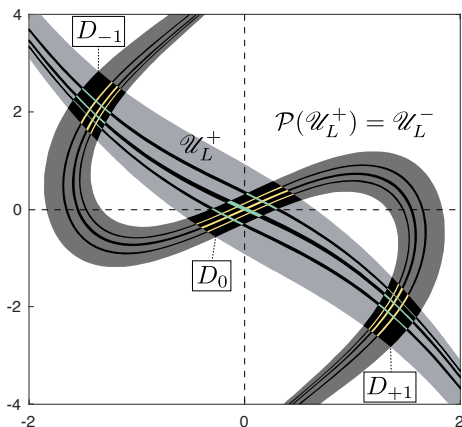
- all $\{H_n\}$ have monotone increasing / decreasing borders which are graphs of γ -Lipschitz functions, and $\rho(H_{n+1}) \leq (1/\mu)\rho(H_n)$, $\mu > 1$;
- all $\{V_n\}$ have monotone decreasing / increasing borders which are graphs of γ -Lipschitz functions, and $\rho(V_{n+1}) \leq (1/\nu)\rho(V_n)$, $\nu > 1$;

then the intersection $h \cap v$ consists of just one point!

Here $\rho(\cdot)$ is a vertical (for H_n) or horizontal (for V_n) width of the strips.



$$D\mathcal{P}_p, D\mathcal{P}_p^{-1}$$



$D\mathcal{P}_p$ – linearisation of the map \mathcal{P} at the point p ; $D\mathcal{P}_p^{-1}$ – its inverse.

If linear operators $D\mathcal{P}_p, D\mathcal{P}_p^{-1}$ satisfy some restrictions then the conditions of the above mentioned theorem are valid!

Figure 18: $H_{i,j}$ (yellow) and $V_{i,j}$ (green) are the points of interest.

Theorem about h -strips mapping

Theorem 5 (About h -strips mapping)

Let Poincaré map \mathcal{P} and its inverse \mathcal{P}^{-1} are defined on an island set $\bigcup_{i \in S} D_i$, where S – set of indices, $\forall i, j \in S$ set $V_{j,i} = \mathcal{P}^{-1}D_j \cap D_i$ is non-empty, \mathcal{P} is defined on the closure $\overline{V_{j,i}}$, and one the following conditions held:

- (1) borders α_i^\pm of an island D_i are increasing curves, $\forall p \in \overline{V_{j,i}}$ signs of the operator $D\mathcal{P}_p = (a_{mn})$ have exactly one of the following configurations:

$$(a) \begin{pmatrix} + & + \\ + & + \end{pmatrix}, \quad (b) \begin{pmatrix} - & - \\ - & - \end{pmatrix}, \quad (c) \begin{pmatrix} + & + \\ - & - \end{pmatrix}, \quad (d) \begin{pmatrix} - & - \\ + & + \end{pmatrix};$$

borders α_j^\pm of D_j are increasing for (a), (b), and decreasing for (c), (d);

- (2) borders α_i^\pm of an island D_i are decreasing curves, $\forall p \in \overline{V_{j,i}}$ signs of the operator $D\mathcal{P}_p = (a_{mn})$ have exactly one of the following configurations:

$$(a) \begin{pmatrix} + & - \\ + & + \end{pmatrix}, \quad (b) \begin{pmatrix} - & + \\ + & - \end{pmatrix}, \quad (c) \begin{pmatrix} + & - \\ + & - \end{pmatrix}, \quad (d) \begin{pmatrix} - & + \\ - & + \end{pmatrix};$$

borders α_j^\pm of D_j are decreasing for (a), (b), and increasing for (c), (d);

and moreover $\exists \mu > 1$ such that $\forall p \in \overline{V_{j,i}}, |a_{11}| \geq \mu$, then for any monotone h -strip $H \in D_i$, $\forall j \in S$, $\mathcal{P}H \cap D_j = \tilde{H}_j$ is also a monotone h -strip, and $\rho(\tilde{H}_j) \leq (1/\mu)\rho(H)$.

Theorem about v -strips mapping

Theorem 6 (About v -strips mapping)

Let Poincaré map \mathcal{P} and its inverse \mathcal{P}^{-1} are defined on an island set $\bigcup_{i \in S} D_i$, where S – set of indices, $\forall i, j \in S$ set $H_{i,j} = \mathcal{P}D_i \cap D_j$ is non-empty, \mathcal{P}^{-1} is defined on the closure $\overline{H_{i,j}}$, and one the following conditions held:

- (1) borders β_i^\pm of an island D_i are increasing curves, $\forall p \in \overline{H_{i,j}}$ signs of the operator $D\mathcal{P}_0^{-1} = (b_{mn})$ have exactly one of the following configurations:

$$(a) \begin{pmatrix} + & + \\ + & + \end{pmatrix}, \quad (b) \begin{pmatrix} - & - \\ - & - \end{pmatrix}, \quad (c) \begin{pmatrix} + & + \\ - & - \end{pmatrix}, \quad (d) \begin{pmatrix} - & - \\ + & + \end{pmatrix};$$

borders β_j^\pm of D_j are increasing for (a), (b), and decreasing for (c), (d);

- (2) borders β_i^\pm of an island D_i are decreasing curves, $\forall p \in \overline{H_{i,j}}$ signs of the operator $D\mathcal{P}_0^{-1} = (b_{mn})$ have exactly one of the following configurations:

$$(a) \begin{pmatrix} + & - \\ + & + \end{pmatrix}, \quad (b) \begin{pmatrix} - & + \\ + & - \end{pmatrix}, \quad (c) \begin{pmatrix} + & - \\ + & - \end{pmatrix}, \quad (d) \begin{pmatrix} - & + \\ - & + \end{pmatrix};$$

borders β_j^\pm of D_j are decreasing for (a), (b), and increasing for (c), (d);

and moreover $\exists \nu > 1$ such that $\forall p \in \overline{H_{i,j}}$, $|b_{22}| \geq \nu$, then for any monotone v -strip $V \in D_j$, $\forall i \in S$, $\mathcal{P}^{-1}V \cap D_i = \tilde{V}_i$ is also a monotone v -nooca, and $\rho(\tilde{V}_i) \leq (1/\nu)\rho(V)$.

Proof in an asymptotic limit

Denote by $\mathcal{S}(b)$, $b \in \mathbb{R}$, a set of solutions for equation (1) such that $|u(x)| < b$ on the whole real axis \mathbb{R} .

Denote by Ω_n the set of bi-infinite sequences $\{\dots, i_{-1}, i_0, i_1, \dots\}$ where i_k , $k = 0, \pm 1, \dots$, is an integer, $-n \leq i_k \leq n$.

Theorem 7

$\forall N$ there exists a pair $(\tilde{L}_, \tilde{L}_0)$ such that for any pair (L_*, L_0) , $L_* > \tilde{L}_*$ and $0 < L_0 < \tilde{L}_0$, there exist a sequence $b_0 < b_1 < \dots < b_N$, and a homeomorphism T such that $T\mathcal{S}(b_n) = \Omega_n$, $n = 0, 1, \dots, N$.*

Thanks for your attention!