## SMOOTH MANIFOLDS

**Definition.** We say that a topological space M is an n-dimensional topological manifold if M is a second-countable, Hausdorff, and locally-Euclidean.

Locally-Euclidean means that every point has an open neighbourhood homeomorphic to an open subset of  $\mathbb{R}^n$ .

A coordinate chart is a pair  $(U, \varphi)$  where  $U \subseteq M$  and  $\widehat{U} \subseteq \mathbb{R}^n$  are open, and  $\varphi: U \to \widehat{U}$  is a homeomorphism.

We want to be able to differentiate maps between manifolds. *Compatibility* ensures that the smoothness of such maps are independent of the choice of charts.

**Definition.** Let M be a topological manifold. Let  $(U, \varphi)$  and  $(V, \psi)$  be charts. We say  $(U, \varphi)$  and  $(V, \psi)$  are *smoothly compatible* if  $\psi \circ \varphi^{-1} : \varphi(U \cap V) \to \psi(U \cap V)$  is a diffeomorphism between Euclidean spaces.

A smooth atlas  $\mathcal{A}$  is a collection of charts covering M such that any two are smoothly compatible. We say that a chart  $(U, \varphi)$  is compatible with  $\mathcal{A}$  if  $(U, \varphi)$  is compatible with every chart in  $\mathcal{A}$ .

A a smooth manifold is a topological manifold equipped with a maximal smooth atlas, which we call a smooth structure.

In practice, it is impossible to explicitly define a smooth structure. However, we can first define a non-maximal atlas, then extend to a maximal one, as the following proposition shows.

**Proposition.** Let M be a topological manifold, and let A be a smooth atlas. Then there exists a unique smooth structure  $\overline{A}$  containing A.

*Proof.* Define  $\overline{\mathcal{A}} := \{(U, \varphi) \mid (U, \varphi) \text{ is compatible with } \mathcal{A}\}$ . Let us show that  $\overline{\mathcal{A}}$  is (i) a smooth atlas, (ii) is maximal, and (iii) is unique.

(i) Let  $(U, \varphi)$  and  $(V, \psi)$  be two charts in  $\overline{\mathcal{A}}$ . Fix  $\varphi(p) \in \varphi(U \cap V)$ , and let  $(W, \theta)$  be a chart in  $\mathcal{A}$  containing p. Observe that the following diagram commutes:

$$\varphi(U\cap V\cap W) \xrightarrow{\varphi} \theta(U\cap V\cap W) \xrightarrow{\psi} \psi(U\cap V\cap W)$$

Therefore,  $\psi \circ \varphi^{-1} = (\varphi \circ \theta^{-1}) \circ (\theta \circ \psi^{-1})$  is smooth on a neighbourhood of  $\varphi(p)$ . Thus,  $\psi \circ \varphi^{-1}$  is smooth because it is smooth on a neighbourhood of every point in its domain. The argument to show smoothness of  $\varphi \circ \psi^{-1}$  is identical.

- (ii) Next, suppose  $\mathcal{B}$  is a smooth atlas such that  $\overline{\mathcal{A}} \subseteq \mathcal{B}$ . Since  $\mathcal{B}$  contains  $\mathcal{A}$ , every chart in  $\mathcal{B}$  is compatible with  $\mathcal{A}$ , so  $\mathcal{B} \subseteq \overline{\mathcal{A}}$ .
- (iii) Suppose  $\mathcal{B}$  is another smooth structure containing  $\mathcal{A}$ . Since every chart in  $\mathcal{B}$  is compatible with  $\mathcal{A}$ , we have  $\mathcal{B} \subseteq \overline{\mathcal{A}}$ , so  $\mathcal{B} = \overline{\mathcal{A}}$  by maximality of  $\mathcal{B}$ .

We can put different smooth structures on the same underlying topological manifold. The following proposition shows how to know if two different smooth atlases generate the same smooth structure.

**Proposition.** Let M be a topological manifold, and let A and B be smooth atlases. Then  $\overline{A} = \overline{B}$  if and only if  $A \cup B$  is a smooth atlas.

*Proof.* Suppose  $A \cup B$  is not a smooth atlas. Then there exists a chart in B not compatible with A, so the definition of  $\overline{A}$  in the previous proposition shows that B is not a subset of  $\overline{A}$ . In particular,  $\overline{B}$  is not a subset of  $\overline{A}$ .

Conversely, suppose  $A \cup B$  is a smooth atlas. Observe that  $\overline{A \cup B}$  is a smooth structure containing A and B. Uniqueness implies  $\overline{A} = \overline{A \cup B} = \overline{B}$ .