

# Introducing the Estimators with Examples

## Lecture Notes

### Overview

- Before diving into statistical theory, we introduce estimators through examples from our prototype models
- Three workhorse methods:
  1. **Maximum Likelihood (MLE)**
  2. **Generalized Method of Moments (GMM)**
  3. **Minimum Distance**

### Extremum Estimators

- All three methods are **extremum estimators**: estimators characterized as solutions to optimization problems
- **Definition**:  $\hat{\theta}$  is an extremum estimator if:

$$\hat{\theta} = \arg \max_{\theta \in \Theta} Q_N(\theta)$$

where  $\Theta \subset \mathbb{R}^p$

- The objective function  $Q_N(\theta)$  differs across methods but the optimization structure is common

### Key Properties to Establish

- For each estimation approach, we want to establish:
  1. **Consistency**: Does  $\hat{\theta} \rightarrow \theta_0$  as  $N \rightarrow \infty$ ?
    - Does our estimate approach the “true” parameters as we collect more data?
  2. **Inference**: What is the sampling distribution of  $\hat{\theta}$ ?
    - How uncertain are we about our estimates?
    - Can we place reasonable bounds on the correct answer?

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## The Generalized Roy Model

### Model Setup

- Selection equation (linear form):

$$D = \mathbf{1}\{\gamma_0 + \gamma_1 X + \gamma_2 Z - V \geq 0\}$$

- Outcome equations:

$$Y_D = \beta_{D,0} + \beta_{D,1}X + U_D$$

- Distributional assumption:  $V \sim \mathcal{N}(0, 1)$

## Two-Step Estimator

- Our identification argument suggested a **two-step** procedure:

### Step 1: Estimate Selection by Maximum Likelihood

- The probit MLE:

$$\hat{\gamma} = \arg \max_{\gamma} \frac{1}{N} \sum_{n=1}^N D_n \log(\Phi(\mathbf{w}_n \gamma)) + (1 - D_n) \log(1 - \Phi(\mathbf{w}_n \gamma))$$

- Where  $\mathbf{w}_n = [1, X_n, Z_n]$
- $\Phi(\cdot)$  is the standard normal CDF

### Step 2: Estimate Outcomes with Selection Correction

- Estimate outcome equations by OLS using a **selection correction** (Heckman correction)
- Uses  $\hat{\gamma}$  from first stage to construct correction term

## Theoretical Challenge

- This is a **two-step estimator**: second stage relies on first-stage estimates
  - We need to develop theory for how first-stage estimation error affects second-stage inference
  - Standard errors must account for the two-step nature
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## The Search Model

### Setup with Measurement Error

- Observe wages with small *known* measurement error:

$$\log(W_{n,t}^o) = \log(W_{n,t}) + \zeta_{n,t}$$

- Where  $\zeta_{n,t} \sim \mathcal{N}(0, \sigma_{\zeta}^2)$  and  $\sigma_{\zeta} = 0.05$
- Parametric assumption:  $W$  is log-normally distributed with mean  $\mu$  and variance  $\sigma_W^2$

### Parameters to Estimate

- Directly estimated:

$$\theta = (\mu, \sigma_W^2, h, \delta, w^*)$$

- Derived parameters:  $\lambda$  and  $b$  (inverted using model structure)
  - $b$  comes from the reservation wage equation

## The Log-Likelihood

- Let  $X_n = (W^o, t_u, E)$  denote the data (observed wage, unemployment duration, employment status)
- Log-likelihood of a single observation:

$$l(X; \theta) = E \times \int f_{W|W>w^*}(\log(W^o) - \zeta) \phi(\zeta; \sigma_\zeta) d\zeta + (1 - E) \times [\log(h) + t_u \log(1 - h)]$$

- The truncated wage density:

$$f_{W|W>w^*}(w) = \frac{\phi(w; \sigma_W)}{1 - \Phi(w^*/\sigma_W)}$$

## The MLE

- Maximum likelihood estimator:

$$\hat{\theta} = \arg \max_{\theta} \frac{1}{N} \sum_n l(X_n; \theta)$$

## Derived Parameter Estimates

- MLE estimate of job arrival rate:

$$\hat{\lambda} = \hat{h} / (1 - \hat{F}_{W|W>w^*}(\hat{w}^*))$$

- MLE estimate of unemployment value:

$$\hat{b} = w^* - \frac{\hat{\lambda}}{1 - \beta(1 - \hat{\delta})} \int_{\hat{w}^*} (1 - \hat{F}_{W|W>w^*}(w)) dw$$

## Theoretical Questions

- Need to characterize asymptotic properties of both:
  - Direct estimates  $\hat{\theta}$
  - Derived estimates  $\hat{b}$  and  $\hat{\lambda}$  (functions of  $\hat{\theta}$ )
- The Delta Method will be key for derived parameters

## Implementation Notes

- When passing data to the likelihood, use **typed data structures** (NamedTuples) rather than DataFrames
  - DataFrames have untyped columns which can dramatically slow optimization
  - Use transformations (logit, exp) to enforce parameter constraints during optimization
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## The Labor Supply Model

### Setup

- Cross-sectional observations:  $(W_n, H_n, C_n, \mathbf{z}_n)$

- Labor supply equation:

$$\log(H) = \mu - \psi \log(W) - \psi \sigma \log(C) + \epsilon$$

- Instruments  $\mathbf{z}_n$  move consumption and labor supply
- Key assumption:  $\mathbb{E}[\epsilon | \mathbf{z}] = 0$

## Moment Conditions

- The exclusion restriction implies:

$$\mathbb{E}[\epsilon \mathbf{z}] = 0$$

- Parameters:  $\theta = (\mu, \sigma, \psi)$

## Sample Moment

- Define the sample moment:

$$g_N(\theta) = \frac{1}{N} \sum_N (\log(H_n) - \mu - \psi \log(W) - \psi \sigma \log(C)) \mathbf{z}_n$$

## The GMM Estimator

- GMM minimizes a quadratic form in the moments:

$$\hat{\theta} = \arg \min_{\theta} g_N(\theta)' \mathbf{W}_N g_N(\theta)$$

- $\mathbf{W}_N$  is a symmetric, positive definite **weighting matrix**
- Since system is linear, this is a quadratic minimization with known closed-form solution
- But the theory we develop will be more general (nonlinear GMM)

## Key Questions for GMM

1. What choice of  $\mathbf{W}$  gives the “best” estimator?
  - Need to define what “best” means (efficient GMM)
2. Can we implement optimal weighting in finite samples?
  - Feasible efficient GMM

## The Savings Model

### Focus: Income Process Estimation

- Save preference parameter estimation for simulation chapter
- Identification insight: match implied variances and covariances
- When moments outnumber parameters: **over-identification**
- Estimate by **minimum distance**

## The Income Process

- AR(1) transitory component:

$$\varepsilon_{n,t+1} = \rho \varepsilon_{n,t} + \eta_{n,t}, \quad \eta_{n,t} \sim \mathcal{N}(0, \sigma_\eta^2)$$

- Extended specification with permanent heterogeneity:

$$\log(y_{n,t}) = \mu_t + \alpha_n + \varepsilon_{n,t}$$

- Where  $\alpha_n \sim (0, \sigma_\alpha^2)$  is an individual fixed effect
- Initial condition:  $\varepsilon_0 = 0$

## Implied Dynamics

- With  $\varepsilon_0 = 0$ :

$$\varepsilon_t = \sum_{s=1}^t \rho^{t-s} \eta_s$$

- Parameters to estimate:  $\theta = (\rho, \sigma_\alpha^2, \sigma_\eta^2)$

## Moment Restrictions

- Define  $\epsilon = \log(y) - \mu_t = \alpha + \varepsilon$
- Variance at age  $t$ :

$$\mathbb{V}[\epsilon_t] = \sigma_\alpha^2 + \frac{(1 - \rho^{2(t-1)})}{1 - \rho^2} \sigma_\eta^2$$

- Recursive variance relationship:

$$\mathbb{V}[\epsilon_{t+1}] = \sigma_\alpha^2 + \rho^2 \mathbb{V}[\epsilon_t] + \sigma_\eta^2$$

- Autocovariance:

$$\mathbb{C}(\epsilon_t, \epsilon_{t+s}) = \sigma_\alpha^2 + \rho^s \mathbb{V}[\epsilon_t]$$

## Two Alternative Moment Vectors

### Option 1: Variance Profile

$$\mathbf{v} = [\mathbb{V}[\epsilon_1], \mathbb{V}[\epsilon_2], \dots, \mathbb{V}[\epsilon_T]]'$$

### Option 2: Variances and Covariances

$$\mathbf{c} = [\mathbb{V}[\epsilon_t], \mathbb{V}[\epsilon_{t+1}], \mathbb{C}(\epsilon_t, \epsilon_{t+1}), \dots, \mathbb{C}(\epsilon_t, \epsilon_{t+K})]'$$

## The Minimum Distance Estimator

- Let  $\mathbf{v}(\theta)$  be model-implied moments
- Let  $\hat{\mathbf{v}}$  be sample estimates
- Minimum distance estimator:

$$\hat{\theta} = \arg \min_{\theta} (\hat{\mathbf{v}} - \mathbf{v}(\theta))' \mathbf{W} (\hat{\mathbf{v}} - \mathbf{v}(\theta))$$

- $\mathbf{W}$  is a positive definite weighting matrix

## Key Question

- How does choice of  $\mathbf{W}$  affect precision?
- Is there an “optimal” choice? (Same question as GMM)

### STOP FOR DISCUSSION

We identify income risk parameters by matching variance growth with age—attributing all growth to income risk.

- Are you comfortable with this identification strategy?
- Suppose we use this model to evaluate welfare gains from redistributive taxes. How important will these parameters be for how agents value social insurance?
- What other sources could explain variance growth with age?

## The Entry-Exit Model

### Key Insight

- Choice probability  $p(x, a, a')$  is directly observable in the data
- Encodes information about underlying payoff parameters

### Payoff Specification

- Payoff from operating ( $d = 1$ ):

$$u_1(x, a, d') = \phi_0 + \phi_1 x - \phi_2 d' - \phi_3(1 - a)$$

- Payoff from not operating ( $d = 0$ ):

$$u_0(x, a) = \phi_4 a$$

- Parameters:  $\phi = (\phi_0, \phi_1, \phi_2, \phi_3, \phi_4)$

### Estimation Approach 1: Minimum Distance

#### Model-Implied Choice Probabilities

- For each state  $(x, a, a')$ , the model implies:

$$p(x, a, a'; \phi, \beta) = \frac{\exp(v_1(x, a, a'; \phi, \beta))}{\exp(v_0(x, a, a'; \phi, \beta)) + \exp(v_1(x, a, a'; \phi, \beta))}$$

- Where  $v_0$  and  $v_1$  are choice-specific value functions (depend on equilibrium solution)

### Data Structure

- Cross-section:  $(X_m, D_m, A_m, A'_m)_{m=1}^M$  for  $M$  markets
- $X$  takes discrete values in support  $\mathcal{X}$

### Empirical Choice Frequencies

- For each state  $(x, a, a')$ :

$$\hat{p}(x, a, a') = \frac{\sum_m D_m \mathbf{1}\{X_m = x, A_m = a, A'_m = a'\}}{\sum_m \mathbf{1}\{X_m = x, A_m = a, A'_m = a'\}}$$

## The Estimator

- Stack probabilities:  $\mathbf{p}(\theta)$  model-implied,  $\hat{\mathbf{p}}$  empirical
- Minimum distance estimator:

$$\hat{\theta} = \arg \min_{\theta} (\hat{\mathbf{p}} - \mathbf{p}(\theta))' \mathbf{W}_N (\hat{\mathbf{p}} - \mathbf{p}(\theta))$$

## Estimation Approach 2: GMM

### The Residual

- Define:

$$\xi_m = D_m - p(X_m, A_m, A'_m; \phi, \beta)$$

- Key property:  $\mathbb{E}[\xi_m | X_m, A_m, A'_m] = 0$  at true parameters

### Moment Conditions

- This implies:

$$\mathbb{E}[(D_m - p(X_m, A_m, A'_m; \phi, \beta)) \cdot \mathbf{z}_m] = 0$$

- Natural instrument choices—functions of the state:

$$\mathbf{z}_m = [1, X_m, A_m, A'_m, X_m \cdot A_m]'$$

### The GMM Estimator

- Sample moment:

$$g_M(\phi) = \frac{1}{M} \sum_m (D_m - p(X_m, A_m, A'_m; \phi, \beta)) \mathbf{z}_m$$

- GMM estimator:

$$\hat{\phi} = \arg \min_{\phi} g_M(\phi)' \mathbf{W}_M g_M(\phi)$$

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## Summary

| Model           | Estimation Method | Key Features   |
|-----------------|-------------------|--|
| Generalized Roy | Two-step MLE      | Selection correction; two-stage inference            |
| Search          | MLE               | Measurement error integration; derived parameters    |
| Labor Supply    | GMM               | Instrumental variables; weighting matrix choice      |
| Savings         | Minimum Distance  | Variance matching; over-identification               |
| Entry-Exit      | MD or GMM         | Equilibrium constraints; choice probability matching |

## Common Themes

- All are **extremum estimators**: optimize an objective function
- All require theory for:
  - **Consistency**:  $\hat{\theta} \rightarrow \theta_0$
  - **Asymptotic distribution**:  $\sqrt{N}(\hat{\theta} - \theta_0) \rightarrow ?$
- Several involve a **weighting matrix  $\mathbf{W}$** —optimal choice matters
- Some have **multi-step** or **derived parameter** complications