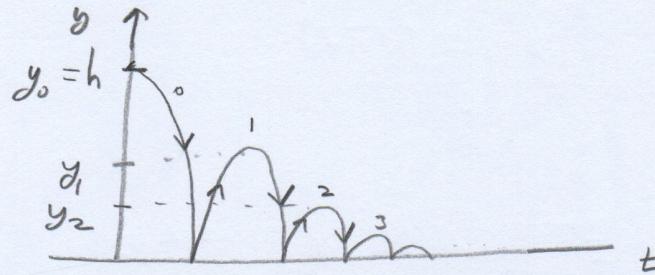


Exercise (5,1)

Inelastic collision of a ball with floor

(1)



$$\eta^2 = \frac{K_{final}}{K_{initial}}$$

$$K_{initial} = \frac{1}{2} m v_0^2 = mg h$$

$$v_0^2 = 2gh$$

$$v_0 = \sqrt{2gh}$$

$$K_{final} = \eta^2 K_{initial}$$

$$= \eta^2 mgh$$

$$= \eta^2 mg y_0$$

$$= mg y_1$$

$$\text{Thus, } y_1 = \eta^2 y_0 = \eta^2 h$$

$$y_2 = \eta^2 y_1 = \eta^4 h$$

$$y_3 = \eta^6 h$$

$$\dots y_N = \eta^N h$$

$$\text{Time} = T_0 + T_1 + T_2 + \dots$$

$$\text{or } h = \frac{1}{2} g T_0^2 \rightarrow T_0 = \sqrt{\frac{2h}{g}}$$

~~T₀~~

$$\therefore \eta^2 h = \frac{1}{2} g \alpha t^2 \rightarrow T_1 = 2 \cdot \alpha t = 2 \sqrt{\frac{2h}{g}}$$

(2)

 T^{h+1} ,

$$\begin{aligned}
 T &= \sqrt{\frac{2h}{g}} \left(1 + 2\gamma + 2\gamma^2 + \dots \right) \\
 &= \sqrt{\frac{2h}{g}} \left[\left(1 + \gamma + \gamma^2 + \gamma^3 + \dots \right) + \left(\gamma + \gamma^2 + \gamma^3 + \dots \right) \right] \\
 &= \sqrt{\frac{2h}{g}} \left[\left(\frac{1}{1-\gamma} \right) + \left(\frac{\gamma}{1-\gamma} \right) \right] \\
 &= \sqrt{\frac{2h}{g}} \left(\frac{1+\gamma}{1-\gamma} \right)
 \end{aligned}
 \quad \left. \begin{array}{l}
 1 + \gamma + \gamma^2 + \dots \\
 = \left(\frac{1}{1-\gamma} \right) - 1 \\
 = \frac{1 - (1-\gamma)}{1-\gamma} \\
 \cancel{\text{WAA}}
 \\ = \frac{1}{1-\gamma}
 \end{array} \right\}$$

Limiting cases:

$$\underline{\gamma = 0:} \quad T = \sqrt{\frac{2h}{g}} \quad \left(\text{time to fall from } y=h \text{ to } y=0 \right)$$

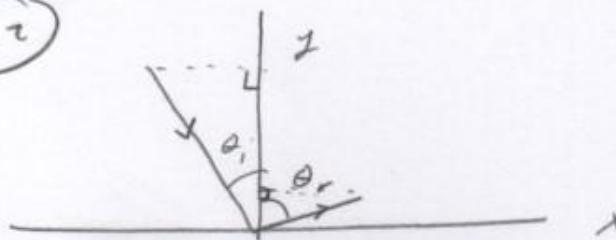
$$\underline{\gamma = 1:} \quad T = \infty \quad \left(\text{ball bounces forever} \right)$$

$$\underline{z \left(\frac{1}{1-\gamma} \right) - 1} = \frac{1}{1-\gamma} (z - (1-\gamma)) \\
 = \frac{1+\gamma}{1-\gamma}$$

Angle of incidence vs. angle of reflection for inelastic collisions

Exercise

(5.2)



$$p_{x, \text{final}} = p_{x, \text{init}}$$

$$p_{y, \text{final}} = \sqrt{\gamma} p_{y, \text{init}}$$

$$\checkmark \quad \text{Thus, } v_{x, \text{final}} = v_{x, \text{init}} = v_x$$

$$v_{y, \text{final}} = \sqrt{\gamma} v_{y, \text{init}}$$

$$v_f^2 = v_{xf}^2 + v_{yf}^2 = v_x^2 + v_{yf}^2 = v_x^2 + \gamma^2 v_{yi}^2$$

$$v_i^2 = v_{xi}^2 + v_{yi}^2 = v_x^2 + v_{yi}^2$$

$$\tan \theta_i = \frac{v_{xi}}{v_{yi}} = \frac{v_x}{v_{yi}}$$

$$\tan \theta_r = \frac{v_{xf}}{v_{yf}} = \frac{v_x}{v_{yf}} = \frac{v_x}{\sqrt{\gamma} v_{yi}} = \frac{1}{\sqrt{\gamma}} \tan \theta_i$$

$$\checkmark \quad \boxed{\tan \theta_r = \frac{1}{\sqrt{\gamma}} \tan \theta_i}$$

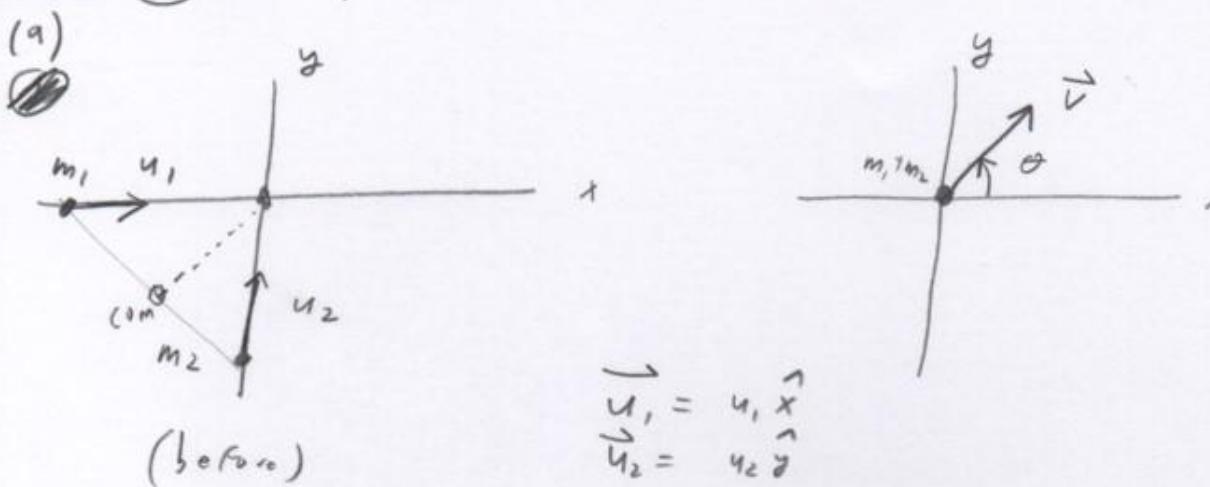
K!

$$\underline{\gamma = 1}: \quad \tan \theta_r = \tan \theta_i \rightarrow \theta_r = \theta_i$$

$$\underline{\gamma = 0}: \quad \tan \theta_r = \infty \tan \theta_i \rightarrow \theta_r = \frac{\pi}{2}$$



Exercise 5.3 Perfectly inelastic collision in different ref frames ①



$$\vec{u}_1 = u_1 \hat{x}$$

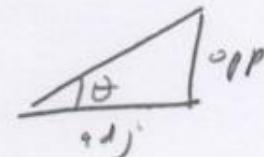
$$\vec{u}_2 = u_2 \hat{y}$$

$$\vec{p}_i = \vec{p}_f \quad \text{conservation of momentum}$$

$$m_1 u_1 \hat{x} + m_2 u_2 \hat{y} = (m_1 + m_2) \vec{v} = M \vec{v}$$

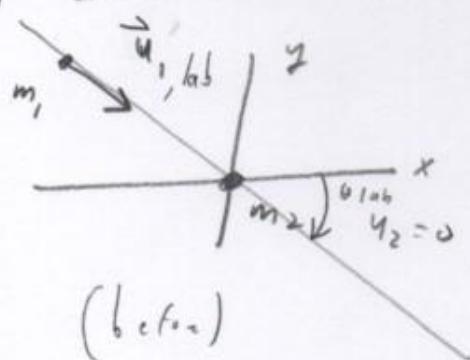
$$\text{Thus, } \vec{v} = \left(\frac{m_1}{M} u_1 \right) \hat{x} + \left(\frac{m_2}{M} u_2 \right) \hat{y}$$

$$\text{Speed: } v = \sqrt{\frac{m_1^2 u_1^2 + m_2^2 u_2^2}{M}}$$



$$\tan \theta = \frac{\left(\frac{m_2 u_2}{M} \right)}{\left(\frac{m_1 u_1}{M} \right)} = \frac{m_2 u_2}{m_1 u_1}$$

(b) Lab frame / m₂ at rest; subtract u₂ \hat{y} from all velocities



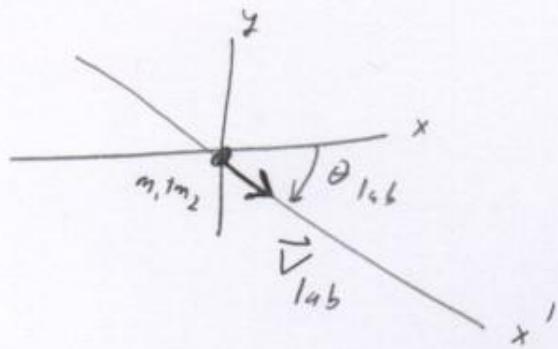
$$\vec{u}_{1, \text{lab}} = u_1 \hat{x} - u_2 \hat{y}, \quad \vec{u}_{2, \text{lab}} = 0$$

$$\vec{p}_{1, \text{lab}, i} = m_1 \vec{u}_{1, \text{lab}}$$

$$\vec{p}_{1, \text{lab}, f} = (m_1 + m_2) \vec{v}_{1, \text{lab}}$$

$$\text{Thus, } \vec{v}_{1, \text{lab}} = \left(\frac{m_1}{M} \right) \vec{u}_{1, \text{lab}} = \left(\frac{m_1}{M} \right) [u_1 \hat{x} - u_2 \hat{y}]$$

Aflos.:



$$\text{Speed: } V_{1,1b} = \frac{m_1}{M} \sqrt{u_1^2 + u_2^2}$$

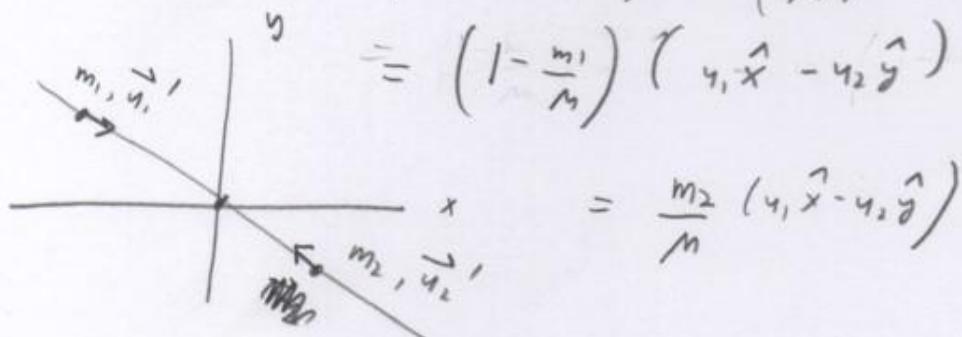
$$\text{Direction: } \tan \theta_{1,1b} = -\frac{u_2}{u_1} \quad (< 0)$$

(c) Barycenter frame ((sum at origin))

\rightarrow combined $m_{1,2}$ at rest at origin after collision

Thus, ~~not~~ subtract $\vec{V}_{1,1b}$ from $\vec{u}_{1,1b}$, $\vec{u}_{2,1b}$
to go to barycenter frame

$$\begin{aligned}\vec{u}_1' &= \vec{u}_{1,1b} - \vec{V}_{1,1b} \\ &= (u_1 \hat{x} - u_2 \hat{y}) - \left(\frac{m_1}{M}\right)[u_1 \hat{x} - u_2 \hat{y}] \\ &= \left(1 - \frac{m_1}{M}\right)(u_1 \hat{x} - u_2 \hat{y})\end{aligned}$$

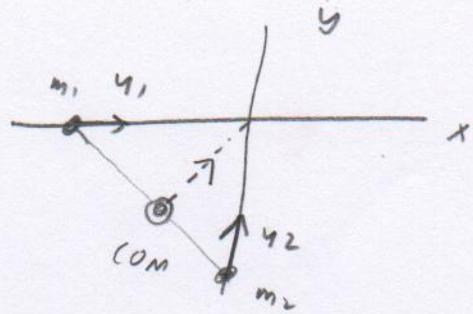


$$\vec{u}_2' = \vec{u}_{2,1b} - \vec{V}_{1,1b} = -\frac{m_1}{M}(u_1 \hat{x} - u_2 \hat{y})$$

Original frame:

$$\vec{u}_1 = u_1 \hat{x}$$

$$\vec{u}_2 = u_2 \hat{y}$$



(3)

Calculate $\vec{u}_1 - \vec{v}$, $\vec{u}_2 - \vec{v}$:

$$\begin{aligned}\vec{u}_1 - \vec{v} &= \cancel{u_1 \hat{x}} - \left(\left(\frac{m_1 u_1}{M} \right) \hat{x} + \left(\frac{m_2 u_2}{M} \right) \hat{y} \right) \\ &= \left(1 - \frac{m_1}{M} \right) u_1 \hat{x} - \frac{m_2 u_2}{M} \hat{y} \\ &= \frac{m_2}{M} \left(u_1 \hat{x} - u_2 \hat{y} \right) \\ &= \vec{u}_1'\end{aligned}$$

$$\begin{aligned}\vec{u}_2 - \vec{v} &= u_2 \hat{y} - \left(\left(\frac{m_1 u_1}{M} \right) \hat{x} + \left(\frac{m_2 u_2}{M} \right) \hat{y} \right) \\ &= -\frac{m_1 u_1}{M} \hat{x} + \underbrace{\left(1 - \frac{m_2}{M} \right) u_2 \hat{y}}_{\frac{m_1}{M}} \\ &= -\frac{m_1}{M} \left(u_1 \hat{x} - u_2 \hat{y} \right)\end{aligned}$$

$$= \vec{u}_2'$$

Thus, $\boxed{\vec{u}_1 - \vec{v} = \vec{u}_1', \quad \vec{u}_2 - \vec{v} = \vec{u}_2'}$

(So barycentre frame is moving with velocity \vec{v})
w.r.t original frame

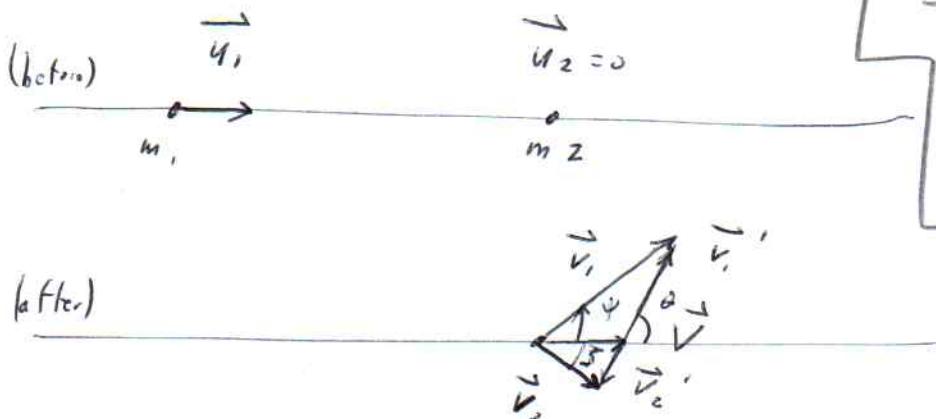
Rel., lab and bary center frames

①

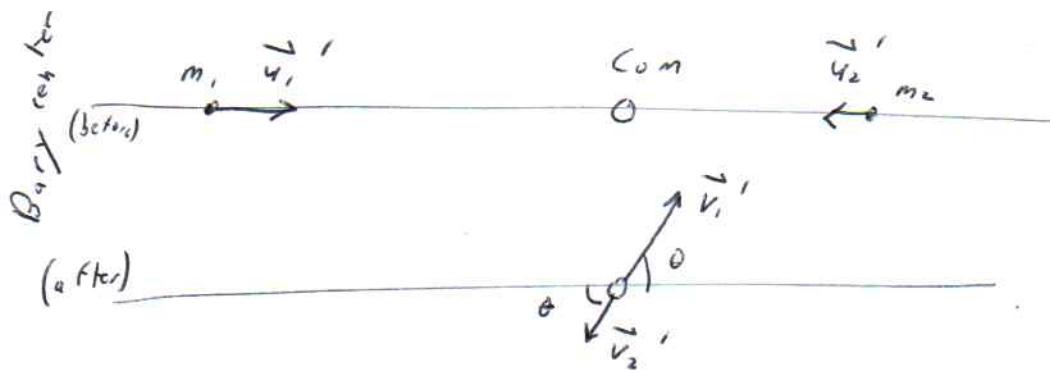
EXAMPLE
5.1

Exercise
5.4

L6



$$\begin{aligned} \vec{v}_1 &= \vec{v} + \vec{v}_1' \\ \vec{v}_2 &= \vec{v} + \vec{v}_2' \end{aligned} \quad \text{primed denotes w.t barycenter frame}$$



Barycenter Frame

$$C \cdot M = 0 \rightarrow m_1 \vec{u}_1' + m_2 \vec{u}_2' = \vec{0}$$

$$m_1 \vec{u}_1' = m_2 \vec{u}_2' \quad \text{where} \quad \vec{u}_1' = \frac{1}{2} \vec{v}_1' \\ \text{Also} \quad m_1 \vec{v}_1' = m_2 \vec{v}_2'$$

$$\vec{u}_2' = \frac{1}{2} \vec{v}_2'$$

$$E_{\text{lab}} : \frac{1}{2} m_1 \vec{u}_1'^2 + \frac{1}{2} m_2 \vec{u}_2'^2 = \frac{1}{2} m_1 \vec{v}_1'^2 + \frac{1}{2} m_2 \vec{v}_2'^2$$

$$\cancel{\frac{1}{2} m_1 (\vec{u}_1'^2 - \vec{v}_1'^2)} = \cancel{\frac{1}{2} m_2 (\vec{v}_2'^2 - \vec{u}_2'^2)}$$

$$m_1 (\vec{u}_1' - \vec{v}_1') (\vec{u}_1' + \vec{v}_1') = m_2 (\vec{v}_2' - \vec{u}_2') (\vec{v}_2' + \vec{u}_2')$$

$$(\vec{u}_1' - \vec{v}_1') (m_1 \vec{u}_1' + m_1 \vec{v}_1') = (\vec{v}_2' - \vec{u}_2') (m_2 \vec{v}_2' + m_2 \vec{u}_2')$$

$$\boxed{m_1 \vec{v}_1' + m_2 \vec{u}_2'} = \boxed{m_1 \vec{u}_1' + m_2 \vec{v}_2'}$$

$$\therefore \vec{u}_1' - \vec{v}_1' = \vec{v}_2' - \vec{u}_2'$$

(2)

$$u_1' - v_1' = v_2' - u_2'$$

$$u_1' - v_1' = \frac{m_1}{m_2} v_1' - \frac{m_1}{m_2} u_1'$$

$$\left(1 + \frac{m_1}{m_2}\right) u_1' = \left(1 + \frac{m_1}{m_2}\right) v_1'$$

$$\rightarrow \boxed{u_1' = v_1'}$$

Similarly: $\boxed{u_2' = v_2'}$

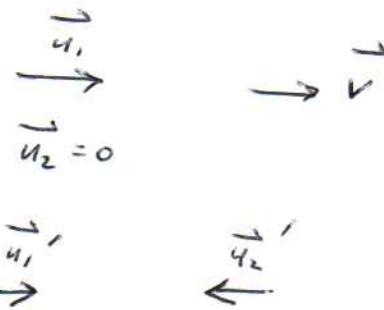
com velocity \vec{V} :

$$(m_1 + m_2) \vec{V} = m_1 \vec{u}_1 + m_2 \vec{u}_2$$

$$\vec{V} = \frac{m_1}{M} \vec{u}_1, \text{ where } M = m_1 + m_2$$

Body centre quantities,

$$\begin{aligned} \vec{u}_1' &= \vec{u}_1 - \vec{V} \\ \vec{u}_2' &= \vec{u}_2 - \vec{V} = -\vec{V} \\ \vec{v}_1' &= \vec{v}_1 - \vec{V} \\ \vec{v}_2' &= \vec{v}_2 - \vec{V} \end{aligned}$$



In terms of magnitudes:

$$\begin{aligned} u_1' &= u_1 - V = u_1 - \frac{m_1}{M} u_1 = u_1 \left(1 - \frac{m_1}{M}\right) = u_1 \frac{m_2}{M} = (v_1') \\ \cancel{u_2'} &= +V = \frac{+m_1 u_1}{M} (= v_2') \end{aligned}$$

Components of \vec{v}_1 , \vec{v}_2 in lab frame:

$$\begin{aligned} v_{1x} &= v_1 \cos \psi = v_{1x}' + V = v_{1x}' \cos \theta + \frac{m_1 u_1}{M} \\ &= v_1 \frac{m_2 \cos \theta}{M} + \frac{m_1 u_1}{M} \\ &= \frac{u_1}{M} (m_2 \cos \theta + m_1) \end{aligned}$$

$$V_{1,y} = V_1 \sin \theta = V_{1y}' = V_1' \sin \theta = u_1 \frac{m_2 \sin \theta}{M}$$

$$\begin{aligned} \text{Therefore, } V_1 &= \sqrt{V_{1x}^2 + V_{1y}^2} \\ &= \frac{u_1}{M} \sqrt{(m_2 \cos \theta + m_1)^2 + (m_2 \sin \theta)^2} \\ &= \frac{u_1}{M} \sqrt{m_2^2 \cos^2 \theta + m_1^2 + 2m_1 m_2 \cos \theta + m_2^2 \sin^2 \theta} \\ &= \frac{u_1}{M} \sqrt{m_1^2 + m_2^2 + 2m_1 m_2 \cos \theta} \end{aligned}$$

$$\begin{aligned} \text{so } \cos \psi &= \frac{\cancel{V_{1y}}}{\cancel{V_1}} = \frac{V_{1x}}{V_1} \\ &= \frac{\cancel{u_1} (m_2 \cos \theta + m_1)}{\cancel{M} \sqrt{m_1^2 + m_2^2 + 2m_1 m_2 \cos \theta}} \\ &= \frac{m_2 \cos \theta + m_1}{\sqrt{m_1^2 + m_2^2 + 2m_1 m_2 \cos \theta}} \end{aligned}$$

Result for target position:

$$\cos \theta \cos \pi - \sin \theta \sin \pi$$

$$\begin{aligned} V_{2x} &= V_2 \cos \beta = V_{2x}' + V \\ &= V_2' \cos (\theta + \pi) + m_1 \frac{u_1}{M} \\ &= -V_2' \cos \theta + m_1 \frac{u_1}{M} \\ &= -\frac{m_1 u_1}{M} \cos \theta + m_1 \frac{u_1}{M} \\ &= \frac{m_1 u_1}{M} (1 - \cos \theta) \end{aligned}$$

$$V_{2y} = V_2 \sin \theta = V_2' \sin \theta$$

$$= V_2' \sin(\theta + \pi) \text{ m}$$

$$= - u_1 \frac{m_1}{M} \sin \theta$$

$$\begin{aligned} & s_{12}(\theta + \pi) \\ &= \sin \theta \cos \pi + \cos \theta \sin \pi \\ &= -\sin \theta \end{aligned} \quad (4)$$

$$\begin{aligned} \Gamma^{\text{loss}}_2, V_2 &= \sqrt{V_{2x}^2 + V_{2y}^2} \\ &= \frac{u_1 m_1}{M} \sqrt{(1 - \cos \theta)^2 + \sin^2 \theta} \\ &= \frac{u_1 m_1}{M} \sqrt{1 + \cos^2 \theta + \sin^2 \theta - 2 \cos \theta} \\ &= \frac{u_1 m_1}{M} \cancel{\sqrt{2(1 - \cos \theta)}} \end{aligned}$$

→

$$\cos \delta = \frac{V_{2x}}{V_2}$$

$$= \frac{\cancel{m_1 u_1} (1 - \cos \theta)}{\cancel{u_1 M} \sqrt{2(1 - \cos \theta)}}$$

$$= \sqrt{\frac{1 - \cos \theta}{2}}$$

$$\begin{aligned} P_1 &\cancel{\text{mass}} = \frac{m_1 u_1}{M} = \frac{m_1}{m_2} \\ P_2 &= \frac{\frac{m_1 u_1}{M}}{\frac{m_1 u_1}{M}} \end{aligned}$$

$$\begin{aligned} & \cos(2\pi - \delta) \\ &= \cos 2\pi \cos \delta + \sin 2\pi \sin \delta \\ &= \cos \delta \end{aligned}$$

Thus, for elastic scattering

$$\cos \psi = \frac{m_2 \cos \theta + m_1}{\sqrt{m_1^2 + m_2^2 + 2 m_1 m_2 \cos \theta}}$$

$$\cos \delta = \sqrt{\frac{1 - \cos \theta}{2}} = \sin \left(\frac{\theta}{2} \right)$$

$$\cos 2\theta = \cos^2 \theta - \sin^2 \theta$$

$$\cancel{= 1 - 2 \sin^2 \theta}$$

$$\sin^2 \theta = \frac{1 - \cos 2\theta}{2}$$

$$\sin \theta = \sqrt{\frac{1 - \cos 2\theta}{2}}$$

$$\cos \delta = \cos \left(\frac{\theta}{2} \right)$$

$$\cos \left(\frac{\theta}{2} - \frac{\theta}{2} \right) = \cos \frac{\pi}{2} \cos \frac{\theta}{2} + \sin \frac{\pi}{2} \sin \frac{\theta}{2} \checkmark$$

Exercise 5.5) Show that for equal-mass elastic scattering $|H\psi| = \pi_2$



Elastic scattering:

$$\cos \psi = \frac{m_2 \cos \theta + m_1}{\sqrt{m_1^2 + m_2^2 + 2m_1 m_2 \cos \theta}}$$

θ : angle in
barycentric
frame

$$(\cos \theta) = \sin \left(\frac{\theta}{2} \right)$$

$$m_1 = m_2 \equiv m \quad (\text{Equal mass})$$

$$\cos \psi = \frac{\cos \theta + 1}{\sqrt{2 + 2 \cos \theta}} = \sqrt{\frac{(\cos \theta + 1)^2}{2}} = \cos \left(\frac{\theta}{2} \right)$$

$$\text{Thus, } \boxed{\psi = \frac{\theta}{2}} \quad \left. \begin{array}{l} \sin x = \cos(x - \pi_2) \\ = \cos x \cos \pi_2 + \sin x \sin \pi_2 \\ = 0 \\ = 1 \end{array} \right\}$$

$$\text{so } \cos \psi = \sin \left(\frac{\theta}{2} \right) = \cos \left(\frac{\theta}{2} - \frac{\pi}{2} \right)$$

$$\rightarrow \boxed{\psi = \frac{\theta}{2} - \frac{\pi}{2}} < 0$$

$$|\psi| = \left| \frac{\theta}{2} - \frac{\pi}{2} \right| \\ = \frac{\pi}{2} - \frac{\theta}{2}$$

$$\text{Hence, } \boxed{\psi - \pi = \frac{\theta}{2} - \left(\frac{\theta}{2} - \frac{\pi}{2} \right) = \frac{\pi}{2}} \quad \left. \begin{array}{l} |\psi| + |\pi| = \frac{\theta}{2} + \frac{\pi}{2} - \frac{\theta}{2} \\ = \frac{\pi}{2} \end{array} \right\}$$

$$\cos 2x = \cos^2 x - \sin^2 x \\ = 2 \cos^2 x - 1$$

$$\cos^2 x = \frac{1 + \cos 2x}{2}$$

Newtonian Scattering

$y_{min} = 1$

Section 5.5

(33)
①

$$\phi_{min} = \int_0^1 \frac{du}{\sqrt{\frac{2\mu R^2}{\lambda^2} / \left(\epsilon - \frac{1}{2\mu r^2} + \frac{GM_M}{r} \right)}}$$

$$= \int_0^1 \frac{du}{\sqrt{\frac{2\mu R^2 \epsilon}{\lambda^2} - u^2 + 2 \frac{GM_M^2 R}{\lambda^2} u}}$$

$$= \int_0^1 \frac{du}{\sqrt{\frac{2\mu R^2 \epsilon}{\lambda^2} + 2 \frac{GM_M^2 R}{\lambda^2} u - u^2}}$$

$$= \int_0^1 \frac{du}{\sqrt{a + bu + cu^2}}$$

\cancel{R} $a = \frac{2\mu R^2 \epsilon}{\lambda^2}, b = \cancel{\frac{2GM_M^2 R}{\lambda^2}}, c = -1$

$$\int_0^1 \frac{du}{\sqrt{R}} = -\frac{1}{\sqrt{-c}} \arcsin \left(\frac{2cu+b}{\sqrt{-a}} \right) \Big|_0^1$$

$$= -\frac{1}{\sqrt{-c}} \left[\arcsin \left(\frac{2c+b}{\sqrt{-a}} \right) - \arcsin \left(\frac{b}{\sqrt{-a}} \right) \right]$$

$b = \frac{2R}{\alpha}$
where
 $\alpha = \frac{\lambda^2}{GM_M^2}$
(latus rectum
for ellipse)

$$-\Delta = b^2 - 4ac = \frac{4R^2}{\alpha^2} + 4 \frac{2\mu R^2 \epsilon}{\lambda^2}$$

$$= \frac{4R^2}{\alpha^2} \left(1 + \frac{2\mu \epsilon \alpha^2}{\lambda^2} \right) = \frac{4R^2}{\alpha^2} \left(1 + \frac{2\mu \epsilon \alpha^2}{GM_M^2 \alpha} \right)$$

$$= \frac{4R^2}{\alpha^2} \left(1 + \frac{2\epsilon \alpha}{GM_M} \right) = \boxed{\frac{4R^2 \epsilon^2}{\alpha^2}}$$

$$\text{where } e^2 = 1 + \frac{2\varepsilon\alpha}{GM_\mu} \geq 1 \quad (\text{For scattering orbits})$$

$$\text{Also, } \sqrt{-\Delta} = \frac{2R\epsilon}{\alpha}$$

$$\begin{aligned} \rightarrow \phi_{min} &= - \left[\arcsin \left(\frac{-2 + \frac{2R}{\alpha}}{\left(\frac{2R\epsilon}{\alpha} \right)} \right) - \arcsin \left(\frac{\frac{2R}{\alpha}}{\frac{2R\epsilon}{\alpha}} \right) \right] \\ &= - \left[\arcsin \left(\frac{1 - \frac{\alpha}{R\epsilon}}{\epsilon} \right) - \arcsin \left(\frac{1}{\epsilon} \right) \right] \\ &= - \left[\arcsin \left(\frac{1 - \frac{\alpha}{R}}{\epsilon} \right) - \arcsin \left(\frac{1}{\epsilon} \right) \right] \end{aligned}$$

where $R = \text{closest approach for } r$.

$$= b \sqrt{\frac{\epsilon - 1}{\epsilon + 1}}$$

impact parameter

$$\begin{aligned} e^2 &= 1 + \left(\frac{bV_\infty^2}{GM} \right)^2 \quad (\text{see below}) \Rightarrow \quad E_m = \frac{1}{2}\mu V_\infty^2 \quad \leftarrow \text{Newtonian} \\ \rightarrow \frac{bV_\infty^2}{GM} &= \sqrt{\epsilon^2 - 1} \quad \ell = \mu b V_\infty \end{aligned}$$

$$\alpha = \frac{\ell^2}{GM\mu^2} \Rightarrow = \frac{\mu^2 b^2 V_\infty^2}{GM} \quad \boxed{\alpha = \frac{b^2 V_\infty^2}{GM}} \quad *$$

BRWAN

$$\begin{aligned} \rightarrow \epsilon^2 &= 1 + 2 \frac{\frac{1}{2}\mu V_\infty^2 \alpha}{GM\mu} \\ &= 1 + \frac{V_\infty^2 \alpha}{GM} \\ &= 1 + \frac{V_\infty^2 \ell^2}{GM GM_\mu^2} \\ &= 1 + \frac{\frac{V_\infty^2}{GM} \frac{\ell^2 b^2 V_\infty^2}{\mu^2}}{\frac{GM}{GM_\mu^2}} = 1 + \frac{(bV_\infty)^2}{GM} \end{aligned}$$

(2) 35

$$\begin{aligned}
 1 - \frac{\alpha}{R} &= 1 - \frac{\alpha}{b \sqrt{\frac{e-1}{e+1}}} = 1 - \left(\frac{\alpha}{b}\right) \sqrt{\frac{e+1}{e-1}} \\
 &= 1 - \frac{b v_\infty^2}{GM} \sqrt{\frac{e+1}{e-1}} \\
 &= 1 - \sqrt{e^2 - 1} \sqrt{\frac{e+1}{e-1}} \\
 &= 1 - \cancel{\sqrt{(e-1)(e+1)}} \sqrt{\frac{e+1}{e-1}} \\
 &= 1 - (e+1) \\
 &= -e.
 \end{aligned}$$

$$\begin{aligned}
 \rightarrow \boxed{\phi_{min}} &= -\left[\arcsin(-1) - \arcsin\left(\frac{1}{e}\right)\right] \\
 &= -\left[-\frac{\pi}{2} - \arcsin\left(\frac{1}{e}\right)\right] \\
 &= \frac{\pi}{2} + \arcsin\left(\frac{1}{e}\right)
 \end{aligned}$$

~~Ans~~

$$2\phi_{min} = \pi + 2\arcsin\left(\frac{1}{e}\right)$$

$$\gamma = \frac{1}{\sqrt{1 - (\frac{u}{c})^2}}$$

$$\theta = 2\phi_{min} - \pi$$

$$= 2\arcsin\left(\frac{1}{e}\right) \quad (\text{Deflection angle})$$

$$\frac{\theta}{2} = \arcsin\left(\frac{1}{e}\right)$$

$$\left(\frac{\gamma}{\theta} = \frac{b v_\infty^2}{GM} \rightarrow \theta = \frac{2GM}{b v_\infty^2} \right)$$

$$\frac{1}{e} = \sin\left(\frac{\theta}{2}\right)$$

$$\begin{aligned}
 \text{Now } \cot\left(\frac{\theta}{2}\right) &= \sqrt{\csc^2\left(\frac{\theta}{2}\right) - 1} = \sqrt{\frac{1}{\sin^2\left(\frac{\theta}{2}\right)} - 1} = \sqrt{e^2 - 1} = \sqrt{\frac{b v_\infty^2}{GM}}
 \end{aligned}$$

①

Exercise 5.6: Gravitational differential cross section

$$q) \frac{d\sigma}{d\Omega} = \frac{b}{\sin\theta} \left| \frac{db}{d\theta} \right|$$

$$\cot\left(\frac{\theta}{2}\right) = \frac{b v_\infty^2}{GM}$$

$$\rightarrow b = \frac{GM}{v_\infty^2} \cot\left(\frac{\theta}{2}\right) \quad \cot = \frac{\cos}{\sin}$$

$$\frac{db}{d\theta} = \frac{GM}{v_\infty^2} \frac{-\sin^2\left(\frac{\theta}{2}\right)\frac{1}{2} - \cos^2\left(\frac{\theta}{2}\right)\frac{1}{2}}{\sin^2\left(\frac{\theta}{2}\right)}$$

$$= -\frac{GM}{2v_\infty^2} \frac{1}{\sin^2\left(\frac{\theta}{2}\right)}$$

$$\text{Thus, } \frac{d\sigma}{d\Omega} = \frac{b}{\sin\theta} \left| \frac{db}{d\theta} \right|$$

$$= \frac{\frac{GM}{v_\infty^2} \cot\left(\frac{\theta}{2}\right)}{\sin\theta} \frac{GM}{2v_\infty^2} \frac{1}{\sin^2\left(\frac{\theta}{2}\right)}$$

$$= \frac{\frac{G^2 M^2}{v_\infty^4}}{2} \frac{1}{\sin\left(\frac{\theta}{2}\right)} \frac{1}{2 \sin\left(\frac{\theta}{2}\right) \cos\left(\frac{\theta}{2}\right)} \frac{1}{\sin^2\left(\frac{\theta}{2}\right)}$$

$$= \boxed{\frac{1}{4} \frac{\frac{G^2 M^2}{v_\infty^4}}{\sin\left(\frac{\theta}{2}\right)}}^4$$

Note: $v_\infty^2 = \frac{2E}{m}$

$$\rightarrow = \frac{G^2 M^2 m^2 \csc^4\left(\frac{\theta}{2}\right)}{16 E^2} = \boxed{\left(\frac{GM_m}{4E}\right)^2 \csc^4\left(\frac{\theta}{2}\right)}$$

$$b) \frac{d\sigma}{dr} = \frac{b}{r\cos\theta} \left| \frac{db}{d\theta} \right|$$

$$= \frac{1}{2} \left| \frac{\frac{db^2}{d\theta}}{1/(r\cos\theta)} \right|$$

c) ~~$\tan(\theta) = \frac{\sin\theta}{\cos\theta}$~~

$$\frac{\sin x}{1 + \cos x} = \frac{2 \sin\left(\frac{x}{2}\right) \cos\left(\frac{x}{2}\right)}{1 + (\cos^2\left(\frac{x}{2}\right) - \sin^2\left(\frac{x}{2}\right))}$$

$$= \frac{2 \sin\left(\frac{x}{2}\right) \cos\left(\frac{x}{2}\right)}{2 \cos^2\left(\frac{x}{2}\right)}$$

$$= \frac{\sin\left(\frac{x}{2}\right)}{\cos\left(\frac{x}{2}\right)}$$

$$= \tan\left(\frac{x}{2}\right)$$

$$\text{Ansatz: } r_0 + \left(\frac{\theta}{2}\right) = \frac{b v_\infty^2}{GM} = \frac{1}{f_{\text{eff}}\left(\frac{\theta}{2}\right)}$$

$$\frac{b v_\infty^2}{GM} = \frac{1 + \cos\theta}{r \sin\theta}$$

(3)

$$\frac{\frac{b}{6} v_{\infty}^2}{m} = \frac{1 + r_{\infty} \theta}{\sin \theta}$$

$$= \frac{1 + r_{\infty} \theta}{\sqrt{1 - r_{\infty}^2 \theta}}$$

$$= \sqrt{\frac{1 + r_{\infty} \theta}{1 - r_{\infty} \theta}}$$

$$\rightarrow \boxed{b^2 = \frac{G^2 m^2}{v_{\infty}^4} \left(\frac{1 + r_{\infty} \theta}{1 - r_{\infty} \theta} \right)}$$

T_{loss}

$$\frac{d\sigma}{d\Omega} = \frac{1}{2} \left| \frac{db^2}{d(r_{\infty} \theta)} \right|$$

$$= \frac{1}{2} \frac{G^2 m^2}{v_{\infty}^4} \frac{(1 - r_{\infty} \theta) - 1}{(1 - r_{\infty} \theta)^2}$$

$$= \frac{1}{2} \frac{G^2 m^2}{v_{\infty}^4} \frac{2}{(1 - r_{\infty} \theta)^2}$$

$$= \frac{1}{2} \frac{G^2 m^2}{v_{\infty}^4} \frac{2}{\left(2 \sin^2 \left(\frac{\theta}{2}\right)\right)^2}$$

$$= \left[\frac{1}{4} \frac{G^2 m^2}{v_{\infty}^4} \frac{1}{\sin^4 \left(\frac{\theta}{2}\right)} \right]$$

$\cos \theta = r_{\infty} / (2 \cdot \frac{\theta}{2})$
 $= r_{\infty}^2 \left(\frac{\theta}{2}\right) - \sin^2 \left(\frac{\theta}{2}\right)$
 $= 1 - 2 \sin^2 \left(\frac{\theta}{2}\right)$
 $2 \sin^2 \left(\frac{\theta}{2}\right) = 1 - r_{\infty} \theta$

Newtonian Calculation for gravitational scattering:

$$\cot\left(\frac{\theta}{2}\right) = \frac{b v_\infty^2}{GM}$$

$$(5.32)$$

Suppose $\theta \ll 1$ (small deflection)

$$\text{Then } \cot\left(\frac{\theta}{2}\right) = \frac{\cot\left(\frac{\theta}{2}\right)}{\tan\left(\frac{\theta}{2}\right)} \approx \frac{1}{\left(\frac{\theta}{2}\right)} = \frac{2}{\theta}$$

$$\rightarrow \frac{2}{\theta} \approx \frac{b v_\infty^2}{GM}$$

$$\theta \approx \frac{2GM}{b v_\infty^2}$$

If we treat light as a Newtonian particle moving at $v_\infty = c$

$$\text{then } \boxed{\theta \approx \frac{2GM}{bc^2}} \quad (\text{Newtonian})$$

$$\text{Compare to GR calculation: } \boxed{\theta \approx \frac{4GM}{bc^2}} \quad (\text{GR})$$

so off by a factor of 2.

problem

(5.8)

Jupiter injection orbit

$$e^2 = 1 + \frac{2E\alpha}{GM_m}, \quad \alpha = a(1-e^2)$$



1) Circular orbit at r_{Es} around Sun:

$$e = 0, \quad \alpha = a_i = r_{Es} = 1 \text{ AU}$$

$$0 = 1 + \frac{2E_i a_i}{GM_m}$$

$$\left[E_i = -\frac{GM_m}{2a_i} \right] = -\frac{GM_m}{a_i} + \frac{1}{2}mV_i^2$$

2) In Jupiter injection orbit: $a_f = 3.15 \text{ AU}$
 $e = 0.683$

$$e^2 - 1 = \frac{2E_f a_f (1-e^2)}{GM_m}$$

$$\left[-\frac{GM_m}{2a_f} = E_f \right] = -\frac{GM_m}{a_i} + \frac{1}{2}mV_f^2$$

$$\begin{aligned} \Delta E &= E_f - E_i \\ &= -\frac{GM_m}{2a_f} - \left(-\frac{GM_m}{2a_i} \right) \\ &= \frac{GM_m}{2} \left(\frac{1}{a_f} - \frac{1}{a_i} \right) \\ &= \frac{GM_m}{2} \frac{\Delta a}{a_f a_i} \end{aligned}$$

Solve for v_i , v_f :

$$-\frac{GM_m}{2q_i} = -\frac{GM_m}{q_i} + \frac{1}{2}mv_i^2$$

$$+\frac{GM_N}{2q_i} = \frac{1}{2}mv_i^2$$

$$v_i = \sqrt{\frac{GM}{q_i}} = \boxed{3 \times 10^4 \text{ m/s}}$$

$$-\frac{GM_N}{2q_f} = -\frac{GM_N}{q_i} + \frac{1}{2}mv_f^2$$

$$GM\left(\frac{1}{q_i} - \frac{1}{2q_f}\right) = \frac{1}{2}v_f^2$$

$$\rightarrow v_f = \sqrt{2GM \frac{2q_f - q_i}{2q_f q_i}}$$

$$= \sqrt{GM \left(\frac{2q_f - q_i}{q_f q_i} \right)}$$

$$= \sqrt{\frac{GM}{1 \text{ AU}} \left(\frac{6.3 - 1}{3.15} \right)}$$

$$= 3 \times 10^4 \text{ m/s} \cdot \sqrt{\frac{5.3}{3.15}}$$

$$= \boxed{3 \times 10^4 \frac{\text{m}}{\text{s}} (1.3)} \quad (30\% \text{ larger})$$

$$\Delta V = v_f - v_i = 3 \times 10^4 \frac{\text{m}}{\text{s}} (1.3 - 1) = \boxed{9 \frac{\text{km}}{\text{s}}}$$

```
function deltaV = calBoost(a_i, a_f)
%
% calculate additional velocity needed to boost from
% elliptical orbit with semi-major axis a_i to an
% elliptical orbit with semi-major axis a_f, assuming
% both orbits have sun at one focal point
%
% input: a_i, a_f in units of AU
%
% example: calBoost(1, 3.15)
%
%%%%%%%%%%%%%
% constants (MKS)
G = 6.67e-11;
M_sun = 2e30;
AU = 1.5e11;

% convert to MKS units
a_i = a_i*AU;
a_f = a_f*AU;

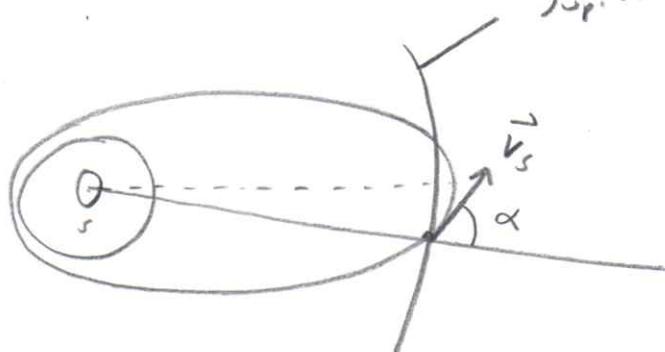
% calculate initial and final velocities and deltaV
v_i = sqrt(G*M_sun/a_i);
v_f = sqrt(2*G*M_sun*(1/a_i-1/(2*a_f)));
deltaV = v_f-v_i;

% display results
fprintf('v_i = %f km/s\n', v_i/1000);
fprintf('v_f = %f km/s\n', v_f/1000);
fprintf('deltaV = %f km/s\n', deltaV/1000);

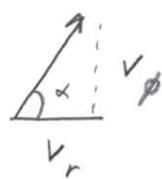
return
```

problem: Calculate t_{max} for Jupiter's gravitational slingshot maneuver

(5.9)



Jupiter's orbit circuit,



$$\tan \alpha = \frac{v_d}{v_r} = \frac{r d\phi/dt}{dr/dt} = \frac{r d\phi}{dr}$$

orbit equation: (elliptic)

$$r = \frac{a(1-e^2)}{1+e \cos \phi}$$

$$\rightarrow 1+e \cos \phi = \frac{a}{r} (1-e^2)$$

$$\cos \phi = \frac{\frac{a}{r} (1-e^2) - 1}{e}$$

$$\frac{dr}{d\phi} = -\frac{a(1-e^2)}{(1+e \cos \phi)^2} (-e \sin \phi)$$

$$= + \frac{ae \sin \phi (1-e^2)}{(1+e \cos \phi)^2}$$

$$= \cancel{-ae^2} + \frac{e \sin \phi}{a(1-e^2)} \frac{a^2 (1-e^2)^2}{(1+e \cos \phi)^2}$$

$$= \frac{e \sin \phi}{a(1-e^2)} r^2$$

$$\begin{aligned}
 \sin\phi &= \sqrt{1 - \cos^2\phi} \\
 &= \sqrt{1 - \frac{[(\frac{a}{r})(1-e^2) - 1]^2}{e^2}} \\
 &= \frac{1}{e} \sqrt{e^2 - (\frac{a}{r})^2(1-e^2)^2 - 1 + 2(\frac{a}{r})(1-e^2)} \\
 &= \frac{1}{e} \sqrt{(1-e^2) - (\frac{a}{r})^2(1-e^2)^2 + 2(\frac{a}{r})(1-e^2)} \\
 &= \frac{1}{e} \sqrt{1-e^2} \sqrt{-1 - (\frac{a}{r})^2(1-e^2) + 2(\frac{a}{r})}
 \end{aligned}$$

thus,

$$\begin{aligned}
 \tan\alpha &= r \frac{d\phi}{dr} \\
 &= r \frac{a(1-e^2)}{e \sin\phi r^2} \\
 &= + \frac{1}{r} \frac{a(1-e^2)}{\sqrt{1-e^2} \sqrt{-1 - (\frac{a}{r})^2(1-e^2) + 2(\frac{a}{r})}} \\
 &= + \frac{a}{r} \frac{\sqrt{1-e^2}}{\sqrt{-1 - (\frac{a}{r})^2(1-e^2) + 2(\frac{a}{r})}} \\
 &= + \frac{a}{r} \frac{\sqrt{1-e^2}}{\sqrt{-1 - (\frac{a}{r})^2(1-e^2) - (\frac{r}{a})^2 + 2\frac{r}{a}}}
 \end{aligned}$$

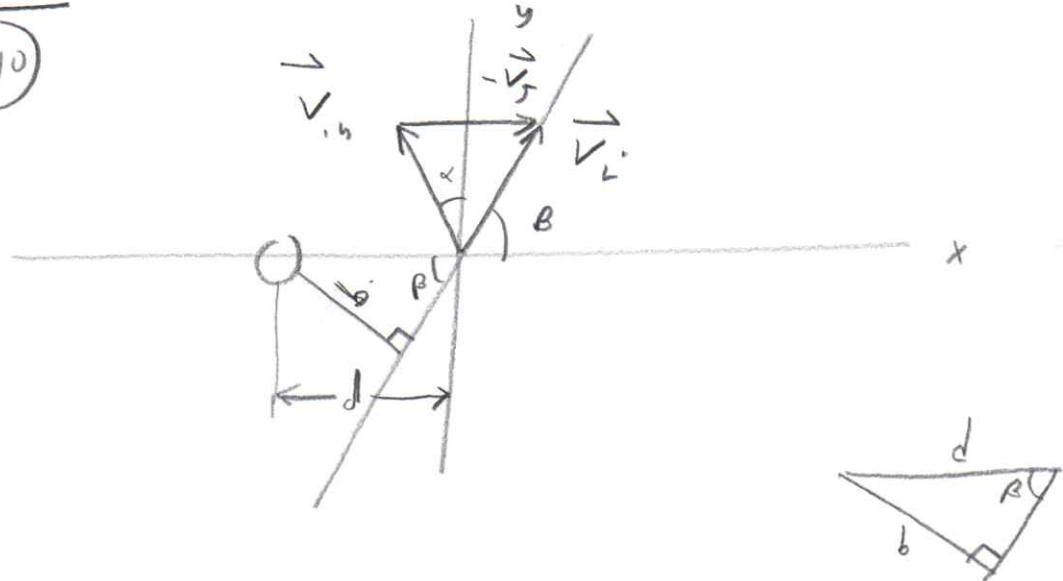
~~Now consider the relation between r and θ~~

$$= \frac{\sqrt{1-e^2}}{\sqrt{-\left(\frac{r}{a}\right)^2 + 2\frac{r}{a} - 1 + e^2}}$$

$$= \frac{\sqrt{1-e^2}}{\sqrt{e^2 - \left(1 - \left(\frac{r}{a}\right)\right)^2}}$$

Problem: Velocities in comoving reference frame

(5.10)



$$\vec{v}_i = \vec{v}_{i,h} - \vec{v}_j$$

$$\sin \beta = \frac{b}{d}$$

$$b = d \sin \beta$$

$$\vec{v}_{i,h} = -v_{i,h} \sin \alpha \hat{x} + v_{i,h} \cos \alpha \hat{y}$$

$$-\vec{v}_j = v_j \hat{x}$$

$$\vec{v}_i = v_i \cos \beta \hat{x} + v_i \sin \beta \hat{y}$$

$$\text{thus, } \tan \beta = \frac{\sin \beta}{\cos \beta}$$

$$= \frac{v_{i,y}}{v_{i,x}}$$

$$= \frac{v_{i,h,y} - v_{j,y}}{v_{i,h,x} - v_{j,x}}$$

$$= \frac{v_{i,h} \cos \alpha}{-v_{i,h} \sin \alpha + v_j}$$

Also, show $v_i^2 = v_{in}^2 + v_j^2 - 2v_{in}v_j \sin\alpha$

Proof: $v_i^2 = (v_{in,x} - v_{j,x})^2 + (v_{in,y} - v_{j,y})^2$

$$= (-v_{in} \sin\alpha + v_j)^2 + (v_{in} \cos\alpha)^2$$
$$= v_{in}^2 \sin^2\alpha + v_j^2 - 2v_{in}v_j \sin\alpha + v_{in}^2 \cos^2\alpha$$
$$= v_{in}^2 + v_j^2 - 2v_{in}v_j \sin\alpha$$

Problem (5.11) Determine final velocity for gravitational slingshot

$$\vec{V}_{out} = (v_i \cos(\theta + \rho) - v_J) \hat{x} + v_i \sin(\theta + \rho) \hat{y}$$

where $\checkmark v_i^2 = v_{in}^2 + v_J^2 - 2 v_{in} v_J \cos \alpha$ (1)

$\checkmark \cot\left(\frac{\theta}{2}\right) = \frac{b v_i^2}{GM_J}$ (2)

$\checkmark t_{ah\beta} = \frac{v_{in} \cos \alpha}{v_J - v_{in} \sin \alpha}$ (3)

$\checkmark t_{an\alpha} = \sqrt{\frac{1-e^2}{e^2 - (1-r/a)^2}}$ (4) where $r = |\vec{r}_{JS}|$

$\checkmark b = d \sin \beta$ (5)

~~Not~~ a, d, e : are initial conditions

$$r_a = 5.3 \text{ AU}; r_p = 1 \text{ AU} \Rightarrow a = 3.15 \text{ AU}$$
$$e = 0.683$$

★ Actually take r_a, r_p, d as input

Need v_{in} : initial velocity of spacecraft before scattering.

$$E = -\frac{GM_0 m_s}{2a}$$

3.15 AU for Jupiter-
1.4 injection
 $a=1.7$

$$-\frac{GM_0 v_{in}}{2a} = -\frac{GM_0 m_s}{r_{JS}} + \frac{1}{2} m_s v_{in}^2$$

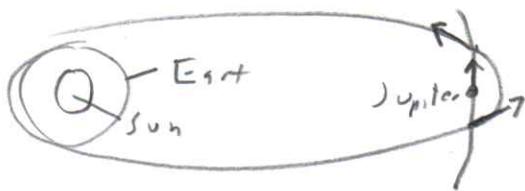
\square at
5.2 AU



$$v_{in} = \sqrt{2 \left(-\frac{GM_0}{2a} + \frac{GM_0}{r_{JS}} \right)}$$

$$= \sqrt{2 GM_0 \left(\frac{1}{r_{JS}} - \frac{1}{2a} \right)}$$

To determine final aphelion distance:



Scatters out at $r_{JS} = 5.2 \text{ AU} \leq q_i$
with v_{out}

$$E = -\frac{GM}{2a_f} = -\frac{GM}{a_i} + \frac{1}{2}v_{out}^2$$

\uparrow
 5.2 AU

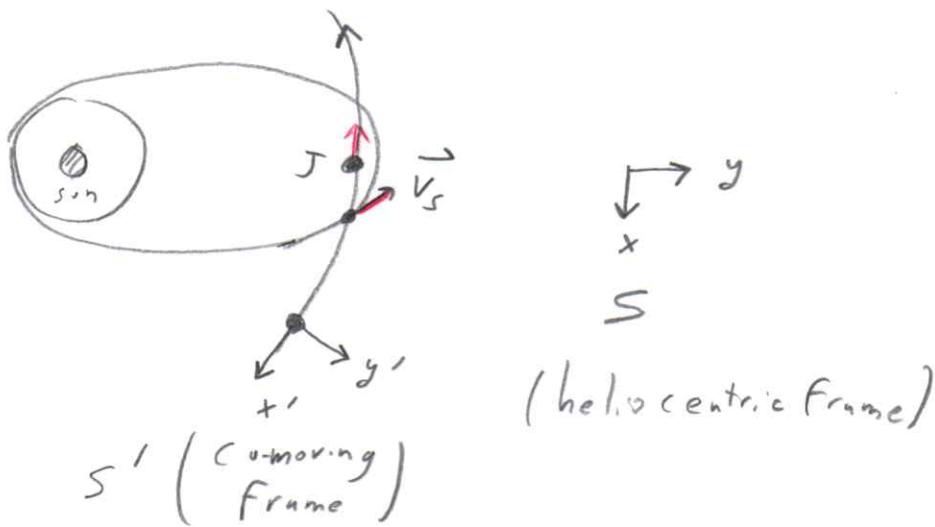
$$-\frac{GM}{2a_f} = -\frac{GM}{a_i} + \frac{1}{2}v_{out}^2$$

$$-\frac{GM}{2} \frac{1}{\left(-\frac{GM}{a_i} + \frac{1}{2}v_{out}^2\right)} = a_f$$

$\frac{\text{soln 1}^{m+1}}{\text{soln 2}}$

$a_f = \frac{-GM/2}{\left(-GM/a_i + \frac{1}{2}v_{out}^2\right)}$

r_{JS}



$$\begin{aligned}
 \vec{v}_{\text{out}} &= \vec{v}_S + \vec{v}_J \\
 &= v_i \cos(\theta + \beta) \hat{x} + v_i \sin(\theta + \beta) \hat{y} \\
 &\quad \cancel{\text{---}} = v_J \hat{x} \\
 &= [v_i \cos(\theta + \beta) - v_J] \hat{x} + v_i \sin(\theta + \beta) \hat{y}
 \end{aligned}$$

```
function jupiterScatter(r_p, r_a, d)
%
% inputs:
%   r_perihelion, r_aphelion, in units of AU
%   d: distance from Jupiter in units of Jupiter radius RJ
%
% e.g., jupiterScatter(1, 5.3, 10)
%
%%%%%%%%%%%%%%%
%
% constants (MKS)
G = 6.67e-11;
M_sun = 2e30;
M_J = 1.9e27;
AU = 1.5e11;
R_J = 7e7; % mean radius jupiter
r_JS = 5.2*AU; % mean orbital radius of jupiter

% convert to MKS units
r_p = r_p*AU;
r_a = r_a*AU;
d = d*R_J;

% calculate a and e from r_p, r_a
a = 0.5*(r_p+r_a);
e = 0.5*(r_a-r_p)/a;

% calculate initial velocity of spacecraft (v_infinity)
v_in = sqrt(2*G*M_sun*(1/r_JS-1/(2*a)));

% calculate orbital velocity of jupiter
v_J = sqrt(G*M_sun/r_JS);

% calculate angles (radians)
alpha = atan(sqrt((1-e^2)/(e^2 - (1-r_JS/a)^2)));
beta = atan(v_in * cos(alpha)/(v_J - v_in*sin(alpha)));
b = d*sin(beta);
v_i = sqrt(v_in^2 + v_J^2 - 2*v_in*v_J*sin(alpha));
theta = 2*acot(b*v_i^2 / (G*M_J));
v_out = sqrt((v_i*cos(theta+beta) - v_J)^2 + (v_i*sin(theta+beta))^2);
phi_out = atan2(v_i*sin(theta+beta), v_i*cos(theta+beta) - v_J);

% calculate aphelion of scattered orbit
a_f = (-G*M_sun/2)/(-G*M_sun/r_JS + 0.5*v_out^2 );
if a_f<0
    a_f = inf;
    display(' ')
    display('spacecraft ejected out of solar system!')
end

% display results
fprintf('\n')
fprintf('v_in = %f km/s\n', v_in/1000);
fprintf('v_out = %f km/s\n', v_out/1000);
fprintf('phi_out = %f degree\n', phi_out*180/pi);
fprintf('aphelion = %f AU\n', a_f/AU);
```

1/24/10, 2.04

```
fprintf('v_J = %f km/s\n', v_J/1000);
fprintf('v_i = %f km/s\n', v_i/1000);
fprintf('alpha = %f degree\n', alpha*180/pi);
fprintf('beta = %f degree\n', beta*180/pi);
fprintf('theta = %f degree\n', theta*180/pi);
fprintf('b = %f R_J\n', b/R_J);
```

```
return
```

```
ans = 7.73261 m/s
ans = 37.62667 km/s
ans = 175.71687 degree
ans = 10.76147 degree
ans = 340.11153 R_J
```

-> end of function, S.I., 184

```
ans = 7.73261 m/s
ans = 37.62667 km/s
ans = 175.71687 degree
ans = 10.76147 degree
ans = 340.11153 R_J
```

```
ans = 7.73261 m/s
ans = 37.62667 km/s
ans = 175.71687 degree
ans = 10.76147 degree
ans = 340.11153 R_J
```

```
ans = 7.73261 m/s
ans = 37.62667 km/s
ans = 175.71687 degree
ans = 10.76147 degree
ans = 340.11153 R_J
```

```
ans = 7.73261 m/s
ans = 37.62667 km/s
ans = 175.71687 degree
ans = 10.76147 degree
ans = 340.11153 R_J
```

```
>> jupiterScatter(1, 5.3, 1000)
```

```
v_in = 7.728081 km/s
v_out = 9.006630 km/s
phi_out = 156.458064 degree
aphelion = 3.408297 AU
v_J = 13.077677 km/s
v_i = 6.015025 km/s
alpha = 74.277803 degree
beta = 20.373932 degree
theta = 16.358148 degree
b = 348.145573 R_J
```

```
>> jupiterScatter(1, 5.3, 100)
```

```
v_in = 7.728081 km/s
v_out = 17.602089 km/s
phi_out = 164.989016 degree
aphelion = 27.603841 AU
v_J = 13.077677 km/s
v_i = 6.015025 km/s
alpha = 74.277803 degree
beta = 20.373932 degree
theta = 110.343328 degree
b = 34.814557 R_J
```

```
>> jupiterScatter(1, 5.3, 10)
```

```
spacecraft ejected out of solar system!
```

```
v_in = 7.728081 km/s
v_out = 18.996130 km/s
phi_out = -176.096827 degree
aphelion = Inf AU
v_J = 13.077677 km/s
v_i = 6.015025 km/s
alpha = 74.277803 degree
beta = 20.373932 degree
theta = 172.040099 degree
b = 3.481456 R_J
```

Problem: Differential cross section for equal-mass particles
in the lab frame

(5.12)

$$\begin{aligned}\left(\frac{d\sigma}{d\Omega}\right)' &= \left(\frac{d\sigma}{d\Omega}\right) \left| \frac{d(\cos\theta)}{d(\cos\psi)} \right| \\ &= \left(\frac{d\sigma}{d\Omega}\right) \left| \frac{d(\cos\theta)}{d(\cos|\frac{\theta}{2}|)} \right| \quad \psi = \frac{\theta}{2} \\ &= \left(\frac{d\sigma}{d\Omega}\right) \left| \frac{\sin\theta d\theta}{\sin\left(\frac{\theta}{2}\right) \pm d\theta} \right| \\ &= \left(\frac{d\sigma}{d\Omega}\right) \frac{2\sin(2\psi)}{\sin\psi} \\ &= \left(\frac{d\sigma}{d\Omega}\right) \frac{4 \sin\psi \cos\psi}{\sin\psi} \\ &= 4 \cos\psi \left(\frac{d\sigma}{d\Omega}\right)\end{aligned}$$

Problem: Calculate $\cot\left(\frac{\theta}{2}\right)$ for Rutherford scattering.

[OLD]

For gravitational scattering:

$$\cot\left(\frac{\theta}{2}\right) = \frac{b v_\infty^2}{GM}$$

Re-express RHS in terms of E , $\hbar\Phi_2$ using

$$GM_M \leftrightarrow \hbar\Phi_2$$

$$E = \frac{1}{2}mv_\infty^2$$

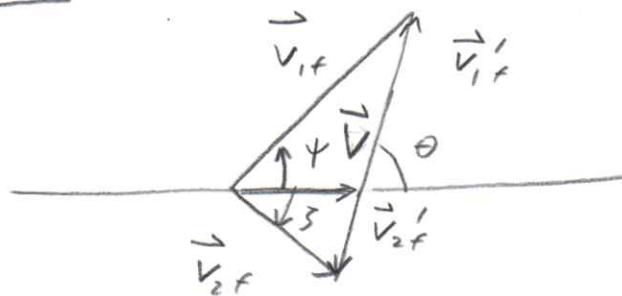
$$\rightarrow v_\infty^2 = \frac{2E}{m}$$

$$\text{Thus, } \cot\left(\frac{\theta}{2}\right) = \frac{b}{GM} \frac{2E}{m}$$

$$= \frac{2Eb}{\hbar\Phi_2}$$

problem 5.13 Verify expression for $\cos \beta$

ANSWER



$$V_{2f} \cos \beta = V - V_{2f}' \cos \theta$$

$$V_{2f} \sin \beta = V_{2f}' \sin \theta$$

Square and add:

$$V_{2f}^2 \cos^2 \beta + V_{2f}^2 \sin^2 \beta$$

$$= (V - V_{2f}' \cos \theta)^2 + (V_{2f}' \sin \theta)^2$$

$$= V^2 + (V_{2f}' \cos \theta)^2 - 2V V_{2f}' \cos \theta + (V_{2f}' \sin \theta)^2$$

$$\boxed{= (V_{2f}')^2}$$

$$= V^2 - 2V V_{2f}' \cos \theta + (V_{2f}')^2$$

Thus, $\boxed{V_{2f}^2 = V^2 - 2V V_{2f}' \cos \theta + (V_{2f}')^2}$

Substitute back into $\cos \beta$ equation:

$$\cos \beta = \frac{V - V_{2f}' \cos \theta}{\sqrt{V^2 - 2V V_{2f}' \cos \theta + (V_{2f}')^2}}$$

Divide by v_{ef}' :

$$\left(\cos \theta \right) = \frac{\frac{V}{v_{ef}'} - \cos \theta}{\sqrt{\left(\frac{V}{v_{ef}'} \right)^2 - 2 \left(\frac{V}{v_{ef}'} \right) \cos \theta + 1}}$$
$$= \frac{\rho_2 - \cos \theta}{\sqrt{\rho_2^2 - 2 \rho_2 \cos \theta + 1}}$$

$$\rho_2 = \frac{V}{v_{ef}'}$$

Problem: Verify

$$\boxed{\text{OLD}} \quad \left(\frac{d\sigma}{dn} \right)' = \frac{(1 + 2\rho \cos \theta + \rho^2)^{3/2}}{1 + \rho \cos \theta} \left(\frac{d\sigma}{dn} \right)$$

Proof: $\left(\frac{d\sigma}{dn} \right)' = \left(\frac{d\sigma}{dn} \right) \left| \frac{d \cos \theta}{d \cos \psi} \right|$

Now: $\cos \psi = \frac{\cos \theta + \rho}{\sqrt{1 + 2\rho \cos \theta + \rho^2}}$

$$d(\cos \psi) = \frac{d(\cos \theta) \sqrt{1 + 2\rho \cos \theta + \rho^2} - \frac{1}{\sqrt{1 + 2\rho \cos \theta + \rho^2}} \cdot 2\rho d(\cos \theta) (\cos \theta + \rho)}{1 + 2\rho \cos \theta + \rho^2}$$

$$= \frac{d(\cos \theta)}{\left[1 + 2\rho \cos \theta + \rho^2 \right]^{3/2}} \left\{ (1 + 2\rho \cos \theta + \rho^2) - \rho (1 + \cos \theta + \rho) \right\}$$

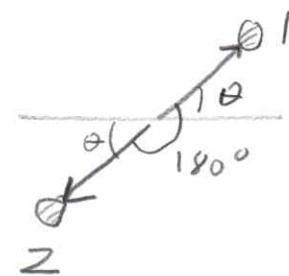
$$= \frac{d(\cos \theta)}{\left[1 + 2\rho \cos \theta + \rho^2 \right]^{3/2}} [1 + \rho \cos \theta]$$

Thus,
$$\boxed{\frac{d(\cos \theta)}{d(\cos \psi)} = \frac{\left[1 + 2\rho \cos \theta + \rho^2 \right]^{3/2}}{1 + \rho \cos \theta}}$$

Problem: Scattering of equal-mass hard spheres in the
Lab frame.

In COM frame:

$$\vec{v}_1' = -\vec{v}_2'$$



In Lab frame:

$$\vec{v}_1 = \vec{V} + \vec{v}_1'$$

$$\vec{v}_2 = \vec{V} + \vec{v}_2' = \vec{V} - \vec{v}_1'$$

Γ_{hv} ,

$$\vec{v}_1 \cdot \vec{v}_2 = (\vec{V} + \vec{v}_1') \cdot (\vec{V} - \vec{v}_1') \\ = V^2 - v_1'^2$$

But: $V = \frac{1}{2} v_\infty \leftarrow$ (for equal mass)
 $v_1' = \pm \frac{1}{2} v_\infty$

so $\boxed{\vec{v}_1 \cdot \vec{v}_2 = 0}$

Problem: Principle of relativity for elastic collisions

(5.1)

For an elastic collision, total KE is conserved

$$\text{i.e., } \sum_I \frac{1}{2} m_I v_{I,i}^2 = \sum_I \frac{1}{2} m_I v_{I,f}^2$$

(before)

(after)

By the principle of relativity, this must hold in all inertial reference frames.

Let S, S' denote two inertial frames related by \vec{u}

$$S \quad S' \rightarrow \vec{u} \quad \text{so} \quad \vec{v}' = \vec{v} - \vec{u}$$

$$\text{Then } \vec{v}'_{F,i} = \vec{v}_{I,i} - \vec{u}$$

$$\vec{v}'_{I,F} = \vec{v}_{I,F} - \vec{u}$$

In S' (cons. of total KE):

$$\sum_I \frac{1}{2} m_I v'_{I,i}^2 = \sum_I \frac{1}{2} m_I v'_{I,f}^2$$

$$\text{LHS} = \sum_I \frac{1}{2} m_I (\vec{v}_{I,i} - \vec{u}) \cdot (\vec{v}_{I,i} - \vec{u})$$

$$= \sum_I \frac{1}{2} m_I (v_{I,i}^2 + u^2 - \vec{u} \cdot \vec{v}_{I,i})$$

$$\text{RHS} = \sum_I \frac{1}{2} m_I (v_{I,f}^2 + u^2 - \vec{u} \cdot \vec{v}_{I,f})$$

Thus,

$$\sum_I \frac{1}{2} m_I v_{I,i}^2 + \frac{1}{2} M u^2 - \frac{1}{2} \vec{u} \cdot \sum_I m_I \vec{v}_{I,i}$$

$$= \sum_I \frac{1}{2} m_I v_{I,f}^2 + \frac{1}{2} M u^2 - \frac{1}{2} \vec{u} \cdot \sum_I m_I \vec{v}_{I,f}$$

$$\cancel{\text{LHS}} \rightarrow 0 = \vec{u} \cdot \left(\sum_I m_I \vec{v}_{I,i} - \sum_I m_I \vec{v}_{I,f} \right)$$

Since \vec{u} is arbitrary

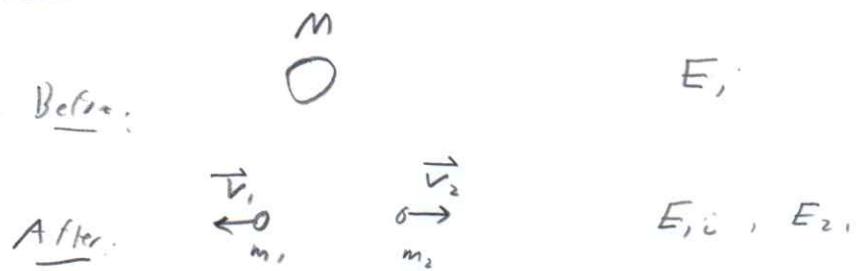
$$\sum_I m_I \vec{v}_{F,i} = \sum_I m_I \vec{v}_{I,f} \quad (\text{cons. of total linear momentum})$$

(1)

Prob 5.2 Disintegration of a particle of mass M into two constituent particles, mass m_1 and m_2 .

Determine Assume internal energy of original particle is ~~E_i~~ E_i and internal energies of constituent particles are E_{1i} , E_{2i} .

Determine velocities of constituent particles.



Conservation of mass and total energy in Newtonian physics. [In SR, total relativistic momentum and total energy are always conserved. Total mass only conserved for elastic collisions.]

Now. $m_1 v_1 = m_2 v_2 \equiv p_0$ (cons of momentum)

$$E_i = E_{1i} + \frac{1}{2} m_1 v_1^2 + E_{2i} + \frac{1}{2} m_2 v_2^2 \quad (\text{cons of } \overset{\text{total}}{E_{\text{energy}}})$$

$$\Delta E_i \equiv E_{1i} - E_{1i} - E_{2i} = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2$$

$$\boxed{\Delta E_i = \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 v_2^2}$$

$$\boxed{m_1 v_1 = m_2 v_2}$$

$$\begin{aligned} \text{Thus, } \Delta E_i &= \frac{1}{2} m_1 v_1^2 + \frac{1}{2} m_2 \left(\frac{m_1 v_1}{m_2} \right)^2 \\ &= \frac{1}{2} m_1 v_1^2 + \frac{1}{2} \frac{m_1^2}{m_2} v_1^2 \\ &= \frac{1}{2} m_1 v_1^2 \left(1 + \frac{m_1}{m_2} \right) \\ &= \frac{1}{2} m_1 v_1^2 \frac{M}{m_2} \end{aligned}$$

A₃₀:

$$\Delta E_i = \frac{1}{2} m_1 \left(\frac{m_2 v_2}{m_1} \right)^2 \frac{M}{m_2}$$

$$= \frac{1}{2} \frac{m_2^2}{m_1} \frac{v_2^2}{m_2} \frac{M}{m_2}$$

$$= \frac{1}{2} m_2 v_2^2 \left(\frac{M}{m_1} \right)$$

Reduced mass: $\mu = \frac{m_1 m_2}{M}$

$$\Delta E_i = \frac{1}{2} m_1^2 v_1^2 \left(\frac{M}{m_1 m_2} \right)$$

$$= \frac{1}{2} \frac{p_0^2}{\mu} \quad (\text{same for 2nd particle})$$



$$\Delta E_i = \frac{1}{2} \frac{m_1^2 v_1^2}{\mu}$$

$$\frac{2\mu \Delta E_i}{m_1^2} = v_1^2$$

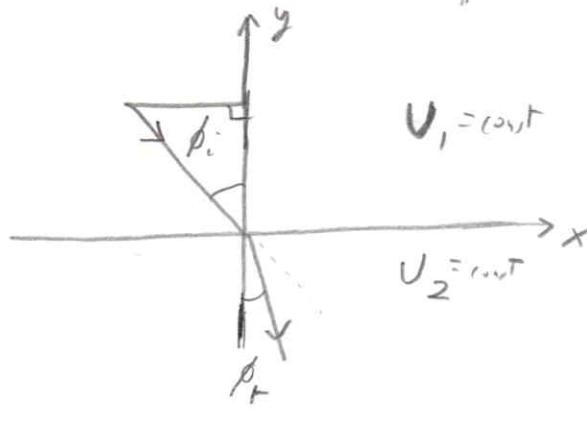
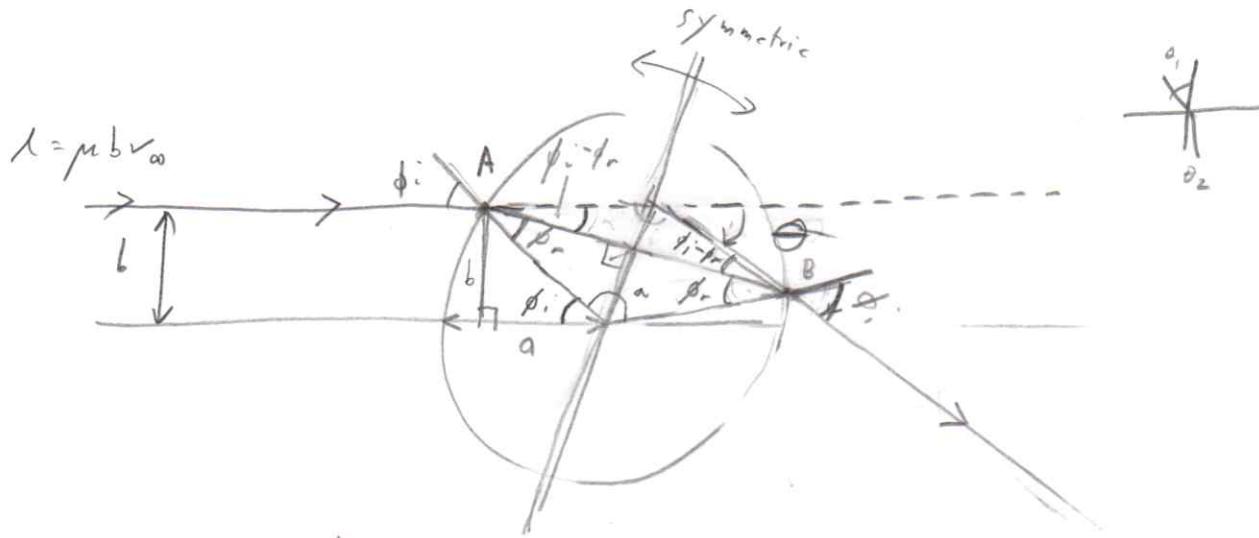
$$v_1 = \sqrt{\frac{2\mu \Delta E_i}{m_1}}$$

$$v_2 = \sqrt{\frac{2\mu \Delta E_i}{m_2}}$$

(5.5) and (5.3)

Problem Scattering off of spherical potential well

$$U(r) = \begin{cases} -U_0 & 0 \leq r \leq a \\ 0 & r > a \end{cases}$$



$$E_1 = E_2 = E$$

$$E = \frac{1}{2} \mu (x_1^2 + y_1^2) + U_1$$

$$= \frac{1}{2} \mu (x_2^2 + y_2^2) + U_2$$

$$\frac{1}{2} \mu v_i^2 + U_1 = \frac{1}{2} \mu v_f^2 + U_2$$

$$\boxed{\frac{v_2^2 - v_1^2}{m} = \frac{2(U_1 - U_2)}{m}}$$

const. of energy

~~$$\frac{x_2^2 - x_1^2}{m} = \frac{2(U_1 - U_2)}{m}$$~~

Now

$$\sin \phi_i = \frac{x_1}{v_1}, \quad \sin \phi_f = \frac{x_2}{v_2}$$

But $x_1 = x_2$

so $\boxed{v_1 \sin \phi_i = v_2 \sin \phi_f}$

const.
of
momentum
in
x-direction

~~$$\tan \phi_i = \frac{x_1}{y_1}$$~~

~~$$\tan \phi_f = \frac{x_2}{y_2} = \frac{x_1}{y_2}$$~~

~~$$\therefore \tan \phi_i = \frac{y_1}{x_1} = \frac{y_2}{x_2} = \tan \phi_f$$~~

$$\text{Thus, } v_1 \sin \phi_i = v_2 \sin \phi_r$$

$$v_2^2 - v_1^2 = \frac{2}{m} (U_1 - U_2)$$

$$\begin{aligned} \sin \phi_i &= \frac{v_2}{v_1} \sin \phi_r \\ &= \frac{\sqrt{v_1^2 + \frac{2}{m} (U_1 - U_2)}}{v_1} \sin \phi_r \\ &= \sqrt{1 + \frac{2}{m v_1^2} (U_1 - U_2)} \sin \phi_r \end{aligned}$$

$$\text{Thus, } \boxed{n = \sqrt{1 + \frac{2(U_1 - U_2)}{m v_1^2}}}, \boxed{\sin \phi_i = n \sin \phi_r}$$



$$\text{For } U_1 = 0, U_2 = -U_0$$

(at A):

$$\begin{aligned} n &= \sqrt{1 + \frac{2(0 - (-U_0))}{m v_{\infty}^2}} \\ &= \sqrt{1 + \frac{2U_0}{m v_{\infty}^2}} > 1 \end{aligned}$$

$$\underline{\text{Geometry}}: 2\phi_r + \alpha = \pi$$

$$2(\phi_i - \phi_r) + \beta = \pi$$

$$\theta + \beta = \pi$$

$$\text{Thus, } \boxed{\theta = 2(\phi_i - \phi_r)} \rightarrow \boxed{\cancel{\text{cancel}}}$$

$$\text{Also, } \boxed{\sin \phi_i = \frac{b}{a}}$$

$$\boxed{\phi_r = \phi_i - \frac{\theta}{2}}$$

$$s_o \quad \phi_r = \phi_i - \frac{\theta}{2}$$

~~sin~~

$$\begin{aligned} \frac{1}{n} &= \frac{\sin \phi_r}{\sin \phi_i} = \frac{\sin(\phi_i - \frac{\theta}{2})}{\frac{b}{a}} \\ &= \frac{1}{a} \left(\sin \phi_i \cos \left(\frac{\theta}{2} \right) + \cos \phi_i \sin \left(\frac{\theta}{2} \right) \right) \\ &= \frac{a}{b} \left[\frac{b}{a} \cos \left(\frac{\theta}{2} \right) + \sqrt{1 - \left(\frac{b}{a} \right)^2} \sin \left(\frac{\theta}{2} \right) \right] \\ &= \cos \left(\frac{\theta}{2} \right) + \frac{a}{b} \sqrt{1 - \left(\frac{b}{a} \right)^2} \sin \left(\frac{\theta}{2} \right) \\ &= \cos \left(\frac{\theta}{2} \right) + \sqrt{\left(\frac{a}{b} \right)^2 - 1} \sin \left(\frac{\theta}{2} \right) \end{aligned}$$

$$\frac{1}{n} = \cos \left(\frac{\theta}{2} \right) + \sqrt{\left(\frac{a}{b} \right)^2 - 1} \sin \left(\frac{\theta}{2} \right)$$

$$\left(\frac{\frac{1}{n} - \cos \left(\frac{\theta}{2} \right)}{\sin \left(\frac{\theta}{2} \right)} \right)^2 = \left(\frac{a}{b} \right)^2 - 1$$

$$\left(\frac{1 - n \cos \left(\frac{\theta}{2} \right)}{n \sin \left(\frac{\theta}{2} \right)} \right)^2 + 1 = \left(\frac{a}{b} \right)^2$$

$$\frac{\left(1 - n \cos \left(\frac{\theta}{2} \right) \right)^2 + n^2 \sin^2 \left(\frac{\theta}{2} \right)}{n^2 \sin^2 \left(\frac{\theta}{2} \right)} = \left(\frac{a}{b} \right)^2$$

$$\begin{aligned} \text{Numerator:} \quad & 1 + n^2 \cos^2 \left(\frac{\theta}{2} \right) - 2 n \cos \left(\frac{\theta}{2} \right) + n^2 \sin^2 \left(\frac{\theta}{2} \right) \\ & = 1 + n^2 - 2 n \cos \left(\frac{\theta}{2} \right) \end{aligned}$$

T h o,

$$\boxed{\left(\frac{a}{b}\right)^2 = \frac{1 - 2n \cos\left(\frac{\theta}{2}\right) + b^2}{n^2 \sin^2\left(\frac{\theta}{2}\right)}}$$

$$\frac{d\sigma}{d\Omega} = \frac{b}{\sin\theta} \left| \frac{db}{d\theta} \right|$$

Differentiate:

$$b^{-2}$$

$$-2 \left(\frac{a^2}{b^2} \right) \left(\frac{db}{d\theta} \right) = \cancel{\frac{n^2}{2} \sin^2\left(\frac{\theta}{2}\right)} n^2 \sin^2\left(\frac{\theta}{2}\right) - \cancel{\frac{b^2 \sin^2\left(\frac{\theta}{2}\right)}{2} \cos\left(\frac{\theta}{2}\right)} \left(1 - 2n \cos\left(\frac{\theta}{2}\right) + b^2 \right)$$
$$n^4 \sin^4\left(\frac{\theta}{2}\right)$$

$$-2 \left(\frac{a^2}{b^2} \right) \frac{1}{b} \frac{db}{d\theta} = \frac{\cancel{n^2 \sin^2\left(\frac{\theta}{2}\right)} - \cancel{n^2 \sin^2\left(\frac{\theta}{2}\right) \cos\left(\frac{\theta}{2}\right)} \left(1 - 2n \cos\left(\frac{\theta}{2}\right) + b^2 \right)}{n^2 \cancel{\sin^4\left(\frac{\theta}{2}\right)}}$$

$$\rightarrow \frac{1}{b} \left(\frac{db}{d\theta} \right) = -\frac{1}{2} \left(\frac{b}{a} \right)^2 \frac{n \sin^2\left(\frac{\theta}{2}\right) - \cos\left(\frac{\theta}{2}\right) \left(1 - 2n \cos\left(\frac{\theta}{2}\right) + b^2 \right)}{n^2 \sin^2\left(\frac{\theta}{2}\right)}$$
$$= -\frac{1}{2} \frac{\cancel{n \sin^2\left(\frac{\theta}{2}\right)}}{\left(1 - 2n \cos\left(\frac{\theta}{2}\right) + b^2 \right)} \frac{\cancel{\sin^2\left(\frac{\theta}{2}\right) - \cos\left(\frac{\theta}{2}\right) \left(1 - 2n \cos\left(\frac{\theta}{2}\right) + b^2 \right)}}{\cancel{n^2 \sin^2\left(\frac{\theta}{2}\right)}}$$
$$= -\frac{1}{2} \frac{n \sin^2\left(\frac{\theta}{2}\right) - \cos\left(\frac{\theta}{2}\right) \left(1 - 2n \cos\left(\frac{\theta}{2}\right) + b^2 \right)}{\sin^2\left(\frac{\theta}{2}\right) \left(1 - 2n \cos\left(\frac{\theta}{2}\right) + b^2 \right)}$$

$$\frac{d\sigma}{d\Omega} = \frac{b}{\sin\theta} \left| \frac{db}{d\theta} \right|$$

$$= \frac{1}{2 \sin\left(\frac{\theta}{2}\right) \cos\left(\frac{\theta}{2}\right)} b^2 + \left| \frac{db}{d\theta} \right|$$

$$\sin\left(\frac{\theta}{2}\right) \\ = 2 \sin\theta \cos\theta$$

$$= \frac{1}{2\cos(\theta)} \frac{\frac{a^2 n^2 - \cancel{a^2 n^2}}{(1 - 2n\cos(\theta) + n^2)}}{\frac{1}{2} \left| \frac{n\sin^2(\theta) - \cos(\theta)(1 - 2n\cos(\theta) + n^2)}{\cancel{a^2 n^2}(1 - 2n\cos(\theta) + n^2)} \right|}$$

$$= \frac{\cancel{a^2 n^2}}{4\cos(\theta)} \frac{\left| n\sin^2(\theta) - \cos(\theta)(1 - 2n\cos(\theta) + n^2) \right|}{(1 - 2n\cos(\theta) + n^2)^2}$$

Numerator: $|n\sin^2(\theta) - \cos(\theta)(1 - 2n\cos(\theta) + n^2)|$

$$= |n\sin^2(\theta) - \cos(\theta) + 2n\cos^2(\theta) - n^2\cos(\theta)|$$

$$= |n(1 - \cos^2(\theta)) - \cos(\theta) + 2n\cos^2(\theta) - n^2\cos(\theta)|$$

$$= |n - n\cos^2(\theta) - \cos(\theta) + 2n\cos^2(\theta) - n^2\cos(\theta)|$$

$$= |n - \cos(\theta) + n\cos^2(\theta) - n^2\cos(\theta)|$$

$$= |(n - \cos(\theta)) - n\cos(\theta)(n - \cos(\theta))|$$

$$= |(n - \cos(\theta))(1 - n\cos(\theta))|$$

$$= \underline{\underline{n\cos(\theta)}}$$

$$= |(n\cos(\frac{\theta}{2}) - 1)(n - \cos(\frac{\theta}{2}))|$$

$$\frac{d\sigma}{d\Omega} = \frac{a^2 n^2}{4\cos(\frac{\theta}{2})} \frac{|(n\cos(\frac{\theta}{2}) - 1)(n - \cos(\frac{\theta}{2}))|}{(1 - 2n\cos(\theta) + n^2)^2}$$

6

wht is maximum θ ?

$$\left(\frac{d}{b}\right)^2 = \frac{1 - 2n \cos(\theta/2) + n^2}{n^2 \sin^2(\theta/2)}$$

$$b = b(\theta) \Leftrightarrow \theta = \theta(b)$$

want to set $\theta = \frac{d\theta}{db}$

Differentiate wrt b :

$$\begin{aligned} -\frac{2n^2}{b^3} &= \frac{\cancel{2} n \sin\left(\frac{\theta}{2}\right) \frac{d\theta}{db} n^2 \sin^2\left(\frac{\theta}{2}\right) - \cancel{2} n^2 \cancel{\sin^2\left(\frac{\theta}{2}\right)} \cos\left(\frac{\theta}{2}\right) \frac{d\theta}{db}}{n^4 \sin^4\left(\frac{\theta}{2}\right)} \\ &= \frac{\left[n^3 \sin^3\left(\frac{\theta}{2}\right) - n^2 \sin\left(\frac{\theta}{2}\right) \cos\left(\frac{\theta}{2}\right)\right] \frac{d\theta}{db}}{n^4 \sin^4\left(\frac{\theta}{2}\right)} \end{aligned}$$

get same expression for $\frac{db}{d\theta}$ as before

$$\left[\text{recall } \frac{db}{d\theta} = \frac{1}{\left(\frac{d\theta}{db}\right)} \right]$$

obviously $b \leq a$

$$b = 0 \rightarrow \theta = 0$$

$$b = a \rightarrow 1 = \frac{1 - 2n \cos\left(\frac{\theta}{2}\right) + n^2}{n^2 \sin^2\left(\frac{\theta}{2}\right)}$$

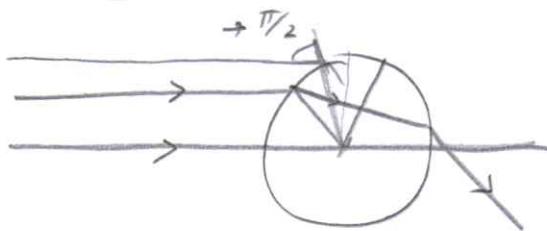
$$n^2 \sin^2\left(\frac{\theta}{2}\right) = 1 - 2n \cos\left(\frac{\theta}{2}\right) + n^2$$

$$\begin{aligned}\sigma &= 1 - 2n \cos\left(\frac{\theta}{2}\right) + n^2 \left(1 - \sin^2\left(\frac{\theta}{2}\right)\right) \\ &= 1 - 2n \cos\left(\frac{\theta}{2}\right) + n^2 \left(n^2 / \frac{4}{2}\right) \\ &= \left(1 - n \cos\left(\frac{\theta}{2}\right)\right)^2\end{aligned}$$

Thus, $\cos\left(\frac{\theta}{2}\right) = \frac{1}{n}$

$\boxed{\cos\left(\frac{\theta_{\max}}{2}\right) = \frac{1}{n}}$

~~max = 1 of last cycle~~



$$\sin \phi_i = \frac{b}{a}$$

$$b=a \rightarrow \phi_i = \frac{\pi}{2} \rightarrow \sin \phi_i = n \sin \phi_r$$

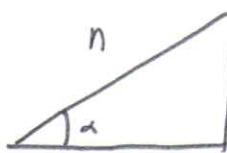
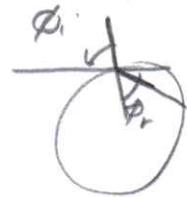


$$1 = n \sin \phi_r$$

$$\frac{1}{n} = \sin \phi_r$$

$$\begin{aligned}\theta = 2(\phi_i - \phi_r) &= 2\left(\frac{\pi}{2} - \arcsin\left(\frac{1}{n}\right)\right) \\ &= \pi - 2\arcsin\left(\frac{1}{n}\right)\end{aligned}$$

$$\frac{\theta}{2} = \frac{\pi}{2} - \arcsin\left(\frac{1}{n}\right) \rightarrow \cos\left(\frac{\theta}{2}\right) = \cos\left(\frac{\pi}{2} - \arcsin\left(\frac{1}{n}\right)\right)$$



$$\begin{aligned}&= \cos\left(\frac{\pi}{2} - \arcsin\left(\frac{1}{n}\right)\right) + \sin\left(\frac{\pi}{2} - \arcsin\left(\frac{1}{n}\right)\right) \\ &= \frac{1}{n}\end{aligned}$$

$$n = 5$$

$$\sin \alpha =$$

$$\text{So } \boxed{\cos\left(\frac{\theta}{2}\right) = \frac{1}{n}} \text{ when } b=a$$

Total cross section:

$$\sigma_T = \pi a^2 \quad (\text{obvious since no scattering for } b > a)$$

check by integrating:

$$\sigma_T = \int_{\theta_{\min}}^{\pi} \left(\frac{d\sigma}{d\Omega} \right) d\Omega, \quad d\Omega = 2\pi \sin \theta d\theta$$

$$= 2\pi \int_0^{2\arccos(\frac{1}{n})} d\theta \sin \theta \left(\frac{d\sigma}{d\Omega} \right)$$

$$= 2\pi \int_0^{2\arccos(\frac{1}{n})} d\theta \sin \theta$$

$$= \frac{\# \pi a^2 n^2}{4} \int_0^{2\arccos(\frac{1}{n})} d\theta \underbrace{\sin(\theta)}_{\sin(\frac{\theta}{2})} \frac{(n \cos(\frac{\theta}{2}) - 1)(n \cos(\frac{\theta}{2}) + 1)}{\left(1 - 2n \cos(\frac{\theta}{2}) + n^2\right)^2}$$

$$= \pi a^2 n^2 \int_0^{2\arccos(\frac{1}{n})} \underbrace{\sin(\frac{\theta}{2})}_{-\cos(\frac{\theta}{2})} d\theta \frac{(n \cos(\frac{\theta}{2}) - 1)(n \cos(\frac{\theta}{2}) + 1)}{\left(1 - 2n \cos(\frac{\theta}{2}) + n^2\right)^2}$$

$$\boxed{\begin{aligned} & \text{let } X = \cos(\frac{\theta}{2}) \\ & \theta = 0 \rightarrow X = 1 \\ & \theta = 2\arccos(\frac{1}{n}) \rightarrow X = \frac{1}{n} \end{aligned}}$$

$$= 2\pi a^2 n^2 \int_{\frac{1}{n}}^1 dx \frac{(nx - 1)(nx + 1)}{\left(1 - 2nx + n^2\right)^2}$$

$$\boxed{\begin{aligned} & X = \cos(\frac{\theta}{2}) \\ & dx = -\frac{1}{2} \sin(\frac{\theta}{2}) d\theta \quad y = nx \end{aligned}}$$



$$\sigma_T = 2\pi a^2 n^2 \int_{\frac{1}{n}}^1 dx \frac{(nx-1)(n-x)}{[(1+n^2) - 2nx]^2}$$

$$\begin{aligned} n-x &= n - \frac{(1+n^2)y}{2n} \\ &= \frac{(n^2-1)+4y}{2n} \end{aligned} \quad (9)$$

Let: $y = (1+n^2) - 2nx \quad x = \frac{(1+n^2)-y}{2n} \rightarrow nx-1 = \frac{(1+n^2)-y}{2} - 1$

$$dy = -2n dx \quad \rightarrow \quad dx = \frac{dy}{-2n}$$

$$\begin{aligned} x = \frac{1}{n} &\rightarrow u = (1+n^2) - 2n(\frac{1}{n}) = 1+n^2-2 = n^2-1 \\ x = 1 &\rightarrow u = (1+n^2) - 2n = \cancel{(1+n^2)} \cdot (n-1)^2 \end{aligned}$$

$$\begin{aligned} \sigma_T &= 2\pi a^2 n^2 \int_{(n-1)^2}^{n^2-1} \frac{dy}{2n} \frac{\left(\frac{(n^2-1)-y}{2}\right)}{u^2} \frac{\left(\frac{(n^2-1)+y}{2}\right)}{u^2} \\ &= 2\pi a^2 n^2 \frac{1}{8\pi n^2} \int_{(n-1)^2}^{(n^2-1)} \frac{dy}{u^2} \left(\frac{(n^2-1)-y}{2} \right) \left(\frac{(n^2-1)+y}{2} \right) \\ &= \frac{\pi}{4} a^2 \int_{(n-1)^2}^{n^2-1} du \frac{(n^2-1)^2 - y^2}{u^2} \\ &= \frac{\pi}{4} a^2 \int_{(n-1)^2}^{n^2-1} dy \left[\frac{(n^2-1)^2}{u^2} - 1 \right] \\ &= \frac{\pi}{4} a^2 \left\{ \left(n^2-1 \right)^2 \left(\frac{-1}{4} \right) \Big|_{(n-1)^2}^{n^2-1} - (n^2-1) + (n-1)^2 \right\} \\ &= \frac{\pi}{4} a^2 \left\{ -\left(n^2-1 \right)^2 / \frac{1}{n^2-1} - \frac{1}{(n-1)^2} - (n^2-1) + (n-1)^2 \right\} \\ &= \frac{\pi}{4} a^2 \left\{ -\left(n^2-1 \right) + (n+1)^2 - (n^2-1) + (n-1)^2 \right\} \\ &= \frac{\pi}{4} a^2 \left\{ -\cancel{n^2+1} + \cancel{n^2+2n+1} - \cancel{n^2+1} + \cancel{n^2+2n+1} \right\} = \boxed{\pi a^2} \end{aligned}$$

(5.4)

Problem (a) Total cross-section for particle falling into center $U(r) = -\frac{A}{r^2}$ ($A > 0$)

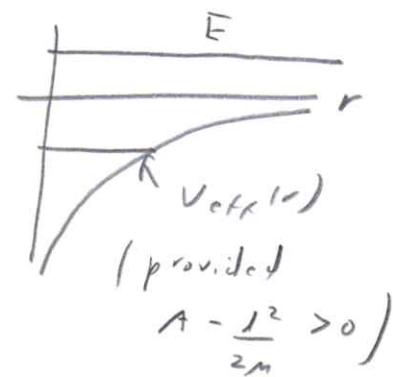
~~(b)~~

$$U_{\text{eff}}(r) = \frac{k^2}{2Mr^2} + U(r)$$

$$= \frac{k^2}{2Mr^2} - \frac{A}{r^2}$$

$$= -\frac{1}{r^2} \left(A - \frac{k^2}{2M} \right)$$

$$< 0 \quad \text{if} \quad A - \frac{k^2}{2M} > 0$$



particle falls
into center
for any E

$$\text{Now: } b = \mu b v_\infty$$

$$\text{so } A - \frac{\mu^2 b^2 v_\infty^2}{2M} > 0$$

$$\text{or } \frac{\mu b^2 v_\infty^2}{2} < A$$

$$b < \sqrt{\frac{2A}{\mu v_\infty^2}} \equiv b_{\max}$$

$$\sigma_T = \pi b^2$$

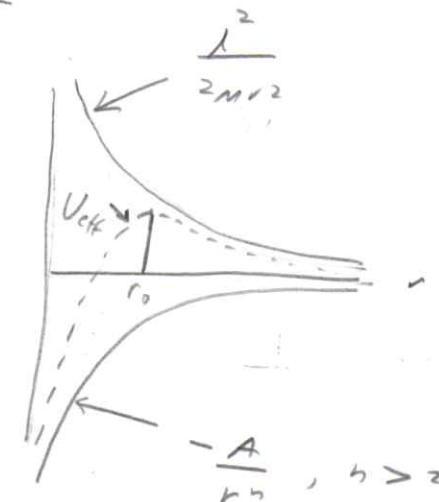
$$= \frac{\pi 2A}{M v_\infty^2}$$

$$\boxed{\frac{2\pi A}{M v_\infty^2}}$$

$$b) V(r) = -\frac{A}{r^n}, \quad A > 0, \quad n > 2$$

$$\begin{aligned} U_{\text{eff}}(r) &= V(r) + \frac{l^2}{2Mr^2} \\ &= -\frac{A}{r^n} + \frac{l^2}{2Mr^2} \end{aligned}$$

~~Particle fills to infinity~~



$$\begin{aligned} \frac{dU_{\text{eff}}}{dr} &= +n\frac{A}{r^{n+1}} - \frac{l^2}{Mr^3} \\ &= \frac{nA}{r^{n+1}} - \frac{l^2}{Mr^3} \end{aligned}$$

$$\left. \frac{dU_{\text{eff}}}{dr} \right|_{r=r_0} = 0 \iff \left. \frac{nA}{r^{n+1}} \right|_{r=r_0} = \left. \frac{l^2}{Mr^3} \right|_{r=r_0}$$

$$\left. \frac{nA}{r^{n+2}} \right|_{r=r_0} = \frac{l^2}{M}$$

$$\therefore \boxed{r_0 = \left(\frac{nMA}{l^2} \right)^{\frac{1}{n-2}}}$$

~~$$\frac{U_{\text{eff}}}{m \omega_x} = U_{\text{eff}}(r_0)$$~~

~~$$= -\frac{A}{\left(\frac{nMA}{l^2} \right)^{\frac{1}{n}}} + \frac{l^2}{2M \left(\frac{nMA}{l^2} \right)^{\frac{1}{n}}}$$~~

~~$$= -A \frac{2M \left(\frac{nMA}{l^2} \right)^{\frac{1}{n}}}{l^2} + \frac{l^2}{2M \left(\frac{nMA}{l^2} \right)^{\frac{1}{n}}} \left(-\frac{1}{2} \right)$$~~

~~$$2M \left(\frac{nMA}{l^2} \right)^{\frac{1-n}{2}}$$~~

$$= \frac{2\mu A \left(\frac{nMA}{\lambda^2} \right)^{\frac{1}{n}} + \lambda^2 \left(\frac{nMA}{\lambda^2} \right)^{-\frac{1}{2}}}{2M \left(\frac{nMA}{\lambda^2} \right)^{\frac{2-n}{2n}}}$$

$$\left| U_{eff} \right| = U_{eff}(r_0)$$

$$= -\frac{A}{r_0^n} + \frac{\lambda^2}{2Mr_0^2}$$

$$= -\frac{2\mu Ar_0^2 + \lambda^2 r_0^n}{2Mr_0^{n+2}}$$

$$= \frac{r_0^2 \left[-2\mu A + \lambda^2 r_0^{n-2} \right]}{2Mr_0^{n+2}}$$

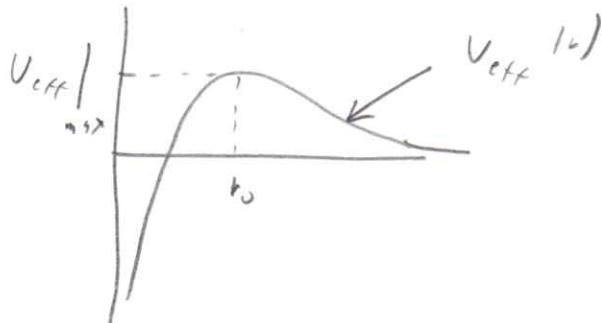
$$= \frac{1}{2Mr_0^n} \left[-2\mu A + \lambda^2 \frac{nMA}{\lambda^2} \right]$$

$$= \frac{(n-2)\mu A}{2\mu r_0^n}$$

$$= \frac{(n-2)A}{2} \quad \frac{1}{\left(\frac{nMA}{\lambda^2} \right)^{\frac{n}{n-2}}}$$

$$= \frac{(n-2)A}{2} \quad \frac{1}{\left(\frac{nMA}{\mu b^2 v_\infty^2} \right)^{\frac{n}{n-2}}}$$

$$= \frac{(n-2)A}{2} \quad \left(\frac{\mu b^2 v_\infty^2}{A_n} \right)^{\frac{n}{n-2}}$$



Need $E > V_{\text{eff}} / b_{\text{max}}$
for particle to stay $r_0 \parallel r_0$
regular

Total cross section $\sigma_T = \pi b_{\text{max}}^2$

Where b_{max} given by setting $E = V_{\text{eff}} / b_{\text{max}}$

$$\frac{1}{2} M v_\infty^2 = \frac{(n-2) A}{Z} \left(\frac{M b_{\text{max}}^2 v_\infty^2}{A n} \right)^{\frac{n}{n-2}}$$

$$\frac{M v_\infty^2}{A^{(n-2)}} = \left(\frac{M b_{\text{max}}^2 v_\infty^2}{A n} \right)^{\frac{n}{n-2}}$$

$$\left(\frac{M v_\infty^2}{A^{(n-2)}} \right)^{\frac{n-2}{n}} = \frac{M b_{\text{max}}^2 v_\infty^2}{A n}$$

$$\rightarrow b_{\text{max}}^2 = \frac{A_n}{M v_\infty^2} \left(\frac{M v_\infty^2}{A^{(n-2)}} \right)^{1 - \frac{2}{n}}$$

$$= n \left(\frac{M v_\infty^2}{A} \right)^{-\frac{2}{n}} \frac{1}{(n-2)^{\frac{n-2}{n}}}$$

$$= n (n-2)^{\frac{2-n}{n}} \left(\frac{A}{M v_\infty^2} \right)^{\frac{2}{n}}$$

so
$$\boxed{\sigma_T = \pi b_{\text{max}}^2 = \pi n (n-2)^{\frac{2-n}{n}} \left(\frac{A}{M v_\infty^2} \right)^{\frac{2}{n}}}$$

Particle motion in GR: (scattering calculation) (1)

56 57 $ds^2 = -\left(1 - \frac{2GM}{r_c^2}\right)c^2 dt^2 + \left(1 - \frac{2GM}{r_c^2}\right)^{-1} dr^2 + r^2 \left(\frac{d\theta^2}{1 - \frac{2GM}{r_c^2}} + \sin^2\theta d\phi^2\right)$
 $\theta = \frac{\pi}{2}$

No 4:

$$-E c^2 = -c^2 \left(1 - \frac{2GM}{r_c^2}\right) \left(\frac{dt}{d\lambda}\right)^2 + \left(1 - \frac{2GM}{r_c^2}\right)^{-1} \left(\frac{dr}{d\lambda}\right)^2 + r^2 \left(\frac{d\phi}{d\lambda}\right)^2$$

where $\begin{cases} E = 1 & \text{for massive particle} \\ \lambda = \tau & (\text{proper time}) \end{cases}$

or $E = 0, \lambda = \text{affine parameter}$ For photon

~~Defn~~
Conserved quantities $E = \left(1 - \frac{2GM}{r_c^2}\right) \left(\frac{dt}{d\lambda}\right) c^2$
 $L = r^2 \frac{d\phi}{d\lambda}$

E, L $\begin{cases} \text{energy, momentum of photons} \\ \frac{\text{energy}}{m}, \frac{\text{momentum}}{m} \text{ for massive particle of mass } m \end{cases}$

So:

$$-E c^2 = -c^2 \left(1 - \frac{2GM}{r_c^2}\right) \frac{\left(\frac{E}{c^2}\right)^2}{\left(1 - \frac{2GM}{r_c^2}\right)^2} + \left(1 - \frac{2GM}{r_c^2}\right)^{-1} \left(\frac{dr}{d\lambda}\right)^2 + r^2 \left(\frac{L^2}{r^4}\right)$$

$$-E c^2 = -\left(1 - \frac{2GM}{r_c^2}\right)^{-1} \frac{E^2}{c^2} + \left(1 - \frac{2GM}{r_c^2}\right)^{-1} \left(\frac{dr}{d\lambda}\right)^2 + \frac{L^2}{r^2}$$

$$-E c^2 \left(1 - \frac{2GM}{r_c^2}\right) = -\frac{E^2}{c^2} + \left(\frac{dr}{d\lambda}\right)^2 + \left(1 - \frac{2GM}{r_c^2}\right) \frac{L^2}{r^2}$$

$$\frac{1}{2} \left(\frac{dr}{d\lambda} \right)^2 + \frac{1}{2} \left(1 - \frac{2GM}{rc^2} \right) \frac{L^2}{r^2} + \frac{1}{2} \epsilon c^2 \left(1 - \frac{2GM}{rc^2} \right) = \frac{1}{2} \frac{E^2}{c^2}$$

$$\boxed{\frac{1}{2} \left(\frac{dr}{d\lambda} \right)^2 + V_{\text{eff}}(r) = \frac{1}{2} \frac{E^2}{c^2}}$$

$$\text{where } V_{\text{eff}}(r) = \frac{1}{2} \left(1 - \frac{2GM}{rc^2} \right) \left(\frac{L^2}{r^2} + \epsilon c^2 \right)$$

$$= \left(1 - \frac{2GM}{rc^2} \right) \cancel{\left(\frac{L^2}{r^2} + \epsilon c^2 \right)} \left(\frac{1}{2} \right) \left(\frac{L^2}{r^2} + \epsilon c^2 \right)$$

~~$\frac{L^2}{r^2}$~~

$$= \frac{1}{2} \left\{ \frac{L^2}{r^2} - \frac{2GML^2}{c^2 r^3} + \epsilon c^2 - \frac{2GM\epsilon}{r} \right\}$$

$$= \frac{1}{2} \epsilon c^2 - \underbrace{\epsilon \frac{GM}{r} + \frac{L^2}{2r^2} - \frac{GML^2}{c^2 r^3}}_{\substack{\text{Newtonian grav. pr} \\ \text{for massive part.}}} - \underbrace{\frac{GM}{c^2 r^3}}_{\substack{\text{G-R} \\ \text{correction}}}$$

$$\frac{dr}{d\lambda} = \sqrt{2 \left(\frac{1}{2} \frac{E^2}{c^2} - V_{\text{eff}}(r) \right)}$$

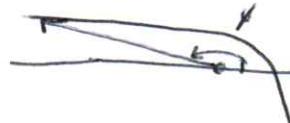
$$\text{Turning point: } R \text{ where } \left. \frac{dr}{d\lambda} \right|_{r=R} = 0$$

$$\frac{1}{2} \frac{E^2}{c^2} - V_{\text{eff}}(R) = 0$$

$$\frac{1}{2} \frac{E^2}{c^2} = V_{\text{eff}}(R)$$

$$= \frac{1}{2} \epsilon c^2 - \epsilon \frac{GM}{R} + \frac{L^2}{2R^2} - \frac{GML^2}{c^2 R^3}$$

$$\frac{d\phi}{dr} = \frac{d\phi}{dr} \frac{dr}{d\tau}$$



$$= \frac{L}{r^2} \sqrt{\frac{1}{2 \left(\frac{1}{2} \frac{\dot{E}^2}{c^2} - V_{eff}(r) \right)}}$$

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Fate - sign
since $\phi \downarrow$ or
 $r \rightarrow \infty$ goes from
 ∞ to $r_{min} \in R$)

$$\frac{L}{r^2} \sqrt{\frac{1}{\left(\frac{1}{2}\epsilon c^2 - \epsilon \frac{GM}{R} + \frac{L^2}{2r^2} - \frac{GML^2}{c^2 R^3} - \frac{1}{2}\epsilon c^2 + \epsilon \frac{GM}{r} - \frac{L^2}{2r^2} + \frac{GML^2}{c^2 r^3}\right)}}$$

$= \overbrace{W^T R^T}^{R^T} R \overbrace{A' M}^Z M$

VERA

$\therefore \sqrt{r^2 + R^2 - 2Rr \cos \theta}$

$$= \frac{L}{r^2} \sqrt{\frac{1}{2 \left(-\epsilon GM \left(\frac{1}{R} - \frac{1}{r} \right) + \frac{L^2}{2} \left(\frac{1}{R^2} - \frac{1}{r^2} \right) - \frac{GML^2}{c^2} \left(\frac{1}{R^3} - \frac{1}{r^3} \right) }}}$$

$$d\phi = \frac{L}{r^2} \frac{dr}{\sqrt{1 - \frac{2M}{r}}}$$

$$= \frac{L}{R} \frac{(-dy)}{\sqrt{}} \quad \text{(Note: The denominator is implied to be 1)}$$

$$u = \frac{R}{r}$$

$$\frac{1}{r} = \frac{1}{R}$$

$$\frac{d\phi}{dt} = \frac{-du}{\sqrt{\frac{2R^2}{L^2} \left(-\epsilon GM \left(\frac{1}{R} - \frac{1}{r} \right) + \frac{L^2}{2} \left(\frac{1}{R^2} - \frac{1}{r^2} \right) - \frac{GM L^2}{c^2 R^3} \left(\frac{1}{R^3} - \frac{1}{r^3} \right) }}$$

$$= \frac{-du}{\sqrt{\frac{2R^2}{L^2} \left(-\epsilon \frac{GM}{R} (1-u) + \frac{L^2}{2R^2} (1-u^2) - \frac{GM L^2}{c^2 R^3} (1-u^3) \right)}}$$

$$= \frac{-du}{\sqrt{\frac{2}{L^2} u (1-u^2) - \epsilon \frac{2GM R (1-u)}{L^2} - \frac{2GM}{R c^2} (1-u^3)}}$$

$$= \frac{-du}{\sqrt{1-u^2} \sqrt{1 - \epsilon \frac{2GM R (1-u)}{L^2 (1-u^2)} - \frac{2GM}{R c^2} (1-u^3)}}$$

$$= \frac{-du}{\sqrt{1 + A \left(\frac{1-u}{1-u^2} \right) + B \left(\frac{1-u^3}{1-u^2} \right)}}$$

$$\phi_m = \pi \int_0^1 \frac{du / \sqrt{1-u^2}}{\sqrt{1 + A \left(\frac{1-u}{1-u^2} \right) + B \left(\frac{1-u^3}{1-u^2} \right)}}$$

$A = -\epsilon \frac{2GM R}{L^2}$
 $B = -\frac{2GM}{R c^2}$

Approximations:

$$\frac{1}{\sqrt{1+A\left(\frac{1-u}{1-u^2}\right)+B\left(\frac{1-u^3}{1-u^2}\right)}} \approx 1 - \frac{1}{2}A\left(\frac{1-u}{1-u^2}\right) - \frac{1}{2}B\left(\frac{1-u^3}{1-u^2}\right)$$

$$\phi_u = \pi - \left\{ \underbrace{\int_0^1 \frac{du}{\sqrt{1-u^2}}}_{I_1} - \underbrace{\frac{1}{2}A \int_0^1 \frac{du}{\sqrt{1-u^2}} \left(\frac{1-u}{1-u^2} \right)}_{I_2} - \underbrace{\frac{1}{2}B \int_0^1 \frac{du}{\sqrt{1-u^2}} \left(\frac{1-u^3}{1-u^2} \right)}_{I_3} \right\}$$

$$I_1 = \int_0^1 \frac{du}{\sqrt{1-u^2}}$$

$u = \cos \theta$
 $du = -\sin \theta d\theta$

$u=0, 1 \rightarrow \theta=\frac{\pi}{2}, 0$

$$= - \int_{-\frac{\pi}{2}}^0 \frac{\cancel{\sin \theta} d\theta}{\cancel{\sin \theta}} = + \int_0^{\frac{\pi}{2}} d\theta = \boxed{\frac{\pi}{2}}$$

$$I_2 = \int_0^1 \frac{du}{\sqrt{1-u^2}} \underbrace{\left(\frac{1-u}{1-u^2} \right)}_{\frac{1}{1+u}} = \int_0^{\frac{\pi}{2}} d\theta \underbrace{\left(\frac{1}{1+\cos \theta} \right)}_{d\left(t_{\tan}\left(\frac{\theta}{2}\right)\right)} = t_{\tan}\left(\frac{\pi}{2}\right) \int_0^{\frac{\pi}{2}} = \boxed{1}$$

$$I_3 = \int_0^1 \frac{du}{\sqrt{1-u^2}} \left(\frac{1-u^3}{1-u^2} \right) = \int_0^1 \frac{du}{\sqrt{1-u^2}} \frac{(1-u)(1+u+u^2)}{(1-u)(1+u)}$$

$$= \int_0^1 \frac{du}{\sqrt{1-u^2}} \left[\frac{1}{1+u} + u \right] \quad \frac{1+u+u^2}{1+u} = \frac{1+u(1+u)}{1+u}$$

$$= \int_0^{\frac{\pi}{2}} d\theta \left[\frac{1}{1+\cos \theta} + \cos \theta \right] \quad = \frac{1}{1+u} + u$$

$$= 1 + \int_0^{\frac{\pi}{2}} \cos \theta d\theta$$

$$= 1 + \sin \theta \Big|_0^{\frac{\pi}{2}} = \boxed{2}$$

thus,

$$\begin{aligned}\phi_m &= \pi - \left[\frac{\pi}{2} - \frac{1}{2} A \cdot 1 - \frac{1}{2} B \cdot 2 \right] \\ &= \frac{\pi}{2} + \frac{A}{2} + B\end{aligned}$$

$$\begin{aligned}\theta &= \pi - 2\phi_m \\ &= \pi - 2 \left(\frac{\pi}{2} + \frac{A}{2} + B \right) \\ &= -A - 2B \\ &= -\frac{e \frac{2GM}{L^2}}{c^2} + \frac{4GM}{R_c^2}\end{aligned}$$

For small angle deflection $R \approx b$ (b = closest approach
= impact parameter)

Then:

$$\begin{aligned}\theta &= e \frac{2GM}{L^2} + \frac{4GM}{b c^2} \\ &= \frac{2GM}{b c^2} \left(\frac{e b c^2}{L^2} + 2 \right)\end{aligned}$$

Light: $e=0 \rightarrow \boxed{\theta = \frac{4GM}{b c^2}}$

Massive particle $e=1 \rightarrow \theta = \frac{2GM}{b c^2} \left(\frac{b c^2}{L^2} + 2 \right)$

$$\begin{aligned}L &= \frac{e}{\mu} = \cancel{\frac{e}{\mu}} \frac{b}{\mu} \sqrt{\frac{E^2 - E_0^2}{c^2}} \quad (= b_p) \\ &= \frac{b}{\mu} \sqrt{\frac{\gamma^2 \mu^2 c^4 - \mu^2 c^4}{c^2}} \\ &= b c \sqrt{\gamma^2 - 1} = \boxed{\frac{b c \beta}{\sqrt{1-\beta^2}}} = \frac{b V_{\infty}}{\sqrt{1-\beta^2}}\end{aligned}$$

$$\gamma = \frac{1}{\sqrt{1-\beta^2}} \rightarrow \gamma^2 = \frac{1}{1-\beta^2} \rightarrow \gamma^2 - 1 = \frac{1}{1-\beta^2} - 1 = \frac{\beta^2}{1-\beta^2}$$

(7)

140,

$$\theta = \frac{2GM}{bc^2} \left(\frac{1}{\beta^2} (1 - \beta^2) + 2 \right)$$

$$= \frac{2GM}{bc^2} \left(\frac{1}{\beta^2} - 1 + 2 \right)$$

$$= \frac{2GM}{bc^2} \left(\frac{1}{\beta^2} + 1 \right)$$

$$= \boxed{\frac{2GM}{bc^2 \beta^2} (1 + \beta^2)}$$

Grundthyr & Rydbergs:

$$\begin{array}{l} \text{P. 96} \\ \left(\begin{smallmatrix} 2.264 \\ \# 8 \end{smallmatrix} \right) \end{array} \quad \int \frac{x^3 dx}{\sqrt{R^3}} = \frac{c \Delta x^2 + b (10ac - 3b^2)x + a (8ac - 3b^2)}{c^2 \Delta \sqrt{R}} \\ \text{or} \quad - \frac{3b}{2c^2} \int \frac{dx}{\sqrt{R}}$$

$$\begin{array}{l} \text{P. 94} \\ \left(\begin{smallmatrix} 2.261 \\ \# 8 \end{smallmatrix} \right) \end{array} \quad \int \frac{dx}{\sqrt{R}} = - \frac{1}{\sqrt{-\Delta}} \arcsin \left(\frac{2cx+b}{\sqrt{-\Delta}} \right) \\ c < 0, \quad \Delta < 0$$

where $R = a + bx + cx^2$
 $\Delta = 4ac - b^2$
 $-\Delta = b^2 - 4ac$

suppose: $c = -1, b = 0, a = \frac{1}{b^2}$ $\rightarrow \Delta = 4ac - b^2 = -\frac{4}{b^2}$
 $\sqrt{-\Delta} = \frac{2}{b}$

$$\int \frac{dy}{\left(\frac{1}{b^2} - y^2\right)^{\frac{1}{2}}} = -\frac{1}{\sqrt{1+y^2}} \arcsin \left(\frac{-2y}{\left(\frac{2}{b}\right)} \right) = -\arcsin \left(-by \right) + \text{const}$$

$$\begin{array}{l} \text{P. 96:} \\ \left(\begin{smallmatrix} 2.264 \\ \# 5 \end{smallmatrix} \right) \end{array} \quad \int \frac{dx}{\sqrt{R^3}} = \frac{2(2cx+b)}{\Delta \sqrt{R}} \quad \text{or}$$

- For Schwarzschild

$$d\tau^2 = - \left(1 - \frac{2M}{r}\right) dt^2 \quad (160)$$

for fixed (r, θ, ϕ) .

- Thus, the periods between emission and reception at $r = r_A$ and $r = r_B$ are related by

$$\frac{\Delta\tau_B}{\Delta\tau_A} = \left(\frac{1-2M/r_B}{1-2M/r_A}\right)^{1/2} \quad (161)$$

- The frequencies ($\omega_{A,B} := 2\pi/\Delta\tau_{A,B}$) are thus related by

$$\frac{\omega_B}{\omega_A} = \left(\frac{1-2M/r_A}{1-2M/r_B}\right)^{1/2} \quad (162)$$

- Hence, taking $r_B \rightarrow \infty$, $\omega_B = \omega_\infty$, $r_A = R$, $\omega_A = \omega$ yields

$$\omega_\infty = \omega \sqrt{1 - \frac{2M}{R}} \quad (163)$$

This is the gravitational redshift formula for Schwarzschild spacetime.

- The above expression reduces to the weak-field result in the limit of large R :

$$\omega_\infty \approx \omega \left(1 - \frac{M}{R}\right) \quad (164)$$

7.3 Particle motion in Newtonian gravity

- For a spherically symmetric source of attraction $V = -GMm/r$, total energy

$$E = \frac{1}{2}m|\vec{v}|^2 + V(r) \quad (165)$$

and angular momentum

$$\vec{L} = \vec{r} \times \vec{p} \quad (166)$$

are conserved.

- Using spherical symmetry to restrict to motion in the equatorial plane ($\theta = \pi/2$):

$$L = |\vec{r} \times \vec{p}| = mr^2 \frac{d\phi}{dt} \quad (167)$$

- In terms of L , the total total energy can be written as

$$E = \frac{1}{2}m \left(\frac{dr}{dt}\right)^2 + V_{\text{eff}}(r) \quad (168)$$

where the *effective potential* is given by

$$V_{\text{eff}}(r) := -\frac{GMm}{r} + \frac{1}{2} \frac{L^2}{mr^2} \quad (169)$$

- Exercise: Prove the above.
- The effective potential $V_{\text{eff}}(r)$ goes to zero (from below) as $r \rightarrow \infty$; it goes to ∞ at $r = 0$; and it has a minimum at $r = r_{\min} := L^2/GMm^2$. The minimum value of the effective potential is also the minimum allowed value of the energy given by $E_{\min} := -G^2M^2m^3/2L^2$.
- Exercise: Prove the above statements.
- There are three types of trajectories depending on the value of E :
 - (i) $E = E_{\min}$: A stable circular orbit at $r = r_{\min}$.
 - (ii) $E_{\min} < E < 0$: Bound orbits between turning points $r = r_1$ and $r = r_2$ ($r_1 < r_2$). These bound orbits are actually ellipses (discussed in more detail later).
 - (iii) $E \geq 0$: Scattering orbits that come in from $r = \infty$, make a closest approach at $r = r_1$, and then return to ∞ . ($E = 0$ is a parabola, $E > 0$ are hyperbolae.)

- Exercise: Show that for the circular orbit at $r = r_{\min}$, Kepler's 3rd law holds in the form

$$\Omega^2 = \frac{GM}{r_{\min}^3} \quad (170)$$

where $\Omega := d\phi/dt$ (which is constant for a circular orbit).

- To prove that the trajectories correspond to circles, ellipses, parabolas, etc., we need to find $\phi(r)$. Hence, we need to integrate

$$\frac{d\phi}{dr} = \frac{d\phi}{dt} \frac{dt}{dr} = \frac{L}{mr^2} \left[\frac{2}{m}(E - V_{\text{eff}}(r)) \right]^{-1/2} \quad (171)$$

- The integral is most simply done by making a change of variables to $u := 1/r$. Using (for $a < 0$)

$$\int \frac{du}{\sqrt{au^2 + bu + c}} = \frac{-1}{\sqrt{-a}} \sin^{-1} \left[\frac{2au + b}{\sqrt{b^2 - 4ac}} \right] \quad (172)$$

one can show that

$$\phi(r) = \phi_0 + \sin^{-1} \left[\frac{2au + b}{\sqrt{b^2 - 4ac}} \right] \quad (173)$$

where

$$a = \frac{-L^2}{m^2}, \quad b = 2GM, \quad c = \frac{2E}{m}, \quad u = \frac{1}{r} \quad (174)$$

- Exercise: Prove the above.
- Taking ϕ_0 to be the value of $\phi(r)$ at closest approach, one eventually finds

$$r(\phi) = \frac{\alpha}{1 + \epsilon \cos \phi} \quad (175)$$

where

$$\alpha = \frac{L^2}{GMm^2}, \quad \epsilon = \left(1 + \frac{2EL^2}{G^2M^2m^3} \right)^{1/2} \quad (176)$$

- Exercise: Prove the above.

- The equation

$$r(\phi) = \frac{\alpha}{1 + \epsilon \cos \phi} \quad (177)$$

corresponds to a *conic section*—i.e., a cut of a right circular cone by a plane with slope ϵ relative to horizontal. $\epsilon = 0$ corresponds to a circle; $0 < \epsilon < 1$ corresponds to ellipses; $\epsilon = 1$ corresponds to a parabola; and $\epsilon > 1$ corresponds to hyperbolae.

- For fixed L , the allowed values of ϵ are determined by the allowed values for E . In particular, $E = E_{\min}$ corresponds to $\epsilon = 0$; $E_{\min} < E < 0$ corresponds to $0 < \epsilon < 1$; $E = 0$ corresponds to $\epsilon = 1$; $E > 0$ corresponds to $\epsilon > 1$.
- For an ellipse, ϵ is the *eccentricity* and 2α is the *latus rectum*. (In terms of the semi-major axis a of an ellipse, a , α and ϵ are related by $\alpha = a(1 - \epsilon^2)$.)
- Exercise: Explicitly show that, for an ellipse with eccentricity ϵ and latus rectum 2α , the radial distance r from a point P on the ellipse to the focus satisfies Eq. (177), where ϕ is the angle between the line connecting the focal point to P and the semi-major axis.

7.4 Particle motion in Schwarzschild spacetime

- For Schwarzschild, the energy (at infinity) per unit particle rest mass

$$e := \frac{E}{m} = \left(1 - \frac{2M}{r}\right) \frac{dt}{d\tau} = -\frac{1}{m} g_{t\alpha} p^\alpha \quad (178)$$

and angular momentum per unit particle rest mass

$$\ell := \frac{L}{m} = r^2 \sin^2 \theta \frac{d\phi}{d\tau} = \frac{1}{m} g_{\phi\alpha} p^\alpha \quad (179)$$

are conserved.

- Since the Schwarzschild geometry is spherically symmetric, the trajectory will be in a 2-d plane. Taking this to be the equatorial plane ($\theta = \pi/2$),

$$\ell = r^2 \frac{d\phi}{d\tau} \quad (180)$$

- Exercise: Using the above conserved quantities, show that

$$-1 = \mathbf{u} \cdot \mathbf{u} = g_{\alpha\beta} u^\alpha u^\beta \quad (181)$$

is equivalent to

$$\mathcal{E} = \frac{1}{2} \left(\frac{dr}{d\tau} \right)^2 + V_{\text{eff}}(r) \quad (182)$$

where

$$\mathcal{E} := \frac{e^2 - 1}{2} \quad (183)$$

and

$$V_{\text{eff}}(r) := -\frac{M}{r} + \frac{\ell^2}{2r^2} - \frac{M\ell^2}{r^3} \quad (184)$$

- NOTE: The last term $-M\ell^2/r^3$ in the effective potential is what's responsible for the differences between Newtonian gravity and GR for particle motion in a spherically symmetric potential—e.g., the perihelion precession of Mercury, existence of plunge orbits, etc.
- The shape of the effective potential $V_{\text{eff}}(r)$ depends on the value of ℓ^2/M^2 .
- If $\ell^2/M^2 > 12$, the effective potential has two extrema corresponding to a local maximum and local minimum. The extreme values of r are given by

$$r = r_{\max} := \frac{\ell^2}{2M} \left[1 \pm \sqrt{1 - \frac{12M^2}{\ell^2}} \right]. \quad (185)$$

- Exercise: Prove the above statements. (Hint: The local maximum and minimum are determined by setting $dV_{\text{eff}}(r)/dr = 0$.)
- If $\ell^2/M^2 = 12$, the effective potential has a point of inflection at $r_{\min} = r_{\max} = 6M =: r_{\text{ISCO}}$. This is the radius of the Innermost Stable Circular Orbit, hence the acronym ISCO.
- If $\ell^2/M^2 < 12$, the effective potential has no local maxima or minima.
- For $\ell^2/M^2 > 12$, there are five types of trajectories depending on the value of \mathcal{E} :
 - (i) $\mathcal{E} = \mathcal{E}_{\min}$: A stable circular orbit at $r = r_{\min}$.
 - (ii) $\mathcal{E}_{\min} < \mathcal{E} < 0$: Bound orbits between turning points $r = r_1$ and $r = r_2$ ($r_1 < r_2$). Unlike the case for Newtonian gravity, these bound orbits are not closed; they are ellipses whose turning points precess (more about this later).
 - (iii) $0 \leq \mathcal{E} < \mathcal{E}_{\max}$: Scattering orbits that come in from $r = \infty$, make a closest approach at $r = r_1$, and then return to ∞ . (The particle can actually orbit around the centre of curvature a number of times before returning to ∞ .)
 - (iv) $\mathcal{E} = \mathcal{E}_{\max}$: An unstable circular orbit at $r = r_{\max}$. Unstable circular orbits do not exist for Newtonian gravity.
 - (v) $\mathcal{E} > \mathcal{E}_{\max}$: A plunge orbit in which the particle comes in from $r = \infty$ and eventually hits the surface of the star or falls inside the event horizon ($r = 2M$) of a black hole. These plunge orbits do not exist for Newtonian gravity.

- Exercise: Show that for the stable circular orbit at $r = r_{\min}$, Kepler's 3rd law holds in the form

$$\Omega^2 = \frac{M}{r_{\min}^3} \quad (186)$$

where $\Omega := d\phi/dt$ (note the derivative with respect to t not τ).

- Bound orbits precess. If we define

$$\delta\phi_{\text{prec}} := \Delta\phi - 2\pi \quad (187)$$

where $\Delta\phi$ is calculated from one turning point $r = r_1$ back to $r = r_1$, one can show that the first-order correction to the Newtonian result ($\delta\phi_{\text{prec}} = 0$) is

$$\delta\phi_{\text{prec}} \approx \frac{6\pi G}{c^2} \frac{M}{a(1-\epsilon^2)} \quad (188)$$

- The largest precession occurs for small a and large ϵ —i.e., Mercury in our solar system. Substituting the values for Mercury gives $\delta\phi_{\text{prec}} \approx 43$ arcseconds per century, in agreement with observation. This retrodiction was one of the major triumphs of GR.
- Radial infall from rest at $r = \infty$ has $\mathcal{E} = 0$, $\ell = 0$, $\theta = \text{const}$, and $\phi = \text{const}$. The effective potential simplifies to $V_{\text{eff}}(r) = -M/r$ and the radial equation can be written as

$$\frac{d\tau}{dr} = -\sqrt{\frac{r}{2M}} \quad (189)$$

It has solution

$$\tau - \tau_* = -\frac{2}{3} \frac{1}{\sqrt{2M}} r^{3/2} \quad (190)$$

where $\tau = \tau_*$ corresponds to $r = 0$.

- Note that it takes a *finite* amount of proper time to fall from any finite r (e.g., $r = 10M$) to $r = 2M$.
- The same radial infall, described in terms of the Schwarzschild coordinate time t , satisfies the differential equation

$$\frac{dt}{dr} = \frac{dt}{d\tau} \frac{d\tau}{dr} = -\sqrt{\frac{r}{2M}} \left(1 - \frac{2M}{r}\right)^{-1} \quad (191)$$

- This has solution

$$t - t_* = 2M \left[-\frac{2}{3} \left(\frac{r}{2M}\right)^{3/2} - 2 \left(\frac{r}{2M}\right)^{1/2} + \log \left| \frac{\sqrt{r/2M} + 1}{\sqrt{r/2M} - 1} \right| \right] \quad (192)$$

where $t = t_*$ corresponds to $r = 0$.

- Exercise: Prove the above.
- Note that, contrary to what we found for proper time, it takes an *infinite* amount of coordinate time to fall from any finite r (e.g., $r = 10M$) to $r = 2M$.

7.5 Light rays in Schwarzschild spacetime

- For light rays in Schwarzschild spacetime, the energy (at infinity)

$$e := \left(1 - \frac{2M}{r}\right) \frac{dt}{d\lambda} = -g_{t\alpha} p^\alpha \quad (193)$$

and angular momentum

$$\ell := r^2 \sin^2 \theta \frac{d\phi}{d\lambda} = g_{\phi\alpha} p^\alpha \quad (194)$$

are conserved, where $p^\alpha := dx^\alpha/d\lambda$ with λ an affine parameter for the motion.

- Spherical symmetry implies motion in a 2-d plane. Taking this to be the equatorial plane ($\theta = \pi/2$),

$$\ell = r^2 \frac{d\phi}{d\lambda} \quad (195)$$

- Exercise: Using the above conserved quantities, show that

$$0 = \mathbf{u} \cdot \mathbf{u} = g_{\alpha\beta} u^\alpha u^\beta \quad (196)$$

implies

$$\frac{1}{b^2} = \frac{1}{\ell^2} \left(\frac{dr}{d\lambda} \right)^2 + W_{\text{eff}}(r) \quad (197)$$

where

$$b^2 := \frac{\ell^2}{e^2} \quad (198)$$

and

$$W_{\text{eff}}(r) := \frac{1}{r^2} \left(1 - \frac{2M}{r} \right) \quad (199)$$

- NOTE: The motion depends only on the ratio ℓ/e , since a different choice of affine parameter changes the values of ℓ and e , but not their ratio.
- b has the interpretation of an *impact parameter*—it is the perpendicular distance (at large r) between the direction of the light ray and a parallel line passing through the centre of curvature. In other words, $\ell = bp$ at large r , where p is the magnitude of the linear momentum.
- The shape of the effective potential $W_{\text{eff}}(r)$ is independent of ℓ .
- The effective potential has one extremum corresponding to a local maximum at $r = r_{\text{max}} = 3M$. The value of $W_{\text{eff}}(r)$ at $r = 3M$ is

$$W_{\text{max}} := W_{\text{eff}}(r = 3M) = \frac{1}{27M^2} \quad (200)$$

$W_{\text{eff}}(r)$ goes to zero (from above) as $r \rightarrow \infty$; it equals 0 at $r = 2M$.

- Exercise: Prove the above.

- There are three types of trajectories depending on the value of $1/b^2$:

(i) $0 < 1/b^2 < W_{\text{max}}$: Scattering orbits that come in from $r = \infty$, make a closest approach at $r = r_1$, and then return to ∞ . (The light ray can actually orbit around the centre of curvature a number of times before returning to ∞ .) Hence light is deflected by a spherically symmetric potential in GR.

(ii) $1/b^2 = W_{\text{max}}$: A unstable circular orbit at $r = r_{\text{max}} = 3M$.

(iii) $1/b^2 > W_{\text{max}}$: A plunge orbit in which light comes in from $r = \infty$ and eventually hits the surface of the star or falls inside the event horizon ($r = 2M$) of a black hole.

Note that a small impact parameter b means small angular momentum ℓ , and hence a greater chance for capture by the star or black hole.

- To determine the deflection of light, one needs to integrate

$$\frac{d\phi}{dr} = \frac{d\phi}{d\lambda} \frac{d\lambda}{dr} = \pm \frac{1}{r^2} \left[\frac{1}{b^2} - W_{\text{eff}}(r) \right]^{-1/2} \quad (201)$$

- We define the deflection angle via

$$\delta\phi_{\text{def}} := \Delta\phi - \pi \quad (202)$$

where

$$\Delta\phi := 2 \int_{\infty}^{r_1} \frac{d\phi}{dr} dr \quad (203)$$

with r_1 being the closest approach of the trajectory.

- Keeping only the leading order correction terms to the Newtonian result, we find

$$\delta\phi_{\text{def}} \approx \frac{4GM}{bc^2} \quad (204)$$

- Exercise: Prove the above.

- For light grazing the Sun (i.e., $M = M_{\odot}$, $b = R_{\odot}$), $\delta\phi_{\text{def}} \approx 1.7$ arcseconds, which was verified by Eddington in 1919 during a solar eclipse. This prediction was another major success of GR.
- The deflection of light as it passes a source of curvature also gives rise to a *time delay* effect, as compared to straight line travel time in Newtonian gravity.
- To calculate the excess time delay one needs to integrate

$$\frac{dt}{dr} = \frac{dt}{d\lambda} \frac{d\lambda}{dr} = \pm \frac{1}{b} \left(1 - \frac{2M}{r}\right)^{-1} \left[\frac{1}{b^2} - W_{\text{eff}}(r)\right]^{-1/2} \quad (205)$$

- Consider sending light or a radar signal from the Earth (past the Sun) to a reflector located at r_R , and then waiting for the reflected signal. The total travel time of the signal is given by

$$(\Delta t)_{\text{tot}} = 2t(r_{\oplus}, r_1) + 2t(r_R, r_1) \quad (206)$$

where r_1 is the closest approach to the Sun, r_{\oplus} and r_R are distances of the Earth and reflector from the Sun, and $t(r, r_1)$ is the time that it takes the signal to travel from r to r_1 .

- We define the excess time delay as

$$(\Delta t)_{\text{excess}} := (\Delta t)_{\text{tot}} - 2\sqrt{r_{\oplus}^2 - r_1^2} - 2\sqrt{r_R^2 - r_1^2} \quad (207)$$

where the last two terms give the travel time from Newtonian theory.

- If we assume $r_1 \ll r_{\oplus}$ and r_R , and carry out the calculation keeping only the first-order correction terms, we find

$$(\Delta t)_{\text{excess}} \approx \frac{4GM}{c^3} \left[\log\left(\frac{4r_R r_{\oplus}}{r_1^2}\right) + 1 \right] \quad (208)$$

- Exercise: Prove the above.

- The excess time delay has also been confirmed experimentally.