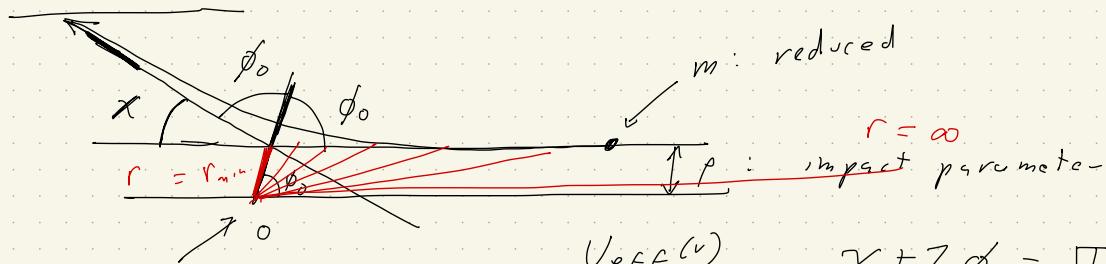


Lecture #16 Thurs 10/14

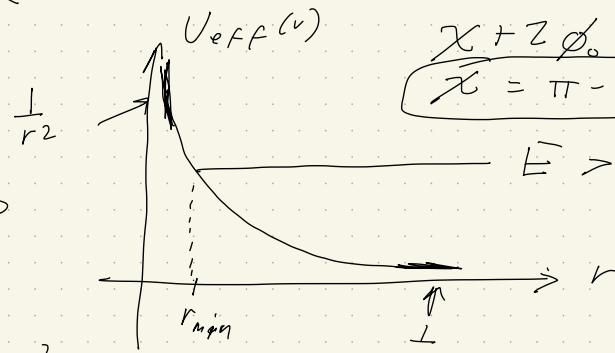


COM
of original
system

$$U(r) = \frac{\alpha}{r}, \quad \alpha > 0$$

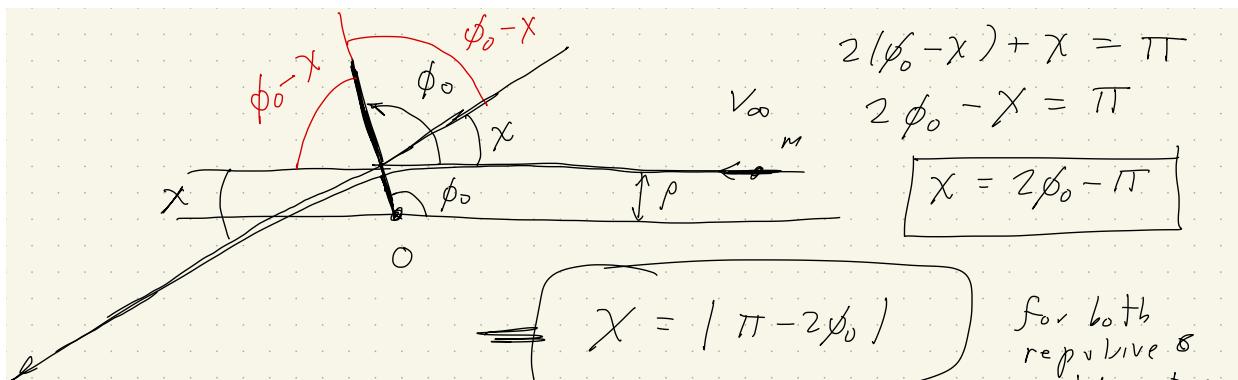
(repulsive)

$$\begin{aligned} U_{\text{eff}}(r) &= U(r) + \frac{M_z^2}{2mr^2} \\ &= \frac{\alpha}{r} + \frac{M_z^2}{2mr^2} \end{aligned}$$



$$E = U_{\text{eff}}(r_{\min})$$

↑
turning point



$$2(\phi_0 - \chi) + \chi = \pi$$

$$2\phi_0 - \chi = \pi$$

$$\boxed{\chi = 2\phi_0 - \pi}$$

$\chi = |\pi - 2\phi_0|$
for both
repulsive &
attractive

$$U(r) = -\frac{\alpha}{r}$$

$$U_{\text{eff}}(r) = -\frac{\alpha}{r} + \frac{M_z^2}{2mr^2}$$



$$\boxed{E = \frac{1}{2}mv_\infty^2, \quad M = m\rho v_\infty}$$

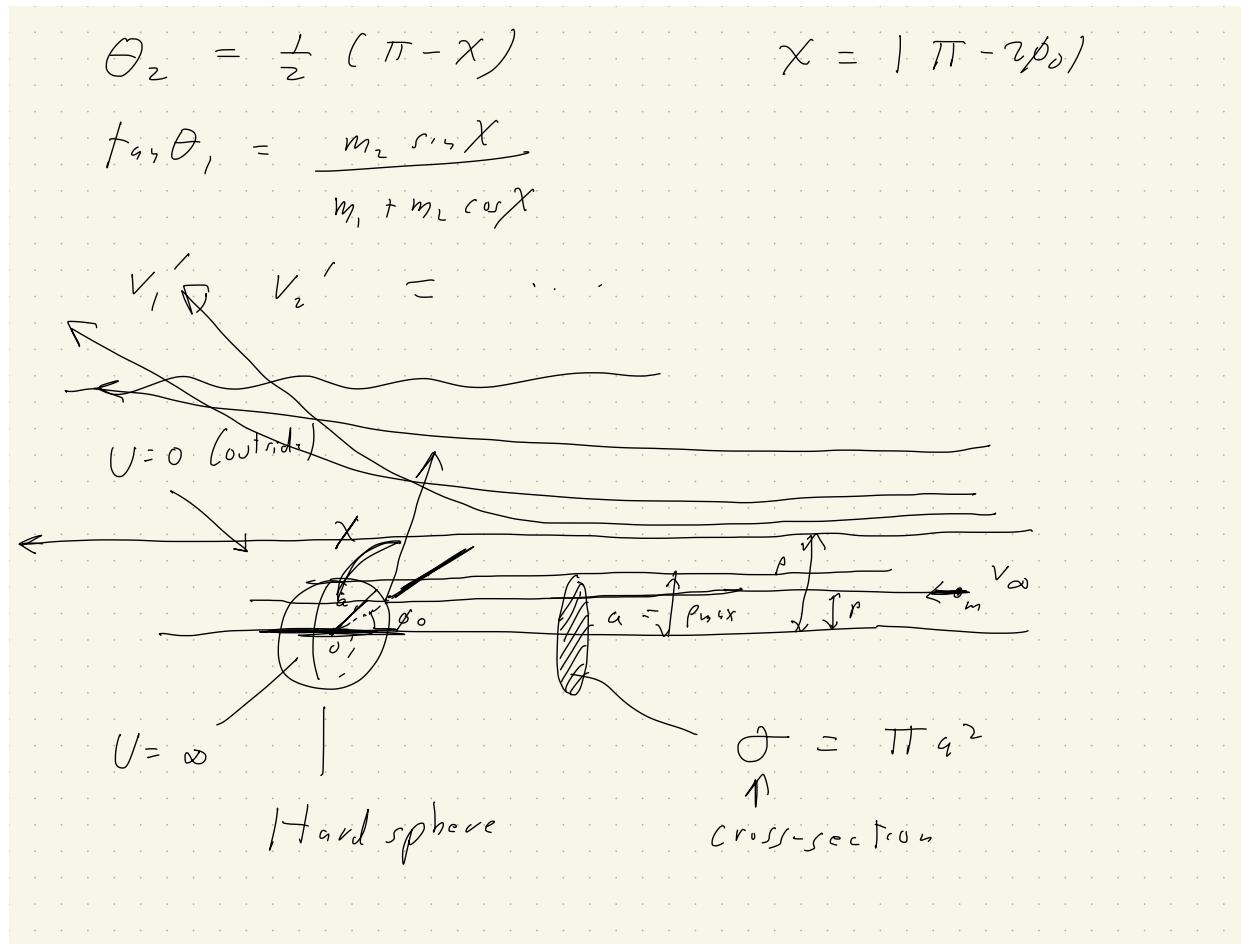
E, M
 ρ, v_∞

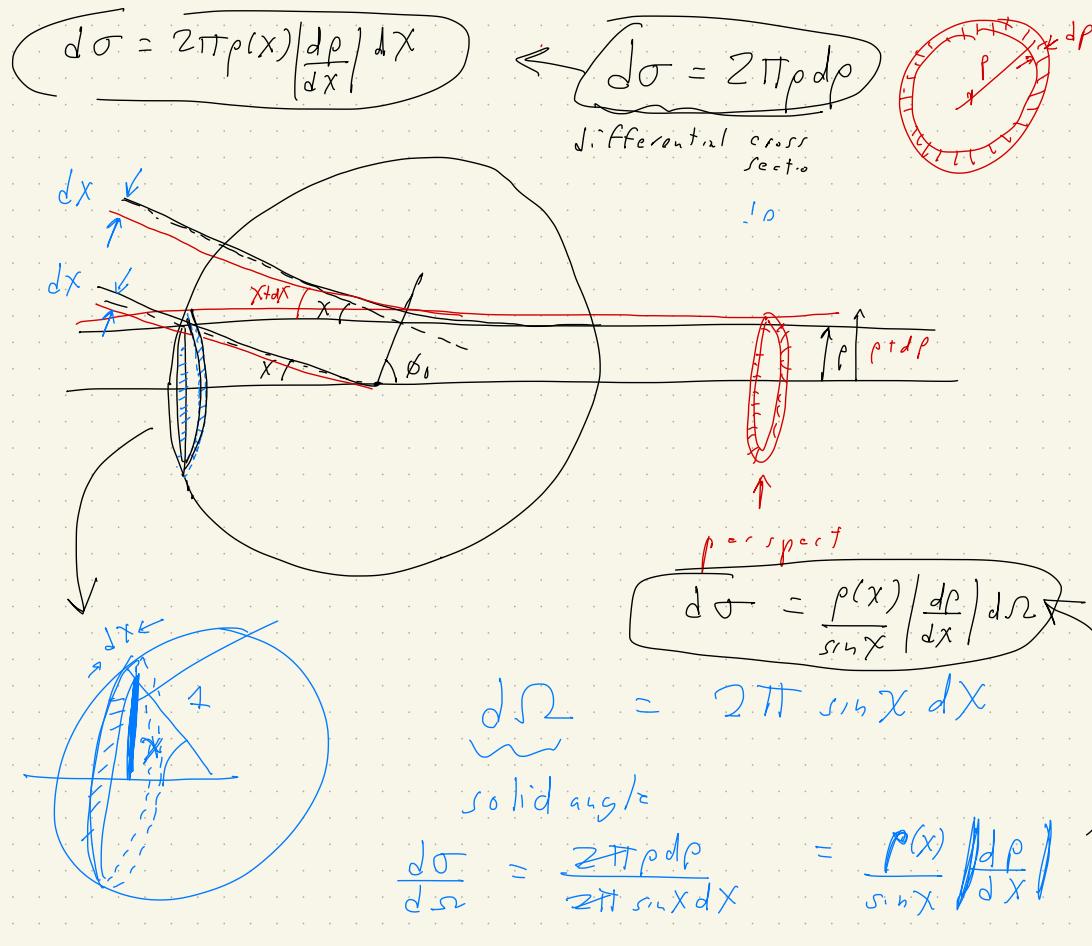
Sec 14:

$$t = \pm \int \frac{dr}{\sqrt{\dots}} + \text{const}$$

$$\Rightarrow \phi = \pm \int \frac{M dr/r^2}{\sqrt{2m(E - U(r)) - \frac{M^2}{r^2}}} + \text{const}$$

$$\begin{aligned} \phi_0 &= \int_{r_{min}}^{\infty} \frac{M dr/r^2}{\sqrt{2m(E - U(r)) - \frac{M^2}{r^2}}} & E = U_{eff}(r_{min}) \\ &= \int_{r_{min}}^{\infty} \frac{m_p v_{\infty} dr/r^2}{\sqrt{2m\left(\frac{1}{2} m v_{\infty}^2 - U(r)\right) - \frac{m_p^2 v_{\infty}^2}{r^2}}} & M = m_p v_{\infty} \\ &= \int_{r_{min}}^{\infty} \frac{p dr/r^2}{\sqrt{1 - \frac{U(r)}{\frac{1}{2} m v_{\infty}^2} - \frac{p^2}{r^2}}} \end{aligned}$$





$$\frac{d\sigma}{d\Omega} = \frac{\rho}{\sin x} \left| \frac{dp}{dx} \right| \quad \text{Com frame}$$

$$\frac{d\sigma_1}{d\Omega} = \frac{\rho}{\sin \theta_1} \left| \frac{dp}{d\theta_1} \right| \quad \text{Lab frame } \theta_1$$

$$\frac{d\sigma_2}{d\Omega_2} = \frac{\rho}{\sin \theta_2} \left| \frac{dp}{d\theta_2} \right| \quad \text{Lab frame } \theta_2$$

$$\begin{aligned}
 \frac{d\sigma_1}{d\Omega_1} &= \frac{\sin x}{\sin \theta_1} \left| \frac{dx}{d\theta_1} \right| \frac{d\sigma}{d\Omega} \\
 &= \left| \frac{d(\cos x)}{d(\cos \theta_1)} \right| \left(\frac{d\sigma}{d\Omega} \right)
 \end{aligned}$$

calculated
for the
Com

Lecture #17: Tues Oct 19th

Next week: start small oscillations

Today / Thurs: Q & A (collisions and scattering)

Lecture #18: Thur Oct 21st

Next week: small oscillations

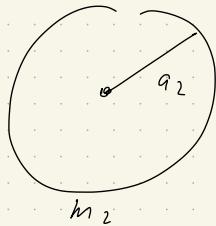
Today: Q & A, Quiz #3

(last 20 minutes)

Q3 name.pdf

Quiz #3:

Two hard spheres with masses m_1, m_2
and radii a_1, a_2 :



$$\rho(X) = (a_1 + a_2) \cos\left(\frac{X}{2}\right)$$

a) Find $\rho = \rho(X)$ where $X =$ scattering angle w.r.t. com frame

b) What value of ρ will give $\theta_2 = 60^\circ$?

$$2\theta_2 + X = \pi \rightarrow X = \pi - 2\theta_2 \\ = 60^\circ$$

$$\rho = (a_1 + a_2) \cos(30^\circ) \\ = \frac{\sqrt{3}}{2} (a_1 + a_2)$$

Lec #19: 10/26

Small oscillations:

Sec 21

more
than
1d

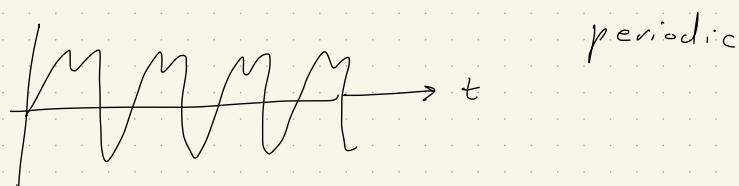
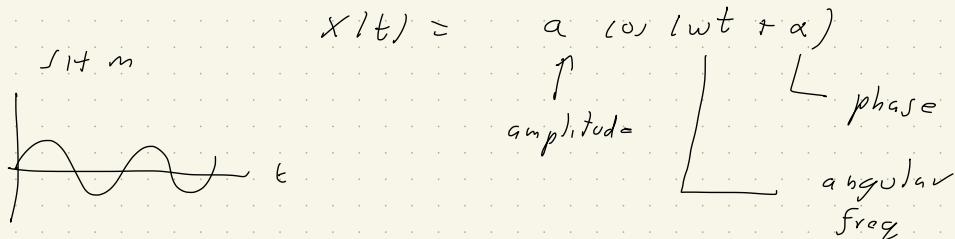
free oscillations
in 1-d

Forced oscillations
in 1d

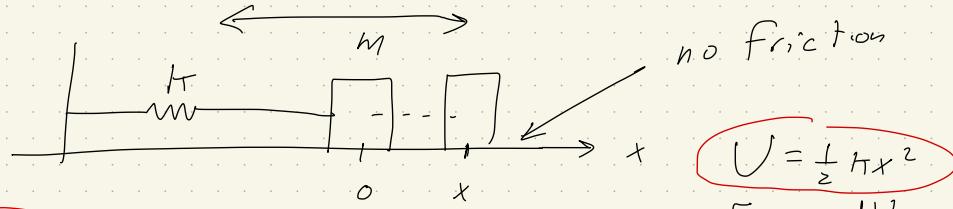
Damping: Sec 25 (not covered)

SHM: (simple harmonic motion)
i) sinusoidal

$$\omega = \frac{2\pi}{T}$$



Example:



$$F = -kx$$

restoring

$$U = \frac{1}{2} kx^2$$
$$F = -\frac{dU}{dx}$$
$$= -kx$$

$$F = mx'' = -kx \rightarrow x'' = -\frac{k}{m}x$$

soln:

$$x = c_1 \cos \omega t + c_2 \sin \omega t$$
$$\omega = \sqrt{\frac{k}{m}}$$

Alternatives:

$$x = a \cos(\omega t + \alpha)$$

$$x = \operatorname{Re}[A e^{i\omega t}], A = a e^{i\alpha}$$

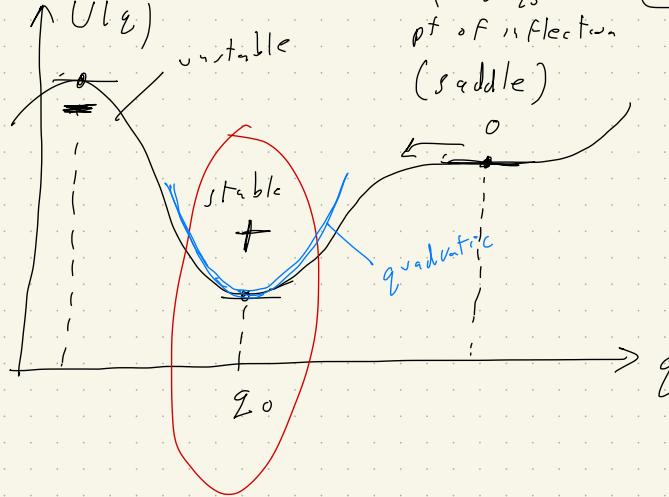
$$\left. \begin{array}{l} T = \frac{1}{2} m \dot{x}^2 \\ U = \frac{1}{2} k x^2 \end{array} \right\} L = T - U = \frac{1}{2} m \dot{x}^2 - \frac{1}{2} k x^2$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{x}} \right) = \frac{\partial L}{\partial x} \rightarrow m \ddot{x} = -kx$$

$$U(q) = q^3$$

$$q_0$$

More generally: $\left(\frac{d^2 U}{d q^2} \Big|_{q_0} = 0 \right)$ $(L = \frac{1}{2} m \dot{q}^2 - U(q))$



$$\text{Equilibrium: } (q = q_0)$$

$$0 = F = -\frac{dU}{dq} \Big|_{q_0}$$

stable:

$$\frac{d^2 U}{d q^2} \Big|_{q_0} > 0$$

$$V = \text{const}, T$$

Expansion: (about q_0) \Rightarrow equilibrium $K > 0$

$$U(q) = U(q_0) + \underbrace{\frac{dU}{dq} \Big|_{q_0} (q - q_0)}_{\text{const}} + \frac{1}{2} \underbrace{\left(\frac{d^2 U}{d q^2} \Big|_{q_0} \right)}_{\text{ignore}} (q - q_0)^2 + \frac{1}{3!} \underbrace{\frac{d^3 U}{d q^3} \Big|_{q_0} (q - q_0)^3}_{\text{ignore for } q - q_0 \text{ small}} + \dots$$

$$U(q) \approx \frac{1}{2} k x^2$$

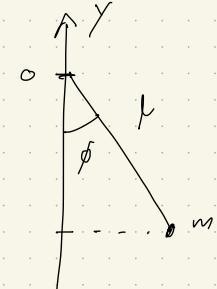
$$\begin{aligned} T &= \frac{1}{2} q(q) \dot{q}^2 \\ &= \frac{1}{2} q(q_0) \dot{x}^2 \\ &\approx \frac{1}{2} m \dot{x}^2 \end{aligned}$$

$$x = q - q_0$$

$$K = \frac{d^2 U}{d q^2} \Big|_{q_0}$$

$$L \approx \frac{1}{2} m \dot{x}^2 - \frac{1}{2} K x^2$$

Simple pendulum:

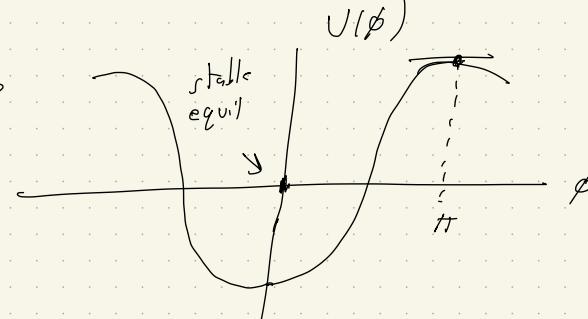


$$U = mgx \\ = -mgl \cos \phi$$

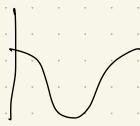
$$T = \frac{1}{2} m l^2 \dot{\phi}^2$$

$$U = -mg l \cos \phi$$

$$L = \frac{1}{2} m l^2 \dot{\phi}^2 + mg l \cos \phi$$



$$\phi_0 = 0 \text{ (equilibrium)}$$



$$\cos \phi = 1 - \frac{1}{2} \phi^2 + \dots$$

$$\cos \phi = \underbrace{\cos 0}_1 + \underbrace{\frac{d(\cos \phi)}{d\phi}}_{\phi=0} \cdot \phi + \frac{1}{2} \underbrace{\frac{d^2(\cos \phi)}{d\phi^2}}_{\phi=0} \phi^2 + \dots$$

$$= 1 - \frac{1}{2} \phi^2 + \dots$$

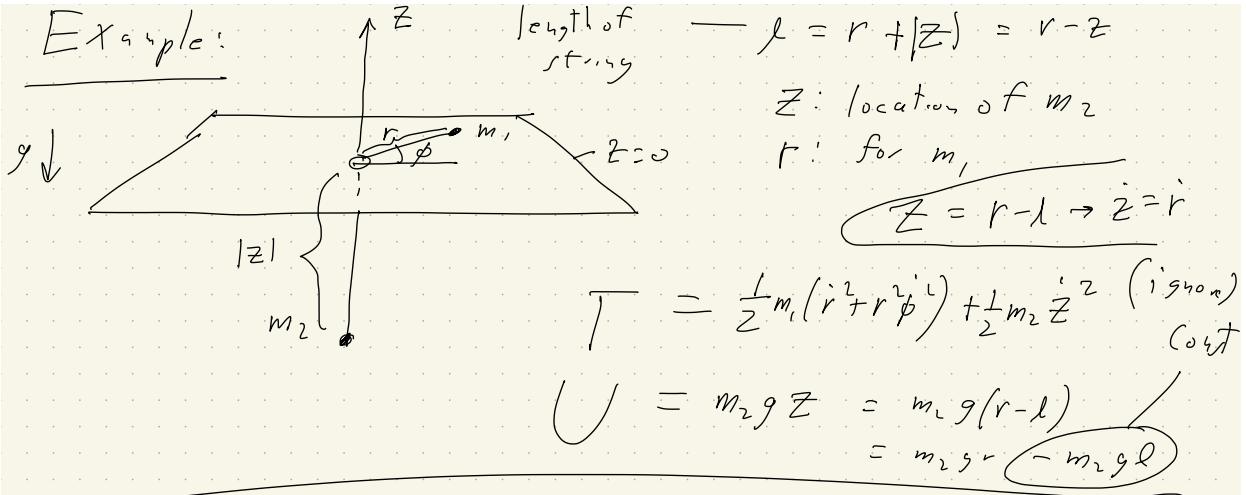
$$L = \frac{1}{2} m l^2 \dot{\phi}^2 + mg l \left(1 - \frac{1}{2} \phi^2 \right)$$

$$= \frac{1}{2} \cancel{(m l^2)} \dot{\phi}^2 - \frac{1}{2} \cancel{mg l} \phi^2 + \underbrace{mg l}_{\text{igno...}}$$

$$L = \frac{1}{2} m \dot{x}^2 - \frac{1}{2} \cancel{m} \phi^2$$

$$\omega = \sqrt{\frac{k}{m}} \\ = \sqrt{\frac{mg l}{ml^2}} = \sqrt{\frac{g}{l}}$$

Example:

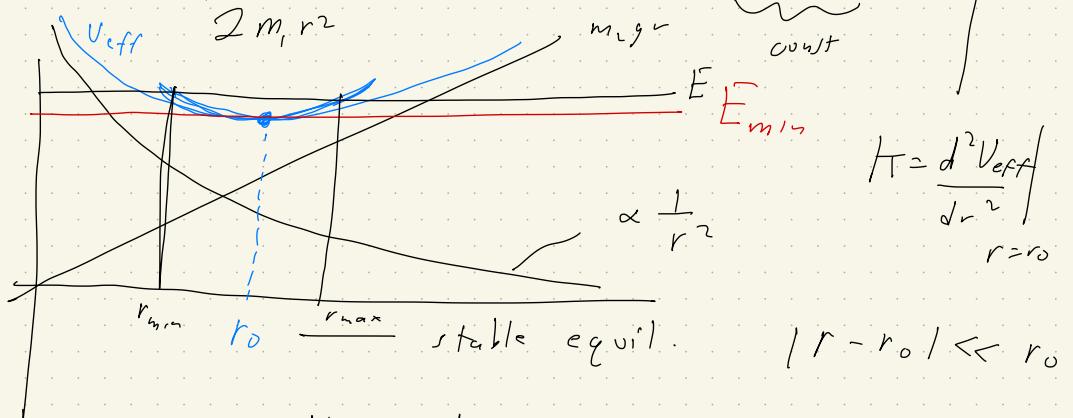


$$i) M_z = \frac{\partial L}{\partial \dot{\phi}} = m_1r^2\dot{\phi} \rightarrow \dot{\phi} = \frac{M_z}{m_1r^2}$$

$$ii) E = T + U = \frac{1}{2}(m_1 + m_2)r^2 + \underbrace{\frac{1}{2}m_1r^2\dot{\phi}^2}_{\frac{M_z^2}{2m_1r^2}} + m_2gr$$

$$E = \frac{1}{2}(m_1 + m_2)r^2 + U_{eff}(r)$$

$$U_{eff}(r) = \frac{M_z^2}{2m_1r^2} + m_2gr = U(r_0) + \frac{1}{2}k(r - r_0)^2$$



$$r_0 = ? \quad 0 = \frac{dU_{eff}}{dr} \Big|_{r=r_0}$$

$$= -\frac{M_z^2}{m_1r_0^3} + m_2g \rightarrow \boxed{M_z^2 = m_1m_2g r_0^3}$$

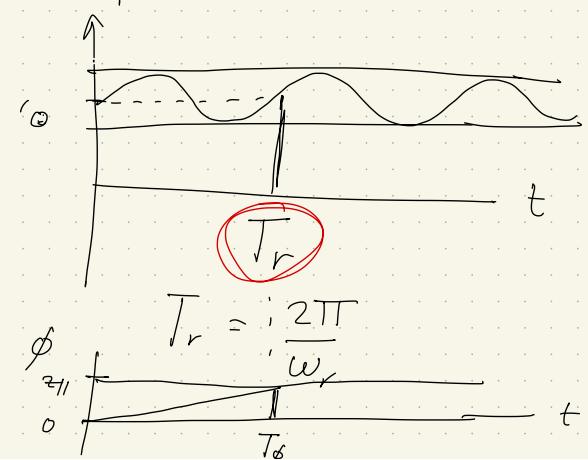
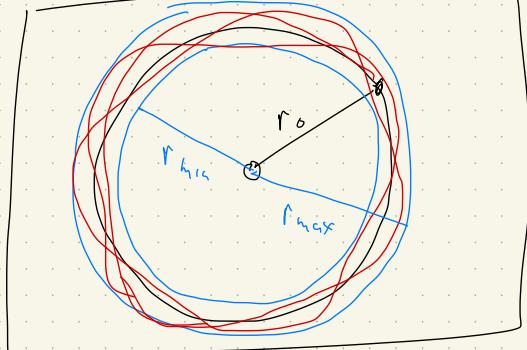
$$\left. \frac{d^2 U_{\text{eff}}}{dr^2} \right|_{r=r_0} = \frac{3 M_z^2}{m_1 r_0^4}$$

$$= \frac{3 m_1 m_2 g r_0^3}{m_1 r_0^4}$$

$$= \frac{3 m_2 g}{r_0} = K$$

$\omega_r = \sqrt{\frac{K}{m_1 + m_2}}$

$= \sqrt{\frac{3 m_2 g}{(m_1 + m_2) r_0}}$



$$T_\phi = \frac{2\pi}{\omega_\phi} = \frac{2\pi}{\dot{\phi}|_{r_0}}$$

$$\dot{\phi} = \frac{M_z}{m_1 r^2}$$

$$\omega_\phi = \left. \dot{\phi} \right|_{r=r_0} = \frac{M_z}{m_1 r_0^2} = \frac{\sqrt{m_1 m_2 g r_0^3}}{m_1 r_0^2}$$

$$\omega_\phi = \sqrt{\frac{m_2 g}{m_1 r_0}}$$

Compare to

$$\omega_r = \sqrt{\frac{3 m_2 g}{(m_1 + m_2) r_0}}$$

$$F + \frac{3}{m_1 + m_2} = \frac{1}{m_1} \quad \text{then} \quad \omega_r = \omega_{\phi}$$

$$\begin{cases} 3m_1 = m_1 + m_2 \\ 2m_1 = m_2 \end{cases}$$

Lec #20: 10/28

Forced oscillations:

$$m\ddot{x} = -kx + F(t)$$

$$\ddot{x} + \frac{k}{m}x = \frac{F(t)}{m}$$

$$\boxed{\ddot{x} + \omega^2 x = \frac{F(t)}{m}}, \quad \omega = \sqrt{\frac{k}{m}}$$

general sol'n:

$$x(t) = x_h(t) + x_p(t)$$

\uparrow
homogeneous
 $(F(t)=0)$

$$V(x) = \frac{1}{2}kx^2 - F(t)$$

$$\frac{\partial}{\partial t} \left(\frac{\partial L}{\partial \dot{x}} \right) = \frac{\partial L}{\partial x}$$

$$L = T - V$$

$$\frac{\partial L}{\partial x} = -kx + F(t)$$

\downarrow
particular
(any solution for $F(t)$)

$$\boxed{x_h(t) = a \cos(\omega t + \alpha)}$$

a, α : two constants
(initial condition)

$$\text{Suppose: } F(t) = f \cos(\gamma t + \beta)$$

$$\ddot{x}_p + \omega^2 x_p = \frac{f}{m} \cos(\gamma t + \beta)$$

G Vers ! ! $x_p(t) = b \cos(\gamma t + \beta)$

$$-b\gamma^2 \cos(\gamma t + \beta) + \omega^2 b \cos(\gamma t + \beta) = \frac{f}{m} \cos(\gamma t + \beta)$$

$$b(\omega^2 - \gamma^2) = \frac{f}{m}$$

$$\rightarrow b = \frac{f}{m(\omega^2 - \gamma^2)}$$

$$x_p(t) = \frac{f}{m(\omega^2 - \gamma^2)} \cos(\gamma t + \beta)$$

$10 \cos(\omega t)$

$$x(t) = a \cos(\omega t + \alpha) + \frac{f}{m(\omega^2 - \gamma^2)} \cos(\gamma t + \beta)$$

$$x(t) = a \cos(\omega t + \alpha) + \frac{f}{m(\omega^2 - \gamma^2)} [\cos(\gamma t + \beta) - \cos(\omega t + \alpha)]$$

$$\underbrace{\quad}_{\frac{\partial}{\partial}}$$

1' hospital's

$$= \frac{\frac{d}{d\gamma} (\text{num})}{\frac{d}{d\gamma} (\text{den})} \Big|_{\gamma \rightarrow \omega}$$

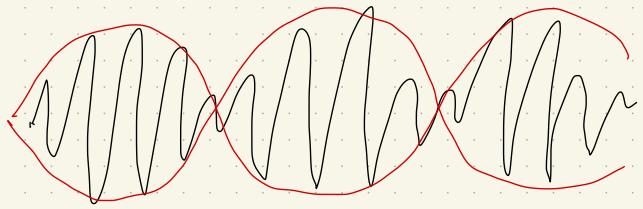
$$= \frac{+ft \sin(\omega t + \alpha)}{+2m\omega}$$

at resonance

$$\downarrow (\gamma = \omega)$$

$$= \frac{ft}{2m\omega} \sin(\omega t + \alpha)$$

$$x(t) = a \cos(\omega t + \alpha) + \frac{ft}{2m\omega} \sin(\omega t + \alpha)$$



$$\frac{\omega + \gamma}{2}$$

$$|\omega - \gamma| = \omega_{\text{beat}}$$

General: for arbitrary $F(t)$

$$F(t) = \Re \int_{-\infty}^{\infty} d\gamma \tilde{F}(\gamma) e^{i\gamma t}$$

Fourier transform

$\ddot{x} + \omega^2 x = \frac{F(t)}{m}$

Let: $\xi = \dot{x} + i\omega x$

Math methods
 $y = y(x)$

complex $\dot{\xi} = \ddot{x} + i\omega \dot{x}$
 $= \ddot{x} + i\omega (\xi - i\omega x)$
 $= \ddot{x} + i\omega \xi + \omega^2 x$

$\dot{\xi} - i\omega \xi = \ddot{x} + \omega^2 x = \frac{F(t)}{m}$

Homog: $\dot{\xi}_h - i\omega \xi_h = 0 \rightarrow \xi_h(t) = A e^{i\omega t}$

Guess: $\xi_p(t) = A(t) e^{i\omega t}$

replace complex constant

$$\boxed{\ddot{\xi}_p - i\omega \dot{\xi}_p = \frac{F(t)}{m}}, \quad \xi_p = A(t)e^{i\omega t}$$

$$\rightarrow \dot{A}e^{i\omega t} + iA\omega e^{i\omega t} - i\omega A e^{i\omega t} = \frac{F(t)}{m}$$

$$\dot{A} = \frac{e^{-i\omega t} F(t)}{m}$$

$$A(t) = \int dt \frac{F(t)}{m} e^{-i\omega t} + \text{const}$$

$$\boxed{\xi(t) = e^{i\omega t} \left[\int_0^t dt' \frac{F(t')}{m} e^{-i\omega t'} + \xi_0 \right]}$$

$$\boxed{\xi = x + i\omega x \rightarrow \begin{cases} x(t) = \frac{1}{\omega} \text{Im}(\xi(t)) \\ \text{Complex constant } (\mathbb{I}, \mathbb{C}') \end{cases}}$$

$$y' + P(x)y = Q(x) \quad f(x)dx = g(y)dy$$

$$\frac{dy}{dx} + P(x)y - Q(x) = 0$$

$$\boxed{1 dy + (P(x)y - Q(x)) dx = 0} \neq dU$$

$$dU(x,y) = \frac{\partial U}{\partial x} dx + \frac{\partial U}{\partial y} dy$$

$$\frac{\partial^2 U}{\partial y \partial x}$$

$$\frac{\partial^2 U}{\partial x \partial y}$$

M. Boas
Mathematical Methods

$$\mu(x) [dy + (P(x)y - Q(x))dx] = dU$$

$$\frac{d\mu}{dx} = \frac{\partial}{\partial y} (P(x)y - Q(x)) \mu(x)$$

$$\frac{d\mu}{dx} = P(x) \mu(x)$$

$$\int \frac{d\mu}{\mu} = \int P(x) dx$$

$$\ln \mu = \int P(x) dx$$

$$\int p(x) dx$$

$$\mu(x) = e$$