

problem: (B.1) show $\alpha \wedge \beta = (-1)^{pq} \beta \wedge \alpha$

$$\alpha = \sum_{i_1 < i_2 < \dots < i_p} \alpha_{i_1 i_2 \dots i_p} dx^{i_1} \wedge dx^{i_2} \wedge \dots \wedge dx^{i_p}$$

$$\beta = \sum_{j_1 < j_2 < \dots < j_q} \beta_{j_1 j_2 \dots j_q} dx^{j_1} \wedge dx^{j_2} \wedge \dots \wedge dx^{j_q}$$

$$\alpha \wedge \beta = \sum_i \sum_j \alpha_{i_1 \dots i_p} \beta_{j_1 \dots j_q} (dx^{i_1} \wedge \dots \wedge dx^{i_p})$$

$$\wedge (dx^{j_1} \wedge \dots \wedge dx^{j_q})$$

need to move
each of these
through p coord
differentials

$$(-1)^p \dots (-1)^p$$

q times

$$= (-1)^{p+\dots+p}$$

$$= (-1)^{pq}$$

$$= (-1)^{pq} \sum_i \sum_j \alpha_{i_1 \dots i_p} \beta_{j_1 \dots j_q} (dx^{j_1} \wedge \dots \wedge dx^{j_q}) (dx^{i_1} \wedge \dots \wedge dx^{i_p})$$

$$= (-1)^{pq} \sum_i \sum_j \beta_{j_1 \dots j_q} \alpha_{i_1 \dots i_p} (dx^{j_1} \wedge \dots \wedge dx^{j_q}) (dx^{i_1} \wedge \dots \wedge dx^{i_p})$$

$$= (-1)^{pq} \beta \wedge \alpha$$

Problem: (B.2) show $d(\alpha \wedge \beta) = (d\alpha) \wedge \beta + (-1)^p \alpha \wedge d\beta$

$$\underbrace{[d(\alpha \wedge \beta)]_{i_1 \dots \pi \ell \dots m}}_{p+q+1} = (p+q+1) d_{[i_1} (\alpha \wedge \beta)_{\pi \dots \ell \dots m]}$$

$$= (p+q+1) d_{[i_1} \left(\frac{(p+q)!}{p! q!} \alpha_{\pi \dots \ell \dots m} \beta_{\ell \dots m} \right)$$

$$= \frac{(p+q+1)(p+q)!}{p! q!} \left\{ \left(d_{[i_1} \alpha_{\pi \dots \ell \dots m} \right) \beta_{\ell \dots m} \right. \\ \left. + \alpha_{\pi \dots \ell \dots m} d_{[i_1} \beta_{\ell \dots m} \right\}$$

\swarrow
 move to front through p indices

$$= \frac{(p+q+1)(p+q)!}{p! q!} \left\{ \frac{1}{p+1} (d\alpha)_{[i_1 \pi \dots \ell \dots m]} \beta_{\ell \dots m} \right. \\ \left. + (-1)^p \alpha_{[i_1 \dots \pi} (d\beta)_{\pi \dots \ell \dots m]} \right\}$$

$$= \frac{(p+q+1)!}{p! q!} \left\{ \frac{1}{(p+1)} \frac{p!}{(p+q+1)!} (d\alpha \wedge \beta)_{i_1 \dots \pi \ell \dots m} \right. \\ \left. + (-1)^p \frac{1}{(q+1)} \frac{p! (q+1)!}{(p+q+1)!} (\alpha \wedge d\beta)_{i_1 \dots \pi \ell \dots m} \right\}$$

$$= (d\alpha \wedge \beta)_{i_1 \dots \pi \ell \dots m} + (-1)^p (\alpha \wedge d\beta)_{i_1 \dots \pi \ell \dots m}$$

$$= [d\alpha \wedge \beta + (-1)^p \alpha \wedge d\beta]_{i_1 \dots \pi \ell \dots m}$$

(B.3)

(1)

Problem: $d(d\alpha) = 0$

a) In 3-dimensions, let $\alpha = 0$ be a ~~2~~ 0-form

$$\text{Then } d\alpha \leftrightarrow \vec{\nabla} \alpha$$

$$\text{Also } d(1\text{-form}) = \vec{\nabla} \times (1\text{-form})$$

$$\text{So } d(d\alpha) = d(\vec{\nabla} \alpha) \\ = \vec{\nabla} \times \vec{\nabla} \alpha$$

b) In 3-dimensions, let $\alpha = 1$ be a 1-form

$$\text{Then } d(1\text{-form}) = \epsilon_{ijk} (\vec{\nabla} \times \vec{\alpha})_k$$

$$d(2\text{-form}) = 3 d[\epsilon_{ijk} \beta_{jk}]$$

3-form
(contract with ϵ^{ijk} to get a scalar)

$$\epsilon^{ijk} (d\beta)_{ijk} = 3 \epsilon^{ijk} d_i (\beta_{jk})$$

$$= 3 d_i (\epsilon^{ijk} \beta_{jk})$$

$$= 3 \vec{\nabla} \cdot \vec{V}$$

$$\text{where } \vec{V} = \epsilon^{ijk} \beta_{jk}$$

$$\text{But } \beta_{jk} = \epsilon_{jke} (\vec{\nabla} \times \vec{\alpha})_e$$

$$\rightarrow \vec{V} = \epsilon^{ijk} \epsilon_{jke} (\vec{\nabla} \times \vec{\alpha})_e$$

$$= \epsilon^{ijk} \epsilon_{jke} (\vec{\nabla} \times \vec{\alpha})_e$$

$$= (\delta_e^i \delta_j^j - \delta_j^i \delta_e^j) (\vec{\nabla} \times \vec{\alpha})_e$$

$$= 3 (\vec{\nabla} \times \vec{\alpha})_i - (\vec{\nabla} \times \vec{\alpha})_i = 2 (\vec{\nabla} \times \vec{\alpha})_i$$

Thus,

$$d(d\alpha) = 3! \vec{\nabla} \cdot (\vec{\nabla} \times \vec{\alpha})$$

form

$$\text{so } d(d\alpha) = 0 \Leftrightarrow \boxed{\vec{\nabla} \cdot (\vec{\nabla} \times \vec{\alpha}) = 0}$$

(B.4)

Problem: ~~is~~ closed but globally not exact

$$\alpha = \frac{1}{x^2 + y^2} (-y dx + x dy)$$

a) Check that $d\alpha = 0$

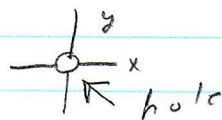
$$\begin{aligned} d\alpha &= - \frac{1}{(x^2 + y^2)^2} (2x dx + 2y dy) \wedge (-y dx + x dy) \\ &\quad + \frac{1}{(x^2 + y^2)} [-dy \wedge dx + dx \wedge dy] \end{aligned}$$

$$\begin{aligned} &= - \frac{1}{(x^2 + y^2)^2} [2x^2 dx \wedge dy + 2y^2 dx \wedge dy] \\ &\quad + \frac{1}{(x^2 + y^2)} [dx \wedge dy + dx \wedge dy] \end{aligned}$$

$$= - \frac{1}{(x^2 + y^2)^2} 2(x^2 + y^2) dx \wedge dy + \frac{2 dx \wedge dy}{(x^2 + y^2)}$$

$$= \boxed{0}$$

b) Globally not exact since sphere is topologically non-trivial



c) $x^2 + y^2 = r^2$
 $x = r \cos \phi$, $y = r \sin \phi$

$$\begin{aligned} \rightarrow \alpha &= \frac{1}{r^2} [-r \sin \phi (dr \cos \phi - r \sin \phi d\phi) \\ &\quad + r \cos \phi (dr \sin \phi + r \cos \phi d\phi)] \end{aligned}$$

$$= \frac{1}{r^2} \left[\frac{-r \sin \phi \cos \phi}{r^2} dr + r^2 \sin^2 \phi d\phi \right. \\ \left. + \frac{r \cos \phi \sin \phi}{r^2} dr + r^2 \cos^2 \phi d\phi \right]$$

$$= d\phi$$

$$\text{so } d\phi = \frac{1}{x^2+y^2} (-y dx + x dy)$$

locally defined (not single-valued)
for closed loops
enclosing the origin



(B.5)

Problem:

$$\alpha = A dx + B dy \quad \text{in } 2\text{-d}$$

Frobenius: $\underbrace{d\alpha \wedge \alpha}_{\text{3-form}} = 0$

3-form so automatically zero!

Check:

$$\begin{aligned} d\alpha &= \left(\frac{\partial A}{\partial x} dx + \frac{\partial A}{\partial y} dy \right) \wedge dx \\ &\quad + \left(\frac{\partial B}{\partial x} dx + \frac{\partial B}{\partial y} dy \right) \wedge dy \\ &= \frac{\partial A}{\partial y} dy \wedge dx + \frac{\partial B}{\partial x} dx \wedge dy \\ &= \left(\frac{\partial B}{\partial x} - \frac{\partial A}{\partial y} \right) dx \wedge dy \end{aligned}$$

$$\begin{aligned} \rightarrow d\alpha \wedge \alpha &= \left(\frac{\partial B}{\partial x} - \frac{\partial A}{\partial y} \right) dx \wedge dy \wedge (A dx + B dy) \\ &= \boxed{0} \end{aligned}$$

(B.G)

Problem:

~~Sources~~ ~~www.google.com~~

$$\alpha = yz dx + xz dy + dz \quad \text{in } \mathbb{R}^3$$

$$a) \quad d\alpha = z dy \wedge dx + y dz \wedge dx \\ + z dx \wedge dy + x dz \wedge dy$$

$$= -z dx \wedge dy + y dz \wedge dx \\ + z dx \wedge dy + x dz \wedge dy$$

$$= dz \wedge (y dx + x dy)$$

$$d\alpha \wedge \alpha = dz \wedge (y dx + x dy) \wedge (yz dx + xz dy + dz)$$

$$= dz \wedge x dy \wedge yz dx$$

$$+ dz \wedge y dx \wedge xz dy$$

$$= -xyz (dx \wedge dy \wedge dz) + xyz (dx \wedge dy \wedge dz)$$

$$= \boxed{0}$$

Thus \rightarrow integrable

$$b) \quad \mu\alpha = e^{xy} [yz dx + xz dy + dz]$$

$$d\varphi = d[z e^{xy}]$$

$$= dz e^{xy} + z e^{xy} y dx + z e^{xy} x dy$$

$$= e^{xy} [dz + yz dx + xz dy]$$

$$= \mu\alpha$$

(3.7)

Problem: $dx \wedge dy = r dr \wedge d\phi$

$$x = r \cos \phi, \quad y = r \sin \phi$$

$$dx = \cos \phi dr - r \sin \phi d\phi$$

$$dy = \sin \phi dr + r \cos \phi d\phi$$

$$dx \wedge dy = (\cos \phi dr - r \sin \phi d\phi) \wedge (\sin \phi dr + r \cos \phi d\phi)$$

$$= r \cos^2 \phi dr \wedge d\phi - r \sin^2 \phi d\phi \wedge dr$$

$$= r (\cos^2 \phi + \sin^2 \phi) dr \wedge d\phi$$

$$= r dr \wedge d\phi$$

Problem: (8.8)

(11)

Stokes' : $\int_R d\alpha = \oint_{\partial R} \alpha$

\uparrow
 $(p-1 \text{ form})$

p=1 : $\alpha = 0\text{-form} \rightarrow U \text{ function}$
 $d\alpha = dU \rightarrow \vec{\nabla} U$

RHS = $U(2) - U(1)$

LHS = $\int_1^2 \sum_i (d\alpha)_i \cdot \underbrace{\frac{dx^i}{ds}}_{(\frac{d\vec{s}}{ds})^i} ds$
 $= \int_1^2 (\vec{\nabla} U) \cdot d\vec{s}$

so $\boxed{\int_1^2 \vec{\nabla} U \cdot d\vec{s} = U(2) - U(1)}$

Fund thm of gradients

p=2 : $\alpha = 1\text{-form} \rightarrow \text{vector } A_i = \alpha_i$
 $d\alpha = 2\text{-form} = (d\alpha)_{ij} = \sum_{\pi} \epsilon_{ij\pi} (\vec{\nabla} \times \vec{A})_{\pi}$
 RHS = $\oint_{C=\partial S} \sum_i \alpha_i \left(\frac{dx^i}{ds} \right) ds = \oint_{C=\partial S} \vec{A} \cdot d\vec{s}$

LHS = $\int_S \sum_{i < j} (d\alpha)_{ij} \cdot \frac{\partial(x^i, x^j)}{\partial(u, v)} du dv$
 $= \int_S \sum_{i < j} \sum_{\pi} \epsilon_{ij\pi} (\vec{\nabla} \times \vec{A})_{\pi} \frac{\partial(x^i, x^j)}{\partial(u, v)} du dv$

$$= \int_S \sum_{i < j} \left(\vec{\nabla} \times \vec{A} \right)_{ij} \underbrace{\sum_{i < j} \epsilon_{ijk} \frac{\partial(x^i, x^j)}{\partial(u, v)}}_{n_k da} du dv$$

$$= \int_S \left(\vec{\nabla} \times \vec{A} \right) \cdot \hat{n} da$$

so $\boxed{\int_S \left(\vec{\nabla} \times \vec{A} \right) \cdot \hat{n} da = \oint_{\partial S} \vec{A} \cdot d\vec{J}}$ Stokes!

p=3: $\alpha = 2\text{-form} \rightarrow \text{vector } A^i = \sum_{i < j} \epsilon^{ijk} \alpha_{jk}$

$$d\alpha = 3\text{-form} = (d\alpha)_{ijk}$$

$$\sum_{i < j < k} \epsilon^{ijk} (d\alpha)_{ijk} = \sum_{i < j < k} 3 \epsilon^{ijk} \partial_i \alpha_{jk}$$

$$= \sum_{i < j < k} 3 \partial_i (\epsilon^{ijk} \alpha_{jk})$$

$$= 3 \sum_i \partial_i \left(\underbrace{\sum_{j < k} \epsilon^{ijk} \alpha_{jk}}_{2 A^i} \right) = 3! (\vec{\nabla} \cdot \vec{A})$$

$$\text{so } \sum_{i < j < k} \epsilon^{ijk} (d\alpha)_{ijk} = 3! (\vec{\nabla} \cdot \vec{A}) \Leftrightarrow (d\alpha)_{ijk} = (\vec{\nabla} \cdot \vec{A}) \epsilon_{ijk}$$

Using $\sum_{i < j < k} \epsilon^{ijk} \epsilon_{ijk} = 3!$

Now: $A^i = \frac{1}{2} \sum_{j < k} \epsilon^{ijk} \alpha_{jk} = \frac{1}{2} \epsilon^{ijk} \alpha_{jk}$

$$2 A^i \epsilon^{ilm} = \epsilon^{ijk} \epsilon^{ilm} \alpha_{jk}$$

$$= (\delta^j_l \delta^k_m - \delta^j_m \delta^k_l) \alpha_{jk} = \alpha_{lm} - \alpha_{ml} = 2 \alpha_{lm}$$

Thus, $\alpha_{lm} = A^l \in^{ilm}$

so $\alpha_{ij} = \sum_k \epsilon_{ijk} A^k$

(3)

or ~~$\alpha_{ij} = \sum_k \epsilon_{ijk} A^k$~~

$$RHS = \oint_{\partial R} \alpha$$

$$= \oint_{\partial S} \sum_{i < j} \alpha_{ij} \frac{\partial(x^i, x^j)}{\partial(u, v)} du dv$$

$$= \oint_{\partial S} \sum_{i < j} \sum_k \epsilon_{ijk} A^k \frac{\partial(x^i, x^j)}{\partial(u, v)} du dv$$

$$= \oint_{\partial S} \sum_k A^k \underbrace{\sum_{i < j} \epsilon_{ijk} \frac{\partial(x^i, x^j)}{\partial u \partial v}}_{n_{\pi} d\mathbf{a}} du dv$$

$$= \oint_{\partial S} \vec{A} \cdot \hat{n} d\mathbf{a}$$

$$= \oint_{\partial S} \vec{A} \cdot \hat{n} d\mathbf{a}$$

$$LHS = \int_R d\alpha$$

$$= \int_R \sum_{i < j < k} (d\alpha)_{ijk} \frac{\partial(x^i, x^j, x^k)}{\partial(u, v, w)} du dv dw$$

$$= \int_R (\vec{\nabla} \cdot \vec{A}) \underbrace{\sum_{i < j < k} \epsilon_{ijk} \frac{\partial(x^i, x^j, x^k)}{\partial(u, v, w)}}_{dV} du dv dw$$

$$= \int_R (\vec{\nabla} \cdot \vec{A}) dV$$

Thus, $\boxed{\int_R (\vec{\nabla} \cdot \vec{A}) dV = \oint_{\partial R} \vec{A} \cdot \hat{n} d\mathbf{a}}$