

$$\begin{aligned} Z &= -l \cos \theta \\ X &= l \sin \theta \cos \phi \\ Y &= l \sin \theta \sin \phi \end{aligned}$$

$$U = mgZ = -mgl \cos \theta$$

$$\begin{aligned} T &= \frac{1}{2} m v^2 \\ &= \frac{1}{2} m l^2 [\sin^2 \theta \dot{\phi}^2 + \dot{\theta}^2] \end{aligned}$$

$$L = T - U = \frac{1}{2} m l^2 [\dot{\theta}^2 + \sin^2 \theta \dot{\phi}^2] + mgl \cos \theta$$

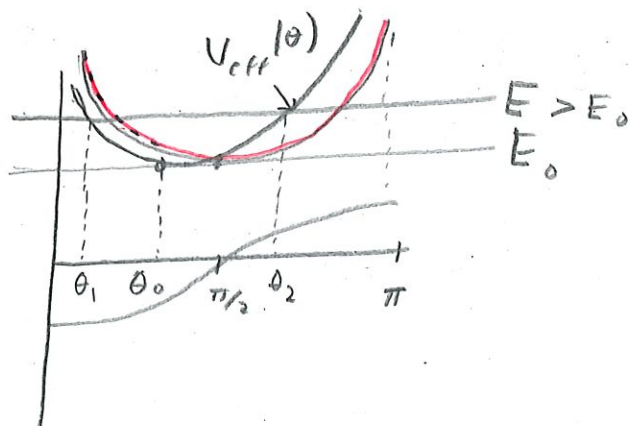
$$\rightarrow P_{\phi} = \frac{\partial L}{\partial \dot{\phi}} = m l^2 \sin^2 \theta \dot{\phi} = \text{const}$$

$$E = T + U = \text{const}$$

$$= \frac{1}{2} m l^2 [\dot{\theta}^2 + \sin^2 \theta \frac{P_{\phi}^2}{m^2 l^4 \sin^4 \theta}] + mgl \cos \theta$$

$$= \frac{1}{2} m l^2 \dot{\theta}^2 + \underbrace{\frac{P_{\phi}^2}{2 m l^2 \sin^2 \theta}}_{V_{\text{eff}}(\theta)} + mgl \cos \theta$$

Effective potential



$$\frac{P_{\phi}^2}{2 m l^2 \sin^2 \theta}$$

Turning points:

$$E = V_{\text{eff}}(\theta)$$

$$E = V_{\text{eff}}(\theta_1) = V_{\text{eff}}(\theta_2)$$

(see page 3; cubic equation)

$$E_0 : \theta = \theta_0 = \text{const}$$

From:

$$\sqrt{\frac{2}{m\lambda^2} (E - U_{eff}(\theta))} = \frac{1}{\frac{d\theta}{dt}}$$

$$\int dt = \int \frac{d\theta}{\sqrt{\frac{2}{m\lambda^2} (E - U_{eff}(\theta))}}$$

$$\rightarrow \left[ t = \sqrt{\frac{m\lambda^2}{2}} \int \frac{d\theta}{\sqrt{E - U_{eff}(\theta)}} + \text{const} \right] \quad (1)$$

$$\sqrt{\frac{2}{m\lambda^2} (E - U_{eff}(\theta))} = \left( \frac{1}{\frac{d\theta}{dt}} \frac{dt}{d\phi} \right) \frac{d\phi}{dt}$$

$$\sqrt{\frac{2}{m\lambda^2} (E - U_{eff}(\theta))} = \frac{d\theta}{d\phi} \frac{p_\phi}{m\lambda^2 \sin^2 \theta}$$

$$\begin{aligned} \rightarrow d\phi &= \frac{p_\phi}{m\lambda^2 \sin^2 \theta} \frac{d\theta}{\sqrt{\frac{2}{m\lambda^2} (E - U_{eff}(\theta))}} \\ &= \frac{p_\phi}{\sqrt{m\lambda^2 \cdot 2}} \frac{d\theta / \sin^2 \theta}{\sqrt{E - U_{eff}(\theta)}} \end{aligned}$$

$$\rightarrow \left[ \phi = \frac{p_\phi}{\sqrt{2m\lambda^2}} \int \frac{d\theta / \sin^2 \theta}{\sqrt{E - U_{eff}(\theta)}} + \text{const} \right] \quad (2)$$

(2)

Now:  $t = \sqrt{\frac{m l^2}{2}} \int \frac{d\theta}{\sqrt{E - U_{\text{eff}}(\theta)}} + \text{const}$

$$E - U_{\text{eff}}(\theta) = E - \frac{p_\phi^2}{2m l^2 \sin^2 \theta} + m g l \cos \theta$$

$$= \frac{1}{2m l^2 \sin^2 \theta} \left[ 2m E l^2 \sin^2 \theta - p_\phi^2 + 2m^2 g l^3 \sin^2 \theta \cos \theta \right]$$

$$= \frac{1}{2m l^2 \sin^2 \theta} \left[ 2m E l^2 (1 - \cos^2 \theta) - p_\phi^2 + 2m^2 g l^3 (1 - \cos^2 \theta) \cos \theta \right]$$

$$= \frac{1}{2m l^2 \sin^2 \theta} \left[ (2m E l^2 - p_\phi^2) + 2m^2 g l^3 \cos \theta - 2m E l^2 \cos^2 \theta - 2m^2 g l^3 \cos^3 \theta \right]$$

$$= \frac{1}{2m l^2 \sin^2 \theta} \left[ a + b \cos \theta + c \cos^2 \theta + d \cos^3 \theta \right]$$

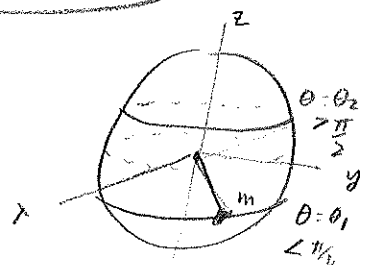
Turning points:  $0 = a + b \cos \theta + c \cos^2 \theta + d \cos^3 \theta$

Solve cubic: Two roots between  $-1$  and  $+1$   
 $0 \leq \theta_{1,2} \leq \pi$   $\infty$

Also:  $\phi = \frac{p_\phi}{\sqrt{2m} l^2} \int \frac{d\theta}{\sqrt{\sin^4 \theta (E - U_{\text{eff}}(\theta))}}$

$$\sin^4 \theta (E - U_{\text{eff}}(\theta)) = \frac{\sin^2 \theta}{2m l^2} \left[ a + b \cos \theta + c \cos^2 \theta + d \cos^3 \theta \right]$$

Same cubic to get  
 turning points.



Form of integrals:

(4)

$$I_1 \equiv \int \frac{d\theta}{\sqrt{E - U_{eff}(\theta)}}$$

$$\text{and } I_2 \equiv \int \frac{d\theta}{\sin^2 \theta \sqrt{E - U_{eff}(\theta)}}$$

$$\text{Let } x = \cos \theta \rightarrow dx = -\sin \theta d\theta = -\sqrt{1-x^2} d\theta$$

~~$I_1$~~

$$I_1 = \int \frac{d\theta \sqrt{1-x^2}}{\sqrt{a+bx+cx^2+dx^3}} \sqrt{2ml^2}$$

$$= \sqrt{2ml^2} \int \frac{dx}{\sqrt{a+bx+cx^2+dx^3}}$$

GBR

Elliptic function  
of 1st kind  
 $F(,)$

$$I_2 = \int \frac{d\theta \sqrt{2ml^2}}{\sqrt{(1-x^2)(a+bx+cx^2+dx^3)}}$$

$$= -\sqrt{2ml^2} \int \frac{dx}{(1-x^2) \sqrt{a+bx+cx^2+dx^3}}$$

$$x = \cos \theta$$

$$dx = -\sin \theta d\theta$$

$$= -\sqrt{1-x^2} d\theta$$

$$d\theta = -\frac{dx}{\sqrt{1-x^2}}$$

→ Combination of  
elliptic functions  
of 1st and 3rd kind

Elliptic Integrals1<sup>st</sup> kind:

$$F(\phi, k) = \int_0^{\phi} \frac{d\theta}{\sqrt{1 - k^2 \sin^2 \theta}} \quad 0 < k^2 < 1$$

$$= \int_0^{\sin \phi} \frac{dt}{\sqrt{(1 - k^2 t^2)(1 - t^2)}}$$

2<sup>nd</sup> kind:

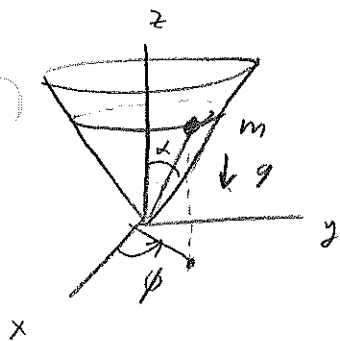
$$E(\phi, k) = \int_0^{\phi} \sqrt{1 - k^2 \sin^2 \theta} \, d\theta$$

$$= \int_0^{\sin \phi} \sqrt{\frac{1 - k^2 t^2}{1 - t^2}} \, dt$$

3<sup>rd</sup> kind:

$$\Pi(n, \phi, k) = \int_0^{\pi} \frac{d\theta}{(1 - n \sin^2 \theta) \sqrt{1 - k^2 \sin^2 \theta}}$$

$$= \int_0^{\sin \phi} \frac{dt}{(1 - n t^2) \sqrt{(1 - k^2 t^2)(1 - t^2)}}$$



spherical coords:  $(r, \theta = \alpha, \phi)$

$$T = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2 + r^2 \sin^2 \theta \dot{\phi}^2) \big|_{\theta = \alpha}$$

$$= \frac{1}{2} m (\dot{r}^2 + r^2 \sin^2 \alpha \dot{\phi}^2)$$

$$U = m g z$$

$$= m g r \cos \alpha$$

$$L = T - U$$

$$= \frac{1}{2} m (\dot{r}^2 + r^2 \sin^2 \alpha \dot{\phi}^2) - m g r \cos \alpha$$

No explicit  $t$  or  $\phi$  dependence

$$\rightarrow P_{\phi} = \frac{\partial L}{\partial \dot{\phi}} = \text{const}$$

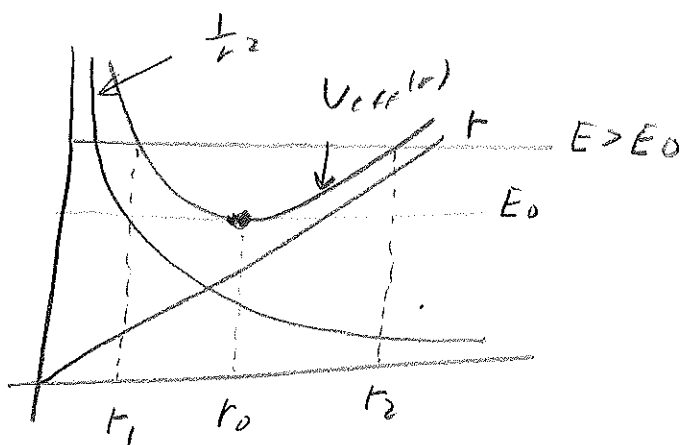
$$\& E = T + U = \text{const}$$

$$P_{\phi} = \frac{\partial L}{\partial \dot{\phi}} = m r^2 \sin^2 \alpha \dot{\phi} \rightarrow \dot{\phi} = \frac{P_{\phi}}{m r^2 \sin^2 \alpha}$$

$$E = \frac{1}{2} m (\dot{r}^2 + r^2 \sin^2 \alpha \left( \frac{P_{\phi}}{m r^2 \sin^2 \alpha} \right)^2) + m g r \cos \alpha$$

$$= \frac{1}{2} m \dot{r}^2 + \frac{P_{\phi}^2}{2 m r^2 \sin^2 \alpha} + m g r \cos \alpha$$

$$= \frac{1}{2} m \dot{r}^2 + U_{\text{eff}}(r)$$



$$U_{\text{eff}}(r) = \frac{P_{\phi}^2}{2 m r^2 \sin^2 \alpha} + m g r \cos \alpha$$

Turning points:

$$E = U_{\text{eff}}(r_1) = U_{\text{eff}}(r_2)$$

Find minimum of  $U_{eff}$ :

(2)

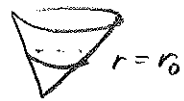
$$0 = \left. \frac{dU_{eff}}{dr} \right|_{r=r_0}$$

$$= \frac{-p_\phi^2}{m \sin^2 \alpha r_0^3} + mg \cos \alpha$$

$$\rightarrow \frac{p_\phi^2}{m \sin^2 \alpha r_0^3} = mg \cos \alpha$$

$$r_0^3 = \frac{p_\phi^2}{m^2 g \sin^2 \alpha \cos \alpha}$$

$$r_0 = \left( \frac{p_\phi^2}{m^2 g \sin^2 \alpha \cos \alpha} \right)^{\frac{1}{3}} \quad \text{--- for a circular orbit}$$



EOM:

$$\frac{2}{m} (E - U_{eff}(r)) = \dot{r}^2 = \left( \frac{dr}{dt} \right)^2$$

$$\frac{dr}{dt} = \sqrt{\frac{2}{m} (E - U_{eff}(r))}$$

$$\int dt = \int \frac{dr}{\sqrt{\frac{2}{m} (E - U_{eff}(r))}}$$

$\rightarrow$

$$t = \sqrt{\frac{m}{2}} \int \frac{dr}{\sqrt{E - \frac{p_\phi^2}{2mr^2 \sin^2 \alpha} - mgr \cos \alpha}} \quad t_{cont}$$

Also:

$$\sqrt{\frac{2}{m} (E - U_{eff}(r))} = \frac{dr}{dt} = \left( \frac{dr}{d\phi} \right) \frac{d\phi}{dt}$$

$$\sqrt{\frac{2}{m} (E - U_{eff}(r))} = \left( \frac{dr}{d\phi} \right) \frac{p_\phi}{m r^2 \sin^2 \alpha}$$

$$d\phi = \left( \frac{p_\phi}{m \sin^2 \alpha} \right) \frac{dr}{r^2 \sqrt{\frac{2}{m} (E - U_{eff}(r))}}$$

$$\rightarrow \phi = \frac{p_\phi}{\sqrt{2m} \sin^2 \alpha} \int \frac{dr}{r^2 \sqrt{E - \frac{p_\phi^2}{2m r^2 \sin^2 \alpha} - mgr \cos \alpha}} + \text{const}$$

Now:

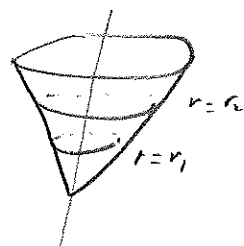
$$E - U_{eff}(r) = E - \frac{p_\phi^2}{2m r^2 \sin^2 \alpha} - mgr \cos \alpha$$

$$= \frac{p_\phi^2}{2m r^2 \sin^2 \alpha} \left( \frac{2m E \sin^2 \alpha}{p_\phi^2} r^2 - 1 - \frac{2m^2 g \sin^2 \alpha \cos \alpha}{p_\phi^2} r^3 \right)$$

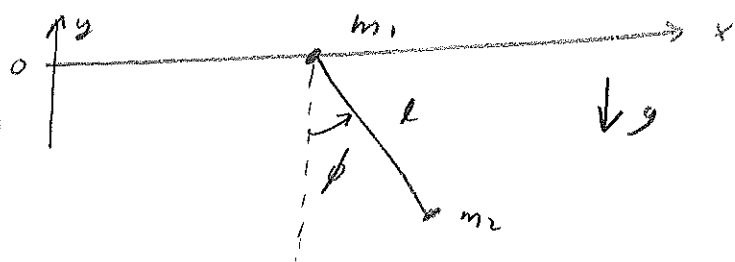
$$= \frac{p_\phi^2}{2m r^2 \sin^2 \alpha} [a + br + cr^2 + dr^3]$$

$$\left. \begin{array}{l} a = -1 \\ b = 0 \end{array} \right\} = (r-r_1)(r-r_2)(r-r_3) \quad \text{--- two roots } r_1, r_2 > 0 \text{ with } r_1 < r < r_2$$

$$c = \frac{2m E \sin^2 \alpha}{p_\phi^2}, \quad d = -\frac{2m^2 g \sin^2 \alpha \cos \alpha}{p_\phi^2}$$







$$x_1 = x, y_1 = 0$$

$$x_2 = x + l \sin \phi$$

$$y_2 = -l \cos \phi$$

$$U = m_2 g y_2 = -m_2 g l \cos \phi$$

$$T = \frac{1}{2} m_1 \dot{x}_1^2 + \frac{1}{2} m_2 (\dot{x}_2^2 + \dot{y}_2^2)$$

$$= \frac{1}{2} m_1 \dot{x}^2 + \frac{1}{2} m_2 (\dot{x}^2 + \underbrace{l^2 \cos^2 \phi \dot{\phi}^2 + 2 \dot{x} \dot{\phi} l \cos \phi + \underbrace{l^2 \sin^2 \phi \dot{\phi}^2}}_{})$$

$$= \frac{1}{2} m_1 \dot{x}^2 + \frac{1}{2} m_2 (\dot{x}^2 + l^2 \dot{\phi}^2) + m_2 l \cos \phi \dot{x} \dot{\phi}$$

$$= \frac{1}{2} (m_1 + m_2) \dot{x}^2 + \frac{1}{2} m_2 l^2 \dot{\phi}^2 + m_2 l \cos \phi \dot{x} \dot{\phi}$$

$$L = T - U$$

$$= \frac{1}{2} (m_1 + m_2) \dot{x}^2 + \frac{1}{2} m_2 l^2 \dot{\phi}^2 + m_2 l \cos \phi \dot{x} \dot{\phi} + m_2 g l \cos \phi$$

Since  $L$  does not depend explicitly on  $t$  or on  $x$

$$p_x \equiv \frac{\partial L}{\partial \dot{x}} = (m_1 + m_2) \dot{x} + m_2 l \cos \phi \dot{\phi} = \text{const}$$

$$E = \dot{x} \frac{\partial L}{\partial \dot{x}} + \dot{\phi} \frac{\partial L}{\partial \dot{\phi}} - L = \text{const}$$

where

$$E = \dot{x} [(m_1 + m_2) \dot{x} + m_2 l \cos \phi \dot{\phi}] + \dot{\phi} [m_2 l^2 \dot{\phi} + m_2 l \cos \phi \dot{x}] - \frac{1}{2} (m_1 + m_2) \dot{x}^2 - \frac{1}{2} m_2 l^2 \dot{\phi}^2 - m_2 l \cos \phi \dot{x} \dot{\phi} - m_2 g l \cos \phi$$

$$E = \frac{1}{2}(m_1 + m_2) \dot{x}^2 + \frac{1}{2} m_2 l^2 \dot{\phi}^2 + m_2 l \cos \phi \dot{x} \dot{\phi} - m_2 g l \cos \phi \quad (2)$$

$$= T + U$$

Now,  $p_x = (m_1 + m_2) \dot{x} + m_2 l \cos \phi \dot{\phi} = \text{const}$

$$\rightarrow \dot{x} = \frac{p_x - m_2 l \cos \phi \dot{\phi}}{m_1 + m_2}$$

Thus,

$$E = \frac{1}{2} (m_1 + m_2) \frac{1}{(m_1 + m_2)^2} \left( p_x^2 + m_2^2 l^2 \cos^2 \phi \dot{\phi}^2 - 2 p_x m_2 l \cos \phi \dot{\phi} \right)$$

$$+ \frac{1}{2} m_2 l^2 \dot{\phi}^2 + m_2 l \cos \phi \dot{\phi} \left( \frac{p_x - m_2 l \cos \phi \dot{\phi}}{m_1 + m_2} \right) - m_2 g l \cos \phi$$

$$= \frac{1}{2(m_1 + m_2)} p_x^2 - \frac{1}{2(m_1 + m_2)} m_2^2 l^2 \cos^2 \phi \dot{\phi}^2 + \frac{1}{2} m_2 l^2 \dot{\phi}^2 - m_2 g l \cos \phi$$

$$= \frac{1}{2(m_1 + m_2)} p_x^2 + \frac{1}{2} m_2 l^2 \dot{\phi}^2 \left[ 1 - \left( \frac{m_2}{m_1 + m_2} \right) \cos^2 \phi \right] - m_2 g l \cos \phi$$

$$= \underbrace{\frac{1}{2(m_1 + m_2)} p_x^2}_{\text{constant}} + \frac{1}{2} m_2 l^2 \dot{\phi}^2 \left[ 1 - \left( \frac{m_2}{m_1 + m_2} \right) \cos^2 \phi \right] - m_2 g l \cos \phi$$

Thus,  $\left( E - \frac{1}{2(m_1 + m_2)} p_x^2 + m_2 g l \cos \phi \right) = \frac{1}{2} m_2 l^2 \left[ 1 - \left( \frac{m_2}{m_1 + m_2} \right) \cos^2 \phi \right] \dot{\phi}^2$

$$E' = \text{const}$$

$$\sqrt{\frac{2}{m_2 l^2 \left[ 1 - \left( \frac{m_2}{m_1 + m_2} \right) \cos^2 \phi \right]}} (E' + m_2 g l \cos \phi) = \frac{d\phi}{dt}$$

~~Then~~

$$dt = \frac{d\phi}{\sqrt{\frac{2}{m_2 l^2 \left[ 1 - \left( \frac{m_2}{m_1 + m_2} \right) \cos^2 \phi \right]}} (E' + m_2 g l \cos \phi)}$$

$$\rightarrow t = \int \frac{d\phi}{\sqrt{\frac{2}{m_2 l^2} \sqrt{\frac{E' + m_2 g l \cos \phi}{1 - \left( \frac{m_2}{m_1 + m_2} \right) \cos^2 \phi}}} + \cos \phi, t$$

$$= \sqrt{\frac{m_2 l^2}{2}} \int d\phi \sqrt{\frac{1 - \left( \frac{m_2}{m_1 + m_2} \right) \cos^2 \phi}{E' + m_2 g l \cos \phi}} + \cos \phi, t$$

$$= l \sqrt{\frac{m_2}{2(m_1 + m_2)}} \int d\phi \sqrt{\frac{(m_1 + m_2) - m_2 \cos^2 \phi}{E' + m_2 g l \cos \phi}} + \cos \phi, t$$

$$= l \sqrt{\frac{m_2}{2(m_1 + m_2)}} \int d\phi \sqrt{\frac{m_1 + m_2 \sin^2 \phi}{E' + m_2 g l \cos \phi}} + \cos \phi, t$$

$$\left( \text{using } 1 - \cos^2 \phi = \sin^2 \phi \right)$$

If we work in reference frame where  $p_x = 0$ , (4)

$$\begin{aligned} \text{then } 0 &= (m_1 + m_2) \dot{x} + m_2 l \cos \phi \dot{\phi} \\ &= (m_1 + m_2) \dot{x} + m_2 l \frac{d}{dt} [\sin \phi] \\ &= \frac{d}{dt} [(m_1 + m_2) x + m_2 l \sin \phi] \end{aligned}$$

$$\rightarrow \boxed{(m_1 + m_2) x + m_2 l \sin \phi = \text{const}} \quad \leftrightarrow \quad \text{Diagram showing a horizontal line with a point labeled } x \text{ and a segment of length } l \text{ at an angle } \phi \text{ to the horizontal, with mass } m_1 + m_2 \text{ indicated below the segment.}$$

Recall:

~~$$\begin{aligned} x_2 &= x + l \sin \phi \\ &= \left( x + \frac{m_2 l \sin \phi}{m_1 + m_2} \right) \\ &= \frac{m_1 x + m_2 x + m_2 l \sin \phi}{m_1 + m_2} \end{aligned}$$~~

Choose const so that  $\phi = 0 \Leftrightarrow x = x_0$

Then,  $\text{const} = x_0 (m_1 + m_2)$

$$\rightarrow x + \left( \frac{m_2}{m_1 + m_2} \right) l \sin \phi = x_0$$

$$x = x_0 - \left( \frac{m_2}{m_1 + m_2} \right) l \sin \phi$$

Result:  $m_2$  located at

$$\begin{aligned} x_2 &= x + l \sin \phi = x_0 - \left( \frac{m_2}{m_1 + m_2} \right) l \sin \phi + l \sin \phi \\ &= x_0 + l \sin \phi \left( \frac{m_1}{m_1 + m_2} \right) \end{aligned}$$

$$y_2 = -l \cos \phi$$

Thus,

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$$x_2 - x_0 = l \sin \phi \left( \frac{m_1}{m_1 + m_2} \right)$$

$$y_2 = -l \cos \phi$$

$$\rightarrow \frac{x_2 - x_0}{l \left( \frac{m_1}{m_1 + m_2} \right)} = \sin \phi, \quad \frac{y_2}{l} = -\cos \phi$$

$$\frac{(x_2 - x_0)^2}{l^2 \left( \frac{m_1}{m_1 + m_2} \right)^2} + \frac{y_2^2}{l^2} = 1$$

$$\underline{\text{Eq.}}: \frac{(x_2 - x_0)^2}{a^2} + \frac{(y_2 - y_0)^2}{b^2} = 1$$

$$\rightarrow \boxed{a = l \left( \frac{m_1}{m_1 + m_2} \right), \quad b = l}$$

NOTE:

$$\text{limit } m_1 \gg m_2 \rightarrow a \approx l, \quad b = l$$

$\rightarrow$  circle.

