SD-TSIA: Ridge / Tikhonov

Joseph Salmon

http://josephsalmon.eu Télécom ParisTech

Outline

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Algorithms and computational aspects

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Ridge Definitions

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Reminder

$$\mathbf{y} = X\boldsymbol{\theta}^{\star} + \boldsymbol{\varepsilon}$$

- $\mathbf{y} \in \mathbb{R}^n$ observations
- $X \in \mathbb{R}^{n \times p}$ is the design matrix (column-wise: features)
- $oldsymbol{ heta}^{\star} \in \mathbb{R}^p$ is the **true** model parameter we aim at finding
- $\boldsymbol{\varepsilon} \in \mathbb{R}^n$ is the noise

Rem: possibly a supplementary variable is added for the constants

Singular Value Decomposition (SVD)

Theorem Golub and Van Loan (2013)

For any matrix $X \in \mathbb{R}^{n \times p}$, there exists two orthogonal matrices $U = [\mathbf{u}_1, \dots, \mathbf{u}_n] \in \mathbb{R}^{n \times n}$ and $V = [\mathbf{v}_1, \dots, \mathbf{v}_p] \in \mathbb{R}^{p \times p}$, such that

$$U^{\top}XV = \operatorname{diag}(s_1, \dots, s_{\operatorname{rg}(X)}) = \Sigma \in \mathbb{R}^{n \times p}$$

with $s_1 \geqslant s_2 \geqslant \cdots \geqslant s_{\operatorname{rg}(X)} > 0$, with $\operatorname{rg}(X) = \operatorname{rang}(X)$.

 $\underline{\mathsf{Rem}} \colon \forall i, i' \in [n], j, j' \in [p], \text{ one has } \mathbf{u}_i^\top \mathbf{u}_{i'} = \delta_{i,i'} \text{ and } \mathbf{v}_j^\top \mathbf{v}_{j'} = \delta_{j,j'}$

$$X = U\Sigma V^{\top} \Leftrightarrow X = \sum_{i=1}^{\operatorname{rg}(X)} s_i \mathbf{u}_i \mathbf{v}_i^{\top}$$

A least squares solution is then:

$$\hat{\boldsymbol{\theta}}^{\mathrm{OLS}} = X^{+}\mathbf{y} = \sum_{i=1}^{\mathrm{rg}(X)} \frac{1}{s_{i}} \mathbf{v}_{i} \mathbf{u}_{i}^{\top} \mathbf{y}$$

Numerical instabilities

$$\hat{\boldsymbol{\theta}}^{\mathrm{OLS}} = X^{+}\mathbf{y} = \sum_{i=1}^{\mathrm{rg}(X)} \frac{1}{s_{i}} \mathbf{v}_{i} \mathbf{u}_{i}^{\top} \mathbf{y}$$

If the smallest singular values s_i get close to zero then the numerical solution of the SVD is unstable!

<u>Rem</u>: this drawback is common not only for least squares, but also to other inverse problems (also referred to as "ill posed" in numerical analysis and signal processing)

Normal equations

A solution least squares solution θ need to satisfy:

$$X^{\top}X\dot{\boldsymbol{\theta}} = X^{\top}\mathbf{y} \Leftrightarrow V\Sigma^{\top}\Sigma V^{\top}\boldsymbol{\theta} = V\Sigma^{\top}U^{\top}\mathbf{y}$$

and if we look for $\pmb{\theta}$ with the following form: $\pmb{\theta} = V \pmb{\beta}$, this is equivalent to

$$\boldsymbol{\Sigma}^{\top} \boldsymbol{\Sigma} \boldsymbol{\beta} = \boldsymbol{\Sigma}^{\top} \boldsymbol{U}^{\top} \mathbf{y}$$

 $\Sigma^{ op}\Sigma$ diagonal with $r=\mathrm{rang}(X)$ non zero elements that are the s_i^2

$$\Sigma^{\top} \Sigma = \begin{bmatrix} s_1^2 & & 0 & & \\ & \ddots & & 0 \\ 0 & & s_r^2 & & \\ & 0 & & 0 \end{bmatrix} \in \mathbb{R}^{p \times p}$$

Normal equations (continued)

Regularized alternative: solve normal equations where

$$\begin{bmatrix} s_1^2 & & 0 & & \\ & \ddots & & & \\ 0 & & s_r^2 & & \\ & & & & \end{bmatrix} \text{ replaced by } \begin{bmatrix} s_1^2 & & 0 & & \\ & \ddots & & & \\ 0 & & s_r^2 & & \\ & & & & & \end{bmatrix} + \lambda \operatorname{Id}_p$$

It can be re-written by:

$$(\lambda \operatorname{Id}_p + \Sigma^{\top} \Sigma) \boldsymbol{\beta} = \Sigma^{\top} U^{\top} \mathbf{y}$$

i.e.,we add a small $\lambda>0$ to all the eigen values of $X^{\top}X$, λ being called the **regularization parameter**

$$\boldsymbol{\beta} = (\lambda \operatorname{Id}_p + \boldsymbol{\Sigma}^{\top} \boldsymbol{\Sigma})^{-1} \boldsymbol{\Sigma}^{\top} \boldsymbol{U}^{\top} \mathbf{y}$$

and hence

$$\boldsymbol{\theta} = V(\lambda \operatorname{Id}_p + \Sigma^{\mathsf{T}} \Sigma)^{-1} \Sigma^{\mathsf{T}} U^{\mathsf{T}} \mathbf{y}$$

Ridge: explicit formulation

With the SVD, the following equation simplifies:

$$\boldsymbol{\theta} = V(\lambda \operatorname{Id}_p + \Sigma^{\mathsf{T}} \Sigma)^{-1} \Sigma^{\mathsf{T}} U^{\mathsf{T}} \mathbf{y}$$

This gives a simple formulation for the Ridge estimator

$$\widehat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}} = (\lambda \operatorname{Id}_{p} + X^{\top} X)^{-1} X^{\top} \mathbf{y}$$

Reminder: under the full rank hypothesis $\hat{\boldsymbol{\theta}}^{OLS} = (X^{\top}X)^{-1}X^{\top}\mathbf{y}$

Rem:
$$\lim_{\lambda \to 0^+} \hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}} = \hat{\boldsymbol{\theta}}^{\mathrm{OLS}}$$

$$\lim_{\lambda \to +\infty} \hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}} = 0 \in \mathbb{R}^{p}$$

Kernel trick

Kernel trick: According to whether n>p or $n\leqslant p$, it is more suitable to consider the following equivalent formulation of the Ridge estimator:

$$X^{\top} (XX^{\top} + \lambda \operatorname{Id}_n)^{-1} \mathbf{y} = (X^{\top} X + \lambda \operatorname{Id}_p)^{-1} X^{\top} \mathbf{y}$$

- ▶ LHS: inverse/solve an $n \times n$ matrix
- ▶ RHS: inverse/solve an $p \times p$ matrix

Rem: this property is also useful for kernel method such as SVM (cf.machine learning course)

Exo: Show the kernel trick using the SVD of X

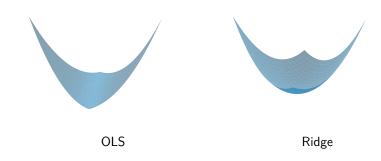
Ridge / Tikhonov : penalized definition

$$\hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}} = \operatorname*{arg\,min}_{\boldsymbol{\theta} \in \mathbb{R}^p} \quad \left(\quad \underbrace{\|\mathbf{y} - X\boldsymbol{\theta}\|_2^2}_{\text{data fitting}} \quad + \underbrace{\lambda \|\boldsymbol{\theta}\|_2^2}_{\text{regularization}} \right)$$

- Note that the *Ridge* estimator is **unique** for any fixed $\lambda > 0$
- We recover the limiting cases:

$$\lim_{\lambda o 0} \hat{m{ heta}}_{\lambda}^{ ext{rdg}} = \hat{m{ heta}}^{ ext{OLS}} ext{(solution with smallest } \| \cdot \|_2 ext{ norm)} \ \lim_{\lambda o +\infty} \hat{m{ heta}}_{\lambda}^{ ext{rdg}} = 0 \in \mathbb{R}^p$$

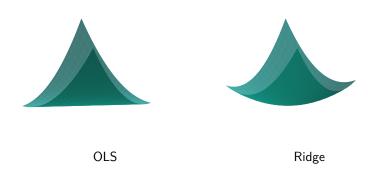
Link between the two formulation thanks to the first order conditions: for $f(\boldsymbol{\theta}) = \|\mathbf{y} - X\boldsymbol{\theta}\|_2^2/2 + \lambda \|\boldsymbol{\theta}\|_2^2/2$ $\nabla f(\boldsymbol{\theta}) = X^\top (X\boldsymbol{\theta} - \mathbf{y}) + \lambda \boldsymbol{\theta} = 0 \Leftrightarrow (X^\top X + \lambda \operatorname{Id}_p) \boldsymbol{\theta} = X^\top \mathbf{y}$



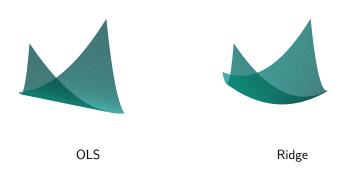
Regularize: simplify the problem when ill-conditioned



Regularize: simplify the problem when ill-conditioned



 $\label{eq:Regularize:model} Regularize: \ simplify \ the \ problem \ when \ ill-conditioned$



Regularize: simplify the problem when ill-conditioned



Regularize: simplify the problem when ill-conditioned

Constraint interpretation

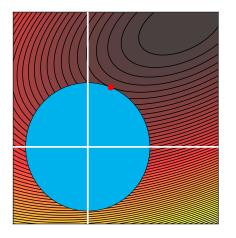
A "Lagrangian" formulation is as follows:

has for a certain
$$T>0$$
 the same solution as:
$$\begin{cases} \arg\min_{{\boldsymbol{\theta}}\in\mathbb{R}^p}\|{\mathbf{y}}-X{\boldsymbol{\theta}}\|_2^2\\ \text{s.t. } \|{\boldsymbol{\theta}}\|_2^2\leqslant T \end{cases}$$

Rem: the link $T \leftrightarrow \lambda$ is not explicit!

- If $T \to 0$ we recover the null vector: $0 \in \mathbb{R}^p$
- If $T \to \infty$ we recover $\hat{\boldsymbol{\theta}}^{\text{OLS}}$ (un-constrained)

Level lines and and constraints set



Optimization under ℓ_2 constraints

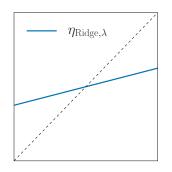
The orthogonal case

Consider the simple case:
$$X^{\top}X = \mathrm{Id}_p$$

$$\hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}} = (\lambda \, \mathrm{Id}_p + X^{\top}X)^{-1}X^{\top}\mathbf{y}$$

$$\hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}} = (\lambda \, \mathrm{Id}_p + \mathrm{Id}_p)^{-1}X^{\top}\mathbf{y} = \frac{1}{\lambda + 1}X^{\top}\mathbf{y}$$

$$\hat{\mathbf{y}} = \frac{1}{\lambda + 1}\mathbf{y} = (\eta_{\mathrm{rdg},\lambda}(\mathbf{y}_i))_{i=1,\dots,n}$$



<u>Rem</u>: the real function $\eta_{rdg,\lambda}$ is a linear contraction (shrinkage)

Associated prediction

From the *Ridge* coefficient:

$$\hat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}} = (\lambda \operatorname{Id}_p + X^{\top} X)^{-1} X^{\top} \mathbf{y}$$

the associated prediction is given by:

$$\hat{\mathbf{y}} = X \hat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}} = X (\lambda \operatorname{Id}_p + X^{\top} X)^{-1} X^{\top} \mathbf{y}$$

Rem: the estimator \hat{y} is linear w.r.t. y

Rem: reminding $X = \sum_{i=1}^{\operatorname{rg}(X)} s_i \mathbf{u}_i \mathbf{v}_i^{\top}$, (SVD) the matrix $H_{\lambda} := X(\lambda \operatorname{Id}_p + X^{\top}X)^{-1}X^{\top} = \sum_{j=1}^{\operatorname{rg}(X)} \frac{s_j^2}{s_j^2 + \lambda} \mathbf{u}_j \mathbf{u}_j^{\top}$ is the equivalent of the **hat matrix** If $\lambda \neq 0$, we do not have $H_{\lambda}^2 = H_{\lambda} = \sum_{j=1}^{\operatorname{rg}(X)} \mathbf{u}_j \mathbf{u}_j^{\top}$ anymore, so H_{λ} is not a projection (in general).

N remarks

Reminder: normalizing the p features the same way is necessary if you want the penalty to be similar for all features:

- center the observation and the features ⇒ no coefficient for the constants (hence no constraint on it)
- not centering features ⇒ do not put constraint on the constant feature (bias/intercept)

$$\hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}} = \operatorname*{arg\,min}_{\boldsymbol{\theta} \in \mathbb{R}^p} \|\mathbf{y} - X\boldsymbol{\theta} - \theta_0 \mathbf{1}_n\|_2^2 + \lambda \sum_{j=1}^p \theta_j^2$$

Alternative (without normalization): change the penalty in

$$\underset{\boldsymbol{\theta} \in \mathbb{R}^p}{\arg\min} \|\mathbf{y} - X\boldsymbol{\theta}\|_2^2 + \lambda \sum_{j=1}^p \alpha_j \boldsymbol{\theta}_j^2 \quad (\textit{e.g., } \alpha_j = \|\mathbf{x}_j\|_2^2)$$

Rem: for cross validation one can use $\frac{\|\mathbf{y}-X\boldsymbol{\theta}\|_2^2}{2n}$ rather than $\frac{\|\mathbf{y}-X\boldsymbol{\theta}\|_2^2}{2}$ as the data fitting part

Normalization (continued)

Consider the estimator Ridge with variables $X' = [\mathbf{x}_1', \dots, \mathbf{x}_K']$, such that there exist a linear link $\sum_{k=1}^K \mu_k \mathbf{x}_k' = 1$ (e.g.,qualitative variable):

$$\hat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}} = \underset{\boldsymbol{\theta} \in \mathbb{R}^{p}, \boldsymbol{\theta}' \in \mathbb{R}^{K}}{\text{arg min}} \|\mathbf{y} - X\boldsymbol{\theta} - X'\boldsymbol{\theta}' - \theta_{0}\mathbf{1}_{n}\|_{2}^{2} + \lambda \sum_{j=1}^{p} \theta_{j}^{2} + \lambda \sum_{k=1}^{K} \theta_{k}'^{2}$$

is equivalent to solve :

$$\hat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}} = \underset{\boldsymbol{\theta} \in \mathbb{R}^{p}, \boldsymbol{\theta}' \in \mathbb{R}^{K}}{\text{arg min}} \|\mathbf{y} - X\boldsymbol{\theta} - X'\boldsymbol{\theta}' - \theta_{0}\mathbf{1}_{n}\|_{2}^{2} + \lambda \sum_{j=1}^{p} \theta_{j}^{2} + \lambda \sum_{k=1}^{K} \theta_{k}'^{2}$$

Exo: proof; help: cf.Park (2006), page 35

General form of the bias

Under Additive White Gaussian Noise (AWGN) assumption $\mathbf{y} = X\boldsymbol{\theta}^{\star} + \boldsymbol{\varepsilon}$ with $\mathbb{E}(\boldsymbol{\varepsilon}) = 0$:

$$\mathbb{E}(\hat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}}) = \mathbb{E}[(\lambda \operatorname{Id}_{p} + X^{\top} X)^{-1} X^{\top} \mathbf{y}]$$

$$= \mathbb{E}[(\lambda \operatorname{Id}_{p} + X^{\top} X)^{-1} X^{\top} X \boldsymbol{\theta}^{\star} + (\lambda \operatorname{Id}_{p} + X^{\top} X)^{-1} X^{\top} \boldsymbol{\varepsilon}]$$

$$= (\lambda \operatorname{Id}_{p} + X^{\top} X)^{-1} X^{\top} X \boldsymbol{\theta}^{\star}$$

$$= \sum_{i=1}^{\operatorname{rg}(X)} \frac{s_{i}^{2}}{s_{i}^{2} + \lambda} \mathbf{v}_{i} \mathbf{v}_{i}^{\top} \boldsymbol{\theta}^{\star}$$

Rem: one recovers
$$\mathbb{E}(\hat{\boldsymbol{\theta}}^{\text{OLS}}) = \sum_{i=1}^{\operatorname{rg}(X)} \mathbf{v}_i \mathbf{v}_i^{\top} \boldsymbol{\theta}^{\star}$$
 when $\lambda \to 0$

Rem: the bias is
$$\mathbb{E}(\hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}}) - \boldsymbol{\theta}^{\star} = -\lambda (X^{\top}X + \lambda \operatorname{Id}_{p})^{-1}\boldsymbol{\theta}^{\star}$$

Variance in the general case

Under the assumption $\mathbb{E}(\varepsilon) = 0$, and with a homoscedastic model: $\mathbb{E}(\varepsilon \varepsilon^\top) = \sigma^2 \operatorname{Id}_n$

Variance / Covariance

$$V_{\lambda}^{\mathrm{rdg}} = \mathbb{E}\left((\hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}} - \mathbb{E}(\hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}}))(\hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}} - \mathbb{E}(\hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}})^{\top}\right)$$

Explicit computation:

$$\begin{split} \dot{V}_{\lambda}^{\mathrm{rdg}} = & \mathbb{E}(\dot{\lambda} \operatorname{Id}_{p} + X^{\top} X)^{-1} X^{\top} \boldsymbol{\varepsilon} \boldsymbol{\varepsilon}^{\top} X (\lambda \operatorname{Id}_{p} + X^{\top} X)^{-1}) \\ &= (\lambda \operatorname{Id}_{p} + X^{\top} X)^{-1} X^{\top} \mathbb{E}(\boldsymbol{\varepsilon} \boldsymbol{\varepsilon}^{\top}) X (\lambda \operatorname{Id}_{p} + X^{\top} X)^{-1} \\ &= \sigma^{2} (\lambda \operatorname{Id}_{p} + X^{\top} X)^{-2} X^{\top} X \quad \text{(matrix commute here)} \\ &= \sum_{i=1}^{\operatorname{rg}(X)} \frac{s_{i}^{2} \sigma^{2}}{(s_{i}^{2} + \lambda)^{2}} \mathbf{v}_{i} \mathbf{v}_{i}^{\top} \end{split}$$

<u>Rem</u>: one recovers $V^{\text{OLS}} = \sum_{i=1}^{\operatorname{rg}(X)} \frac{\sigma^2}{s_i^2} \mathbf{v}_i \mathbf{v}_i^{\mathsf{T}}$ when $\lambda \to 0$

Rem: one find a null variance when $\dot{\lambda} \rightarrow \infty$

Prediction risk

Homoscedastic assumption: $\mathbb{E}(\varepsilon \varepsilon^{\top}) = \sigma^2 \operatorname{Id}_n$

Quadratic prediction risk $\mathbb{E}\|Xoldsymbol{ heta}^{\star}-X\hat{oldsymbol{ heta}}_{\lambda}^{\mathrm{rdg}}\|^2$

Under the Homoscedastic assumption:

$$R_{\text{pred}}(\boldsymbol{\theta}^{\star}, \hat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}}) = \mathbb{E}\left[(\hat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}} - \boldsymbol{\theta}^{\star})^{\top} (X^{\top} X)(\hat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}} - \boldsymbol{\theta}^{\star})\right]$$

Explicit computation (begins as for OLS):

$$R_{\text{pred}}(\boldsymbol{\theta}^{\star}, \hat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}}) = \mathbb{E}\left[(\hat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}} - \boldsymbol{\theta}^{\star})^{\top} (X^{\top}X) (\hat{\boldsymbol{\theta}}_{\lambda}^{\text{rdg}} - \boldsymbol{\theta}^{\star}) \right]$$

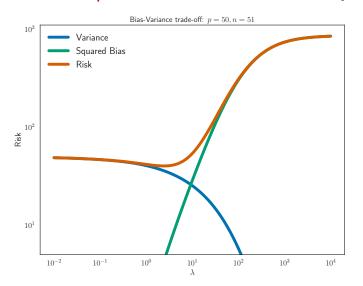
$$= \mathbb{E}\left[(X(X^{\top}X + \lambda \operatorname{Id}_{p})^{-1} X^{\top} \boldsymbol{\varepsilon})^{\top} (X(X^{\top}X + \lambda \operatorname{Id}_{p})^{-1} X^{\top} \boldsymbol{\varepsilon}) \right]$$

$$+ \lambda^{2} \boldsymbol{\theta}^{\star \top} (X^{\top}X + \lambda \operatorname{Id}_{p})^{-2} \boldsymbol{\theta}^{\star}$$

$$= \sum_{i=1}^{\operatorname{rg}(X)} \frac{s_{i}^{4} \sigma^{2}}{(s_{i}^{2} + \lambda)^{2}} + \lambda^{2} \boldsymbol{\theta}^{\star \top} (X^{\top}X + \lambda \operatorname{Id}_{p})^{-2} \boldsymbol{\theta}^{\star}$$

$$\underline{\mathsf{Rem}} \colon \lim_{\lambda \to 0} R_{\mathrm{pred}}(\boldsymbol{\theta}^{\star}, \hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}}) = \mathrm{rg}(X)\sigma^{2}, \lim_{\lambda \to \infty} R_{\mathrm{pred}}(\boldsymbol{\theta}^{\star}, \hat{\boldsymbol{\theta}}_{\lambda}^{\mathrm{rdg}}) = \|X\boldsymbol{\theta}^{\star}\|_{2}^{2}$$

Bias / Variance: simulated example



$$X \in \mathbb{R}^{51 \times 50}, \boldsymbol{\theta}^{\star} = (2, 2, 2, 2, 2, 0, \dots, 0)^{\top}$$

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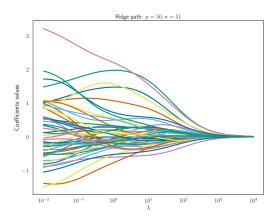
Ridge Definitions

Regularization parameter choice Regularization path Cross-Validation (CV)

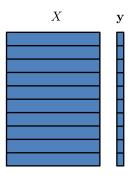
Algorithms and computational aspects

Choosing λ

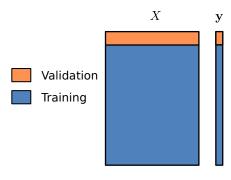
```
n_features = 50; n_samples = 50
X = np.random.randn(n_samples, n_features)
theta_true = np.zeros([n_features, ])
theta_true[0:5] = 2.
y_true = np.dot(X, theta_true)
y = y_true + 1. * np.random.rand(n_samples,)
```



- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, \mathbf{y}) into K blocks (sample-wise):



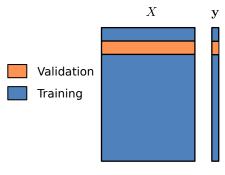
- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, y) into K blocks (sample-wise):



$$k = 1$$

- 1. Compute with the training part the estimators for $\lambda_1, \ldots, \lambda_r$: $\hat{\boldsymbol{\theta}}^{\lambda_1} \qquad \hat{\boldsymbol{\theta}}^{\lambda_r}$
- 2. Evaluate the (prediction) error $\operatorname{Error}_1^k, \ldots, \operatorname{Error}_r^k$ over the validation part,

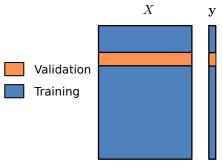
- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, y) into K blocks (sample-wise):



$$k = 2$$

- 1. Compute with the training part the estimators for $\lambda_1, \ldots, \lambda_r$: $\hat{\boldsymbol{\theta}}^{\lambda_1}, \ldots, \hat{\boldsymbol{\theta}}^{\lambda_r}$
- 2. Evaluate the (prediction) error $\operatorname{Error}_1^k, \dots, \operatorname{Error}_r^k$ over the validation part,

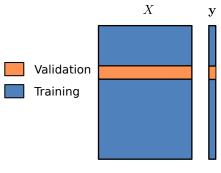
- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, y) into K blocks (sample-wise):



$$k = 3$$

- 1. Compute with the training part the estimators for $\lambda_1, \ldots, \lambda_r$: $\hat{\boldsymbol{\theta}}^{\lambda_1}, \ldots, \hat{\boldsymbol{\theta}}^{\lambda_r}$
- 2. Evaluate the (prediction) error $\operatorname{Error}_1^k, \dots, \operatorname{Error}_r^k$ over the validation part,

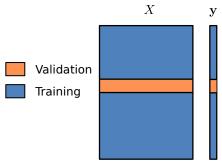
- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, y) into K blocks (sample-wise):



$$k = 4$$

- 1. Compute with the training part the estimators for $\lambda_1,\ldots,\lambda_r$: $\hat{\pmb{\theta}}^{\lambda_1}$ $\hat{\pmb{\theta}}^{\lambda_r}$
- 2. Evaluate the (prediction) error $\operatorname{Error}_1^k, \ldots, \operatorname{Error}_r^k$ over the validation part,

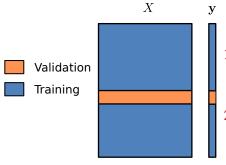
- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, y) into K blocks (sample-wise):



$$k = 5$$

- 1. Compute with the training part the estimators for $\lambda_1, \ldots, \lambda_r$: $\hat{\boldsymbol{\rho}}^{\lambda_1} \qquad \hat{\boldsymbol{\rho}}^{\lambda_r}$
- 2. Evaluate the (prediction) error $\operatorname{Error}_1^k, \dots, \operatorname{Error}_r^k$ over the validation part,

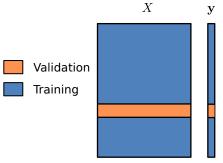
- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, y) into K blocks (sample-wise):



$$k = 6$$

- 1. Compute with the training part the estimators for $\lambda_1, \ldots, \lambda_r$: $\hat{\boldsymbol{\theta}}^{\lambda_1} \qquad \hat{\boldsymbol{\theta}}^{\lambda_r}$
- 2. Evaluate the (prediction) error $\operatorname{Error}_1^k, \dots, \operatorname{Error}_r^k$ over the validation part,

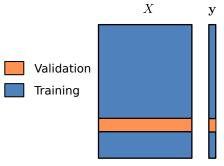
- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, y) into K blocks (sample-wise):



$$k = 7$$

- 1. Compute with the training part the estimators for $\lambda_1, \ldots, \lambda_r$: $\hat{\boldsymbol{\theta}}^{\lambda_1}, \ldots, \hat{\boldsymbol{\theta}}^{\lambda_r}$
- 2. Evaluate the (prediction) error $\operatorname{Error}_1^k, \ldots, \operatorname{Error}_r^k$ over the validation part,

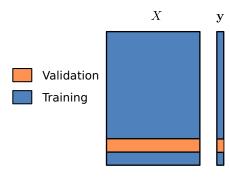
- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, y) into K blocks (sample-wise):



$$k = 8$$

- 1. Compute with the training part the estimators for $\lambda_1, \ldots, \lambda_r$: $\hat{\boldsymbol{\theta}}^{\lambda_1}, \ldots, \hat{\boldsymbol{\theta}}^{\lambda_r}$
- 2. Evaluate the (prediction) error $\operatorname{Error}_1^k, \ldots, \operatorname{Error}_r^k$ over the validation part,

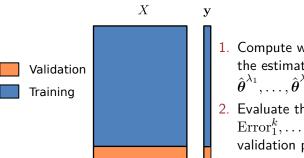
- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, y) into K blocks (sample-wise):



$$k = 9$$

- 1. Compute with the training part the estimators for $\lambda_1, \ldots, \lambda_r$: $\hat{\boldsymbol{\theta}}^{\lambda_1}, \ldots, \hat{\boldsymbol{\theta}}^{\lambda_r}$
- 2. Evaluate the (prediction) error $\operatorname{Error}_1^k, \ldots, \operatorname{Error}_r^k$ over the validation part,

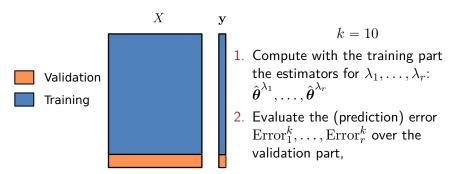
- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, \mathbf{y}) into K blocks (sample-wise):



$$k = 10$$

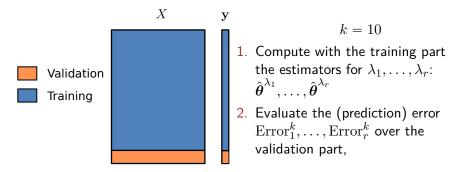
- Compute with the training part the estimators for $\lambda_1,\ldots,\lambda_r$: $\hat{\boldsymbol{\theta}}^{\lambda_1},\ldots,\hat{\boldsymbol{\theta}}^{\lambda_r}$
- 2. Evaluate the (prediction) error $\operatorname{Error}_1^k, \ldots, \operatorname{Error}_r^k$ over the validation part,

- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, \mathbf{y}) into K blocks (sample-wise):



<u>Parameter choice</u>: compute $\widehat{\text{Error}}_1, \dots, \widehat{\text{Error}}_r$, average the errors and choose $\hat{i}^{\text{CV}} \in \llbracket 1, r \rrbracket$ achieving the smallest one

- Choose a grid of r λ 's to test: $\lambda_1, \ldots, \lambda_r$
- ▶ Divide (X, \mathbf{y}) into K blocks (sample-wise):



<u>Parameter choice</u>: compute $\widehat{\operatorname{Error}}_1, \ldots, \widehat{\operatorname{Error}}_r$, average the errors and choose $\widehat{i}^{\operatorname{CV}} \in [\![1,r]\!]$ achieving the smallest one **Re-calibration**: compute $\widehat{\boldsymbol{\theta}}^{\lambda_{i^{\operatorname{CV}}}}$ this time over the whole sample

this time over the whole sample

CV in practice

Extreme cases of CV

- K=1 impossible, needs K=2
- K = n, "leave-one-out" strategy (cf.Jackknife): as many blocks as observations

<u>Rem</u>: K = n (often) computationally efficient but instable

Practical advice:

- "randomise the sample": having samples in random order avoid artifacts block (each fold needs to be representative of the whole sample!)
- standard choices: K = 5, 10

<u>Alternatives</u>: random partition validation/test, time series variants, etc. http://scikit-learn.org/stable/modules/cross_validation.html

<u>Rem</u>: in prediction the best predictors can be averaged/combined instead of recomputing an estimators over the whole set

CV variants sklearn

Crucial points: the structures train/test artificially created should represent faithfully the underlying learning problem

Classical alternatives:

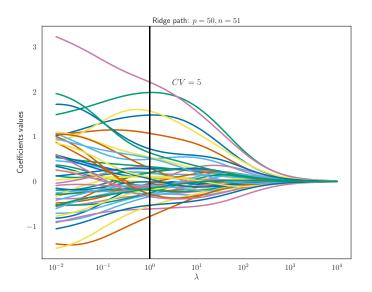
- random partitioning in train/test sets (cf.train_test_split)
- Time series variant: TimeSeriesSplit (never predict the past with future information)
- For classification tasks with unbalanced classes StratifiedKFold

<u>Rem</u>: averaging estimators (with weights reflecting their performance) is also relevant for prediction

More details:

http://scikit-learn.org/stable/modules/cross_validation.html

Choosing λ : example with CV = 5 (I)



Choosing λ : example with CV = 5 (II)

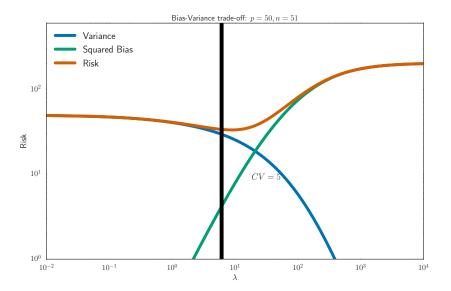


Table of Contents

Ridge Definitions

Regularization parameter choice

Algorithms and computational aspects

Algorithms to compute the Ridge estimator

- 'svd': most stable method, useful for computing many λ 's cause the SVD price is paid only once
- 'cholesky': matrix decomposition leading to a close form solution scipy.linalg.solve
- 'sparse_cg': conjugate gradient descent, useful also for sparse cases and high dimension (set tol/max_iter to a small value)
- stochastic gradient descent approaches : if n is huge

cf.the code of Ridge, ridge_path, RidgeCV in the module linear_model of sklearn

 $\underline{\mathsf{Rem}}$: it is rare to compute the Ridge estimator only for one single λ

Rem: crucial issue of computing SVD for huge matrices...

References I

- G. H. Golub and C. F. van Loan.
 Matrix computations.
 Johns Hopkins University Press, Baltimore, MD, fourth edition, 2013.
- M. Y. Park.
 Generalized linear models with regularization.
 PhD thesis, Stanford University, 2006.