# Modeling and Simulation in Python

Chapter 11

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```
# Configure Jupyter so figures appear in the notebook
%matplotlib inline

# Configure Jupyter to display the assigned value after an assignment
%config InteractiveShell.ast_node_interactivity='last_expr_or_assign'

# import functions from the modsim.py module
from modsim import *
```

#### SIR implementation

0.000000

We'll use a State object to represent the number (or fraction) of people in each compartment.

```
init = State(S=89, I=1, R=0)

values
S
89
I
R
0
```

To convert from number of people to fractions, we divide through by the total.

```
init /= sum(init)

values
S
0.988889
I
0.011111
R
```

make\_system creates a System object with the given parameters.

Here's an example with hypothetical values for beta and gamma.

```
tc = 3
       # time between contacts in days
tr = 4
            # recovery time in days
beta = 1 / tc
                   # contact rate in per day
gamma = 1 / tr
                  # recovery rate in per day
system = make_system(beta, gamma)
values
init
S 0.988889 I 0.011111 R 0.000000 dtyp...
t0
0
t_{end}
98
beta
0.333333
gamma
0.25
```

The update function takes the state during the current time step and returns the state during the next time step.

```
def update_func(state, t, system):
    """Update the SIR model.

state: State with variables S, I, R
    t: time step
    system: System with beta and gamma
```

```
returns: State object
"""
s, i, r = state
infected = system.beta * i * s
recovered = system.gamma * i

s -= infected
i += infected - recovered
r += recovered
return State(S=s, I=i, R=r)
```

To run a single time step, we call it like this:

```
state = update_func(init, 0, system)
values
```

0.985226

I 0.011996

R.

0.002778

Now we can run a simulation by calling the update function for each time step.

```
def run_simulation(system, update_func):
    """Runs a simulation of the system.

system: System object
    update_func: function that updates state

returns: State object for final state
    """

state = system.init

for t in linrange(system.t0, system.t_end):
    state = update_func(state, t, system)

return state
```

The result is the state of the system at t\_end

```
run_simulation(system, update_func)
```

values

 $\mathbf{S}$ 

```
0.520568
I
0.000666
```

R

0.478766

**Exercise** Suppose the time between contacts is 4 days and the recovery time is 5 days. After 14 weeks, how many students, total, have been infected?

Hint: what is the change in S between the beginning and the end of the simulation?

```
def make_system(beta, gamma):
    """Make a system object for the SIR model.
    beta: contact rate in days
    gamma: recovery rate in days
    returns: System object
    init = State(S=89, I=1, R=0)
    init /= sum(init)
    t0 = 0
    t_end = 14
    return System(init=init, t0=t0, t_end=t_end,
                  beta=beta, gamma=gamma)
            # time between contacts in days
tc = 4
tr = 5
            # recovery time in days
beta = 1 / tc
                   # contact rate in per day
gamma = 1 / tr
                  # recovery rate in per day
system = make_system(beta, gamma)
values
init
S 0.988889 I 0.011111 R 0.000000 dtyp...
t0
0
t_{end}
14
beta
0.25
gamma
0.2
```

```
run_simulation(system, update_func)

values
S
0.938488
I
0.019743
R
0.041770
```

## Using TimeSeries objects

If we want to store the state of the system at each time step, we can use one TimeSeries object for each state variable.

```
def run_simulation(system, update_func):
    """Runs a simulation of the system.

Add three Series objects to the System: S, I, R

system: System object
    update_func: function that updates state
    """

S = TimeSeries()
I = TimeSeries()
R = TimeSeries()

state = system.init
t0 = system.t0
S[t0], I[t0], R[t0] = state

for t in linrange(system.t0, system.t_end):
    state = update_func(state, t, system)
    S[t+1], I[t+1], R[t+1] = state

return S, I, R
```

Here's how we call it.

```
def make_system(beta, gamma):
    """Make a system object for the SIR model.

    beta: contact rate in days
    gamma: recovery rate in days

    returns: System object
    """
    init = State(S=89, I=1, R=0)
    init /= sum(init)
```

And then we can plot the results.

Here's what they look like.

```
plot_results(S, I, R)
savefig('figs/chap11-fig01.pdf')
```

### Using a DataFrame

Instead of making three TimeSeries objects, we can use one DataFrame.

We have to use row to selects rows, rather than columns. But then Pandas does the right thing, matching up the state variables with the columns of the DataFrame.

```
def run_simulation(system, update_func):
    """Runs a simulation of the system.

system: System object
    update_func: function that updates state

returns: TimeFrame
"""
```

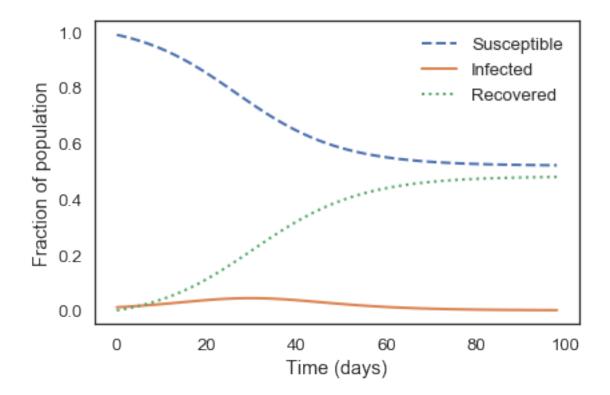


Figure 1: png

```
frame = TimeFrame(columns=system.init.index)
frame.row[system.t0] = system.init

for t in linrange(system.t0, system.t_end):
    frame.row[t+1] = update_func(frame.row[t], t, system)

return frame
```

Here's how we run it, and what the result looks like.

```
tc = 3  # time between contacts in days
tr = 4  # recovery time in days

beta = 1 / tc  # contact rate in per day
gamma = 1 / tr  # recovery rate in per day

system = make_system(beta, gamma)
results = run_simulation(system, update_func)
results.head()
```

I

S

 $\mathbf{R}$ 

0

```
0.988889
0.011111
0.000000
1
0.985226
0.011996
0.002778
0.981287
0.012936
0.005777
3
0.977055
0.013934
0.009011
4
0.972517
0.014988
0.012494
We can extract the results and plot them.
```

```
plot_results(results.S, results.I, results.R)
```

## **Exercises**

Exercise Suppose the time between contacts is 4 days and the recovery time is 5 days. Simulate this scenario for 14 weeks and plot the results.

```
# Solution
tc = 4
          # time between contacts in days
tr = 5  # recovery time in days
                  # contact rate in per day
beta = 1 / tc
gamma = 1 / tr
                 # recovery rate in per day
system = make_system(beta, gamma)
results = run_simulation(system, update_func)
plot_results(results.S, results.I, results.R)
```

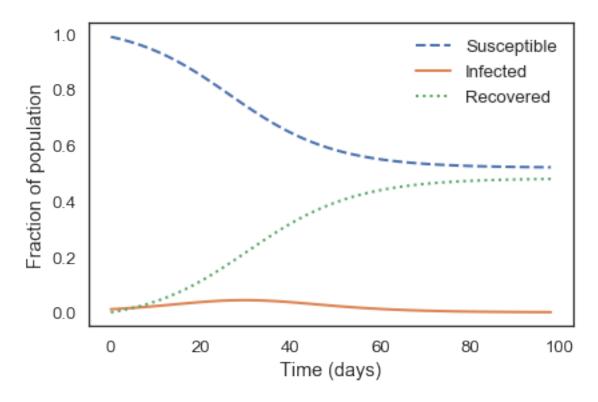


Figure 2: png

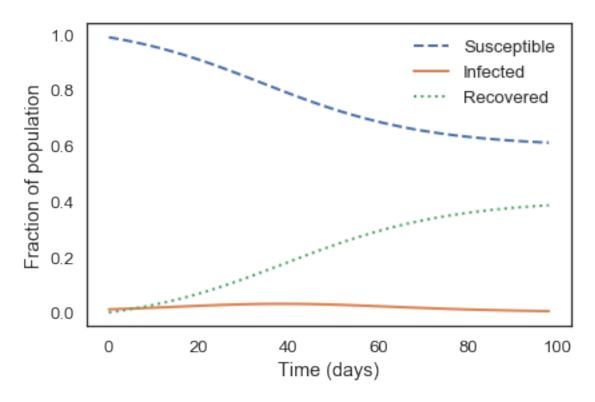


Figure 3: png