## **Parameters and Equilibrium Conditions**

```
P1 = [2 1 1 1 1 1];

P2 = [2 1 1 1 0.99 1];

P3 = [2 1 0.5 1 1 1];

P4 = [2 1 1 1 0.5 1];

E1 = [0 0 0];

E2 = [0 pi pi];

case1 = num2cell([P1,E1]);

case2 = num2cell([P1,E2]);

u = 0;

C = [1 0 0 0 0 0];

D = 0;
```

## Case 1 (L1): P1, E1

```
% pull parameters and initial conditions for case 1
[m0, m1, m2, l1, l2, g, ye, thetale, theta2e] = deal(case1{:});

mt = m0 + m1 + m2;

M = [mt, -m1*l1*cos(theta1e), -m2*l2*cos(theta2e);
    -m1*l1*cos(theta1e), m1*l1^2, 0;
    -m2*l2*cos(theta2e), 0, m2*l2^2];

G = [0,0,0;0,m1*l1*g*cos(theta1e),0;0,0,m2*l2*g*cos(theta2e)];

W = [1 0 0]';

A = [zeros(3), eye(3); M^-1*(-G), zeros(3)]
```

```
A = 6 \times 6
         0
                   0
                              0
                                   1.0000
                                                              0
                                                   0
         a
                   0
                              0
                                   0
                                              1.0000
                                                              0
         0
                   0
                              0
                                        0
                                                   0
                                                        1.0000
         0
            -0.5000
                      -0.5000
                                        0
                                                   0
                                                             0
             -1.5000
         0
                       -0.5000
                                        0
                                                   0
                                                              0
             -0.5000
                        -1.5000
                                        0
                                                   0
                                                              0
```

```
B = [0;0;0;M^{-1}W]
```

```
B = 6×1
0
0
0.5000
0.5000
0.5000
```

```
sys = ss(A,B,C,D);

[v,d] = eig(A)
```

```
v = 6×6 complex
1.0000 + 0.0000i  -1.0000 + 0.0000i  0.0000 - 0.1925i  0.0000 + 0.1925i ...
0.0000 + 0.0000i  0.0000 + 0.0000i  -0.0000 - 0.3849i  -0.0000 + 0.3849i
0.0000 + 0.0000i  0.0000 + 0.0000i  -0.0000 - 0.3849i  -0.0000 + 0.3849i
0.0000 + 0.0000i  0.0000 + 0.0000i  0.2722 - 0.0000i  0.2722 + 0.0000i
0.0000 + 0.0000i  0.0000 + 0.0000i  0.5443 + 0.0000i  0.5443 + 0.0000i
```

```
0.0000 + 0.0000i
                       0.0000 + 0.0000i
                                         0.5443 - 0.0000i
                                                           0.5443 + 0.0000i
  d = 6 \times 6 \text{ complex}
    0.0000 + 0.0000i
                       0.0000 + 0.0000i
                                         0.0000 + 0.0000i
                                                            0.0000 + 0.0000i · · ·
    0.0000 + 0.0000i
                       0.0000 + 0.0000i
                                         0.0000 + 0.0000i
                                                            0.0000 + 0.0000i
    0.0000 + 0.0000i
                       0.0000 + 0.0000i
                                         0.0000 + 1.4142i
                                                            0.0000 + 0.0000i
    0.0000 + 0.0000i
                       0.0000 + 0.0000i
                                         0.0000 + 0.0000i
                                                            0.0000 - 1.4142i
    0.0000 + 0.0000i
                       0.0000 + 0.0000i
                                         0.0000 + 0.0000i
                                                            0.0000 + 0.0000i
    0.0000 + 0.0000i
                       0.0000 + 0.0000i
                                         0.0000 + 0.0000i
                                                            0.0000 + 0.0000i
  pole(sys)
  ans = 6 \times 1 complex
    0.0000 + 0.0000i
    0.0000 + 0.0000i
    0.0000 + 1.4142i
    0.0000 - 1.4142i
   -0.0000 + 1.0000i
   -0.0000 - 1.0000i
  zero(sys)
  ans = 4 \times 1 complex
    0.0000 + 1.0000i
    0.0000 - 1.0000i
    0.0000 + 1.0000i
    0.0000 - 1.0000i
Case 2 (L2): P1, E2
  [m0, m1, m2, 11, 12, g, ye, thetale, theta2e] = deal(case2{:});
 mt = m0 + m1 + m2;
 M = [mt, -m1*11*cos(theta1e), -m2*12*cos(theta2e);
       -m1*11*cos(theta1e), m1*11^2, 0;
       -m2*12*cos(theta2e), 0, m2*12^2];
  G = [0,0,0;0,m1*11*g*cos(thetale),0;0,0,m2*12*g*cos(theta2e)];
  W = [1 \ 0 \ 0]';
  A = [zeros(3), eye(3); M^-1*(-G), zeros(3)]
  A = 6 \times 6
          0
                             0
                                  1.0000
                                                           0
                    0
                                                 0
                    0
                             0
                                            1.0000
          0
                                       0
                                                           0
          0
                    0
                             0
                                       0
                                                 0
                                                      1.0000
          0
              -0.5000
                        -0.5000
                                       0
                                                 0
                                                           0
          0
               1.5000
                         0.5000
                                       0
                                                 0
                                                           0
          0
               0.5000
                         1.5000
                                       0
                                                           0
  B = [0;0;0;M^-1*W]
  B = 6 \times 1
          0
          0
          0
     0.5000
     -0.5000
    -0.5000
  sys = ss(A,B,C,D);
  [v,d] = eig(A)
```

```
v = 6 \times 6
     1.0000 -1.0000 -0.1925 -0.0000 0.1925 0.0000
                0 0.3849 0.5000 -0.3849 -0.5000

0 0.3849 -0.5000 -0.3849 0.5000

0.0000 0.2722 0.0000 0.2722 0.0000

0 -0.5443 -0.5000 -0.5443 -0.5000

0 -0.5443 0.5000 -0.5443 0.5000
         0
            0
            0
            0
            0
d = 6 \times 6
                  0 0 0 0
0 0 0 0
0 -1.4142 0 0
0 0 -1.0000 0
0 0 0 1.4142
0 0 0 0
                                                                          0
0
0
            0
            0
            0
                                                            0 0
1.4142 0
                                                             0
            0
            0
            0
                         0
                                     0
                                                      0 0 1.0000
```

## pole(sys)

ans =  $6 \times 1$ 

0

0

-1.4142 -1.0000

1.4142

1.0000

## zero(sys)

ans =  $4 \times 1$ 

-1.0000

1.0000

-1.0000

1.0000