

Lecture 16: Embedded Domain Specific Language



Outline:

- ▶ Motivation
- ▶ Render pixels in ASCII
- ▶ Shape DSL

Motivation of EDSL



- ▶ Semantic gap between computation domains and programming language abstractions.
- ▶ Shape domain:
 - ▶ Shapes are constructed as circles, squares.
 - ▶ Shapes are composed by operations such as intersect, invert, transform, translate.
 - ▶ Shapes are rendered as pixels on screen.
- ▶ Language domain:
 - ▶ Language provides types, expressions, and functions.
 - ▶ Language provides no shapes or pixels.
 - ▶ Application library is not strict and semantics is vague.

Design of EDSL



- ▶ Identify the primary domain abstractions
- ▶ Define constructors for primitive components
- ▶ Define operators to compose higher-level components
- ▶ Implement run function
 - ▶ interpreter function to *run* the abstraction
 - ▶ compiler function to *compile* the abstraction into lower-level representation.

Shape DSL



► Shape abstraction¹

```
1 data Shape =  
2     -- primitive shapes  
3     Empty | Disc | Square  
4     -- shape operators  
5     | Translate Vec Shape  
6     | Transform Matrix Shape  
7     | Union Shape Shape  
8     | Intersect Shape Shape  
9     | Invert Shape  
10  
11 data Vec      = Vec { vecX, vecY :: Double } -- for offset  
12 data Matrix = Mat Vec Vec -- for rotation/deformation  
13  
14 -- run function: is a point in the shape  
15 inside :: Point -> Shape -> Bool
```

¹adopted from

<https://bitbucket.org/russo/afp-code/src/HEAD/L2/src/?at=master>



Render shape in ASCII



► Convert a shape into a string

```
1 render :: Window  -- text window to display the shape
2           -> Shape   -- shape to be rendered
3           -> String  -- resulting string for the shape
4
5 render win sh = unlines -- [str] to str separated by \n
6             $ map (concatMap putPixel) -- points to strings
7             (pixels win) -- a list of a list of points
8
9 where
10    putPixel p  | p `inside` sh = "[]"
11          | otherwise      = " "
```

Display window

- ▶ Define an abstract window for displaying rendered shapes

```
1 type Point = Vec      -- a point has x/y coordinates
2
3 data Window = Window
4   { bottomLeft    :: Point      -- bottom left corner
5     , topRight     :: Point      -- upper right corner
6     , resolution   :: (Int, Int) -- points per dimension
7   }
8
9 defaultWindow = Window  -- convenient constant
10  { bottomLeft   = point (-1.5) (-1.5)
11    , topRight    = point 1.5 1.5
12    , resolution  = (10, 10)
13  }
```

Display window



- ▶ Define function to convert window to points

```
1 -- Generate [[Point]] corresponding to the pixels of a window
2 pixels :: Window -> [[Point]]
3 pixels (Window p0 p1 (w,h)) =
4   [
5     [
6       -- points per row
7       Vec x y | x <- samples (vecX p0) (vecX p1) w
8     ]
9     -- point rows from top to bottom
10    | y <- reverse $ samples (vecY p0) (vecY p1) h
11  ]
12
13 -- Generate n evenly spaced numbers between x0 and x1
14 samples :: Double -> Double -> Int -> [Double]
15 samples x0 x1 n = take n
16           $ iterate (+dx) x0 -- increment by dx
17 where
18   dx = (x1 - x0) / fromIntegral (n - 1)
```

Run shape

- ▶ A shape abstract is run by checking whether a point is inside the shape.

```
1 inside :: Point -> Shape -> Bool
2 _ `inside` Empty          = False -- no point in empty shape
3 p `inside` Disc           = distance p <= 1 -- disk shape
4 p `inside` Square          = maxnorm p <= 1 -- square shape
5 -- move shape by vector 'v'
6 p `inside` Translate v s = (p `sub` v) `inside` s
7 -- transform shape by matrix 'm'
8 p `inside` Transform m s = (inv m `mul` p) `inside` s
9 p `inside` Union s1 s2    = p `inside` s1 || p `inside` s2
10 p `inside` Intersect s1 s2 = p `inside` s1 && p `inside` s2
11 p `inside` Invert s      = not (p `inside` s)
12
13 -- helper functions
14 distance :: Point -> Double
15 distance p = sqrt $ x*x + y*y
16   where x = vecX p; y = vecY p
17
18 maxnorm :: Point -> Double
19 maxnorm p = max (abs x) (abs y)
20   where x = vecX p; y = vecY p
```

Vector and matrix



► Basic operations on vector and matrix

```
1 data Vec      = Vec { vecX, vecY :: Double }
2 data Matrix = Mat Vec Vec
3
4 matrix :: Double -> Double -> Double -> Double -> Matrix
5 matrix a b c d = Mat (Vec a b) (Vec c d)
6
7 cross (Vec a b) (Vec c d) = a * c + b * d
8
9 -- Matrix multiplication
10 mul :: Matrix -> Vec -> Vec
11 mul (Mat r1 r2) v = Vec (cross r1 v) (cross r2 v)
12
13 -- Matrix inversion
14 inv :: Matrix -> Matrix
15 inv (Mat (Vec a b) (Vec c d)) =
16           matrix (d/k) (-b/k) (-c/k) (a/k)
17   where k = a * d - b * c
18
19 -- Subtraction
20 sub :: Vec -> Vec -> Vec
21 sub (Vec x y) (Vec dx dy) = Vec (x - dx) (y - dy)
```

Render shape



▶ Render an inverted disc

```
1 run :: Shape -> IO()
2 run shape = putStrLn $ render defaultWindow shape
3
4 run $ invert disc
5
6 [] []
7 [] []
8 [] []
9 []
10 []
11 []
12 []
13 []
14 []
15 []
```

Render shape 🔊

- ▶ Render an inverted disc that is zoomed in 50%

```
1 run :: Shape -> IO()
2 run shape = putStrLn $ render defaultWindow shape
3
4 zoom_in n shape = Transform m shape
5     where m = matrix (n/100+1) 0
6                      0          (n/100+1)
7
8 run $ zoom_in 50 $ invert disc
9
10 []
11 []
12 []
13 []
14 []
15 []
16 []
17 []
18 []
19 []
```

Render shape

▶ Render a square

```
1 run :: Shape -> IO()
2 run shape = putStrLn $ render defaultWindow shape
3
4 run $ square
5
6
7
8     []
9     []
10    []
11    []
12    []
13    []
```

Render shape

► Render a rotated square

```
1 run :: Shape -> IO()
2 run shape = putStrLn $ render defaultWindow shape
3
4 -- rotate clock-wise by degrees
5 rotate degree s = Transform m s
6     where m = matrix (cos alpha) (-(sin alpha))
7           (sin alpha) (cos alpha)
8           alpha = pi * (degree/180)
9
10 run $ rotate 30 square -- rotate 30 degrees
11
12 []
13 []
14 []
15 []
16 []
17 []
18 []
19 []
```

Render shape



- ▶ Render a rotated and scaled square

```
1 run :: Shape -> IO()
2 run shape = putStrLn $ render defaultWindow shape
3
4 scale :: Double -> Shape -> Shape -- scale a shape by 's'
5 scale s = Transform (matrix s 0
6                         0 s)
7
8 -- scale up by 1.2 and then rotate 30 degrees clockwise
9 run $ rotate 30 $ scale 1.2 square
10 []
11 []
12 []
13 []
14 []
15 []
16 []
17 []
18 []
19 []
```

Render shape



▶ Render a stretched shape

```
1 run :: Shape -> IO()
2 run shape = putStrLn $ render defaultWindow shape
3
4 -- stretch a shape by X-axis
5 stretchX s = Transform (matrix s 0
                           0 1)
6
7
8 -- stretch a square by X-axis to make a stick
9 stick d = rotate d $ stretchX 0.1 square
10
11 run $ stick 45  -- a stick rotated 45 degrees
12
13
14
15           []
16           []
17           []
18           []
```

Render shape

► Render a unioned shape

```
1 run :: Shape -> IO()
2 run shape = putStrLn $ render defaultWindow shape
3
4 stick d = rotate d $ stretchX 0.1 square
5 -- shift to the left
6 left = Translate (vec (-0.25) 0) $ stick 45
7 -- shift to the right
8 right = Translate (vec (0.25) 0) $ stick (-45)
9 -- union two shapes
10 arms = left `union` right
11
12 run arms
13
14
15
16      []
17      []
18      []
19      []
```

Render shape

► Render a unioned shape

```
1 stick d = rotate d $ stretchX 0.1 square
2 -- shift to the left
3 left = Translate (vec (-0.25) 0) $ stick 45
4 -- shift to the right
5 right = Translate (vec (0.25) 0) $ stick (-45)
6 -- union two shapes
7 arms = left `union` right
8 -- shift downwards
9 legs = Translate (vec 0 (-1)) arms
10 -- scale a square to make a small block
11 block = Translate (vec 0 1) (scale 0.6 square)
12
13 run $ arms `union` legs `union` block
14      [] []
15      [] []
16      [] []
17      [] []
18      []
19      []
20      []
21      []
22      []
23      []
```