

#### Tratamiento de Señales

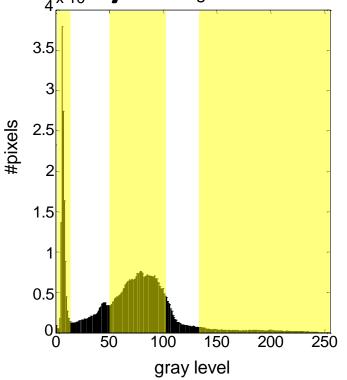
Version 2024-I

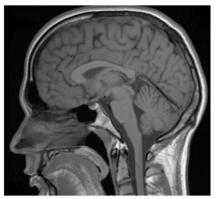
### Ecualización de Histogramas

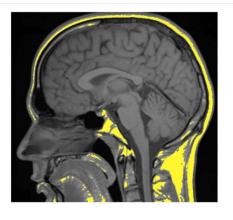
[Capítulo 3]

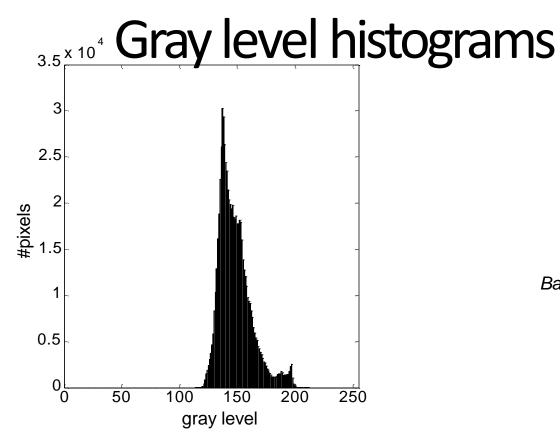
#### Dr. José Ramón Iglesias

DSP-ASIC BUILDER GROUP Director Semillero TRIAC Ingenieria Electronica Universidad Popular del Cesar Gray level histograms image









Bay image

Grav level histogram in viewfinder



### Gray level histograms

- To measure a histogram:
  - For B-bit image, initialize 2<sup>B</sup> counters with 0
  - Loop over all pixels x,y
  - When encountering gray level f[x,y]=i, increment counter # $\iota$
- Normalized histogram can be thought of as an estimate of the probability distribution of the continuous signal amplitude
- Use fewer, larger bins to trade off amplitude resolution against sample size.

### Histogram equalization

Idea:

Find a non-linear transformation

$$g = T(f)$$

that is applied to each pixel of the input image f[x,y], such that a uniform distribution of gray levels results for the output image g[x,y].

### Histogram equalization

Analyse ideal, continuous case first ...

#### **Assume**

- Normalized input values  $0 \le f \le 1$  and output values  $0 \le g \le 1$
- T(f) is differentiable, increasing, and invertible, i.e., there exists

$$f = T^{-1}(g) \qquad 0 \le g \le 1$$

**Goal**: pdf  $p_g(g) = 1$  over the entire range  $0 \le g \le 1$ 

### Histogram equalization for continuous case

From basic probability theory

$$p_f(f)$$
  $\xrightarrow{f} T(f)$   $\xrightarrow{g}$   $p_g(g) = \left[p_f(f)\frac{df}{dg}\right]_{f=T^{-1}(g)}$ 

Consider the transformation function

$$g = T(f) = \int_0^f p_f(\alpha) d\alpha \qquad 0 \le f \le 1$$

### Histogram equalization for discrete case

Now, f only assumes discrete amplitude values  $f_0, f_1, ..., f_{L-1}$  with empirical probabilities

$$P_0 = \frac{n_0}{n}$$
  $P_1 = \frac{n_1}{n}$  !  $P_{L-1} = \frac{n_{L-1}}{n}$  where  $n$  is total number of pixels

■ Discrete approximation of  $g = T(f) = \int_0^f p_f(\alpha) d\alpha$ 

$$g_k = T[f_k] = \sum_{i=0}^k P_i$$
 for  $k = 0, 1, ..., L-1$ 

■ The resulting values  $g_k$  are in the range [0,1] and might have to be scaled and rounded appropriately.

# Histogram equalization

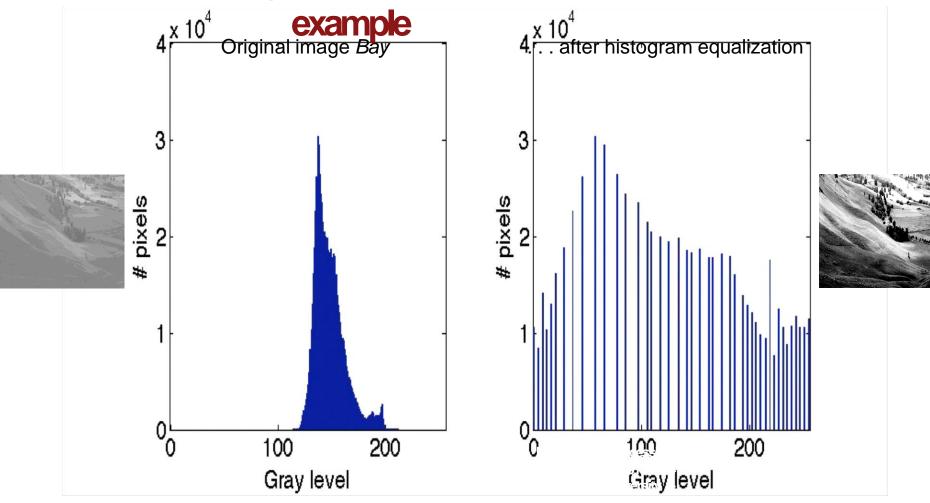


Original image Bay



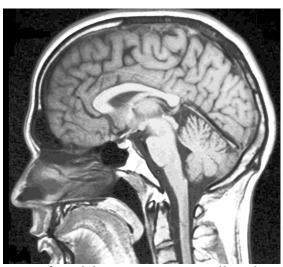
... after histogram equalization

### Histogram equalization

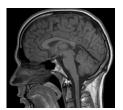


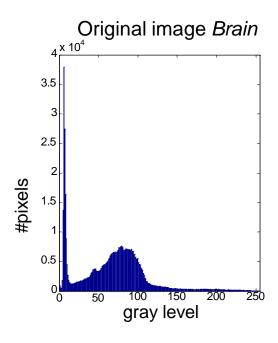


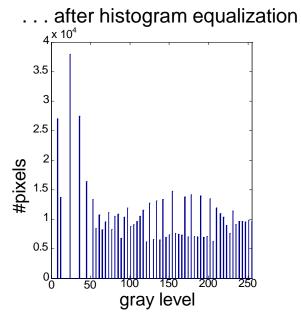
Original image Brain



... after histogram equalization









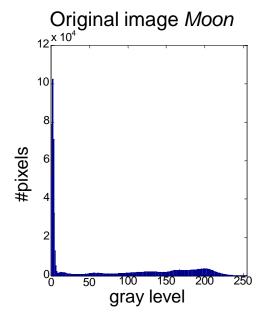


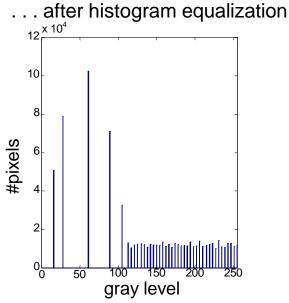
Original image *Moon* 



... after histogram equalization

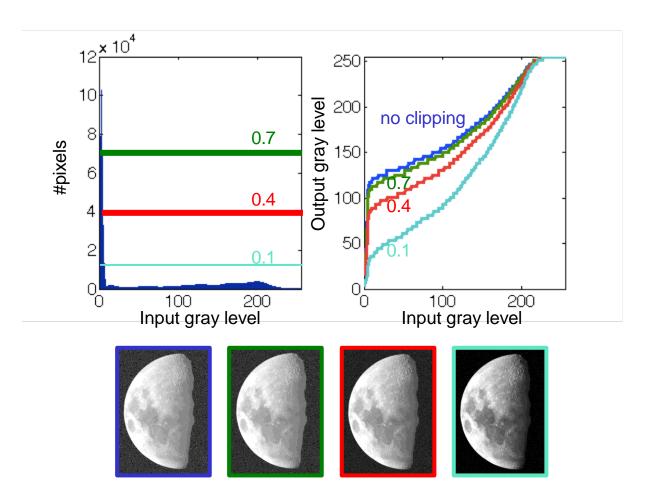




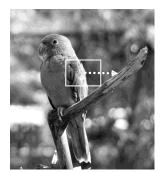




### Contrast-limited histogram equalization



Histogram equalization based on a histogram obtained from a portion of the image



Sliding window approach: different histogram (and mapping) for every pixel



Tiling approach: subdivide into overlapping regions, mitigate blocking effect by smooth blending between neighboring tiles

 Limit contrast expansion in flat regions of the image, e.g., by clipping histogram values.
 ("Contrast-limited adaptive histogram equalization")

[Pizer, Amburn et al. 1987]

Original image Parrot



Global histogram equalization

Adaptive histogram equalization, 8x8 tiles





Adaptive histogram equalization, 16x16 tiles

Original image Dental Xray





Global histogram equalization

Adaptive histogram equalization, 8x8 tiles

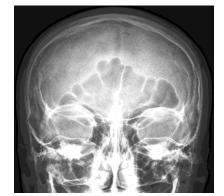




Adaptive histogram equalization, 16x16 tiles

Original image Skull Xray

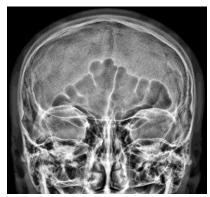




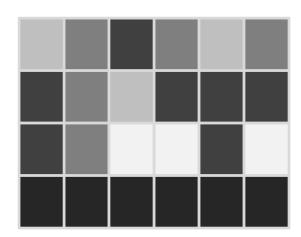
Global histogram equalization

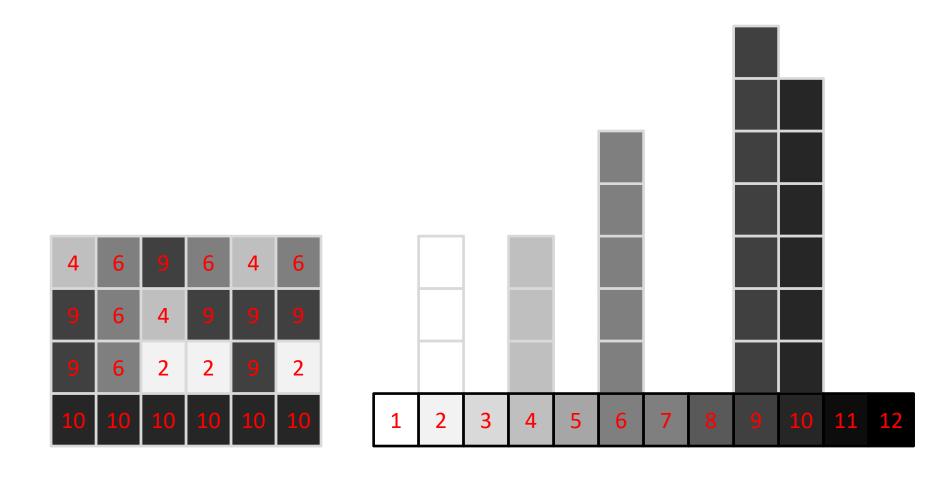
Adaptive histogram equalization, 8x8 tiles

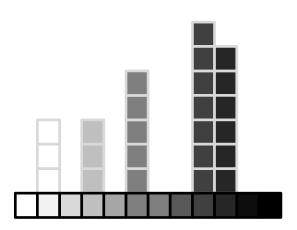


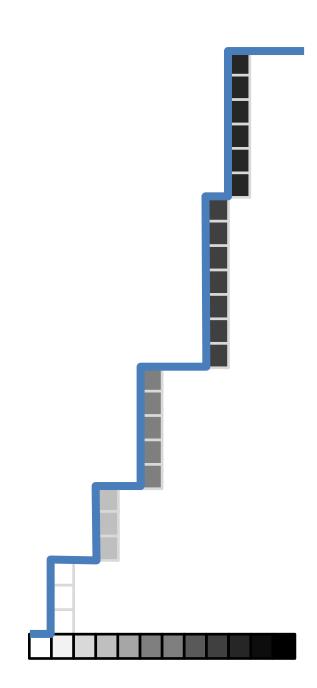


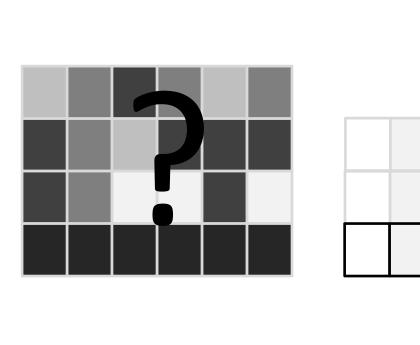
Adaptive histogram equalization, 16x16 tiles

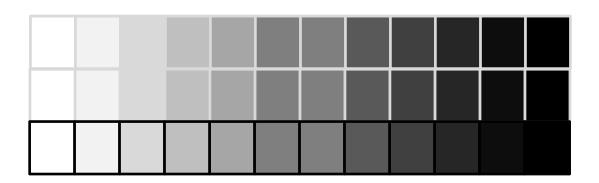




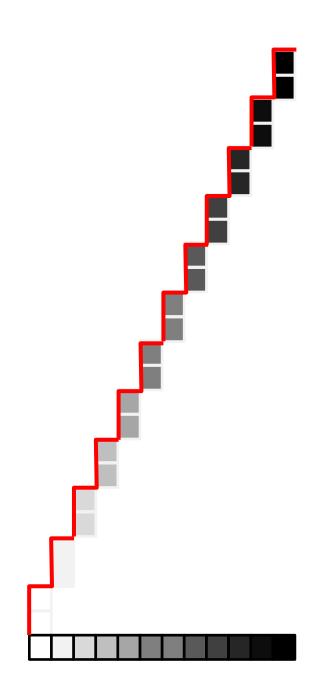


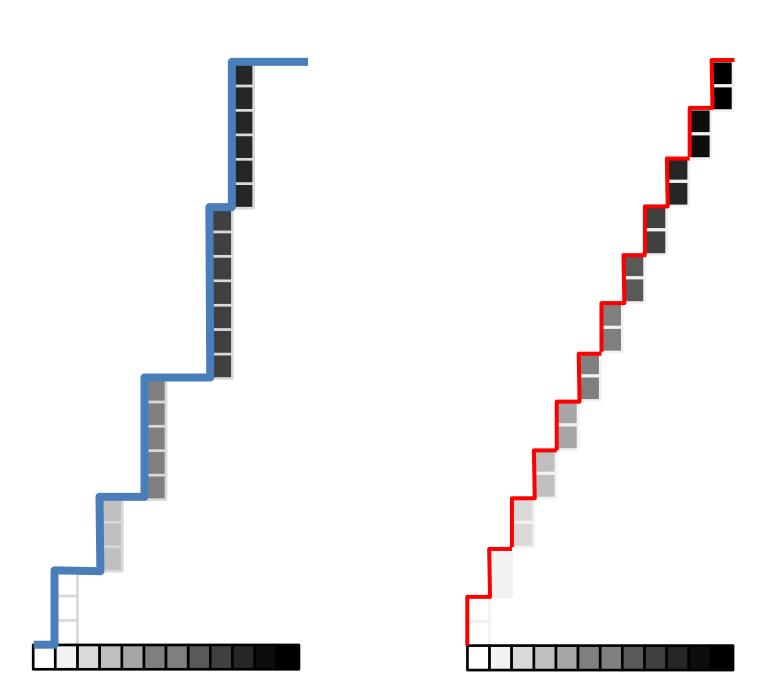


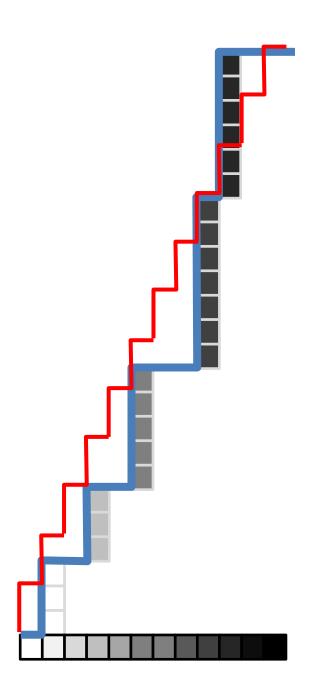


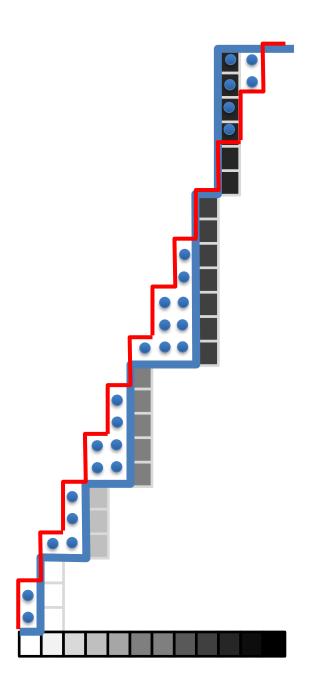




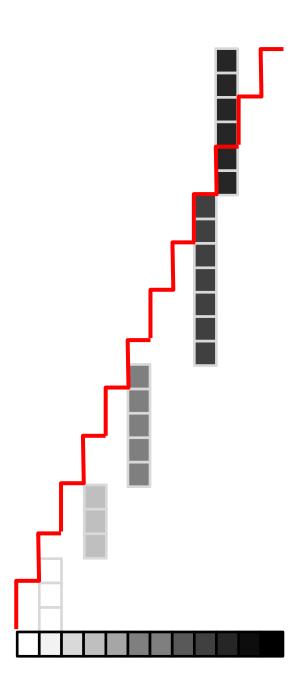


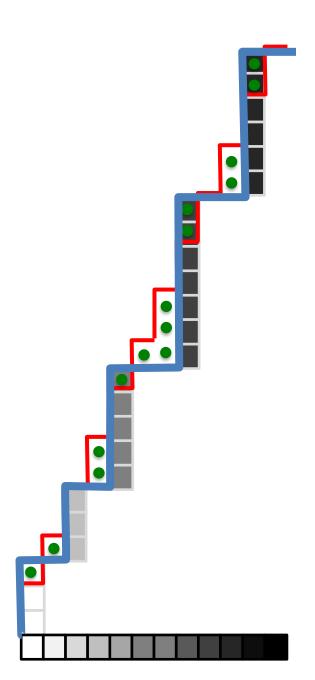




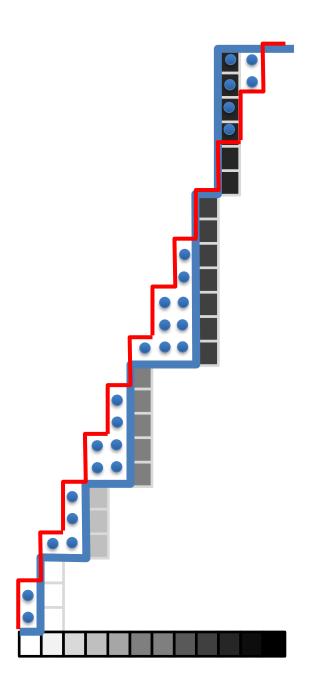


Error = 27 (circles)

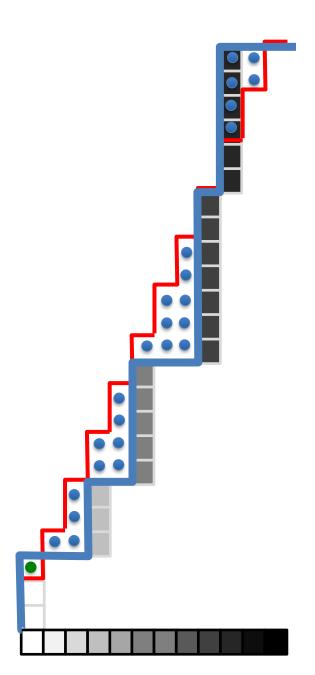




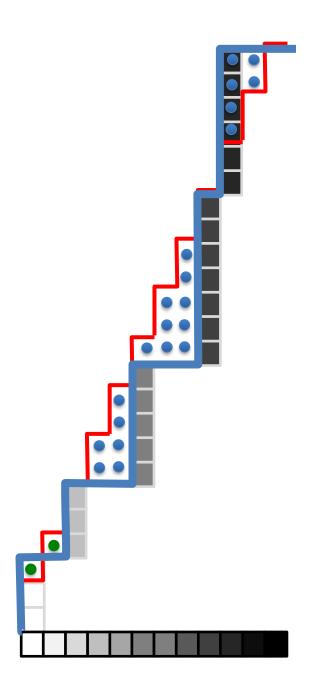
Error = 15



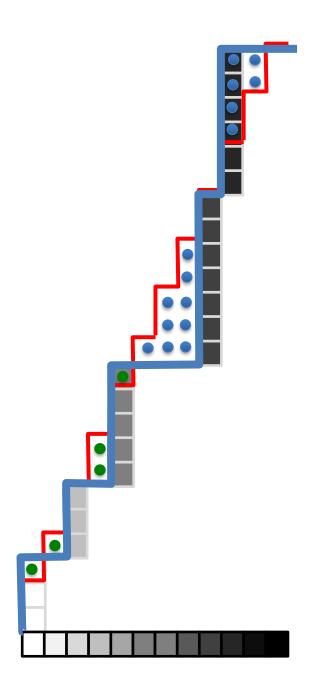
Error = 27 (circles)



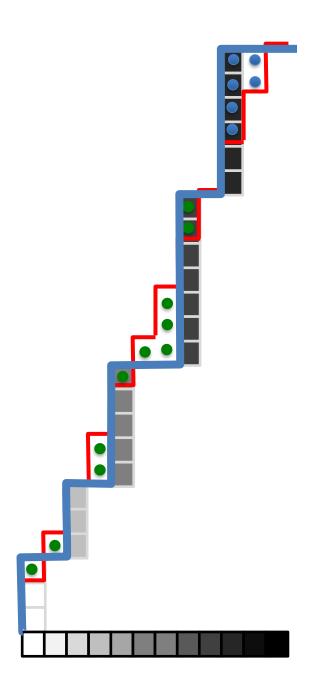
Error = 26 (circles)



Error = 23

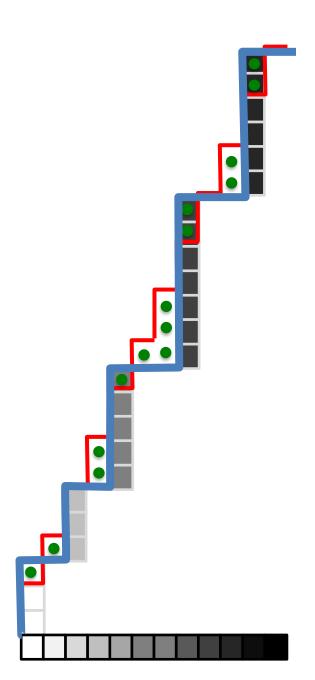


Error = 20



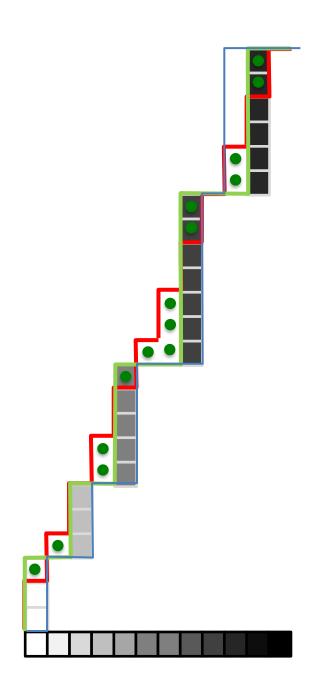
How to shift the bars, so that the difference between ideal accumulative function (red) and real accumulative function (blue) is minimal?

**Error** = **17** 



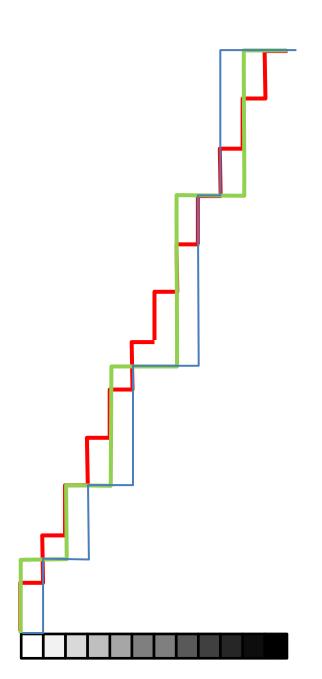
How to shift the bars, so that the difference between ideal accumulative function (red) and real accumulative function (blue) is minimal?

Error = 15

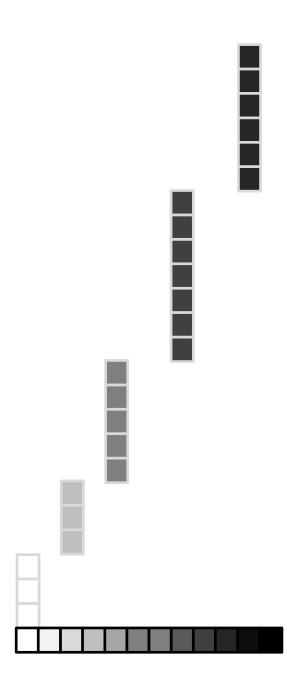


ideal accumulative function (red)
[old] real accumulative function (blue)
[new] real accumulative function (green)

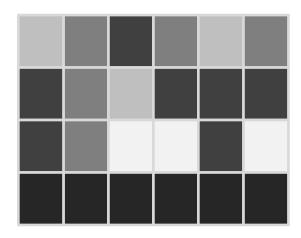
Error = 15 (green circles)

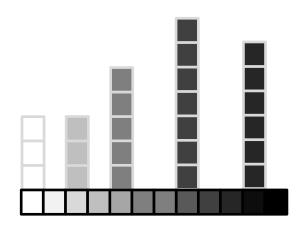


ideal accumulative function (red)
[old] real accumulative function (blue)
[new] real accumulative function (green)

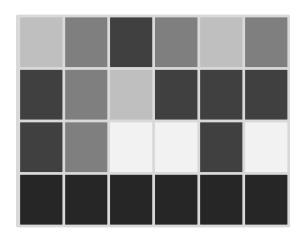


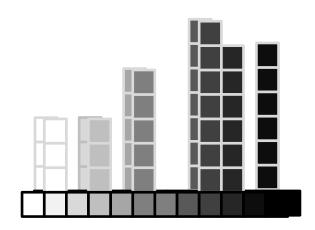
Before



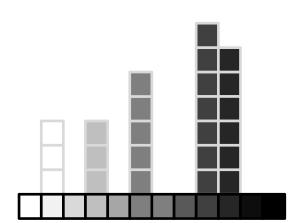


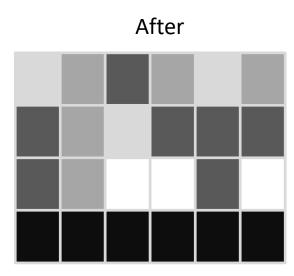
BAFORE

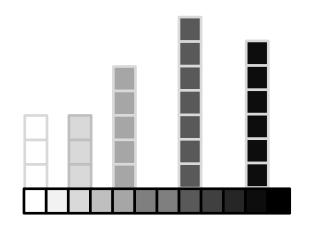




Before



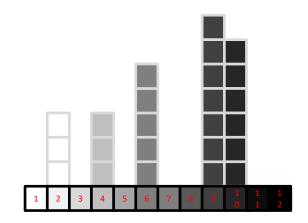


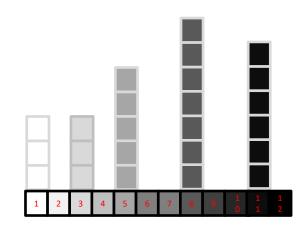


#### Before

4	6	9	6	4	6
9	6	4	9	9	9
9	6	2	2	9	2
10	10	10	10	10	10

3	5	8	5	3	5
8	5	3	8	8	8
8	5	1	1	8	1
11	11	11	11	11	11



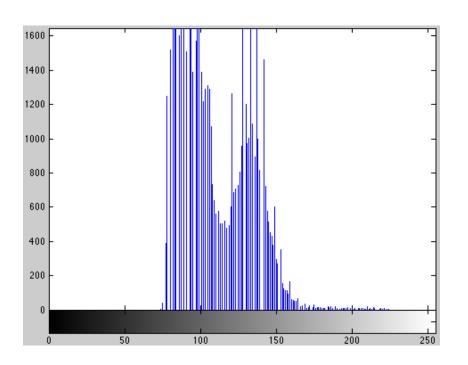


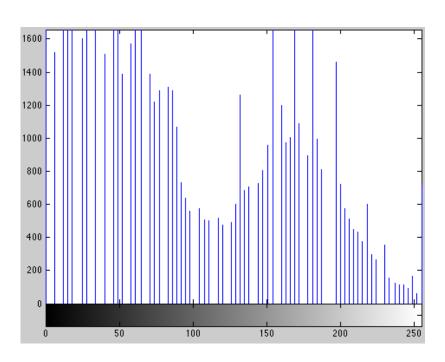
Before

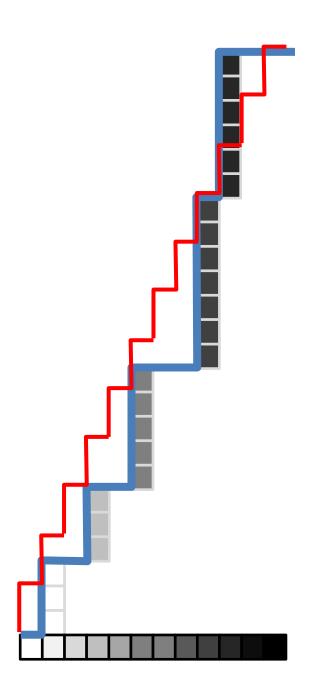




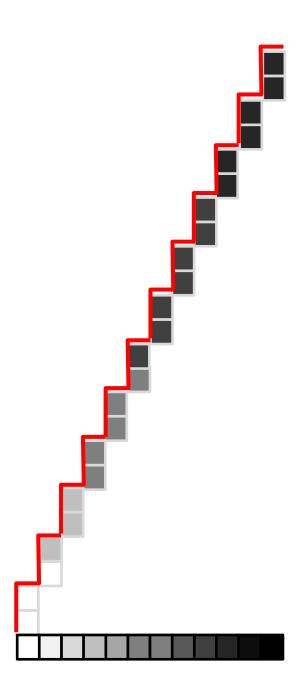
Before



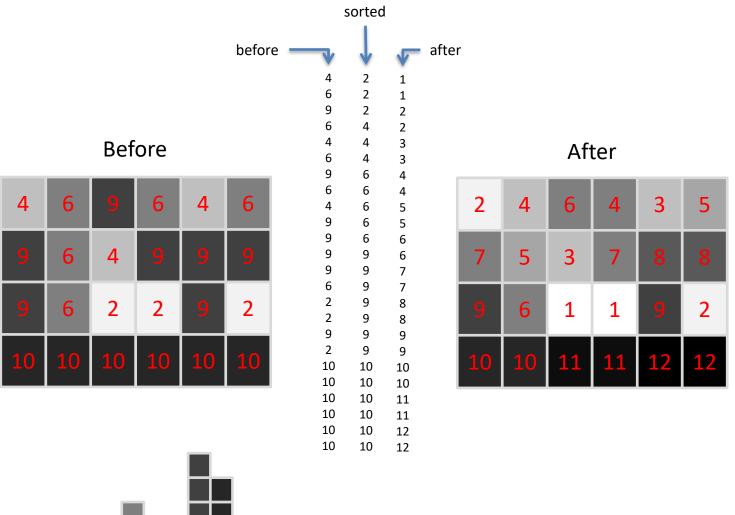


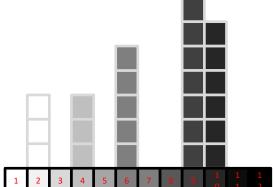


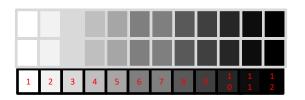
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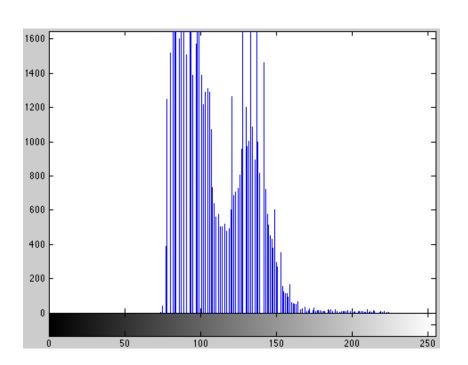


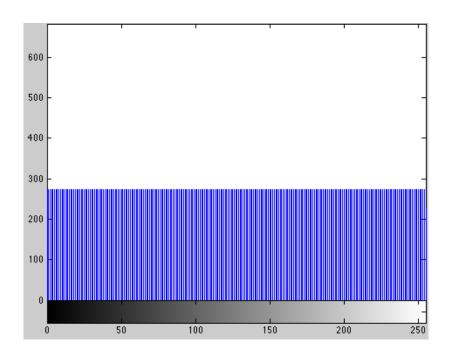
Before





Before After





Method 1



Method 2

