

RWTH Aachen University
Faculty of Mathematics, Computer Science and Natural Sciences
Chair of Computer Science 13 (Computer Vision)
Prof. Dr. Bastian Leibe

Seminar Report

Linear and Nonlinear Filters

Alexander Skretting
Matriculation Number: 445457

Jose Rigel Soeryo Soebandoro
Matriculation Number: 444345

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Advisor: George Lydakis

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Jose Rigel Soeryo Soebandoro

444 345

I. Introduction *Both*

1. Motivation: What problems prompts the use of filters? (*Unwanted noise, enhancement of image properties to extract information*)
2. General difference between Linear and Nonlinear Filters

II. Linear Filters *Jose*

1. Formal definition of Linear Filter *Mathematical formula/definition of a linear filter*
2. Types of Linear Filters: *Box, Gaussian, Derivative* General Formulas, implementation in code
3. Use Cases *Noise Removal, Edge Detection, Image Sharpening*
4. Convolution and Kernel *Matrix Operation, neighboring pixels, normalization, separable convolution* add implementation and code to show how matrices are used to pass pixels and transform them
5. Optimization of sigma values *How to determine the best sigma values, what factors come into play to determine those values, what makes the best result and metrics of 'best' result*
6. Known key differences between each types eg: *How does the edges look with Box Filter vs Gaussian Filter, are there Square artifacts with Box filters?*

III. Nonlinear Filters *Alexander*

1. Formal Defintion of Nonlinear Filters
2. Types of Nonlinear Filters: *Median Filtering, Bilateral Filtering, MinFilter, MaxFilter, MeanShift Filter, CellularAutomaton etc.*
3. Optimal Nonlinear Filtering *Kushner–Stratonovich filtering*
4. Typical applications of Nonlinear filters: *Noise Removal*

IV. Testing and Analysis *Both*

1. Methodology (*Image sets to be used, metrics of analysis to determine quality*)
2. Test scenarios *Noise Removal, Image Sharpening, Edge Detection, Median Filtering, Morphological Filtering*
3. Optimization of parameters based on each types of filter and how the optimization is determined.
4. Results based on test cases (*Graph, Data Table, etc*)
5. Tests limitations *What is and is not possible to be determined based on testing*
6. Results discussion

V. Conclusion *Both*

1. Pros and Cons of each Types of Filters *Is one filter objectively better? Do they work better for different scenarios?*
2. Limitations of Filtering
3. Further Analysis to be done *What can supplement Filters for further use cases in image processing*