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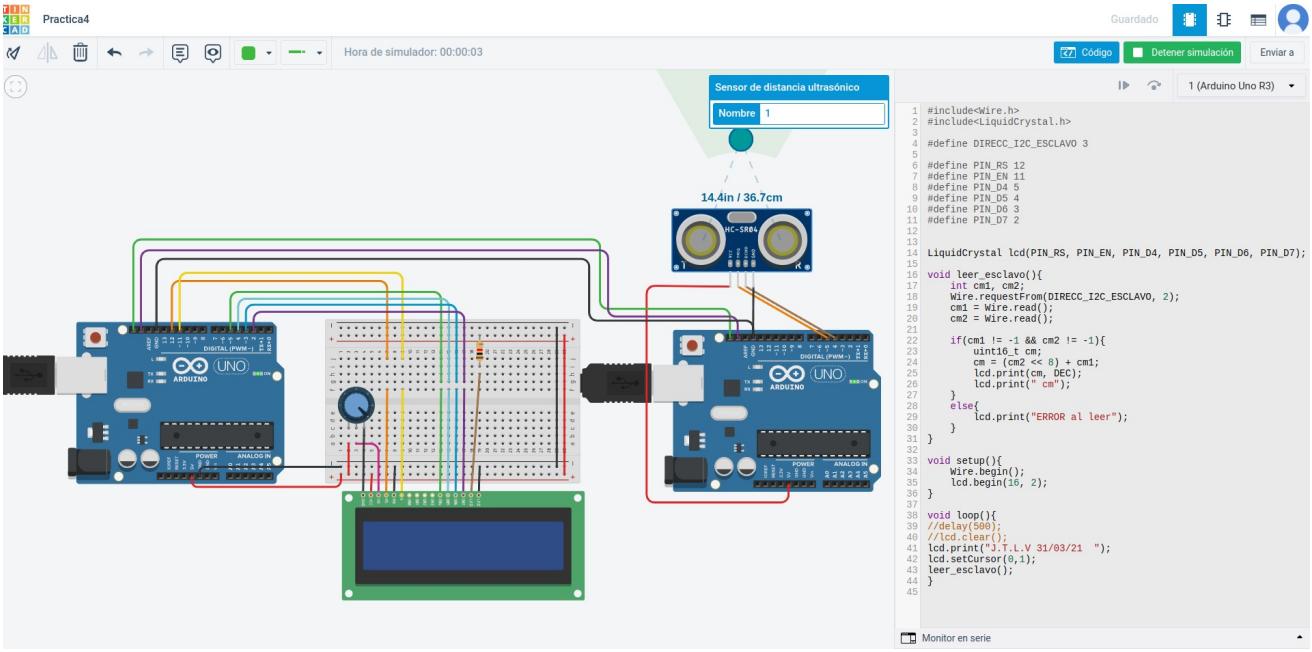
Vinculo Tinkercad:https://www.tinkercad.com/things/hgTnp5ModwZ

Captura pantalla



Codigos fuente:

Master

```
#include<Wire.h>
#include<LiquidCrystal.h>


#define DIRECC_I2C_ESCLAVO 3


#define PIN_RS 12
#define PIN_EN 11
#define PIN_D4 5
#define PIN_D5 4
#define PIN_D6 3
#define PIN_D7 2



LiquidCrystal lcd(PIN_RS, PIN_EN, PIN_D4, PIN_D5, PIN_D6, PIN_D7);


void leer_esclavo(){
        int cm1, cm2;
        Wire.requestFrom(DIRECC_I2C_ESCLAVO, 2);
        cm1 = Wire.read();
```

```
        cm2 = Wire.read();

        if(cm1 != -1 && cm2 != -1){
                uint16_t cm;
                cm = (cm2 << 8) + cm1;
                lcd.print(cm, DEC);
                lcd.print(" cm");
        }
        else{
                lcd.print("ERROR al leer");
        }
}

void setup(){
        Wire.begin();
        lcd.begin(16, 2);
}

void loop(){
//delay(500);
//lcd.clear();
lcd.print("J.T.L.V 31/03/21  ");
lcd.setCursor(0,1);
leer_esclavo();
}
```

Esclavo

```
#include<Wire.h>

#define DIRECC_I2C 3

#define PIN_DISPARADOR 5
#define PIN_ECO 4
#define TIMEOUT_ECO 23200 // <anchura máxima del pulso generado por el
módulo>

uint16_t cm;
```

```
unsigned long leeDistancia(uint8_t triggerPin, uint8_t ecoPin){
        delayMicroseconds(2);
        digitalWrite(triggerPin, HIGH);
        delayMicroseconds(10);
        digitalWrite(triggerPin, LOW);
        return pulseIn(ecoPin, HIGH, TIMEOUT_ECO);
}

void callback_peticion_i2c(){
cm = leeDistancia(PIN_DISPARADOR, PIN_ECO) / 58;
        uint8_t b[2];
        b[0]=lowByte(cm);
        b[1]=highByte(cm);
        Wire.write(b, 2);
}

void setup(){
        pinMode(PIN_DISPARADOR, OUTPUT);
        pinMode(PIN_ECO, INPUT);
    digitalWrite(PIN_DISPARADOR, LOW);

        Wire.begin(DIRECC_I2C);
        Wire.onRequest(callback_peticion_i2c);
}

void loop(){}
```