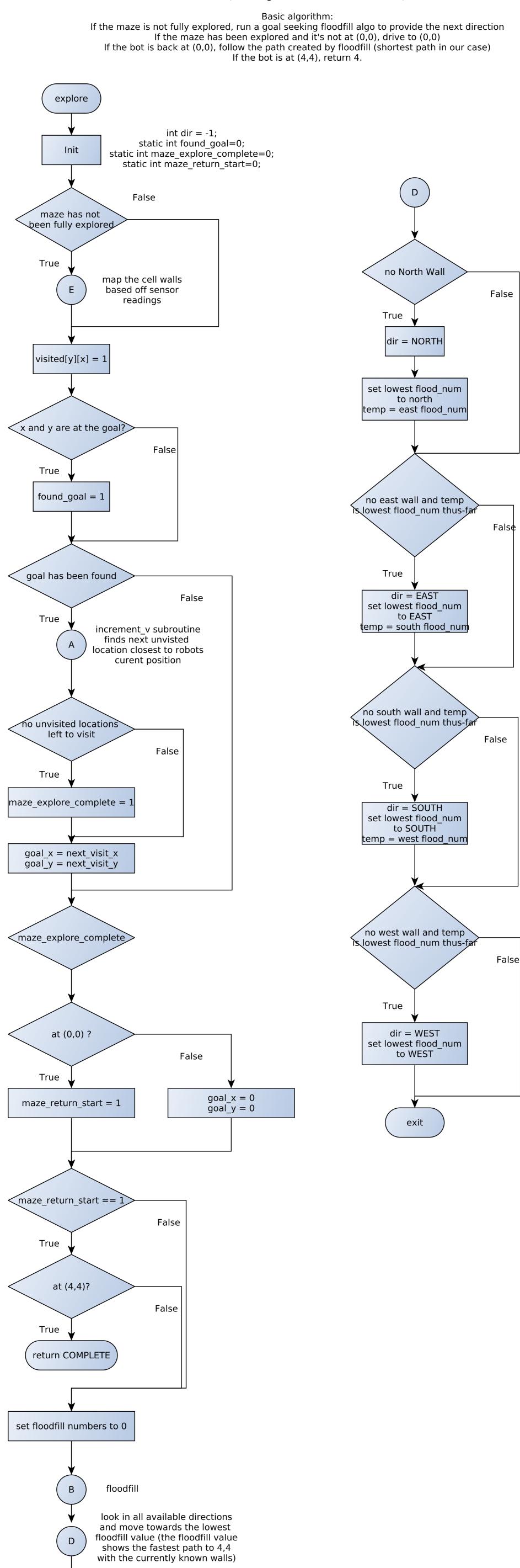
explore:

The explore algorithm started as simply the explore logic. Through programming the assignment, it eventually became the function which determines the next move for the entirety of the maze.

Based off some flags (which hopefully are fairly self descriptive), explore implements different methods to provide the bot with the next move at each cell (including drive back to home and race).



dir >= 0

return DIRECTION

True

False

return ERROR