

Josh Oberhaus

SOFTWARE ENGINEER

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Versatile and driven software engineer with diverse experience in the automotive sector and a passion for improving the safety and reliability of autonomous systems.

Experience

Robert Bosch LLC

Hybrid | Plymouth, MI

TECHNICAL EXPERT - PERCEPTION | TRACKING

Jan. 2024 - Present

SENIOR SOFTWARE ENGINEER - PERCEPTION | TRACKING

Sep. 2018 - Jan. 2024

- Served as a technical lead for a global platform perception / fusion software team.
- Brought critical contributions to tracking performance to help secure a strategic acquisition.
- Realized tracking gains and simplified tuning through architectural changes for a 5 radar 1 video configuration.
- Optimized radar-based perception for a new generation of radar sensor.
- Developed several new features for MATLAB-based tracking visualization tooling, including projection of the components of the Kalman filter, and automation abilities.
- Developed Python-based KPI Tool for single target tracking analysis, integrated and automated its execution as a Jenkins pipeline.
- Increased performance of corner radar-based tracking (C++) by identifying and addressing assumptions made towards front-facing radars.
- Reworked object type classification feature calculations to be more agnostic of sensor-mounting, reducing missed-target scenarios.

Bosch Engineering North America

Farmington Hills, MI

SOFTWARE ENGINEER - PREDICTIVE SAFETY SYSTEMS

Apr. 2016 - Sep. 2018

- Served as the Predictive Safety System (AEB, FCW, System Conditioning) component responsible for a strategic customer.
- Developed Python-based data mining tools to open new opportunities in evaluating data sets from endurance runs.
- Introduced automated tooling to enable customer-friendly overviews for endurance run points of interest.
- Led labelling sessions with the customer, explaining and addressing concerns with any activations.

SOFTWARE ENGINEER

Apr. 2012 - Apr. 2016

- Developed unique solution for criticality classification for marine radar collision warning applications, modified tracking and localization logic to be less dependent on traffic-scenes.
- Designed and implemented Python-based code generation tool chain to allow a Bosch-created library to be integrated into a third-party controller.
- Supported customers on site in solving critical plant issues.
- Created an ABS simulation software (C-based) and testing client (in CANAPE/CAPL) for OEM brake component testing, greatly reducing the OEM endurance run effort.
- Served as diagnostic component responsible and integrator in Electronic Power Steering (EPS) and EBCM projects.
- Integrated ASIL-D control functions in EPS unit, to facilitate level three functions, the first for that product generation.
- Network and diagnostic communication component responsible for multiple EPS and EBCM projects; configured, implemented, and tested several CAN and diagnostic stacks (J1939, UDS) in C.
- Led global diagnostic communication software development team, coordinating tasks and workload.

Education

Kettering University

Flint, MI

B.S. IN COMPUTER ENGINEERING, SUMMA CUM LAUDE

2008-2012