uC101: Introduction to Microcontrollers / Interfacing with the real world

Josh Johnson

13/5/2019

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Overview

- Assembly of Hardware / Installation of Software
- Microcontroller 101
- Tools
- Bit Math
- Demos
 - Blink
 - Button
 - RGB LED (PWM)
 - Rotary Encoder
 - Charlieplexing

Project Files: github.com/joshajohnson/CBRhardware

Assembly of Hardware



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Software Installation!

Install Arduino IDE

Copy the uC101Library folder to Documents/Arduino/libraries

Open Firmware/blink/blink.ino

In Arduino IDE:

Tools->Board:-> Arduino Nano

Tools->Processor:-> ATmega328p

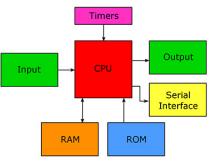
Tools->Port:-> \$comPort

Run blink.ino and confirm that the onboard LED is blinking

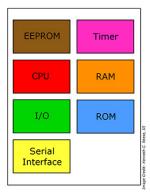
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What is a microcontroller?

Microprocesser: CPU and several supporting chips.



Microcontroller: CPU on a single chip.



Common Options

8 bit

16 bit

ATtiny

- MSP430 (TI)
- ATmega (Atmel / Microchip)
- PIC (Microchip)

32 bit

- STM32 (ST)
- SAM (Atmel/Microchip)
- nRF5x (Nordic Semi)
- ESP8266/32 (Espressif)
- CCxxxx (TI)
- LPCxxxx (NXP)
- PIC32 (Microchip)

32 bit ARM cores

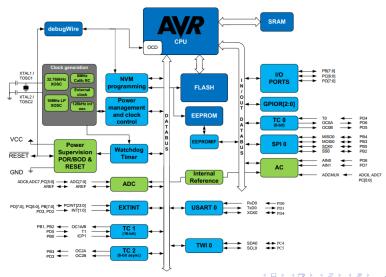
- Cortex-M0/M0+
- Cortex-M1 (FPGA only)
- Cortex-M3
- Cortex-M4 (M3 + DSP + FPU)
- ...

How to choose?

- Compute power
 - 8 bit vs 32 bit
 - DSP / FPU
- Peripherals
 - Wireless
 - WiFi
 - Bluetooth
 - LoRa
 - Cellular
 - USB
 - ADC
 - Ethernet
 - CAN
 - Number of SPI/UART/I2C/Timers

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ATmega328p Architecture

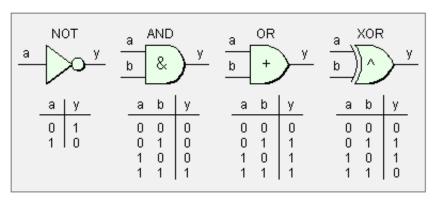


Tools

- Oscilloscope
 - + Great time domain measurements (100 500 MSPS 256 GSPS)
 - - Expensive, short record time
- Logic Analyser
 - + Easy to use UI, long sample time / depth
 - - 1 bit*, low sample rate (25 100 500 MSPS)
 - * some logic analysers have limited analog capabilities
- Debugger
 - Program and debug device
- Multimeter
 - Voltage and resistance measurements
- Development Board
 - Whilst not a tool, extremely helpful whilst bringing up firmware
 - Helpful when developing code the issue isnt (typically) the hardware!

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Bitwise Operators



$$y = a$$
 $y = a & b$ $y = a | b$
NOT $y = a & b$

4□▶
4□▶
4□▶
4□▶
4□▶
4□▶
4□▶
4□▶
4□▶
4□▶
4□▶

```
Binary Numbers
Binary: 0 1 0 0 1 0 1 1
Weight: 128 64 32 16 8 4 2 1
Base 2 (Binary): 0b01001011
Base 10 (Decimal): 75
Base 16 (Hexadecimal): 0x4B
Bit Shifting
a = 5; // binary: 00000101
b = a \ll 3; // binary: 00101000, 40 in decimal
c = b \gg 3; // binary: 00000101, back to 5 like we started
Putting it all together
x = 1; // binary: 00000001
x <<= 3; // binary: 00001000
x = 3; // binary: 00001011 - 3 is 11 in binary
x &= 1; // binary: 00000001
```

Setting Registers

Setting a bit in a register

Clearing a bit in a register

REG = REG &
$$\sim$$
(1 << x);
REG &= \sim (1<

Toggling a bit in a register

REG = REG
$$^(1 << x);$$

REG $^= (1 << x);$

Toggling multiple bits in a register

AVR specific macro to bitshift

What is the difference between the above and the first example (other than two variables)?

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Demo Time!

Me: *Explain my code to colleague*

Colleague:



- I'm a hardware person, not a software person
- Solder is my preferred programming language
- I know enough to be dangerous, nothing more
- More experienced folks, please jump in and correct me / answer questions I can't / point out bad practices
- I'm here to learn like everyone else

blink.ino

- Default blink
- Register level blink
- Nicer blink
- Even nicer blink
- Blink without delay
- Size comparison
- Speed comparison

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- Toggle on press
- Toggle on press with delay
- Button with interrupt
- Debounced button

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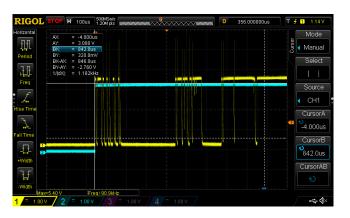
Button Bounce

- What is button bounce?
- How to fix it?
 - Hardware RC Circuit
 - ullet Hardware RC + Schmitt trigger
 - Software Button polling

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Button Bounce

• What is button bounce?

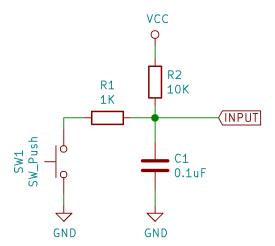


Yellow = actual button, Blue = 'ideal button'

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Button Bounce

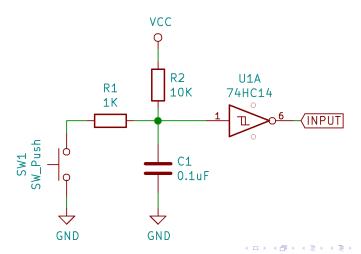
• Fix 1 - RC Circuit



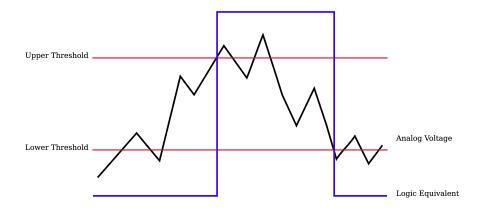
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Button Bounce

• Fix 2 - RC Circuit + Schmitt trigger

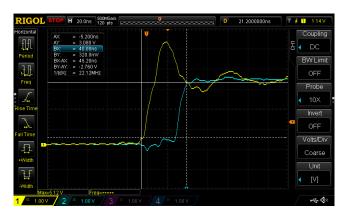


Hysteresis



Button Bounce

• Fix 3 - Button polling (FPGA assignment version)



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Button Bounce

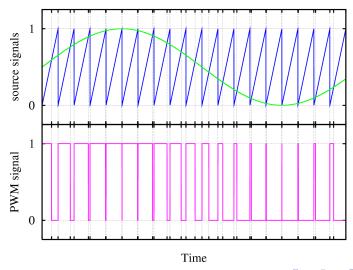
```
• Fix 3 - Button polling (uC101 version)
// Shift in a new value
history = history << 1;
history |= readPin(button);
// Check for button conditions
(history == 0b111111111) ? on = 1 : on = 0;
(history == 0b00000000) ? off = 1 : off = 0;
(history == 0b011111111) ? rising = 1 : rising = 0;
(history == 0b10000000) ? falling = 1 : falling = 0;
```

Above code called every 1-5ms

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pwmLED.ino

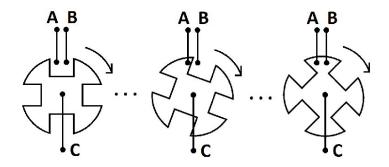
Pulse Width Modulation



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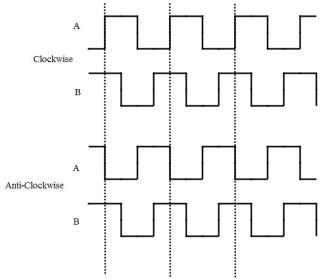
rotaryEncoder.ino

Rotary Encoder Internal Operation



rotary Encoder. in o

Rotary Encoder Output



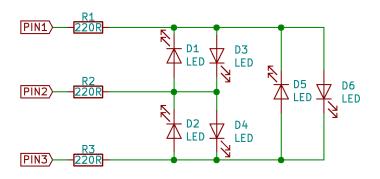
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rotaryEncoder.ino

Rotary Encoder Code

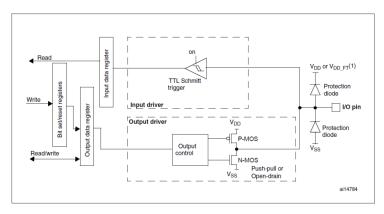
```
(onB && risingA) ? clockwise = 1 : clockwise = 0;
(onB && fallingA) ? antiClockwise = 1 : antiClockwise = 0;
or
(onB && risingA) ? clockwise = 1 : clockwise = 0;
(onA && risingB) ? antiClockwise = 1 : antiClockwise = 0;
or
(fallingA && onB) ? clockwise = 1 : clockwise = 0;
(fallingA && offB) ? antiClockwise = 1 : antiClockwise = 0;
all are functionally identical, however last one can be pin interrupt driven
```

Charlieplexing vs Multiplexing

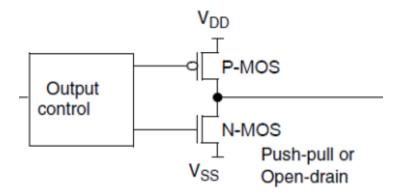


Charlieplexing: numLed = $p^2 - p$ Has to be scanned

How to tristate a pin

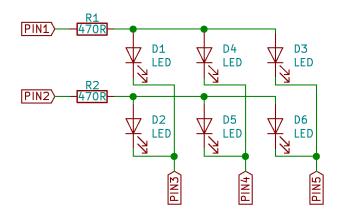


How to tristate a pin



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Charlieplexing vs Multiplexing



Multiplexing: numLed = $\left\lfloor \frac{p^2}{2} \right\rfloor$ Can be continuously driven

The End

Links to resources: uC101/README.md

Next month

- Breadboard to Printed Circuit Board
- Mechanical Design Considerations

Month after that

uC102: Communication Protocol Edition

Say Hello!

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Email: josh@joshajohnson.com

Project Files: github.com/joshajohnson/CBRhardware

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