Breadboard to Printed Circuit Board

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Motivation

- So you have a circuit working on a breadboard, however you need to move it to a PCB.
- You might also have an idea for a design which can't be breadboarded, and want your PCB work the first time.
- You might need it to be battery powered, have a certain form factor, or be lower cost.
- Maybe you are producing them in quantity, or are taking the level of integration up a notch.

How can you achieve these goals?

Project Files: github.com/joshajohnson/CBRhardware

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- What quantity is being produced?
- How much time do I have to spend on the project?
- What size / type of components am I willing to work with?
- I have an development / breakout board, how do I replace it with discrete parts?
- How am I going to program it?
- How will I communicate with it?
- How do I want to power it?
- How will Josh debug it when he makes mistakes?
- Mechanical design considerations.

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What quantity is being produced?

- Low volume
 - Trade off complexity for cost. Examples are prebuilt modules, commonly used parts, flying wires.
- Medium volume
 - Cost starts to become a consideration. See if a small amount of R&D can lower the bill of materials.
 - Assembly time small changes (single sided load, surface mount parts) multiply out to save a lot of time.
- Large volume
 - I'm not qualified to talk to this, but more time can be spent in R&D if it means lower BOM and assembly. e.g. Capacitative buttons vs mechanical, code optimisation vs larger microprocessor.

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How much time to I have to spend on the project?

- Similar considerations to quantity, if short on time, look for more integrated solutions.
 - ullet Display on PCB with 0.1" headers vs display + supporting passives.
 - Arduino Nano / Pro Mini vs DIY ATmega 328p.
 - Power supply brick / LIPO charge module vs rolling your own.
 - Steal designs from Adafruit / Sparkfun.

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What size / type of components am I willing to work with?

- Through hole vs surface mount
 - With correct tools, SMT is quicker and easier than THT.
 - THT is easier to resolve bugs, but takes up more space and some parts are SMT only.
- Component size
 - What sizes are parts available in? e.g. DIP vs SOIC vs TQFP vs QFN.
 - Who is assembling them? e.g. if first timers, go with easier parts.
 - With time, you will figure out what size parts you are happy working with. I personally suggest 0603 if you have steady hands / good eyesight, 0805/1206 otherwise, but larger parts are harder to source.
- Space constraints
 - Do you have to use small parts due to form factor / performance reasons? e.g. 0402 result in less impedance mismatch on traces, however you can use 0603 decoupling caps with little downside.

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I have an development / breakout board, how do I replace it with discrete parts?

- Reference designs
 - Find who makes the board you are using and look for a schematic.
 - If unmarked, probably a Sparkfun / Adafruit clone look on their website.
- Datasheet / application notes
 - Google is your friend.
 - Datasheets typically have a recommended schematic 1/3 down.
 - Application notes go into more detail regarding function of the device and different configurations.
 - Manufacturer probably has an evaluation board with schematics available
- Substitutions
 - Many parts can be substituted for a similar component. e.g. mosfets, transistors, voltage regulators.
 - If looking for a substitute, Texas Instruments, and Analog Devices have great datasheets and app notes.

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How am I going to program it?

- Does my device have a bootloader?
 - 'Arduino compatible' devices all have bootloaders which new ICs don't.
 - Flashing bootloaders may require UART, SPI, SWD, JTAG depending on chip, may also require dedicated programming header.
- UART / Serial
 - Many ICs will have a DFU pin which if held low on startup, will load code from a serial port.
 - STM32, ESP8266 / ESP32, my reflow oven (freescale?), many others are examples of this.
- Serial Peripheral Interface
 - ATmega / ATtiny microprocessors are flashed via SPI.
 - Programmer also required to set fuse bits.
- Single Wire Debug
 - ARM Cortex cores two pins + power allow programming and debugging.

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How will I communicate with it?

- Serial
 - Serial is the easiest method, but will require USB <-> Serial converter.
 - Can place converter on board with USB connector, or leave header exposed and use dedicated cable.
 - Flashing with a serial bootloader is common, e.g. Arduino series.
 - May require reset circuit for serial programming with bootloader.

USB

- USB bootloaders allow for updating over a USB cable, no other parts required.
- If you device has native USB, setting it up as a virtual COM port makes computer think it is a serial port.
- Can also do HID emulation to pretend to be a keyboard/mouse.
- Wireless
 - Wireless communications / firmware updating is possible, serial over bluetooth is common for communications.

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How will I power it?

- Power supply methods
 - USB (5V)
 - Battery (Coin Cell, AA, LIPO)
 - 9/12 VDC
- Voltage regulation
 - Low current OR small input -> output difference: linear regulator.
 - High current OR large input -> output difference OR output > input: switchmode supply.
- Rechargeable batteries.
 - Ensure each cell has charge protection built in.
 - Use a charge controller IC.
 - If using LIPO with circuit at 3V3, can get away with a linear regulator.
 - If 5V is required, boost converter will need be used.
 - Can connect directly to battery as well e.g. Neopixel VCC.

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How will I debug it?

- Power
 - Status LEDs on power rails.
 - Using 1V8? Low Vgs N channel Mosfet on low side of LED.
 - Test points (and ground pads) for every voltage rail.
 - Allow board to be powered from a bench supply, through Vin connection.
- Microcontroller
 - If using a microcontroller / toolchain with debug support, have a debug header on the board.
 - Serial (UART) comms are great to have broken out, even if using USB.
- On Board signals
 - Test points, test points, test points.
 - 1 mm diameter SMD pads don't take up much room, can be easily soldered onto.
 - SMD test points (metal loops) are a great option for ground.

Test points are less useful without plenty of available grounds.

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Mechanical Considerations

- Board size / shape
 - Does the board need to fit into a pre defined area?
 - Do components (connectors, displays, buttons, LEDs) need to be located in a certain position or on a certain side?
- Enclosure choice
 - Does my board need an enclosure?
 - If so, do I want to make my own or purchase a prebuilt enclosure?
 - Plastic box vs aluminium extrusion vs acrylic vs 3D printed.
- Mechanical Modelling
 - Import .STEP into ECAD as a 3D model for a footprint.
 - Export .STEP from ECAD into MCAD (I use KiCad and Fusion360).
 - Draw enclosure around board OR check board fits in designed enclosure.
 - Can export .DXF from MCAD into ECAD, and design board around that

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Snapchat Glasses









Casper Night Light



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Say Hello!

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Project Files: github.com/joshajohnson/CBRhardware

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