# uC101: Introduction to Microcontrollers / Interfacing with the real world

Josh Johnson

13/5/2019

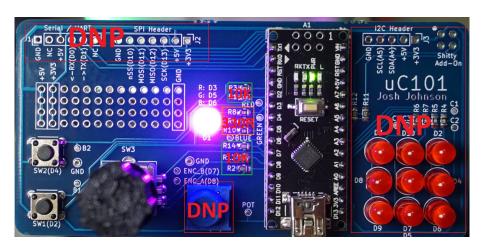
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## Overview

- Assembly of Hardware / Installation of Software
- Microcontroller 101
- Tools
- Bit Math
- Demos
  - Blink
  - Button
  - RGB LED (PWM)
  - Rotary Encoder
  - Charlieplexing

Project Files: github.com/joshajohnson/CBRhardware

# Assembly of Hardware



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## Software Installation!

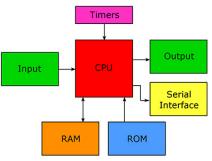
Install Arduino IDE
Copy the uC101Library folder to /Arduino/libraries
In Arduino IDE:
File->Examples->uC101->blink
Tools->Board->Arduino Nano
Tools->Processor->ATmega328p OR
Tools->Processor->ATmega328p (Old Bootloader)
Tools->Port->\$comPort

Run blink.ino and confirm that the onboard LED is blinking

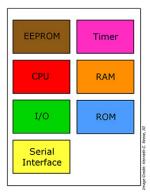
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#### What is a microcontroller?

<u>Microprocesser</u>: CPU and several supporting chips.



Microcontroller: CPU on a single chip.



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#### **Common Options**

8 bit

• ATtiny

16 bit • MSP430

(TI)

- ATmega (Atmel / Microchip)
- PIC (Microchip)

32 bit

- STM32 (ST)
- SAM (Atmel/Microchip)
- nRF5x (Nordic Semi)
- ESP8266/32 (Espressif)
- CCxxxx (TI)
- LPCxxxx (NXP)
- PIC32 (Microchip)

32 bit ARM cores

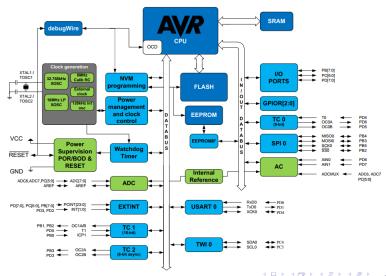
- Cortex-M0/M0+
- Cortex-M1 (FPGA only)
- Cortex-M3
- Cortex-M4 (M3 + DSP + FPU)
- ...

#### How to choose?

- Compute power
  - 8 bit vs 32 bit
  - DSP / FPU
- Peripherals
  - Wireless
    - WiFi
    - Bluetooth
    - LoRa
    - Cellular
  - USB
  - ADC
  - Ethernet
  - CAN
  - Number of SPI/UART/I2C/Timers

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#### ATmega328p Architecture

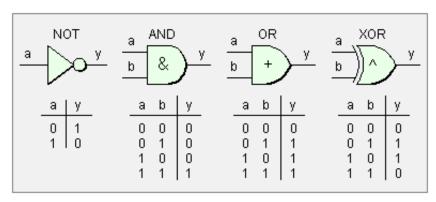


#### Tools

- Oscilloscope
  - + High quality time domain measurements ( $\geq 8$  bits,  $\geq 1$  GSPS)
  - · Expensive, short record time
- Logic Analyser
  - + Easy to use UI, long sample time / depth
  - - 1 bit\*, low sample rate (25 100  $\geq$ 500 MSPS)
  - \* some logic analysers have limited analog capabilities
- Debugger
  - Program and debug device
- Multimeter
  - Voltage and resistance measurements
- Development Board
  - Whilst not a tool, extremely helpful whilst bringing up firmware
  - Helpful when developing code the issue isn't (typically) the hardware!

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# Bitwise Operators



$$y = a$$
  $y = a & b$   
NOT  $y = a & b$ 

$$y = a \& b$$
  $y = a | b$   $y = a ^ b$ 

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```
Binary Numbers
Binary: 0 1 0 0 1 0 1 1
Weight: 128 64 32 16 8 4 2 1
Base 2 (Binary): 0b01001011
Base 10 (Decimal): 75
Base 16 (Hexadecimal): 0x4B
Bit Shifting
a = 5; // binary: 00000101
b = a \ll 3; // binary: 00101000, 40 in decimal
c = b \gg 3; // binary: 00000101, back to 5 like we started
Putting it all together
x = 1; // binary: 00000001
x <<= 3; // binary: 00001000
x = 3; // binary: 00001011 - 3 is 11 in binary
x &= 1; // binary: 00000001
```

# Setting Registers

Setting a bit in a register

Clearing a bit in a register

Toggling a bit in a register

Toggling multiple bits in a register

AVR specific macro to bitshift

```
(1<<x) == _BV(x)

REG = (1<<x) | (1<<y);

REG = _BV(x) | _BV(y);
```

What is the difference between the above and the first example (other than two variables)?

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## Demo Time!

Me: \*Explain my code to colleague\*

## Colleague:



- I'm a hardware person, not a software person
- Solder is my preferred programming language
- I know enough to be dangerous, nothing more
- More experienced folks, please jump in and correct me / answer questions I can't / point out bad practices
- I'm here to learn like everyone else

## blink.ino

- Default blink
- Register level blink
- Nicer blink
- Even nicer blink
- Blink without delay
- Size comparison
- Speed comparison

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- Toggle on press
- Toggle on press with delay
- Button with interrupt
- Debounced button

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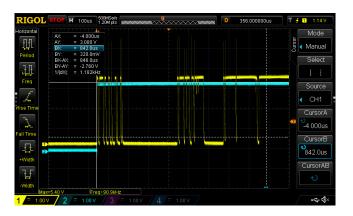
#### **Button Bounce**

- What is button bounce?
- How to fix it?
  - Hardware RC Circuit
  - Hardware RC + Schmitt trigger
  - Software Button polling

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#### **Button Bounce**

• What is button bounce?

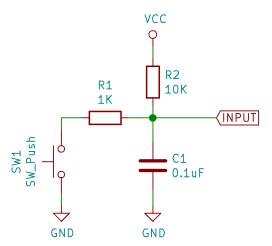


Yellow = actual button, Blue = 'ideal button'

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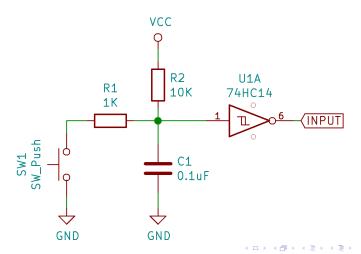
#### **Button Bounce**

• Fix 1 - RC Circuit

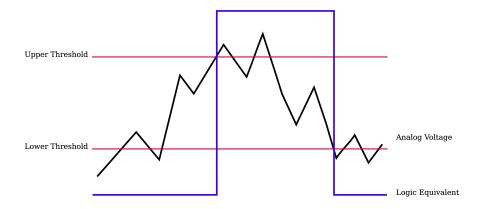


#### **Button Bounce**

• Fix 2 - RC Circuit + Schmitt trigger



## Hysteresis



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#### **Button Bounce**

• Fix 3 - Button polling (FPGA assignment version)



#### **Button Bounce**

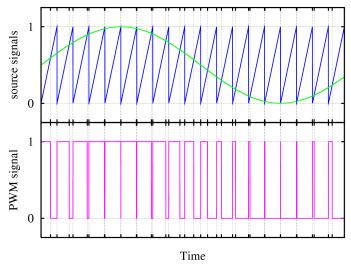
```
• Fix 3 - Button polling (uC101 version)
// Shift in a new value
history = history << 1;
history |= readPin(button);
// Check for button conditions
(history == 0b111111111) ? on = 1 : on = 0;
(history == 0b00000000) ? off = 1 : off = 0;
(history == 0b011111111) ? rising = 1 : rising = 0;
(history == 0b10000000) ? falling = 1 : falling = 0;
```

Above code called every 1-5ms

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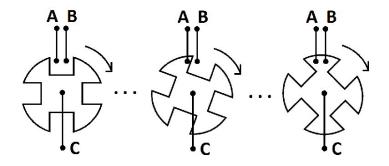
# pwmLED.ino

#### **Pulse Width Modulation**



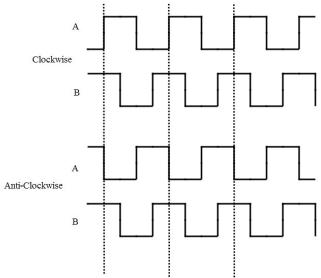
# rotaryEncoder.ino

## **Rotary Encoder Internal Operation**



# rotary Encoder. in o

## **Rotary Encoder Output**



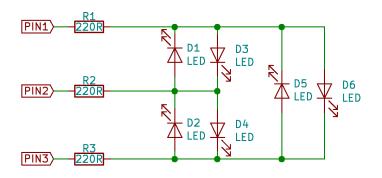
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# rotaryEncoder.ino

#### **Rotary Encoder Code**

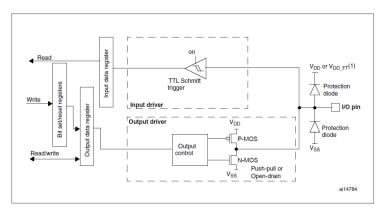
```
(onB && risingA) ? clockwise = 1 : clockwise = 0;
(onB && fallingA) ? antiClockwise = 1 : antiClockwise = 0;
or
(onB && risingA) ? clockwise = 1 : clockwise = 0;
(onA && risingB) ? antiClockwise = 1 : antiClockwise = 0;
or
(fallingA && onB) ? clockwise = 1 : clockwise = 0;
(fallingA && offB) ? antiClockwise = 1 : antiClockwise = 0;
all are functionally identical, however last one can be pin interrupt driven
```

#### Charlieplexing vs Multiplexing

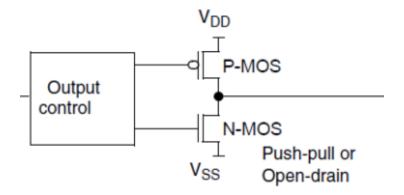


Charlieplexing: numLed =  $p^2 - p$ Has to be scanned

#### How to tristate a pin

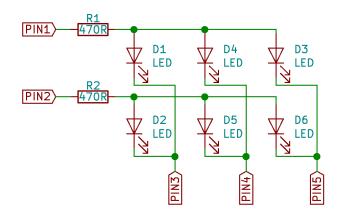


#### How to tristate a pin



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#### Charlieplexing vs Multiplexing



Multiplexing: numLed =  $\left\lfloor \frac{p^2}{2} \right\rfloor$  Can be continuously driven

## The End

Links to resources: uC101/README.md

#### Next month

- Breadboard to Printed Circuit Board
- Mechanical Design Considerations

#### Month after that

uC102: Communication Protocol Edition

Say Hello!

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Email: josh@joshajohnson.com

Project Files: github.com/joshajohnson/CBRhardware