

# BMEG 802 – Advanced Biomedical Experimental Design and Analysis

Bayesian Statistics

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# Recap

- Maximum Likelihood Estimation (MLE)
  - Probability Distribution Function
  - Likelihood function
  - 3 Ways to find the Maximum Likelihood Estimation
    - Analytical (Calculus)
    - Brute Force (Grid Search)
    - Optimization (Gradient Descent)

# Today

## Bayesian Statistics

- Derivation from Set Theory
- Point Probabilities
  - priors, likelihood, posteriors
- Continuous Probabilities
  - Analytical (Conjugate Priors)
  - Numerical

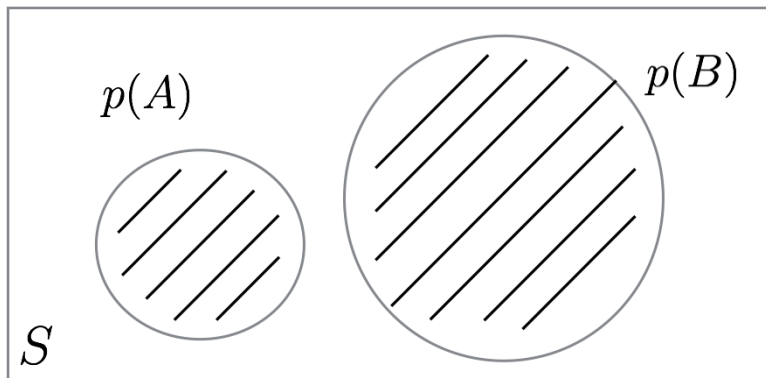
# Bayesian vs. Frequentist

- **Data are treated as fixed observations** vs. data (sample) treated as a random variable
- **Models (parameters) are treated as random variables** vs. models (population parameters) are treated as fixed quantities
- **we compute the probability of all models** vs. we compute the probability of one model ( $H_0$ )
- **we end up with a richer understanding of relative probability of all models** vs. we make a decision (reject  $H_0$  or not)

# Notation

- $S$  = sample space (all possible outcomes)
- $p(A)$  = probability of event  $A$
- $A \cup B$  = union of events  $A$  and  $B$
- $A \cap B$  = intersection of events  $A$  and  $B$
- $p(B|A)$  = probability of  $B$  given  $A$
- $p(A')$  or  $p(A^C)$  or  $p(\bar{A})$  = complement probability of  $p(A)$

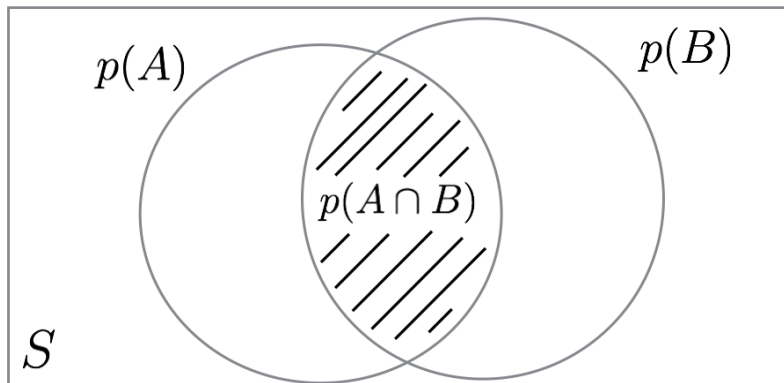
# Mutually Exclusive (Disjoint Probability)



$$p(A \cup B) = p(A) + p(B)$$

$$0.7 = 0.4 + 0.3$$

# Joint Probability

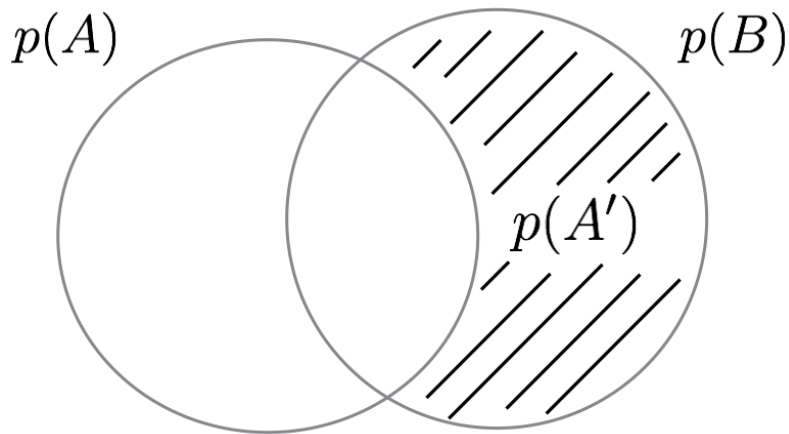


$$p(A \cup B) = p(A) + p(B) - p(A \cap B)$$

$$0.5 = 0.4 + 0.3 - 0.2$$

- the probability of two events occurring simultaneously

# Complement Probability



$$p(A') = 1 - p(A)$$

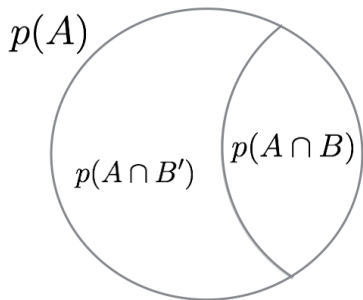


# Marginal Probability

<b>H \ L</b>	<b>Red</b>	<b>Yellow</b>	<b>Green</b>	<b>Marginal probability P(H)</b>
<b>Not Hit</b>	0.198	0.09	0.14	<b>0.428</b>
<b>Hit</b>	0.002	0.01	0.56	<b>0.572</b>
<b>Total</b>	<b>0.2</b>	<b>0.1</b>	<b>0.7</b>	<b>1</b>

- Probability of a single event occurring (hit), independent of other events (light)
- e.g., probabilities of getting in an accident at an intersection irrespective of lights
- note: joint probabilities in each cell

# Marginal Probability



$$p(A \cap B') = p(A) - p(A \cap B)$$

The marginal  $p(A)$  or  $p(B)$  is found by summing their disjoint parts.

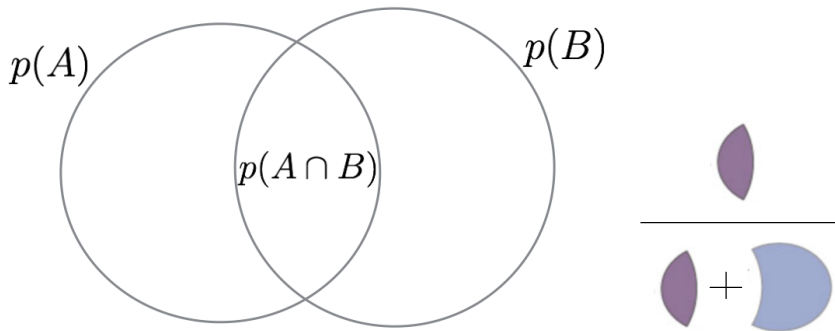
$$p(A) = p(A \cap B) + p(A \cap B'), \text{ and similarly}$$

$$p(B) = p(A \cap B) + p(A' \cap B)$$

# Conditional Probability

- $p(\textit{accepted}) = 0.3$
- $p(\textit{funding}|\textit{accepted}) = 0.43$
- $p(\textit{funding} \cap \textit{accepted}) = p(\textit{funding}|\textit{accepted}) \cdot p(\textit{accepted})$
- $p(\textit{funding} \cap \textit{accepted}) = 0.43 \cdot 0.3 = 0.13$
- Probability that an event occurs given that another specific event *has already* occurred

# Conditional Probability



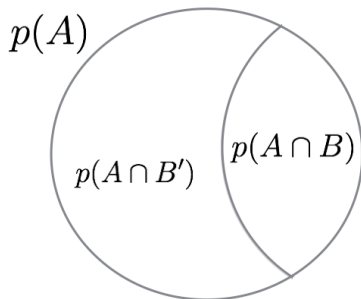
$$p(A \cap B) = p(B|A) \cdot p(A)$$

$$p(B|A) = \frac{p(A \cap B)}{p(A)}$$

$$p(A \cap B) = p(A|B) \cdot p(B) \text{ (in terms of B)}$$

$$p(A|B) = \frac{p(A \cap B)}{p(B)}$$

# Conditional Probability Complements



$$p(A \cap B') = p(B'|A) \cdot p(A)$$

Other friendly complements:

$$p(A' \cap B) = p(B|A') \cdot p(A')$$

$$p(A' \cap B') = p(B'|A') \cdot p(A')$$

# Good News!

Bayes' Theorem is simply a conditional probability!

# Deriving Bayes' Theorem

Remember:

- $p(A|B) = \frac{p(A \cap B)}{p(B)}$ , (eq.1)(slide 11)
- $p(A \cap B) = p(B|A) \cdot p(A)$ , (eq.2)(slide 11)

Substitute (eq.2) into (eq.1):

$$p(A|B) = \frac{p(B|A) \cdot p(A)}{p(B)}, \text{ (eq.3)}$$

That's it!

**In terms of statistical models:**

$$p(model|data) = \frac{p(data|model) \cdot p(model)}{p(data)}$$

# Handy Dandy Steps for Point Estimates

$$p(A|B) = \frac{p(B|A) \cdot p(A)}{p(B)}, (\text{eq.3})$$

*Calculate  $p(B)$  by using its marginal probability*

$$p(B) = p(A \cap B) + p(A' \cap B), (\text{eq.4})(\text{slide 9})$$



# Handy Dandy Steps for Point Estimates

$$p(A|B) = \frac{p(B|A) \cdot p(A)}{p(B)}, (\text{eq.3})$$

*Calculate  $p(B)$  by using its marginal probability*

$$p(B) = p(A \cap B) + p(A' \cap B), (\text{eq.4})(\text{slide 9})$$

*Substitute (eq.4) into (eq.3)*

$$p(A|B) = \frac{p(B|A) \cdot p(A)}{p(A \cap B) + p(A' \cap B)}, (\text{eq.5})$$

# Handy Dandy Steps for Point Estimates

$$p(A|B) = \frac{p(B|A) \cdot p(A)}{p(B)}, (\text{eq.3})$$

**Calculate  $p(B)$  by using its marginal probability**

$$p(B) = p(A \cap B) + p(A' \cap B), (\text{eq.4})(\text{slide 9})$$

**Substitute (eq.4) into (eq.3)**

$$p(A|B) = \frac{p(B|A) \cdot p(A)}{p(A \cap B) + p(A' \cap B)}, (\text{eq.5})$$

**Since,**

$$p(A \cap B) = p(B|A) \cdot p(A), (\text{eq.6})(\text{slide 11})$$

$$p(A' \cap B) = p(B|A') \cdot p(A'), (\text{eq.7})(\text{slide 12})$$

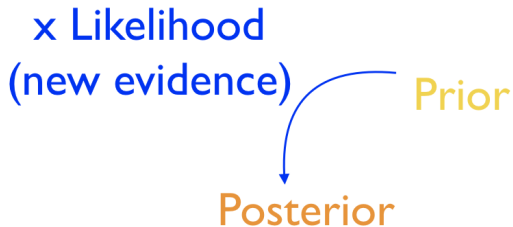
*Substitute (eq.6) and (eq.7) into (eq.5)*

$$p(A|B) = \frac{p(B|A) \cdot p(A)}{p(B|A) \cdot p(A) + p(B|A') \cdot p(A')}, (\text{eq.8})$$

# Why Bayesian???

Powerful way to continually account for new evidence given **prior** beliefs

$$p(A|B) = \frac{p(B|A) \cdot p(A)}{p(B)}$$



# POINT PROBABILITIES

# POINT PROBABILITIES

Powerful way to continually account for new evidence given **prior** beliefs

$$p(A|B) = \frac{p(B|A) \cdot p(A)}{p(B|A) \cdot p(A) + p(B|A') \cdot p(A')}$$

x Likelihood  
(new evidence)

Prior

Posterior

$p(B)$  = marginal probability (e.g., true positive & false positive tests)

classic example:  $A = +\text{covid}$ ,  $A' = -\text{covid}$ ,  $B = + \text{test}$ ,  $B' = - \text{test}$

# Point Estimate Example

Let's say you take a COVID test and it comes out positive. What is the probability that you have COVID?

- Let's assume our initial, prior guess on whether we have covid based on an exposure is 40%,  $p(+covid) = 0.4$ .
- The probability of having a positive test given you have covid is 75%,  $p(+test \mid +covid) = 0.75$ . (i.e., test sensitivity)
- The probability of having a positive test given you do NOT have covid is 25%:  $p(+test \mid -covid) = 0.25$ . (i.e., 1 - test specificity)
- We observe a + test. What is the probability that you have COVID,  $p(+covid \mid +test)$ ?
- note: these are fictitious numbers

# Point Estimate Example

$$p(+covid \mid +test) = \frac{p(+test \mid +covid) \cdot p(+covid)}{p(+test \mid +covid) \cdot p(+covid) + p(+test \mid -covid) \cdot p(-covid)}$$

# Point Estimate Example

## Knowns:

$$p(+covid) = 0.4$$

$$p(+test \mid +covid) = 0.75$$

$$p(+test \mid -covid) = 0.25$$

## Unknowns:

$$p(-covid) = ?$$

$$p(+covid \mid +test) = ?$$



# Point Estimate Example

## Knowns:

$$p(+covid) = 0.4$$

$$p(+test \mid +covid) = 0.75$$

$$p(+test \mid -covid) = 0.25$$

## Unknowns:

$$p(-covid) = 0.6; (1 - 0.4)$$

$$p(+covid \mid +test) = ?$$

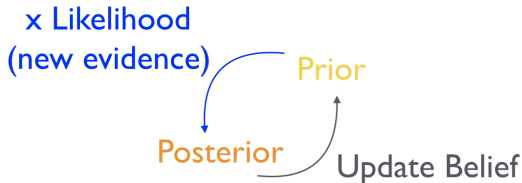
# Point Estimate Example

$$p(+covid \mid +test) = \frac{p(+test \mid +covid) \cdot p(+covid)}{p(+test \mid +covid) \cdot p(+covid) + p(+test \mid -covid) \cdot p(-covid)}$$

$$p(+covid \mid +test) = 0.67 = \frac{0.75 \cdot 0.4}{0.75 \cdot 0.4 + 0.25 \cdot 0.6}$$

# Why Bayesian?

Powerful way to **continually** account for new evidence given prior beliefs



$p(A|B)$  becomes  $p(A)$  on the next iteration!

# Updating

- updating the model (i.e., take another test). Seems like an appropriate thing to do in science
- when new data are gathered, we can re-evaluate a hypothesis
- we do not begin anew (ignorant) each time we ask a question
- previous research provides us information about the merits of the hypothesis
- **the posterior from the previous model becomes the prior for the new model**

# Point Estimate Example - Updating

Let's continue from our previous example. We take another test and it comes out positive. What is our probability of having covid given another positive test?

# Point Estimate Example - Updating

## Knowns:

$$p(+covid) = 0.67$$

$$p(+test \mid +covid) = 0.75$$

$$p(+test \mid -covid) = 0.25$$

## Unknowns:

$$p(-covid) = ?$$

$$p(+covid \mid +test) = ?$$

# Point Estimate Example - Updating

## Knowns:

$$p(+covid) = 0.67$$

$$p(+test \mid +covid) = 0.75$$

$$p(+test \mid -covid) = 0.25$$

## Unknowns:

$$p(-covid) = 0.33; (1 - 0.67)$$

$$p(+covid \mid +test) = ?$$

# Point Estimate Example - Updating

$$p(+covid \mid +test) = \frac{p(+test \mid +covid) \cdot p(+covid)}{p(+test \mid +covid) \cdot p(+covid) + p(+test \mid -covid) \cdot p(-covid)}$$

$$p(+covid \mid +test) = 0.86 = \frac{0.75 \cdot 0.67}{0.75 \cdot 0.67 + 0.25 \cdot 0.33}$$



# Point Estimate Example - Updating

Let's keep going and pretend we observed 5 positive tests in row from our initial belief of 40%. Calculating  $p(+\text{covid}|+\text{test})$  for each iteration leads to:

0.67

0.86

0.95

0.98

0.99

# Influence of PRIOR beliefs

How much of our prediction is influenced by our prior belief that the hand is open or not?

Prior	Posterior
-------	-----------

0.1	0.25
-----	------

0.2	0.43
-----	------

0.3	0.56
-----	------

<b>0.4</b>	<b>0.67</b>
------------	-------------

0.5	0.75
-----	------

0.6	0.82
-----	------

0.7	0.88
-----	------

0.8	0.92
-----	------

0.9	0.96
-----	------

# CONTINUOUS PROBABILITIES

# Bayes with Probability Distributions

- in previous example, the likelihood and prior were both single quantities (point probabilities)
- typically Bayesian approaches use full probability distributions
- essentially allows us to evaluate probability of a whole range of possible models, at once

# Back to the Bayesics

$$p(A|B) = \frac{p(B|A) \cdot p(A)}{p(B)}$$

$$p(\theta|y)d\theta = \frac{p(y|\theta) \cdot p(\theta)d\theta}{\int_a^b p(y|\theta) \cdot p(\theta)d\theta}$$

$$p(\theta|y) = \frac{p(y|\theta) \cdot p(\theta)}{\int_a^b p(y|\theta) \cdot p(\theta)d\theta}$$

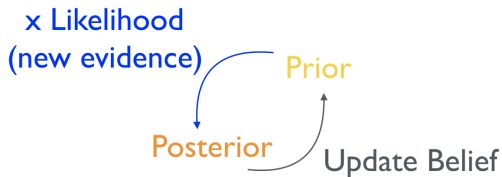
Marginal probability a normalization constant (sum of prior and likelihood)

$$p(\theta|y) \propto p(y|\theta) \cdot p(\theta)$$

More details here: [https://ocw.mit.edu/courses/mathematics/18-05-introduction-to-probability-and-statistics-spring-2014/readings/MIT18\\_05S14\\_Reading13a.pdf](https://ocw.mit.edu/courses/mathematics/18-05-introduction-to-probability-and-statistics-spring-2014/readings/MIT18_05S14_Reading13a.pdf)

# Bayes' Theorem

$$p(\theta|y) \propto \mathcal{L}(y|\theta) \cdot p(\theta)$$



posterior, likelihood, prior can all be defined with probability distributions

# Continuous Probability Example

- Let's revisit the coin flipping example.
- Is the coin fair ( $w = 0.5$ )?
  - **model:** some proposed process by which the outcome of our coin flip is determined.
    - Binomial Distribution
  - **data:**  $k = 2$  heads (# of successes),  $n = 3$  flips

# Likelihood Function

$$\mathcal{L}(w|n, y) = \frac{n!}{y!(n-y)!} w^y (1-w)^{n-y}$$



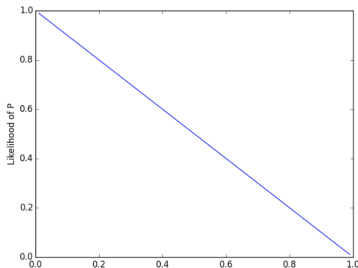
# Likelihood of $W$ for a single toss

$w = 0$  represents the coin is perfectly weighted towards Tails

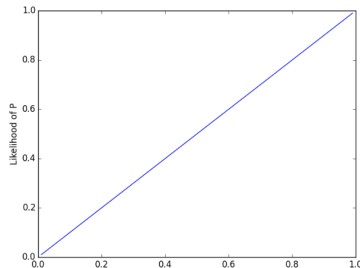
$w = 1$  represents the coin is perfectly weighted towards Heads

First, let's consider a single toss of Tails and a single toss of Heads

**One Tail**



**One Head**



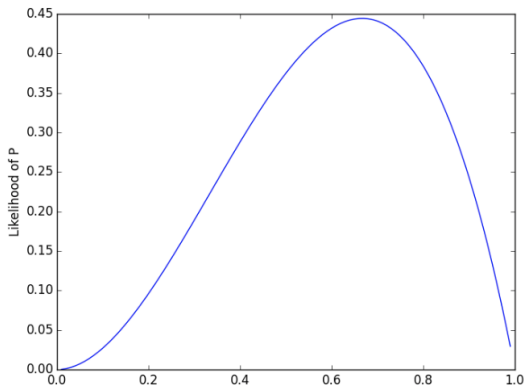
- Note: x-axis is  $w$

# Likelihood of P for 3 tosses

$w = 0$  represents the coin is perfectly weighted towards Tails

$w = 1$  represents the coin is perfectly weighted towards Heads

2 Heads, 1 Tails



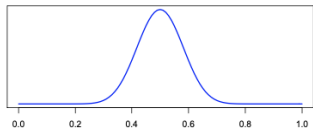
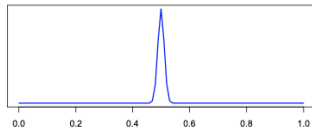
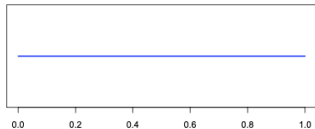
# The Prior

$$p(\theta|y) \propto \mathcal{L}(y|\theta) \cdot p(\theta)$$

- What is our prior belief? Is the coin weighted or not?
  - “uninformative”
    - flat prior - all values of  $w$  are equally likely (Bayes / Laplace):
    - Others - Jeffrey’s prior, reference priors, maximum entropy
  - Informative
    - we have some previous experience / evidence

# The Prior Cont'd

1. I have no clue what  $W$  is (flat prior)
2. Every coin we have seen in the past has been fair
3. Most coins have been relatively fair



# Calculating the Posterior

- Analytical
- Numerical

# Analytical

## Find a Conjugate Prior

1. IF, the posterior and prior are the same type of distribution, they are conjugate distributions
2. THEN, the prior is a conjugate prior to the likelihood function
3. If we have a conjugate prior we can use **hyperparameters** to solve the posterior
4. Hyperparameters solved for many distributions: Conjugate Priors - Wikipedia
  - The Binomical distribution conjugate prior is the Beta distribution
  - The Normal distribution conjugate prior is the Normal distribution

# Analytical

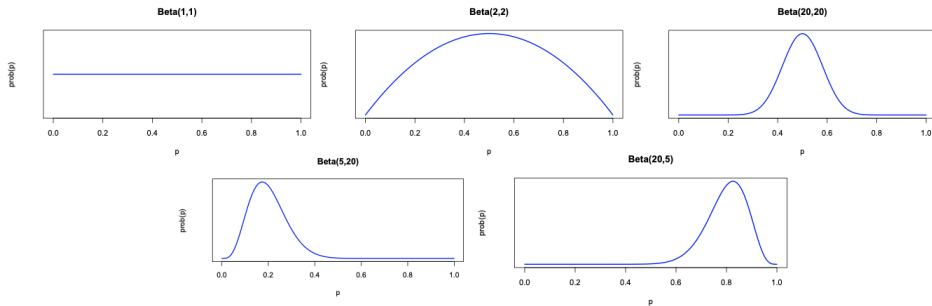
- Back to our coin flipping example.
- Our Likelihood function is the Binomial Distribution
- Binomial distribution's conjugate prior = Beta distribution

$$p(w|\alpha, \beta) = \frac{1}{B(\alpha, \beta)} w^{\alpha-1} (1-w)^{\beta-1}$$

# Beta Distribution Conjugate Prior

$$p(w|\alpha, \beta) = \frac{1}{B(\alpha, \beta)} w^{\alpha-1} (1-w)^{\beta-1}$$

Beta distribution's range  $[0,1]$  convenient for our prior  $w$  somewhere between 0 and 1



\*note: x-axis is  $w$



# Analytically Calculating the Posterior

- If we have a conjugate prior
- Then, the posterior is calculated from parameters used in the likelihood and prior (called **hyperparameters**)

# Analytically Calculating the Posterior Cont'd

Prior:  $p(w|\alpha, \beta) = \frac{1}{B(\alpha, \beta)} w^{\alpha-1} (1-w)^{\beta-1}$

- parameters are:  $\alpha, \beta$

Likelihood:  $\mathcal{L}(w|n, y) = \frac{n!}{y!(n-y)!} w^y (1-w)^{n-y}$

- parameters are:  $k, n$

Posterior = Likelihood \* Prior  $\Rightarrow$  after some heavy calculus / algebra

Posterior:  $p(w|\alpha_h, \beta_h) = \frac{1}{B(\alpha_h, \beta_h)} w^{\alpha_h-1} (1-w)^{\beta_h-1}$

- hyperparameters are:  $\alpha_h, \beta_h$
- $\alpha_h = k + \alpha$
- $\beta_h = n - k + \beta$

# Let's update based on each toss

coin flip:  $n = 3$  trials,  $k = 2$  success

- 1st toss = Heads
- 2nd toss = Tails
- 3rd toss = Heads

Let's assume a flat prior

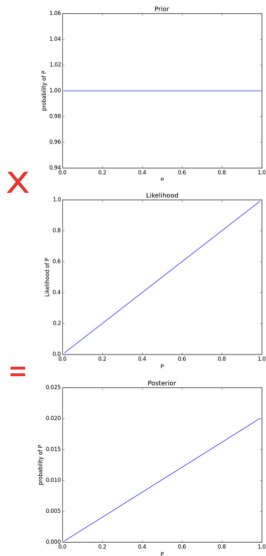
- all  $w$  equal

# Toss One - Heads

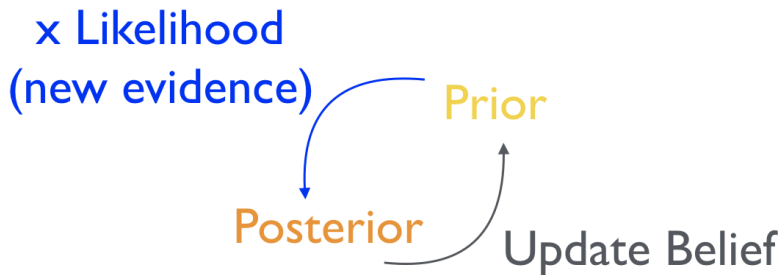
**Prior:**  $p(P|\alpha, \beta); \alpha = 1, \beta = 1$

**Likelihood:**  $L(P|k, n); k = 1, n = 1$

**Posterior:**  $p(P|\alpha_h, \beta_h); \alpha_h = 2, \beta_h = 1$



# Same Update Procedure

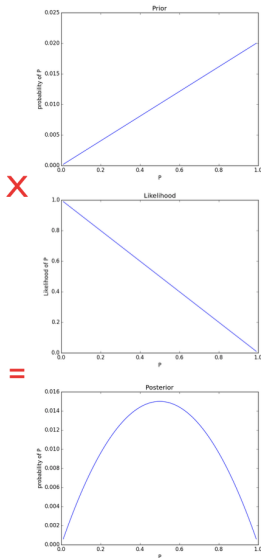


# Toss Two - Tails

**Prior:**  $p(P|\alpha, \beta); \alpha = 2, \beta = 1$

**Likelihood:**  $L(P|k, n); k = 0, n = 1$

**Posterior:**  $p(P|\alpha_h, \beta_h); \alpha_h = 2, \beta_h = 2$

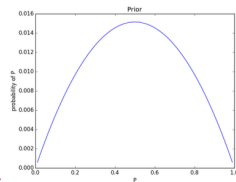


# Toss Three - Heads

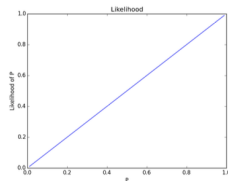
**Prior:**  $p(P|\alpha, \beta); \alpha = 2, \beta = 2$

**Likelihood:**  $L(P|k, n); k = 1, n = 1$

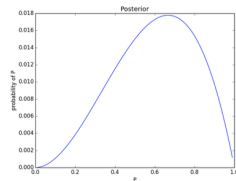
**Posterior:**  $p(P|\alpha_h, \beta_h); \alpha_h = 3, \beta_h = 2$



X



=

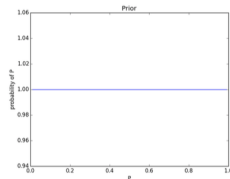


# OR, in a Single Step (all tosses already made)

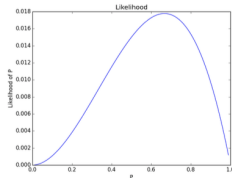
**Prior:**  $p(P|\alpha, \beta); \alpha = 1, \beta = 1$

**Likelihood:**  $L(P|k, n); k = 2, n = 3$

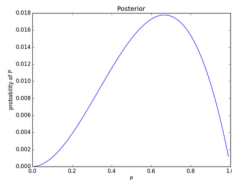
**Posterior:**  $p(P|\alpha_h, \beta_h); \alpha_h = 3, \beta_h = 2$



X

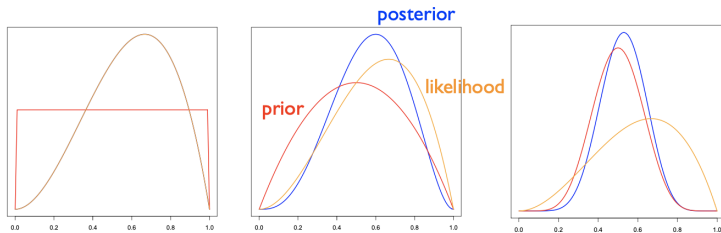


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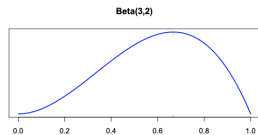


# Effect of Prior



# Analytically Describing the Posterior

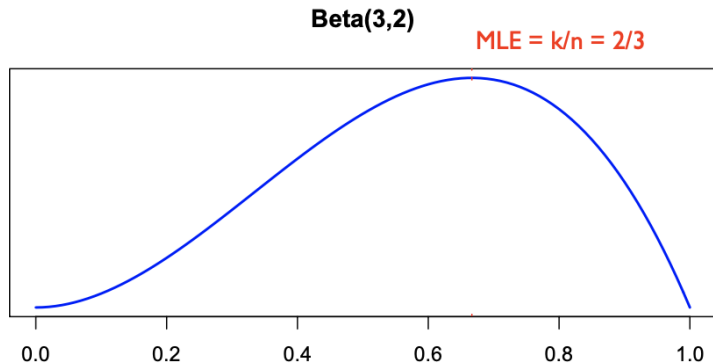
Graphically:



Summary Statistics:

- expression for mean, variance, mode, etc.
- $\text{mean} = \frac{\alpha}{\alpha+\beta}$
- $\text{variance} = \frac{\alpha\beta}{(\alpha+\beta)^2(\alpha+\beta+1)}$

# Bayesian vs. MLE



Bayesian: the posterior tells us the probability of all possible  $w$ 's

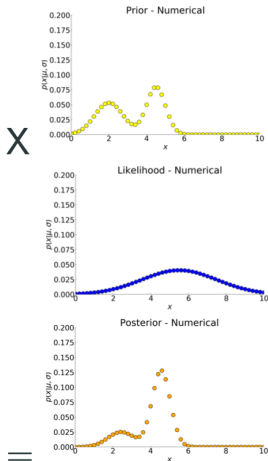
MLE (frequentist approach):  $w$  is 0.667

- does not incorporate prior information

# Numerically Calculating the Posterior

- Option 1: Grid approximation by discretizing the prior
- Option 2: Markov Chain Monte Carlo (MCMC)

# Grid Approximation



Any Shape

Tradeoff between grid coarseness and speed

# Criticisms of Bayesian Approach

- The prior: too much “subjectivity”?
- Data fixed, models (parameters) random
- Often difficult to find analytical solutions

# Advantages of Bayesian Approach

- Bayesian approach allows for incorporating previous findings in a principled way
- frequentist involves testing only one hypothesis (model) : the null hypothesis ...  
Bayesian estimates probability of all models (parameter values)
- interval estimates (and other such measures of posterior) have a clearer meaning than CIs in frequentist approaches
- in Bayesian approach we get full posterior distribution, a much richer picture than just a mean  $\pm$  CI or s.e.

# Applications

- Linear Regression:  
<https://statswithr.github.io/book/introduction-to-bayesian-regression.html>
  - pretty heavy stuff. . .
- Kalman Filters
- Multisensory Integration, Illusions, Sensorimotor Adaptation, etc.
- Bayes Factors
- etc.



# Next Week

Markov Chain Monte Carlo (MCMC)

- sampling the posterior