

# **Lecture 2**

## **FORECASTING FOUNDATIONS AND AUTOREGRESSIVE MODELS**

# **Forecasting foundations:**

## **Conditional Expectations**

# Expected value

Expected value / “population mean”:

$$E(Y) = \begin{cases} \sum_y y \cdot p(y) & Y \text{ is discrete} \\ \int y \cdot f(y) dy & Y \text{ is continuous} \end{cases}$$

# Conditioning

Consider two random variables :  $Y$  and  $X$ .

- *Conditioning on  $X = x$*  implies we take the value of  $X$  as known to be  $x$ .
- Knowing  $X$  might be informative about  $Y$ .
- Formally, the “distribution of  $Y$  conditional on  $X$ ” differs from the “distribution of  $Y$ ”.

# Conditional expectation and Prediction

- Suppose we know the value of random variable  $X$  is  $x$  (i.e. condition on  $X = x$ )
- Using this information, we want to predict the value of  $Y$ .
- The “optimal” predictor of  $Y$  conditional on  $X = x$  is  $E(Y|X = x)$ .
- “Optimal” : minimum mean squared error

# Minimum mean squared error prediction

Let  $g(X)$  denote *any* function of  $X$  that could be used to predict  $Y$ .

The mean squared error (MSE) of  $g(X)$  is

$$\text{MSE}(g) = E[ (Y - g(X))^2 ]$$

The expectation is taken over both  $Y$  and  $X$ .

Can show that  $g(X) = E(Y|X)$  minimises  $\text{MSE}(g)$ .

# Minimum mean squared error prediction

- In econometrics, this is why  $E(Y|X)$  is used as the “population regression function”.
- A functional form is assumed, eg  $E(Y|X) = \beta_0 + \beta_1 X$ .
- Parameters of  $E(Y|X)$  estimated from data.
- The approach will be the same for forecasting.

# Forecasting

- Suppose we have a time series  $Y_t$  for  $t = 1, \dots, n$
- We want to forecast the unknown value of  $Y_{n+1}$ .
- The MSE-optimal forecast of  $Y_{n+1}$  :

$$E(Y_{n+1} | Y_n, Y_{n-1}, \dots, Y_1)$$



# Forecasting

- The MSE-optimal forecast of  $Y_{n+1}$  :

$$E(Y_{n+1} | Y_n, Y_{n-1}, \dots, Y_1)$$

Steps:

1. Specify a *model* for  $E(Y_{n+1} | Y_n, Y_{n-1}, \dots)$ .
2. Estimate model parameters from the data.
3. Evaluate model fit, re-specify as required.
4. Calculate and evaluate forecasts.

# Step 1. Time series model specification

We specify a model for

$$E(Y_t | Y_{t-1}, Y_{t-2}, \dots, Y_1), \quad t = 1, 2, \dots, n$$

The model for  $t = n + 1$  can forecast  $Y_{n+1}$ .

# Step 1. Time series model specification

We specify a model for

$$E(Y_t | Y_{t-1}, Y_{t-2}, \dots, Y_1), \quad t = 1, 2, \dots, n$$

Example. *Autoregressive model of order one:*

$$E(Y_t | Y_{t-1}, Y_{t-2}, \dots, Y_1) = \beta_0 + \beta_1 Y_{t-1}$$

Resembles a cross-section regression:

$$E(Y_i | X_i) = \beta_0 + \beta_1 X_i$$

# Step 1. Time series model specification

Example. *Autoregressive model of order one:*

$$E(Y_t | Y_{t-1}, Y_{t-2}, \dots, Y_1) = \beta_0 + \beta_1 Y_{t-1}$$

Assumes

- linear functional form
- only  $Y_{t-1}$  is useful for forecasting  $Y_t$
- coefficients are constant over time

## Step 2. Model estimation

Example. *Autoregressive model of order one:*

$$E(Y_t | Y_{t-1}, Y_{t-2}, \dots, Y_1) = \beta_0 + \beta_1 Y_{t-1}$$

Recall the minimum MSE property of the conditional expectations function.

If the model is correct, the true values  $\beta_0, \beta_1$  satisfy

$$(\beta_0, \beta_1) = \arg \min_{b_0, b_1} E[ (Y_t - (b_0 + b_1 Y_{t-1}))^2 ]$$

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The sample analog of this is

$$(\hat{\beta}_0, \hat{\beta}_1) = \arg \min_{b_0, b_1} \frac{1}{n-1} \sum_{t=2}^n (Y_t - (b_0 + b_1 Y_{t-1}))^2$$

i.e. least squares estimation!



## Step 3. Evaluate model

Define the (population) forecast error

$$U_t = Y_t - E(Y_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1)$$

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$$U_t = Y_t - E(Y_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1)$$

Taking conditional expectations of both sides:

$$\begin{aligned} & E(U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1) \\ &= E(Y_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1) \\ &\quad - E(Y_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1) \\ &= 0 \end{aligned}$$

## Step 3. Evaluate model

Meaning of

$$E(U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1) = 0 \text{ ?}$$

# Review: Law of Iterated Expectations

If  $Z$  is any random variable then

$$E(Z) = E[ E(Z|X) ]$$

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Inner expectation averages over  $Z$  for each  $X$ .

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If  $Z$  is any random variable then

$$E(Z) = E[ E(Z|X) ]$$

Inner expectation averages over  $Z$  for each  $X$ .

Outer expectation then averages over  $X$ .

## Step 3. Evaluate model

Meaning of

$$E(U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1) = 0 \text{ ?}$$

The LIE implies

$$\begin{aligned} E(U_t) &= E[ E(U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1) ] \\ &= 0 \end{aligned}$$

## Step 3. Evaluate model

Meaning of

$$E(U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1) = 0 \quad ?$$

For any  $j = 1, 2, \dots$ :

$$\begin{aligned} & \text{cov}(U_t, U_{t-j}) \\ &= E[ (U_t - E(U_t)) (U_{t-j} - E(U_{t-j})) ] \quad (\text{defn}) \end{aligned}$$



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$$E(U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1) = 0 \quad ?$$

For any  $j = 1, 2, \dots$ :

$$\begin{aligned} & E[U_t U_{t-j}] \\ &= E[E(U_t U_{t-j} \mid Y_{t-1}, Y_{t-2}, \dots, Y_1)] \quad (\text{LIE}) \end{aligned}$$

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$$\begin{aligned} & E[ U_t U_{t-j} ] \\ &= E[ E( U_t U_{t-j} \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) ] \quad (\text{LIE}) \end{aligned}$$

# Step 3. Evaluate model

Meaning of

$$E(U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1) = 0 \quad ?$$

For any  $j = 1, 2, \dots$ :

$$\begin{aligned} & E[ U_t U_{t-j} ] \\ &= E[ E( U_t \textcolor{red}{U}_{t-j} \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) ] \quad (\text{LIE}) \\ &= E[ \textcolor{red}{U}_{t-j} \cdot E( U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) ] \quad \textcolor{red}{Why?} \end{aligned}$$

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$$\begin{aligned} & E[ U_t U_{t-j} ] \\ &= E[ E( U_t U_{t-j} \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) ] \quad (\text{LIE}) \\ &= E[ U_{t-j} \cdot E( U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) ] \\ &= 0. \end{aligned}$$

## Step 3. Evaluate model

Summary :

$$E(U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1) = 0$$

implies

- i.  $E(U_t) = 0$
- ii.  $\text{cov}(U_t, U_{t-j}) = 0$  for all  $j = 1, 2, \dots$

## Step 3. Evaluate model

Summary :

$$E(U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1) = 0$$

implies

- i.  $E(U_t) = 0$
- ii.  $\text{cov}(U_t, U_{t-j}) = 0$  for all  $j = 1, 2, \dots$

The errors have **no autocorrelation**.

$\Rightarrow$  if a model produces autocorrelated errors, that model must be misspecified.

Why?

$$\begin{aligned} & E( U_t \textcolor{red}{U}_{t-j} \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) \\ &= \textcolor{red}{U}_{t-j} \cdot E( U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) \end{aligned}$$

This is a deceptively important step.



Why?

$$\begin{aligned} & E( U_t \textcolor{red}{U}_{t-j} \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) \\ &= \textcolor{red}{U}_{t-j} \cdot E( U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) \end{aligned}$$

- $\textcolor{red}{U}_{t-j} = Y_{t-j} - E(Y_{t-j} \mid Y_{t-j-1}, Y_{t-j-2}, \dots, Y_1)$

# Why?

$$\begin{aligned} & E( U_t U_{t-j} \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) \\ &= U_{t-j} \cdot E( U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) \end{aligned}$$

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- $Y_{t-j}$  is in the conditioning set.

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- $E(Y_{t-j} \mid Y_{t-j-1}, Y_{t-j-2}, \dots, Y_1)$  is a function of  $Y_{t-j-1}, Y_{t-j-2}, \dots, Y_1$ .

# Why?

$$\begin{aligned} & E( U_t \mathbf{U}_{t-j} \mid \mathbf{Y}_{t-1}, \mathbf{Y}_{t-2}, \dots, \mathbf{Y}_1 ) \\ &= \mathbf{U}_{t-j} \cdot E( U_t \mid \mathbf{Y}_{t-1}, \mathbf{Y}_{t-2}, \dots, \mathbf{Y}_1 ) \end{aligned}$$

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- $\mathbf{Y}_{t-j-1}, \mathbf{Y}_{t-j-2}, \dots, \mathbf{Y}_1$  are in the conditioning set.

# Why?

$$\begin{aligned} & E( U_t U_{t-j} \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) \\ &= U_{t-j} \cdot E( U_t \mid Y_{t-1}, Y_{t-2}, \dots, Y_1 ) \end{aligned}$$

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- Thus  $U_{t-j}$  is in the conditioning set.

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- Thus  $U_{t-j}$  is in the conditioning set, hence can come out of the conditional expectation.



## Why?

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- $U_{t-j} = Y_{t-j} - E(Y_{t-j} \mid Y_{t-j-1}, Y_{t-j-2}, \dots, Y_1)$
- Thus  $U_{t-j}$  is in the conditioning set, hence can come out of the conditional expectation.
- $\text{cov}(U_t, U_{t-j}) = 0$  can be proved because the model conditioning set contains all lags of the dependent and explanatory variables.

# Summary of formalities

- A forecasting model is a model for

$$E(Y_t | Y_{t-1}, Y_{t-2}, \dots, Y_1)$$

- The “analog principle” implies estimation by least squares.
- The forecast errors

$$U_t = Y_t - E(Y_t | Y_{t-1}, Y_{t-2}, \dots, Y_1)$$

should not be autocorrelated.

# Autoregressive models

# Context

- We have a time series  $Y_t$  for  $t = 1, \dots, n$ .  
We want to forecast the unknown value of  $Y_{n+1}$ .
- Suppose we have specified a regression:

$$Y_t = X_t' \beta + Z_t$$

where  $X_t$  contains *deterministic* variables.

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- Example:  $X_t = 1$  (a constant mean)

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- Example:  $X_t = (1, \text{Time}_t)'$  (linear time trend)

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We want to forecast the unknown value of  $Y_{n+1}$ .
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where  $X_t$  contains *deterministic* variables.

- Example:  $X_t = (1, \text{Time}_t, Q_{2,t}, Q_{3,t}, Q_{4,t})'$   
(trend+seasonals)

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We want to forecast the unknown value of  $Y_{n+1}$ .
- Suppose we have specified a regression:

$$Y_t = X_t' \beta + Z_t$$

where  $X_t$  contains *deterministic* variables.

- **Deterministic:** values are known without looking at the data.



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We want to forecast the unknown value of  $Y_{n+1}$ .
- Suppose we have specified a regression:

$$Y_t = X_t' \beta + Z_t$$

where  $X_t$  contains *deterministic* variables.

- We therefore focus on forecasting  $Z_t$ .

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- Suppose we have specified a regression:

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where  $X_t$  contains *deterministic* variables.

- $X_t$  will include an intercept  $\Rightarrow E(Z_t) = 0$ .

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where  $X_t$  contains *deterministic* variables.

- $X_t$  will include an intercept  $\Rightarrow E(Z_t) = 0$ .  
**But**  $E(Z_t) = 0 \not\Rightarrow E(Z_t | Z_{t-1}, Z_{t-2}, \dots, Z_1) = 0$

# First order autoregressive model

$$E(Z_t | Z_{t-1}, Z_{t-2}, \dots, Z_1) = \phi_1 Z_{t-1}$$

# First order autoregressive model

$$E(Z_t | Z_{t-1}, Z_{t-2}, \dots, Z_1) = \phi_1 Z_{t-1}$$

The time series  $Z_t$  is regressed on a *lag* of itself.

- *lag* : a value of the time series in the past
- $Z_{t-1}$  : first lag of  $Z_t$
- $Z_{t-2}$  : second lag of  $Z_t$ , etc

# First order autoregressive model

$$E(Z_t | Z_{t-1}, Z_{t-2}, \dots, Z_1) = \phi_1 Z_{t-1}$$

It will be convenient to write

$$\mathcal{Z}_{t-1} = \{Z_{t-1}, Z_{t-2}, \dots, Z_1\}$$

so

$$E(Z_t | \mathcal{Z}_{t-1}) = \phi_1 Z_{t-1}$$

# Autoregressive (AR) models

First order autoregressive model:

$$E(Z_t | \mathcal{Z}_{t-1}) = \phi_1 Z_{t-1}$$

Second order autoregressive model:

$$E(Z_t | \mathcal{Z}_{t-1}) = \phi_1 Z_{t-1} + \phi_2 Z_{t-2}$$

# Autoregressive (AR) models

First order autoregressive model:

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Second order autoregressive model:

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$p^{\text{th}}$  order autoregressive model:

$$E(Z_t | \mathcal{Z}_{t-1}) = \phi_1 Z_{t-1} + \dots + \phi_p Z_{t-p}$$



# AR( $p$ ) models

$p^{\text{th}}$  order autoregressive model:

$$E(Z_t | \mathcal{Z}_{t-1}) = \phi_1 Z_{t-1} + \dots + \phi_p Z_{t-p}$$

- Estimation: least squares / maximum likelihood
- Fit evaluation: graphs, autocorrelation testing
- Choice of  $p$ : model selection criteria
- Forecasting

# **AR(1) Forecasting**

# How does AR(1) forecasting work?

Consider the AR(1) model

$$Y_t = X_t' \beta + Z_t$$
$$E(Z_t | \mathcal{Z}_{t-1}) = \phi_1 Z_{t-1}$$

# How does AR(1) forecasting work?

At  $t = n + 1$  :

$$Y_{n+1} = X'_{n+1}\beta + Z_{n+1}$$

$$E(Z_{n+1}|\mathcal{Z}_n) = \phi_1 Z_n$$

The optimal forecast for  $Y_{n+1}$  given data to time  $n$  is

$$E(Y_{n+1}|\mathcal{Y}_n) = E(X_{n+1}|\mathcal{Y}_n)'\beta + E(Z_{n+1}|\mathcal{Y}_n)$$

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↑

$$\mathcal{Y}_n = \{Y_n, Y_{n-1}, \dots, Y_1\}$$

# How does AR(1) forecasting work?

At  $t = n + 1$  :

$$Y_{n+1} = X'_{n+1}\beta + Z_{n+1}$$

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At  $t = n + 1$  :

$$Y_{n+1} = X'_{n+1}\beta + Z_{n+1}$$

$$E(Z_{n+1} | \mathcal{Z}_n) = \phi_1 Z_n$$

The optimal forecast for  $Y_{n+1}$  given data to time  $n$  is

$$\begin{aligned} E(Y_{n+1} | \mathcal{Y}_n) &= E(X_{n+1} | \mathcal{Y}_n)' \beta + E(Z_{n+1} | \mathcal{Y}_n) \\ &= X_{n+1}' \beta + E(Z_{n+1} | \mathcal{Z}_n) \end{aligned}$$

because  $X_t$  is deterministic.

# How does AR(1) forecasting work?

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$$Y_{n+1} = X'_{n+1}\beta + Z_{n+1}$$

$$E(Z_{n+1}|\mathcal{Z}_n) = \phi_1 Z_n$$

The optimal forecast for  $Y_{n+1}$  given data to time  $n$  is

$$\begin{aligned} E(Y_{n+1}|\mathcal{Y}_n) &= E(X_{n+1}|\mathcal{Y}_n)'\beta + E(Z_{n+1}|\mathcal{Y}_n) \\ &= \quad \quad \quad '\beta + E(Z_{n+1}|\mathcal{Z}_n) \\ &= \quad \quad \quad '\beta + \phi_1 Z_n \end{aligned}$$



# How does AR(1) forecasting work?

At  $t = n + 1$  :

$$Y_{n+1} = X'_{n+1}\beta + Z_{n+1}$$

$$E(Z_{n+1} | \mathcal{Z}_n) = \phi_1 Z_n$$

The optimal forecast for  $Y_{n+1}$  given data to time  $n$  is

$$E(Y_{n+1} | \mathcal{Y}_n) = X'_{n+1}\beta + \phi_1 Z_n$$

# Lecture 2 Summary

# Lecture 2 Summary

- MSE optimal forecasting is formalised using *conditional expectations*.
- For one-step-ahead forecasts, a correct model for the conditional expectations must have errors **without autocorrelation**.
- An autoregressive model is a regression of  $Y_t$  on its “lags”  $Y_{t-1}, \dots, Y_{t-p}$ .