

Lecture 11

MULTIVARIATE MODELS

Granger causality

Granger causality definitions

Suppose we have two time series, $Y_{1,t}$ and $Y_{2,t}$.

Denote the information sets

$$\mathcal{Y}_{1,t} = \{ Y_{1,t}, Y_{1,t-1}, Y_{1,t-2}, \dots, Y_{1,1} \}$$

$$\mathcal{Y}_{2,t} = \{ Y_{2,t}, Y_{2,t-1}, Y_{2,t-2}, \dots, Y_{2,1} \}$$

$$\mathcal{Y}_t = \mathcal{Y}_{1,t} \cup \mathcal{Y}_{2,t}$$

We have been considering forecasting based on

$$E(Y_{1,n+h} | \mathcal{Y}_{1,n})$$

i.e. using only past values of $Y_{1,t}$

Granger causality definitions

Suppose we have two time series, $Y_{1,t}$ and $Y_{2,t}$.

Denote the information sets

$$\mathcal{Y}_{1,t} = \{ Y_{1,t}, Y_{1,t-1}, Y_{1,t-2}, \dots, Y_{1,1} \}$$

$$\mathcal{Y}_{2,t} = \{ Y_{2,t}, Y_{2,t-1}, Y_{2,t-2}, \dots, Y_{2,1} \}$$

$$\mathcal{Y}_t = \mathcal{Y}_{1,t} \cup \mathcal{Y}_{2,t}$$

We have been considering forecasting based on

$$E(Y_{1,n+h} | \mathcal{Y}_{1,n})$$

Now consider

$$E(Y_{1,n+h} | \mathcal{Y}_n)$$

Granger causality definitions

For any \mathcal{F}_n define:

$$\text{MSE}(Y_{n+h} \mid \mathcal{F}_n) = E[(Y_{n+h} - E(Y_{n+h} \mid \mathcal{F}_n))^2]$$

$E(Y_{n+h} \mid \mathcal{F}_n)$ is the MSE-optimal forecast of Y_{n+h} using the data in \mathcal{F}_n .

Compare

$$\text{MSE}(Y_{1,n+h} \mid \mathcal{Y}_{1,n}) \quad \text{uses } Y_{1,t} \text{ only}$$

and

$$\text{MSE}(Y_{1,n+h} \mid \mathcal{Y}_n) \quad \text{uses } Y_{1,t} \text{ and } Y_{2,t}.$$

Granger causality definitions

Compare

$$\text{MSE}(Y_{1,n+h} \mid \mathcal{Y}_{1,n}) \quad \text{uses } Y_{1,t} \text{ only}$$

and

$$\text{MSE}(Y_{1,n+h} \mid \mathcal{Y}_n) \quad \text{uses } Y_{1,t} \text{ and } Y_{2,t}.$$

Definition. $Y_{2,t}$ “Granger causes” $Y_{1,t}$ if

$$\text{MSE}(Y_{1,n+h} \mid \mathcal{Y}_n) < \text{MSE}(Y_{1,n+h} \mid \mathcal{Y}_{1,n})$$

i.e. forecasts are improved by adding $Y_{2,t}$ to the model.

Granger causality definitions

Definition. $Y_{2,t}$ “Granger causes” $Y_{1,t}$ if

$$\text{MSE}(Y_{1,n+h} \mid \mathcal{Y}_n) < \text{MSE}(Y_{1,n+h} \mid \mathcal{Y}_{1,n})$$

i.e. forecasts are improved by adding $Y_{2,t}$ to the model.

- This is not a definition of *causality*.
- Maybe better called “Granger predictability”...

Granger causality definitions

Definition. $Y_{2,t}$ “Granger causes” $Y_{1,t}$ if

$$\text{MSE}(Y_{1,n+h} \mid \mathcal{Y}_n) < \text{MSE}(Y_{1,n+h} \mid \mathcal{Y}_{1,n})$$

- It is common to test for Granger causality with a (joint) test for the significance of all lags of $Y_{2,t}$ included in a model for $Y_{1,t}$.
- Practically we can compare forecast properties of models for $Y_{1,t}$ with and without $Y_{2,t}$ included.

Vector Autoregression

Bivariate VAR(1)

Suppose we have two time series, $Y_{1,t}$ and $Y_{2,t}$.

Denote the information sets

$$\mathcal{Y}_{1,t} = \{ Y_{1,t}, Y_{1,t-1}, Y_{1,t-2}, \dots, Y_{1,1} \}$$

$$\mathcal{Y}_{2,t} = \{ Y_{2,t}, Y_{2,t-1}, Y_{2,t-2}, \dots, Y_{2,1} \}$$

$$\mathcal{Y}_t = \mathcal{Y}_{1,t} \cup \mathcal{Y}_{2,t}$$

Bivariate VAR(1)

Suppose we have two time series, $Y_{1,t}$ and $Y_{2,t}$.

Denote the information sets

$$\mathcal{Y}_{1,t} = \{ Y_{1,t}, Y_{1,t-1}, Y_{1,t-2}, \dots, Y_{1,1} \}$$

$$\mathcal{Y}_{2,t} = \{ Y_{2,t}, Y_{2,t-1}, Y_{2,t-2}, \dots, Y_{2,1} \}$$

$$\mathcal{Y}_t = \mathcal{Y}_{1,t} \cup \mathcal{Y}_{2,t}$$

Two equations, one lag:

$$E(Y_{1,t} | \mathcal{Y}_{t-1}) = \nu_1 + \Phi_{1,1} Y_{1,t-1} + \Phi_{1,2} Y_{2,t-1}$$

$$E(Y_{2,t} | \mathcal{Y}_{t-1}) = \nu_2 + \Phi_{2,1} Y_{1,t-1} + \Phi_{2,2} Y_{2,t-1}$$

Bivariate VAR(1)

Suppose we have two time series, $Y_{1,t}$ and $Y_{2,t}$.

Denote the information sets

$$\mathcal{Y}_{1,t} = \{ Y_{1,t}, Y_{1,t-1}, Y_{1,t-2}, \dots, Y_{1,1} \}$$

$$\mathcal{Y}_{2,t} = \{ Y_{2,t}, Y_{2,t-1}, Y_{2,t-2}, \dots, Y_{2,1} \}$$

$$\mathcal{Y}_t = \mathcal{Y}_{1,t} \cup \mathcal{Y}_{2,t}$$

Two equations, one lag:

$$E(Y_{1,t} | \mathcal{Y}_{t-1}) = \nu_1 + \Phi_{1,1} Y_{1,t-1} + \Phi_{1,2} Y_{2,t-1}$$

if $\Phi_{1,2} \neq 0$

$\Rightarrow Y_{2,t}$ “Granger causes” $Y_{1,t}$

Bivariate VAR(1)

Two equations, one lag:

$$E(Y_{1,t} | \mathcal{Y}_{t-1}) = \nu_1 + \Phi_{1,1} Y_{1,t-1} + \Phi_{1,2} Y_{2,t-1}$$

$$E(Y_{2,t} | \mathcal{Y}_{t-1}) = \nu_2 + \Phi_{2,1} Y_{1,t-1} + \Phi_{2,2} Y_{2,t-1}$$

Bivariate VAR(1)

Two equations, one lag:

$$E(Y_{1,t} \mid \mathcal{Y}_{t-1}) = \nu_1 + \Phi_{1,1} Y_{1,t-1} + \Phi_{1,2} Y_{2,t-1}$$

$$E(Y_{2,t} \mid \mathcal{Y}_{t-1}) = \nu_2 + \Phi_{2,1} Y_{1,t-1} + \Phi_{2,2} Y_{2,t-1}$$

In matrix form:

$$E \begin{pmatrix} Y_{1,t} \\ Y_{2,t} \end{pmatrix} \mid \mathcal{Y}_{t-1} = \begin{pmatrix} \nu_1 \\ \nu_2 \end{pmatrix} + \begin{pmatrix} \Phi_{1,1} & \Phi_{1,2} \\ \Phi_{2,1} & \Phi_{2,2} \end{pmatrix} \begin{pmatrix} Y_{1,t-1} \\ Y_{2,t-1} \end{pmatrix}$$

$$E(Y_t \mid \mathcal{Y}_{t-1}) = \nu + \Phi_1 Y_{t-1}$$

General K -variate VAR(p)

$k = 1, 2, \dots, K$ equations, with p lags:

$$E(Y_{\textcolor{violet}{k},t} \mid \mathcal{Y}_{t-1}) = \nu_k + \sum_{j=1}^p \sum_{i=1}^K \Phi_{k,i}^{(j)} Y_{\textcolor{brown}{i},t-j}$$

- Each of the $\textcolor{violet}{k} = 1, 2, \dots, K$ equations includes p lags of each of the K variables as predictors.
- Same lag order p for each predictor.
- Each equation has the same predictors.

General K -variate VAR(p)

In matrix form:

$$E(Y_t | \mathcal{Y}_{t-1}) = \nu + \Phi_1 Y_{t-1} + \dots + \Phi_p Y_{t-p}$$

where

$$Y_t = \begin{pmatrix} Y_{1,t} \\ \vdots \\ Y_{K,t} \end{pmatrix} \quad \nu = \begin{pmatrix} \nu_1 \\ \vdots \\ \nu_K \end{pmatrix} \quad \Phi_j = \begin{pmatrix} \Phi_{1,1}^{(j)} & \dots & \Phi_{1,K}^{(j)} \\ \vdots & \ddots & \vdots \\ \Phi_{K,1}^{(j)} & \dots & \Phi_{K,K}^{(j)} \end{pmatrix}$$

Vector Autoregression

Implementation

VAR Model Specification

1. Choose variables
2. Check trends and stationarity
3. Select lag order p :
 - autocorrelation tests
 - minimise AIC

U.S. GDP, Taxes and Government Spending

Real per capita quarterly time series, 1980q1-2019q4:

GDP_t : GDP

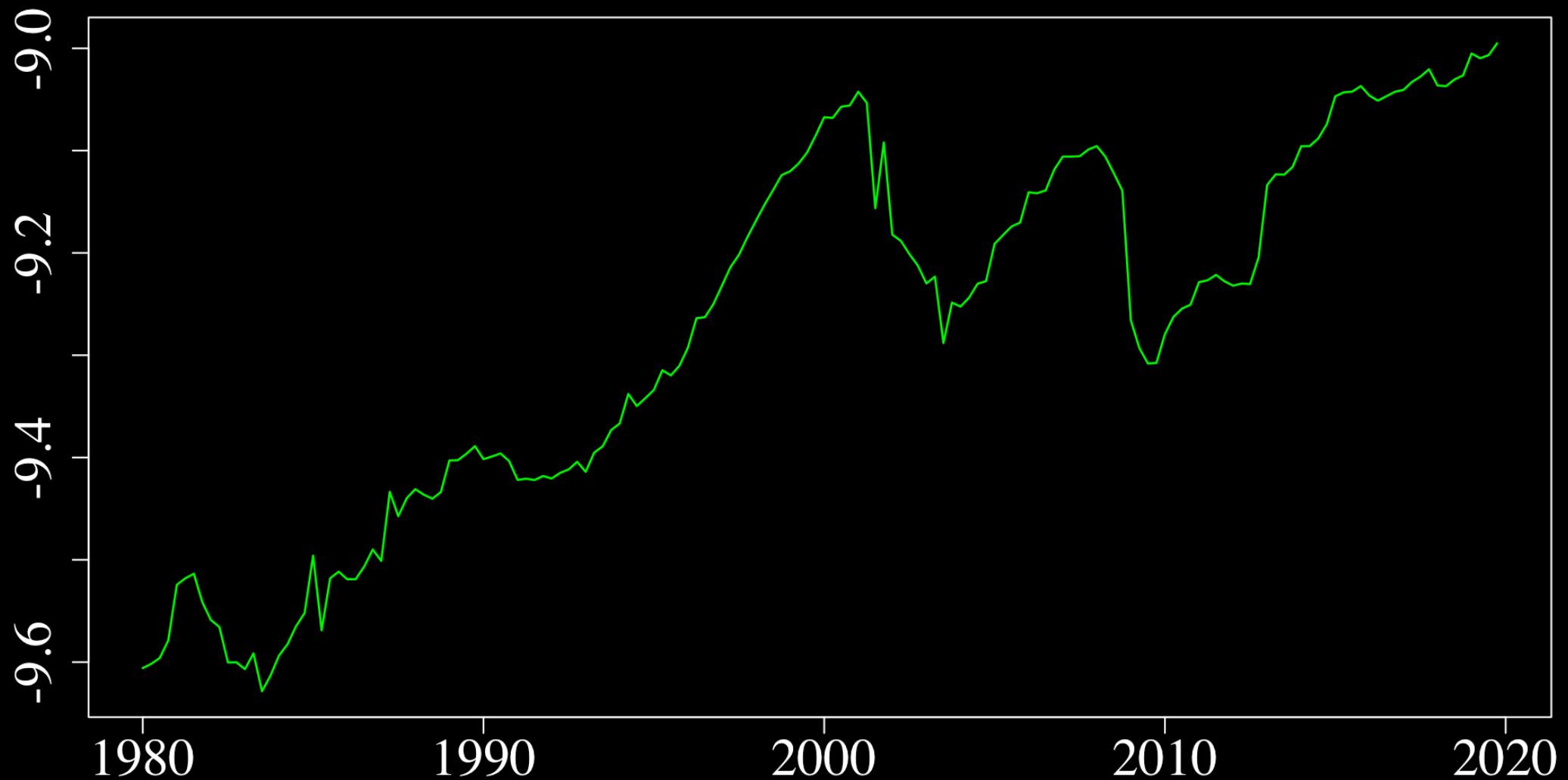
Tax_t : total tax revenue

Govt_t : total government spending

Mertens, K., and Ravn, M.O. (2014) A Reconciliation of SVAR and Narrative Estimates of Tax Multipliers, Journal of Monetary Economics, 68(S), S1–S19.

Woźniak, Tomasz (2025). bsvars: Bayesian Estimation of Structural Vector Autoregressive Models. R package version 4.0.

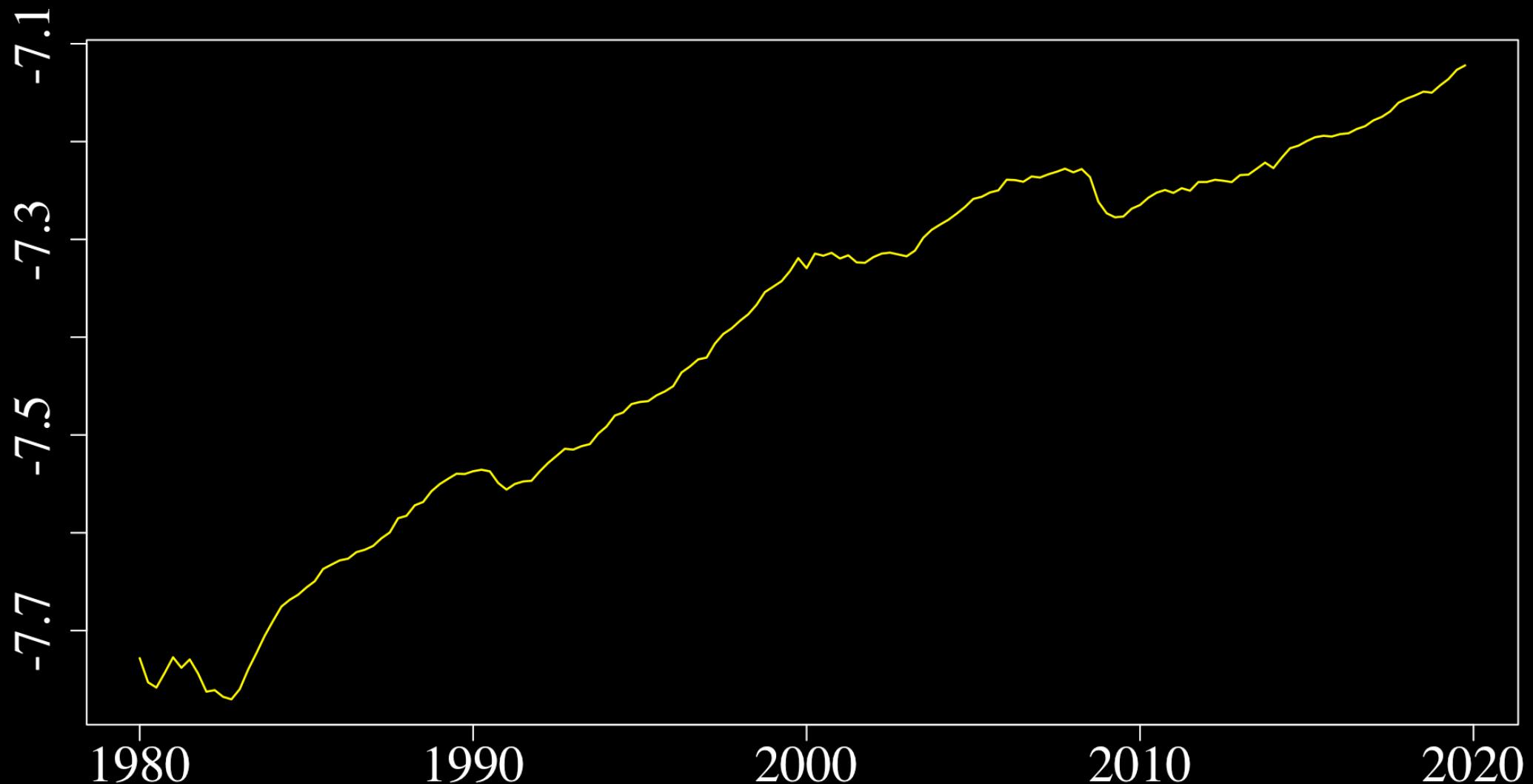
Tax revenue (real, per capita, log)



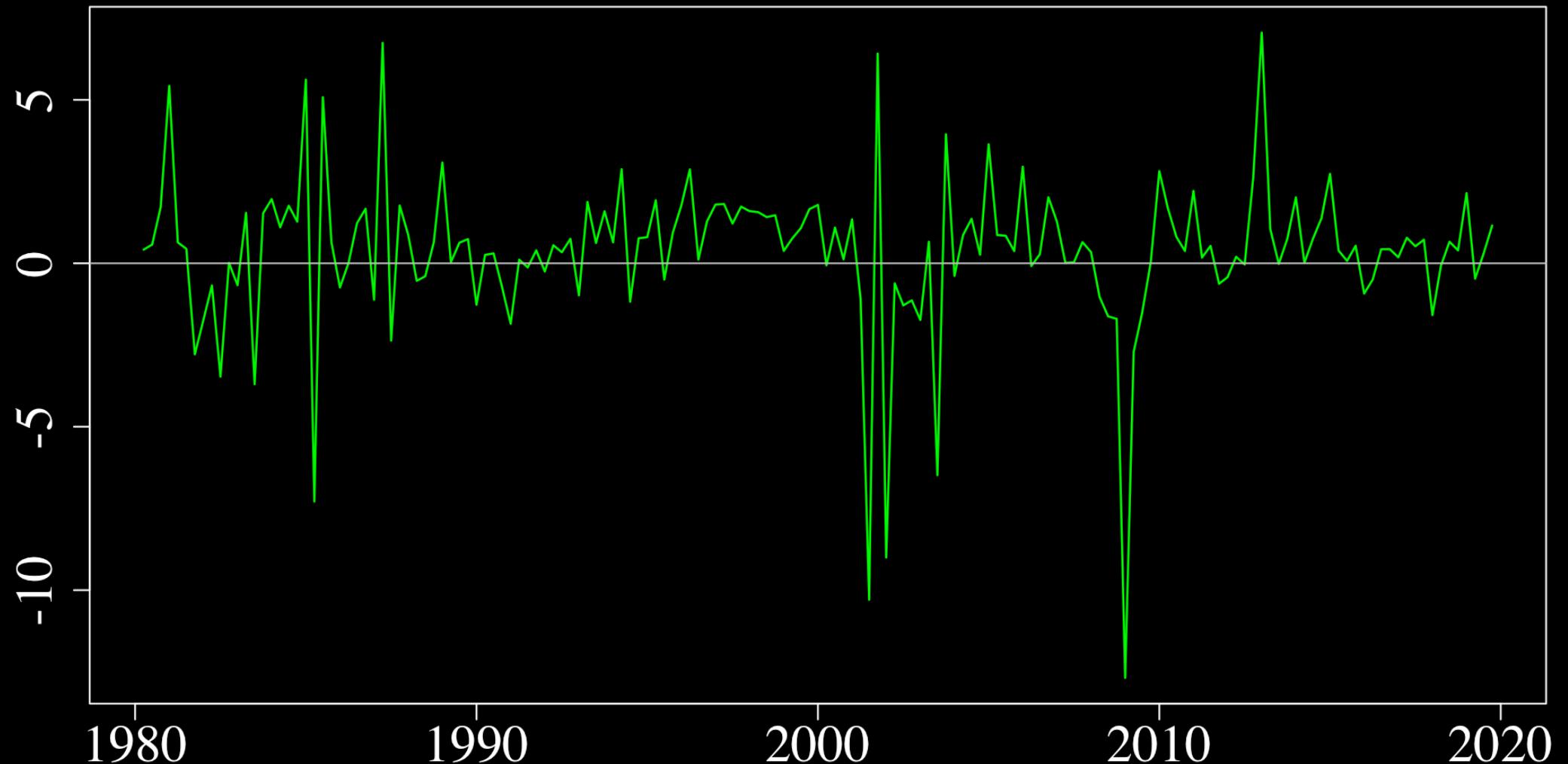
Government expenditure (real, per capita, log)



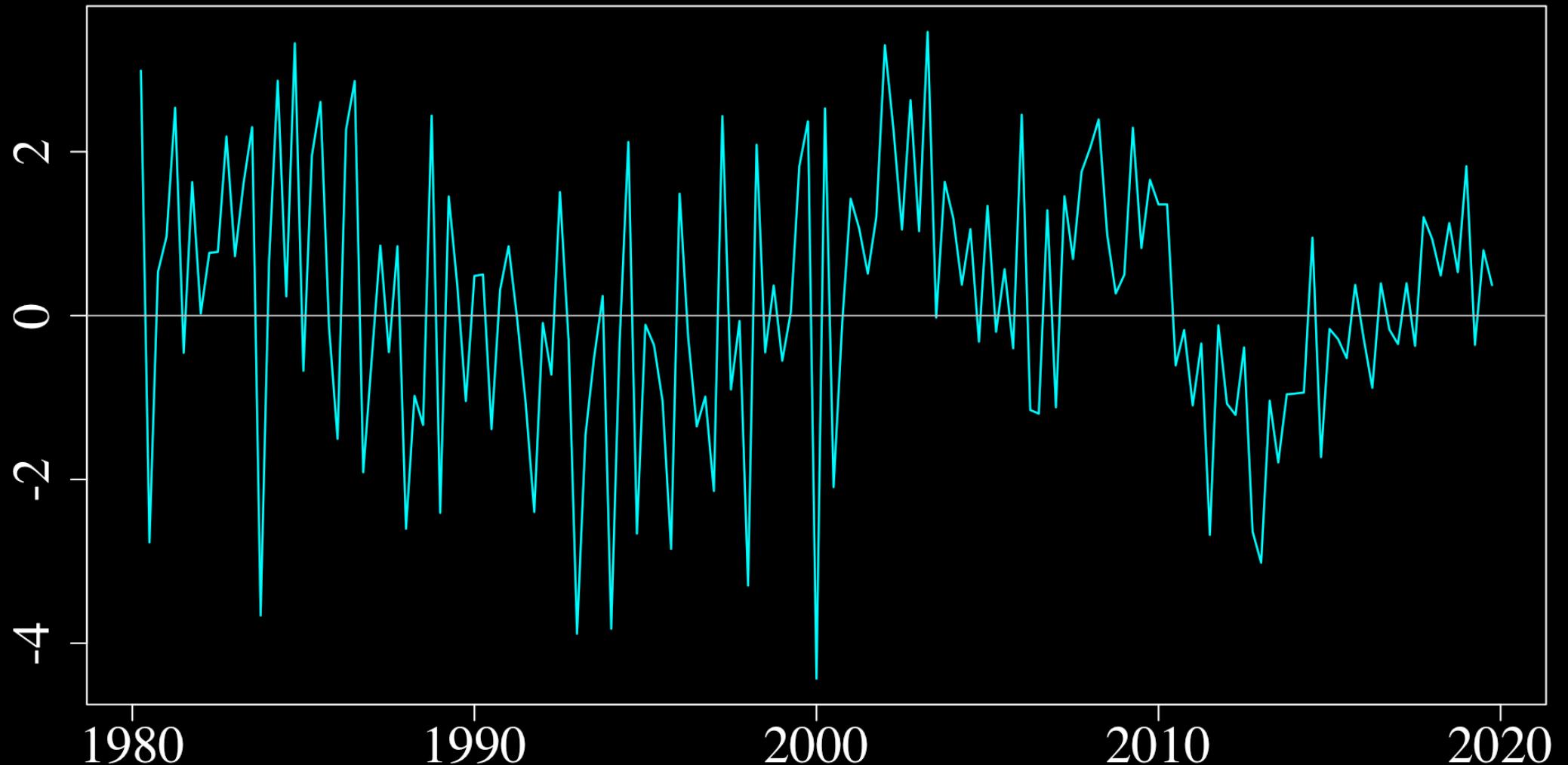
GDP (real, per capita, log)



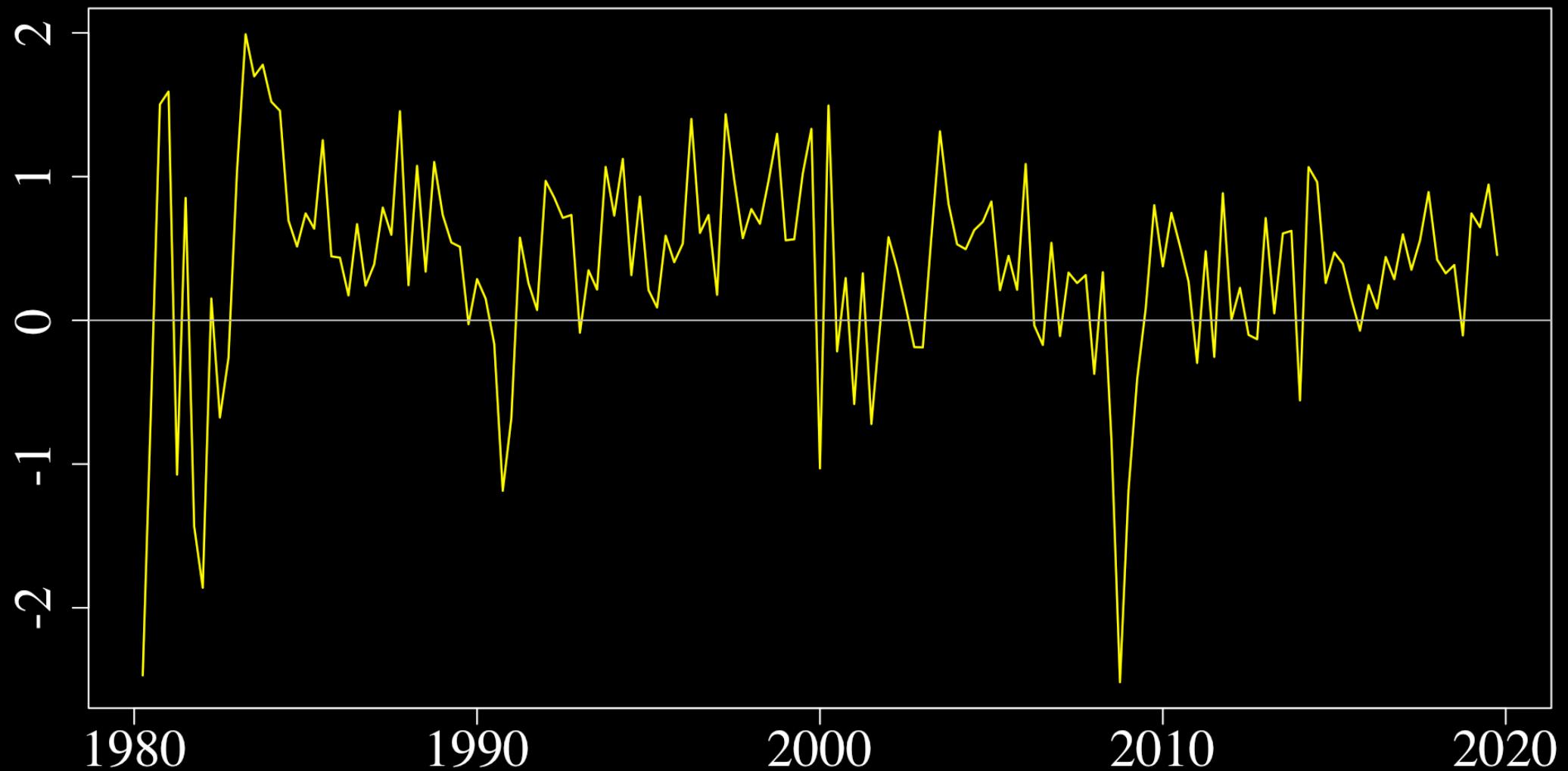
Δ Tax revenue (real, per capita, log)



Δ Govt expenditure (real, per capita, log)



Δ GDP (real, per capita, log)



Select VAR lag order

Select p to minimise AIC:

```
1 library(vars)
2 DY <- data.frame(DTax=DTax, DGovt=DGovt,
3                     DGDP=DGDP)
4 VARp <- VAR(DY, lag.max=8, ic="AIC")
5 print(VARp$p)
```

AIC(n)

3

Select VAR lag order

Check residual autocorrelation of VAR(3):

```
1 VARp <- VAR(DY, p=3)
2 Auto.test <- serial.test(VARp, lags.pt=12)
```

Portmanteau Test (asymptotic)

```
data: Residuals of VAR object VARp
Chi-squared = 85.618, df = 81, p-value =
0.3415 ✓
```

Tax equation

```
1 Coef.Tax <- VARp$varresult$DGDP$coefficient
```

DTax.l1 DGovt.l1 DGDP.l1

-0.017 -0.051 0.312

DTax.l2 DGovt.l2 DGDP.l2

-0.019 -0.038 0.218

DTax.l3 DGovt.l3 DGDP.l3

-0.050 -0.044 0.074

const

0.211

Tax equation

DTax.l1	DGovt.l1	DGDP.l1	$\leftarrow j = 1$
-0.017	-0.051	0.312	
DTax.l2	DGovt.l2	DGDP.l2	$\leftarrow j = 2$
-0.019	-0.038	0.218	
DTax.l3	DGovt.l3	DGDP.l3	$\leftarrow j = 3$
-0.050	-0.044	0.074	

↑

↑

↑

$$\Delta \text{Tax}_{t-j} \quad \Delta \text{Govt}_{t-j} \quad \Delta \text{GDP}_{t-j}$$

Tax equation

$$\begin{aligned}\widehat{E}(\Delta \text{Tax}_t | \mathcal{Y}_{t-1}) = & 0.211 \\& -0.017 \Delta \text{Tax}_{t-1} - 0.051 \Delta \text{Govt}_{t-1} \\& \quad + 0.312 \Delta \text{GDP}_{t-1} \\& -0.019 \Delta \text{Tax}_{t-2} - 0.038 \Delta \text{Govt}_{t-2} \\& \quad + 0.218 \Delta \text{GDP}_{t-2} \\& -0.050 \Delta \text{Tax}_{t-3} - 0.044 \Delta \text{Govt}_{t-3} \\& \quad + 0.074 \Delta \text{GDP}_{t-3}\end{aligned}$$

Government expenditure equation

DTax.l1	DGovt.l1	DGDP.l1	$\leftarrow j = 1$
-0.032	-0.040	-0.188	
DTax.l2	DGovt.l2	DGDP.l2	$\leftarrow j = 2$
-0.079	0.148	0.030	
DTax.l3	DGovt.l3	DGDP.l3	$\leftarrow j = 3$
-0.074	0.192	-0.036	

$$\Delta \text{Tax}_{t-j} \quad \Delta \text{Govt}_{t-j} \quad \Delta \text{GDP}_{t-j}$$

↑ ↑ ↑

Government expenditure equation

$$\begin{aligned}\widehat{E}(\Delta\text{Govt}_t \mid \mathcal{Y}_{t-1}) &= 0.261 \\ -0.032 \Delta\text{Tax}_{t-1} - 0.040 \Delta\text{Govt}_{t-1} & \\ &\quad -0.188 \Delta\text{GDP}_{t-1} \\ -0.079 \Delta\text{Tax}_{t-2} + 0.148 \Delta\text{Govt}_{t-2} & \\ &\quad +0.030 \Delta\text{GDP}_{t-2} \\ -0.074 \Delta\text{Tax}_{t-3} + 0.192 \Delta\text{Govt}_{t-3} & \\ &\quad -0.036 \Delta\text{GDP}_{t-3}\end{aligned}$$

GDP equation

DTax.l1	DGovt.l1	DGDP.l1	$\leftarrow j = 1$
-0.017	-0.051	0.312	
DTax.l2	DGovt.l2	DGDP.l2	$\leftarrow j = 2$
-0.019	-0.038	0.218	
DTax.l3	DGovt.l3	DGDP.l3	$\leftarrow j = 3$
-0.050	-0.044	0.074	

 \uparrow \uparrow \uparrow

$$\Delta \text{Tax}_{t-j} \quad \Delta \text{Govt}_{t-j} \quad \Delta \text{GDP}_{t-j}$$

GDP equation

$$\begin{aligned}\widehat{E}(\Delta\text{GDP}_t \mid \mathcal{Y}_{t-1}) &= 0.211 \\ -0.017 \Delta\text{Tax}_{t-1} - 0.051 \Delta\text{Govt}_{t-1} &\quad + 0.312 \Delta\text{GDP}_{t-1} \\ -0.019 \Delta\text{Tax}_{t-2} - 0.038 \Delta\text{Govt}_{t-2} &\quad + 0.218 \Delta\text{GDP}_{t-2} \\ -0.050 \Delta\text{Tax}_{t-3} - 0.044 \Delta\text{Govt}_{t-3} &\quad + 0.074 \Delta\text{GDP}_{t-3}\end{aligned}$$

Vector Autoregression Forecasting

Tax revenue growth forecasts

```
1 VARpf <- predict(VARp, n.ahead=8)  
2 DTaxf <- VARpf$fcst$DTax[,c("lower", "fcst")]
```

lower	fcst	upper
-3.778	0.391	4.560
-4.037	0.417	4.872
-4.172	0.608	5.389
-4.485	0.304	5.093
-4.446	0.419	5.284
-4.506	0.383	5.272
-4.540	0.357	5.255

Government expenditure growth forecasts

```
1 DGovtf <- VARpf$fcst$DGovt[ ,  
2                           c("lower", "fcst", "upper") ]
```

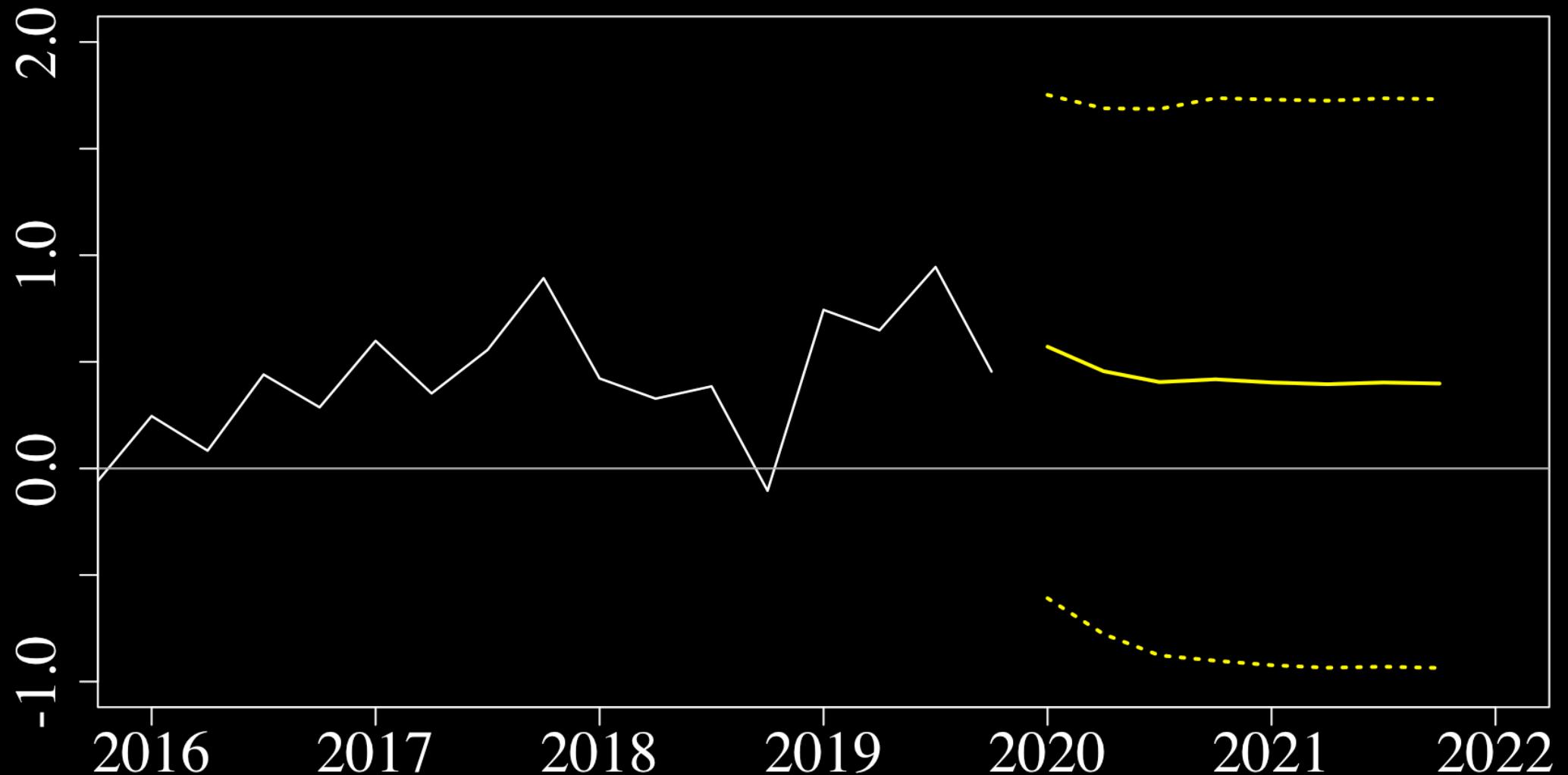
	lower	fcst	upper
-2.783	0.190	3.163	
-2.782	0.208	3.198	
-2.907	0.137	3.182	
-2.965	0.159	3.282	
-2.995	0.143	3.282	
-3.016	0.145	3.306	
-3.010	0.162	3.334	

GDP growth forecasts

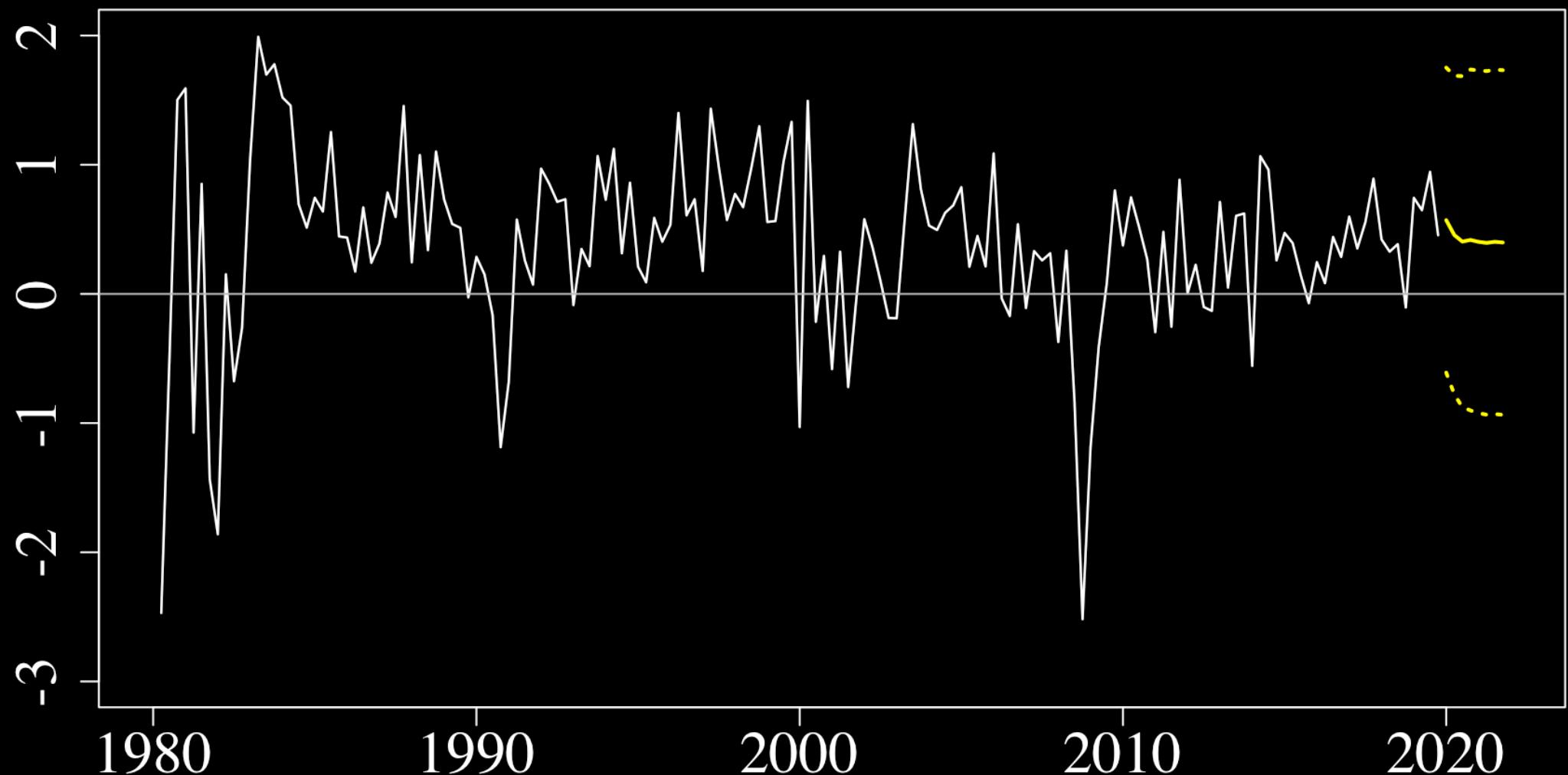
```
1 DGDPf <- VARpf$fcst$DGDP[,  
2 c("lower", "fcst", "upper") ]
```

	lower	fcst	upper
-	-0.609	0.571	1.752
-	-0.777	0.456	1.689
-	-0.877	0.405	1.686
-	-0.902	0.418	1.737
-	-0.923	0.403	1.730
-	-0.935	0.395	1.725
-	-0.930	0.403	1.736

GDP growth forecasts



GDP growth forecasts



Granger causality testing

Does economic growth forecast gov't finances?

```
1 GCtest <- causality(VARp, cause="DGDP")  
2 print(GCtest$Granger)
```

Granger causality H0: DGDP do not Granger-cause DTax DGovt

data: VAR object VARp
F-Test = 5.3586, df1 = 6, df2 = 438, p-value =
2.355e-05 $p < 0.05 \Rightarrow$ Yes!

Granger causality RMSE analysis

VARs for forecasting tax revenue growth:

1. DTax, DGovt, DGDP (*Trivariate*)
 2. DTax, DGovt (*Bivariate*)
 3. DTax, DGDP (*Bivariate*)
 4. DTax (*Univariate AR*)

Granger causality RMSE analysis

VARs for forecasting tax revenue growth:

1. DTax, DGovt, DGDP

$$p = 3$$

2. DTax, DGovt

$$p = 6$$

3. DTax, DGDP

$$p = 2$$

4. DTax (i.e. AR model)

$$p = 3$$

Granger causality RMSE analysis

VARs for forecasting tax revenue growth:

1. DTax, DGovt, DGDP

$$p = 3, \text{RMSE}(\Delta \text{Tax}) = 3.706$$

2. DTax, DGovt

$$p = 6, \text{RMSE}(\Delta \text{Tax}) = 3.734$$

3. DTax, DGDP

$$p = 2, \text{RMSE}(\Delta \text{Tax}) = 3.730$$

4. DTax (i.e. AR model)

$$p = 3, \text{RMSE}(\Delta \text{Tax}) = 3.775$$

Granger causality RMSE analysis

VARs for forecasting tax revenue growth:

1. DTax, DGovt, DGDP

$p = 3$, RMSE(ΔTax) = 3.706 ✓

2. DTax, DGovt

$p = 6$, RMSE(ΔTax) = 3.734

3. DTax, DGDP

$p = 2$, RMSE(ΔTax) = 3.730

4. DTax (i.e. AR model)

$p = 3$, RMSE(ΔTax) = 3.775

Vector Autoregression

Impulse Responses

Impulse Response definitions

Consider: time series $Y_t = (Y_{1,t}, \dots, Y_{K,t})'$
and model $E(Y_t | \mathcal{Y}_{t-1})$.

Denote $\mathcal{Y}_n = \{Y_n \cup \mathcal{Y}_{n-1}\}$.

Usual forecasts based on observed data:

$$E(Y_{n+h} | \mathcal{Y}_n) = E(Y_{n+h} | Y_n \cup \mathcal{Y}_{n-1})$$

Counterfactual with an “impulse” to Y_n :

$$E(Y_{n+h} | (Y_n + \delta) \cup \mathcal{Y}_{n-1})$$

Impulse Response definitions

Usual forecasts based on observed data:

$$E(Y_{n+h} \mid \mathcal{Y}_n) = E(Y_{n+h} \mid Y_n \cup \mathcal{Y}_{n-1})$$

Counterfactual with an “impulse” to Y_n :

$$E(Y_{n+h} \mid (Y_n + \delta) \cup \mathcal{Y}_{n-1})$$

Impulse responses:

$$\begin{aligned} & E(Y_{n+h} \mid (Y_n + \delta) \cup \mathcal{Y}_{n-1}) \\ & - E(Y_{n+h} \mid Y_n \cup \mathcal{Y}_{n-1}) \end{aligned}$$

Change in forecasts due to δ change in Y_n .

Impulse Response definitions

Impulse responses:

$$E(Y_{n+h} \mid (Y_n + \delta) \cup \mathcal{Y}_{n-1}) - E(Y_{n+h} \mid Y_n \cup \mathcal{Y}_{n-1})$$

Change in forecasts due to δ change in Y_n .

Extends the regression interpretation:

$$E(Y_i \mid X_{1,i}, X_{2,i}) = \beta_0 + \beta_1 X_{1,i} + \beta_2 X_{2,i}$$

Impulse Response definitions

Impulse responses:

$$\begin{aligned} & E(Y_{n+h} \mid (Y_n + \delta) \cup \mathcal{Y}_{n-1}) \\ & - E(Y_{n+h} \mid Y_n \cup \mathcal{Y}_{n-1}) \end{aligned}$$

Change in forecasts due to δ change in Y_n .

Extends the regression interpretation:

$$E(Y_i | X_{1,i}, X_{2,i}) = \beta_0 + \beta_1 X_{1,i} + \beta_2 X_{2,i}$$

β_1 : change in $E(Y_i | X_{1,i}, X_{2,i})$ due to
+1 change in $X_{1,i}$

Impulse Response definitions

Impulse responses:

$$\begin{aligned} & E(Y_{n+h} \mid (\textcolor{violet}{Y}_n + \delta) \cup \mathcal{Y}_{n-1}) \\ & - E(Y_{n+h} \mid Y_n \cup \mathcal{Y}_{n-1}) \end{aligned}$$

Change in forecasts due to δ change in Y_n .

Extends the regression interpretation:

$$E(Y_i | X_{1,i}, X_{2,i}) = \beta_0 + \beta_1 X_{1,i} + \beta_2 \textcolor{blue}{X}_{2,i}$$

β_1 : change in $E(Y_i | X_{1,i}, X_{2,i})$ due to
+1 change in $X_{1,i}$ (holding $X_{2,i}$ constant).

Impulse Response definitions

Impulse responses:

$$E(Y_{n+h} \mid (Y_n + \delta) \cup \mathcal{Y}_{n-1}) - E(Y_{n+h} \mid Y_n \cup \mathcal{Y}_{n-1})$$

Change in forecasts due to δ change in Y_n .

Extends the regression interpretation:

$$\begin{aligned} & E(Y_i \mid X_{1,i} + 1, X_{2,i}) - E(Y_i \mid X_{1,i}, X_{2,i}) \\ &= \beta_0 + \beta_1(X_{1,i} + 1) + \beta_2 X_{2,i} \\ &\quad - (\beta_0 + \beta_1 X_{1,i} + \beta_2 X_{2,i}) \end{aligned}$$

Impulse Response definitions

Impulse responses:

$$E(Y_{n+h} \mid (Y_n + \delta) \cup \mathcal{Y}_{n-1}) - E(Y_{n+h} \mid Y_n \cup \mathcal{Y}_{n-1})$$

Change in forecasts due to δ change in Y_n .

Extends the regression interpretation:

$$\begin{aligned} & E(Y_i \mid X_{1,i} + 1, X_{2,i}) - E(Y_i \mid X_{1,i}, X_{2,i}) \\ &= \beta_0 + \beta_1(X_{1,i} + 1) + \beta_2 X_{2,i} \\ &\quad - (\beta_0 + \beta_1 X_{1,i} + \beta_2 X_{2,i}) \\ &= \beta_1 \end{aligned}$$

Impulse Response definitions

Impulse responses:

$$E(Y_{n+h} \mid (Y_n + \delta) \cup \mathcal{Y}_{n-1}) - E(Y_{n+h} \mid Y_n \cup \mathcal{Y}_{n-1})$$

Change in forecasts due to δ change in Y_n .

How to define the “impulse” δ ?

There is HUGE literature on this...

Impulse Response definitions

Impulse responses:

$$E(Y_{n+h} \mid (Y_n + \delta) \cup \mathcal{Y}_{n-1}) - E(Y_{n+h} \mid Y_n \cup \mathcal{Y}_{n-1})$$

Change in forecasts due to δ change in Y_n .

Example:

$$Y_t = \begin{pmatrix} \Delta \text{Tax}_t \\ \Delta \text{Govt}_t \\ \Delta \text{GDP}_t \end{pmatrix}$$

Impulse Response definitions

Impulse responses:

$$E(Y_{n+h} \mid (Y_n + \delta) \cup \mathcal{Y}_{n-1}) - E(Y_{n+h} \mid Y_n \cup \mathcal{Y}_{n-1})$$

Change in forecasts due to δ change in Y_n .

Example:

$$Y_n = \begin{pmatrix} \Delta \text{Tax}_n \\ \Delta \text{Govt}_n \\ \Delta \text{GDP}_n \end{pmatrix} \quad \delta = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Impulse Response definitions

Example:

$$Y_n = \begin{pmatrix} \Delta \text{Tax}_n \\ \Delta \text{Govt}_n \\ \Delta \text{GDP}_n \end{pmatrix} \quad \delta = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Impulse: +1 unit to GDP growth

Impulse Response definitions

Example:

$$Y_n = \begin{pmatrix} \Delta \text{Tax}_n \\ \Delta \text{Govt}_n \\ \Delta \text{GDP}_n \end{pmatrix} \quad \delta = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Impulse: +1 unit to GDP growth

How are forecasts revised in response to this impulse to GDP growth?

Impulse Response Application

```
1 VAR_TGY <- VAR(DY, p=3) ← VAR(3) for growth  
2 IRF <- irf(VAR_TGY,  
3 impulse="DGDP",  
4 ortho=FALSE,  
5 response=c("DTax"),  
6 n.ahead=8)
```

Impulse Response Application

```
1 VAR_TGY <- VAR(DY, p=3)
2 IRF <- irf(VAR_TGY,
3             impulse="DGDP", ← Impulse to
4             ortho=FALSE,           ΔGDP
5             response=c("DTax"),
6             n.ahead=8)
```

Impulse Response Application

```
1 VAR_TGY <- VAR(DY, p=3)
2 IRF <- irf(VAR_TGY,
3             impulse="DGDP",
4             ortho=FALSE, ← +1 unit (more soon.
5             response=c("DTax"),
6             n.ahead=8)
```

Impulse Response Application

Impulse Response Application

Responses of ΔTax_{n+h} forecasts to +1 impulse to ΔGDP_n (with 95% CIs):

	Lower	IRF	Upper	
$t=n$	0.000	0.000	0.000	
$t=n+1$	0.457	1.014	1.625	← 1-step-ahead forecast
$t=n+2$	0.542	1.114	1.713	increased by 1.014
$t=n+3$	-0.452	0.229	0.782	
$t=n+4$	0.131	0.630	0.982	
$t=n+5$	-0.096	0.290	0.537	
$t=n+6$	-0.063	0.217	0.444	

Impulse Response Application

Responses of ΔTax_{n+h} forecasts to +1 impulse to ΔGDP_n (with 95% CIs):

	Lower	IRF	Upper	
t=n	0.000	0.000	0.000	
t=n+1	0.457	1.014	1.625	← 95% CI excludes zero
t=n+2	0.542	1.114	1.713	⇒ significant
t=n+3	-0.452	0.229	0.782	
t=n+4	0.131	0.630	0.982	
t=n+5	-0.096	0.290	0.537	
t=n+6	-0.063	0.217	0.444	

Impulse Response Application

Responses of ΔTax_{n+h} forecasts to +1 impulse to ΔGDP_n (with 95% CIs):

	Lower	IRF	Upper
$t=n$	0.000	0.000	0.000
$t=n+1$	0.457	1.014	1.625
$t=n+2$	0.542	1.114	1.713
$t=n+3$	-0.452	0.229	0.782
$t=n+4$	0.131	0.630	0.982
$t=n+5$	-0.096	0.290	0.537
$t=n+6$	-0.063	0.217	0.444

A 1 unit increase in GDP growth increases the 1-quarter-ahead forecast of Tax growth by 1.014.

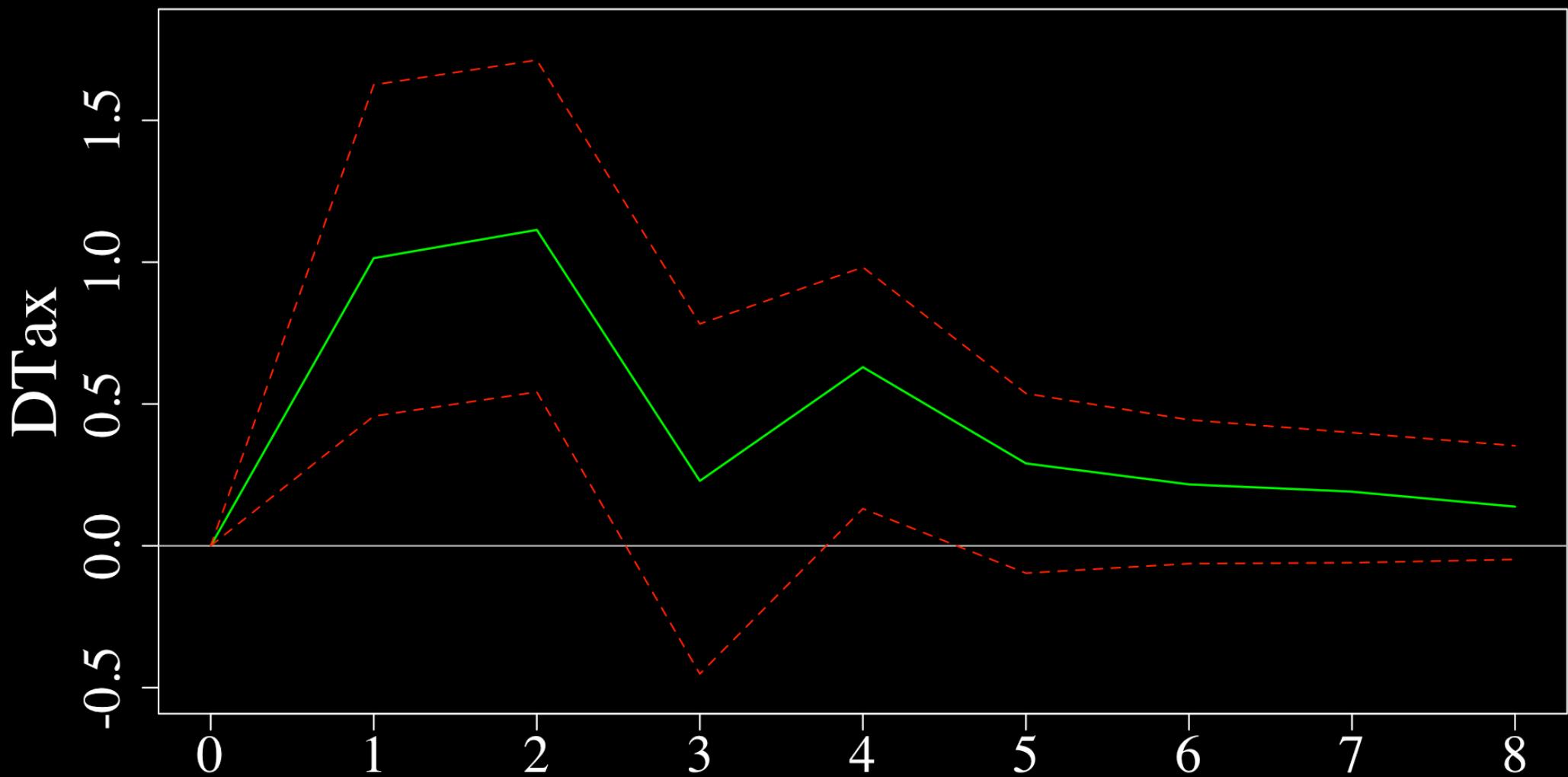
Impulse Response Application

Responses of ΔTax_{n+h} forecasts to +1 impulse to ΔGDP_n (with 95% CIs):

	Lower	IRF	Upper
t=n	0.000	0.000	0.000
t=n+1	0.457	1.014	1.625
t=n+2	0.542	1.114	1.713
t=n+3	-0.452	0.229	0.782
t=n+4	0.131	0.630	0.982
t=n+5	-0.096	0.290	0.537
t=n+6	-0.063	0.217	0.444

A 1 unit increase in GDP growth increases the 2-quarter-ahead forecast of Tax growth by 1.114.

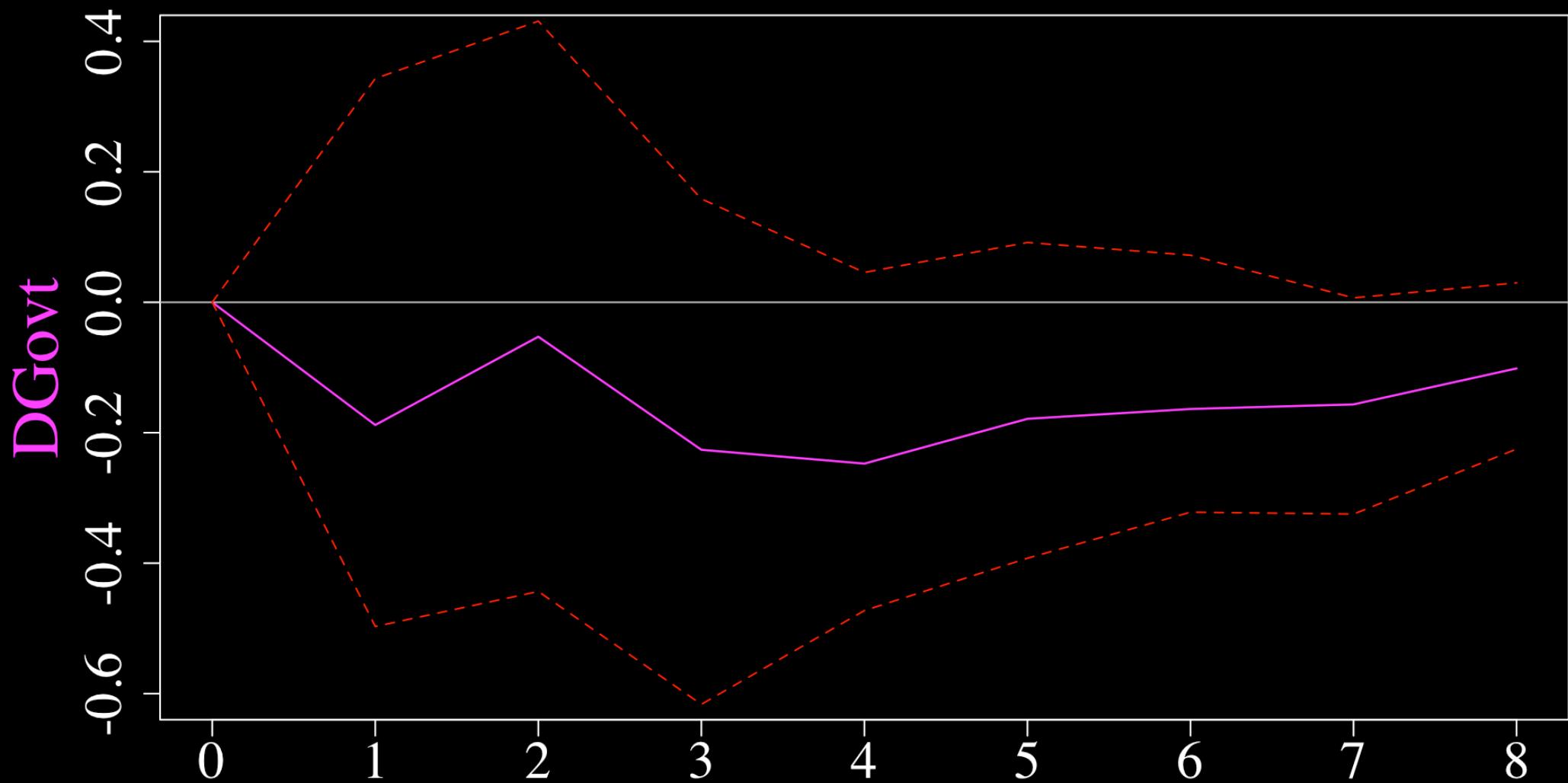
Impulse Response from DGDP



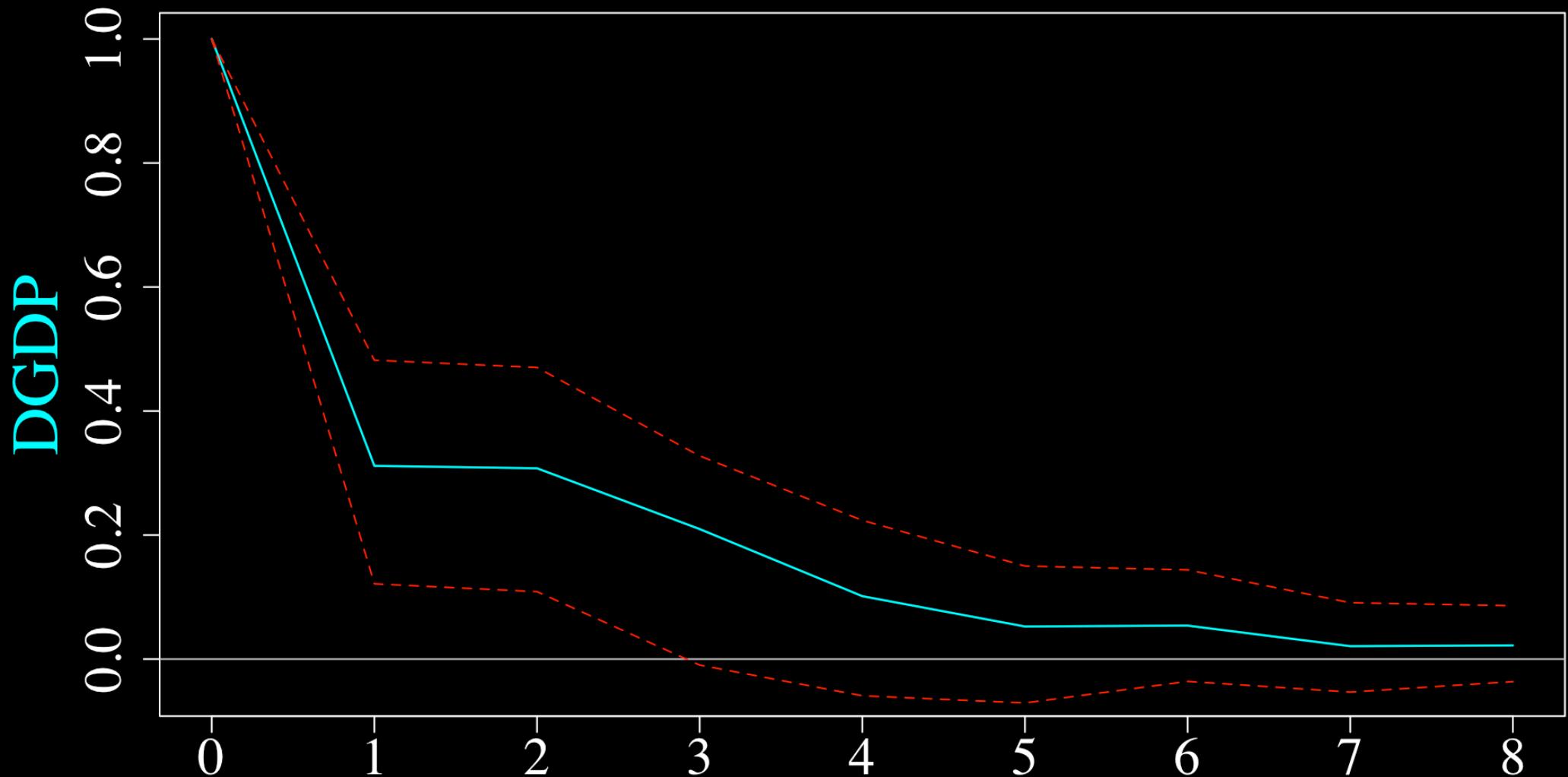
Impulse Response Application

```
1 IRF <- irf(VAR_TGY,  
2               impulse="DGDP",  
3               ortho=FALSE,  
4               response=c("DTax", "DGovt", "DGDP"),  
5               n.ahead=8)
```

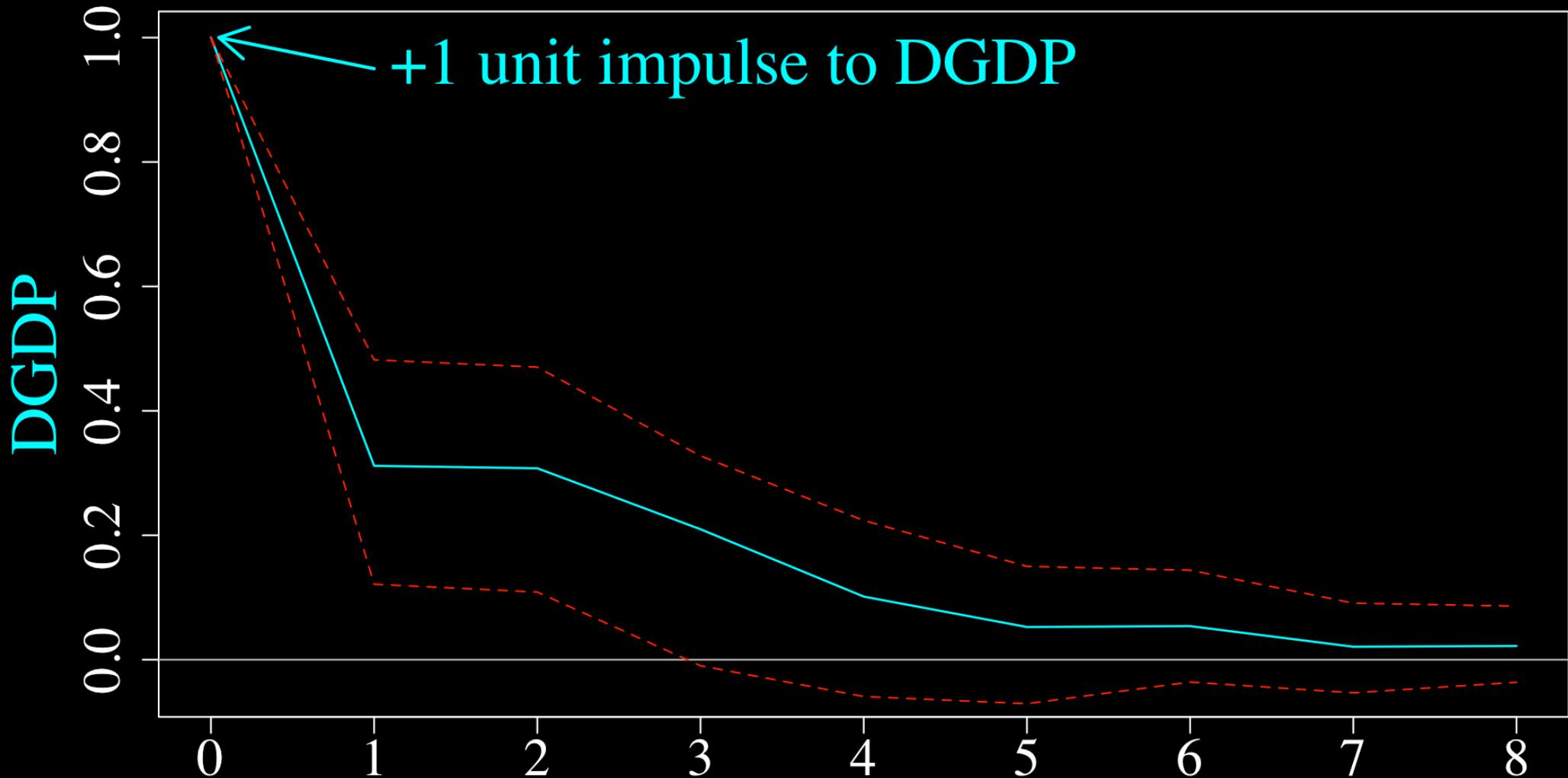
Impulse Response from DGDP



Impulse Response from DGDP



Impulse Response from DGDP



Summary

- Vector autoregression provides a natural extension of univariate AR models.
- Model selection: AIC and residual autocorrelation tests
- Granger “causality”: adding a variable to the model improves forecasts of another variable.
- Impulse responses: how do forecasts change in response to an “impulse” to a variable in the model?