

**Question 3.**

- (a) For a time series  $Y_t$  with  $t = 1, \dots, n$ , and  $\mathcal{Y}_{t-1} = \{Y_{t-1}, \dots, Y_1\}$ , why do we use the conditional expectation  $E(Y_t|\mathcal{Y}_{t-1})$  for one-step-ahead forecasting?

- (b) Define the one-step-ahead prediction error  $U_t = Y_t - E(Y_t|\mathcal{Y}_{t-1})$ . Show that

- (i)  $E(U_t|\mathcal{Y}_{t-1}) = 0$
- (ii)  $E(U_t) = 0$
- (iii)  $E(U_t U_{t-j}) = 0$  for all  $j = 1, 2, \dots$

(c) What is the implication of your answer to part (b) for practical time series model specification?

(d) Define and compare the concepts of *recursive* and *direct* forecasting for two-step-ahead forecasting.

- (e) Are the one-step-ahead prediction errors  $U_t$  defined in part (b) necessarily stationary? If so, justify this. If not, what else is required for  $U_t$  to be stationary?

- (f) Suppose  $Y_t = U_t + \theta_1 U_{t-1}$  is an MA(1) time series where  $U_t$  is a stationary prediction error. Derive  $E(Y_t)$ ,  $\text{var}(Y_t)$ ,  $\text{cov}(Y_t, Y_{t-1})$  and hence the first order autocorrelation  $\text{cor}(Y_t, Y_{t-1})$ . Are these expressions sufficient to conclude that  $Y_t$  is stationary?

- (g) Use the expression for the first order autocorrelation  $\rho_1 = \text{cor}(Y_t, Y_{t-1})$  in the previous part to work out the range of possible values for  $\rho_1$  that can arise from an MA(1) model.

In case it's helpful, the quadratic formula for  $x$  that solves  $ax^2 + bx + c = 0$  is

$$x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}.$$

Suppose a time series produce a first order autocorrelation of 0.8. It is possible that an MA(1) model is appropriate for this time series?