Recall: Classifiers

A linear classifier:

$$h(x; \theta, \theta_0) = \operatorname{sign}(\theta^\top x + \theta_0)$$
$$= \begin{cases} +1 & \text{if } \theta^\top x + \theta_0 > 0\\ -1 & \text{if } \theta^\top x + \theta_0 \le 0 \end{cases}$$

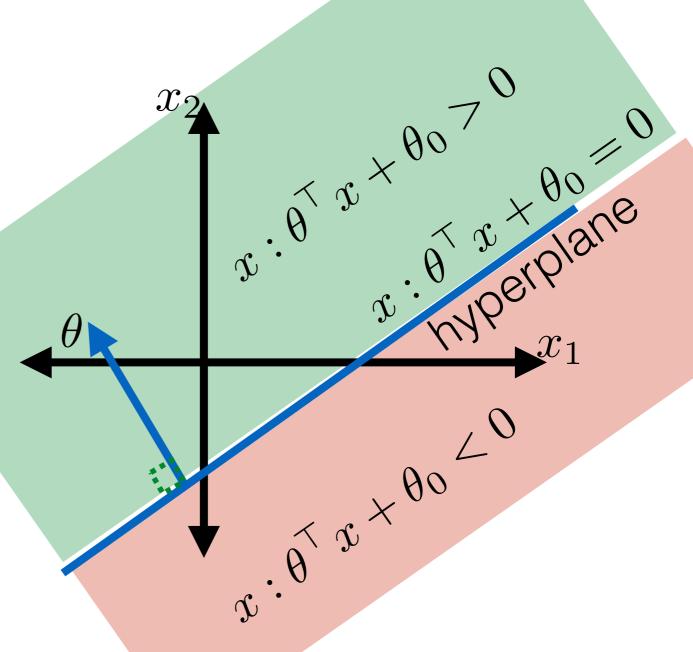
- Hypothesis class \mathcal{H} of all linear classifiers
- 0-1 Loss $L(g,a) = \begin{cases} 0 \text{ if } g = a \\ 1 \text{ else} \end{cases}$

• Training error
$$\mathcal{E}_n(h) = \frac{1}{n} \sum_{i=1}^n L(h(x^{(i)}), y^{(i)})$$
• Example learning algorithm (given)



Set
$$j^* = \operatorname*{argmin}_{j \in \{1, \dots, k\}} \mathcal{E}_n(h^{(j)})$$
 Return $h^{(j^*)}$

[demo]



Perceptron Algorithm

```
Perceptron ( \mathcal{D}_n ; \tau )
   Initialize \theta = \begin{bmatrix} 0 & 0 & \dots & 0 \end{bmatrix}^{\top} [How many 0s?]
   Initialize \theta_0 = 0
   for t = 1 to \tau
      changed = False
      for i = 1 to n
         if y^{(i)}(\theta^{\top}x^{(i)} + \theta_0) \leq 0
             Set \theta = \theta + y^{(i)}x^{(i)}
             Set \theta_0 = \theta_0 + y^{(i)}
              changed = True
```

[i.e. True if either:

A. point is not on the line & prediction is wrong

B. point is on the line

C. initial step]

if not changed

break

Return θ, θ_0

What does an update do?

$$y^{(i)} \left((\theta + y^{(i)} x^{(i)})^{\top} x^{(i)} + (\theta_0 + y^{(i)}) \right)$$

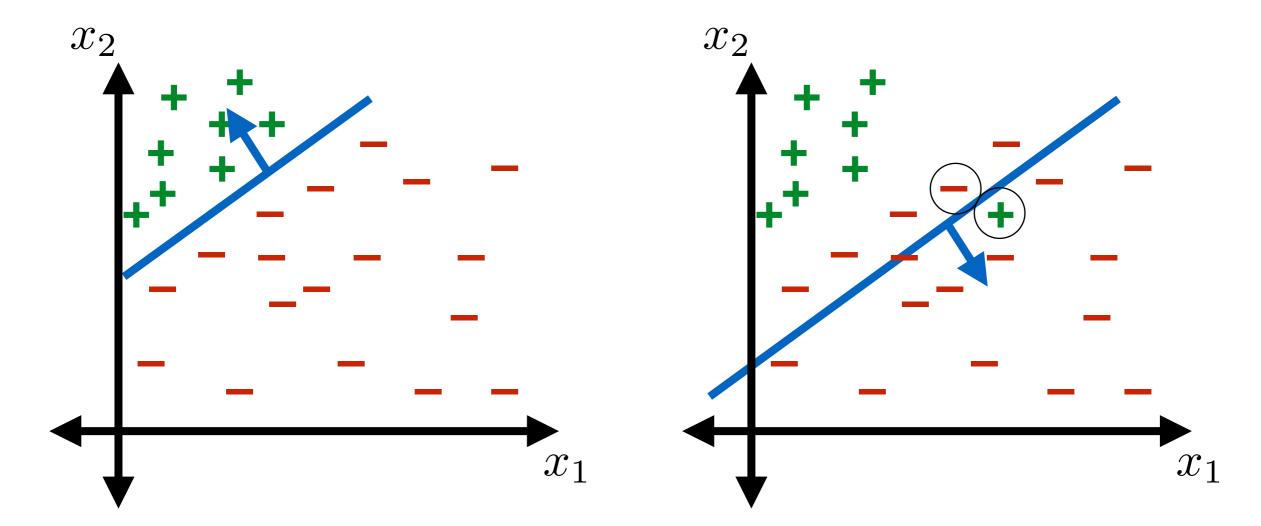
$$= y^{(i)} (\theta^{\top} x^{(i)} + \theta_0) + (y^{(i)})^2 (x^{(i)} x^{(i)} + 1)$$

$$= y^{(i)} (\theta^{\top} x^{(i)} + \theta_0) + (\|x^{(i)}\|^2 + 1)$$

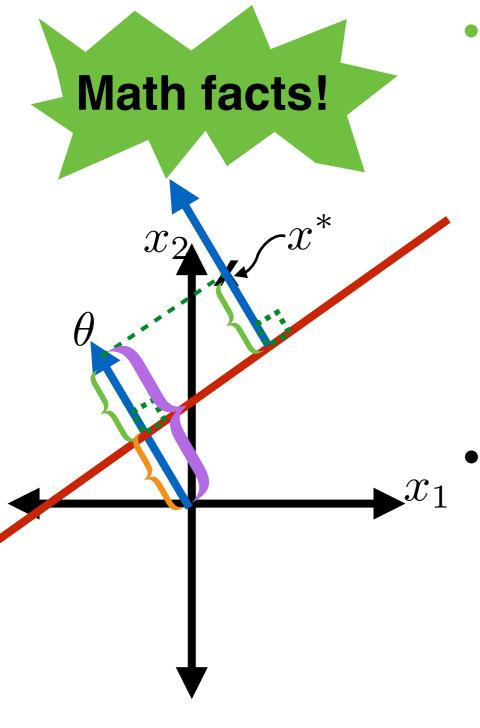
Let's Talk About Classifier Quality

• Definition: A training set \mathcal{D}_n is **linearly** separable if there exist θ, θ_0 such that, for every point index $i \in \{1, \dots, n\}$, we have

$$y^{(i)}(\theta^{\top} x^{(i)} + \theta_0) > 0$$



Let's Talk About Classifier Quality



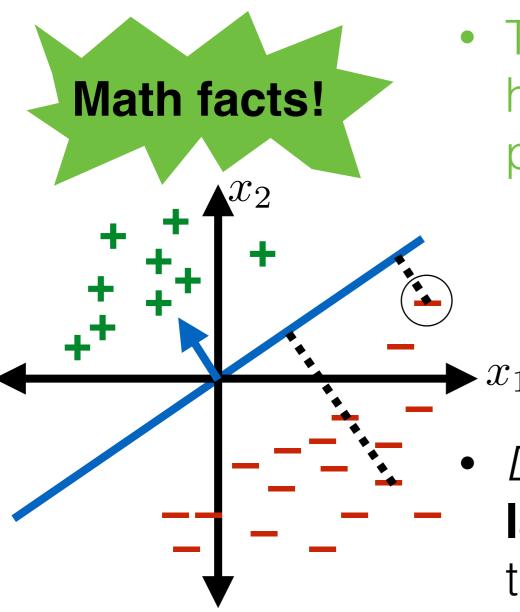
- The signed distance from a hyperplane defined by θ, θ_0 to a point x^* is:
 - = projection of x^* on θ
 - signed distance of line to origin

$$= \frac{\theta^{\top} x^*}{\|\theta\|} - \frac{-\theta_0}{\|\theta\|} = \frac{\theta^{\top} x^* + \theta_0}{\|\theta\|}$$

Definition: The margin of the labelled point (x^*, y^*) with respect to the hyperplane defined by θ, θ_0 is:

$$y^* \left(\frac{\theta^\top x^* + \theta_0}{\|\theta\|} \right)$$

Let's Talk About Classifier Quality



• The signed distance from a hyperplane defined by θ, θ_0 to a point x^* is:

= projection of x^* on θ

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Definition: The margin of the labelled point (x^*, y^*) with respect to the hyperplane defined by θ, θ_0 is:

$$y^* \left(\frac{\theta^\top x^* + \theta_0}{\|\theta\|} \right)$$

• Definition: The margin of the training set \mathcal{D}_n with respect to $\min_{i \in \{1,...,n\}} y^{(i)} \left(\frac{\theta^\top x^{(i)} + \theta_0}{\|\theta\|} \right)$ the hyperplane defined by θ, θ_0 is:

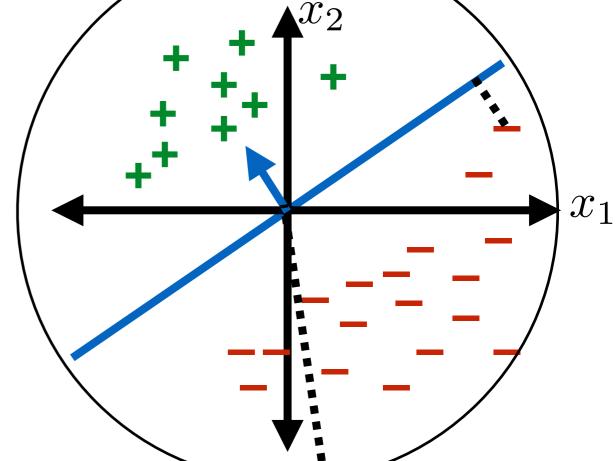
Theorem: Perceptron Performance

Assumptions:

- A. Our hypothesis class = classifiers with separating hyperplanes that pass through the origin (i.e. $\theta_0 = 0$)
- B. There exist θ^* and γ such that $\gamma > 0$ and, for every $i \in \{1, \ldots, n\}$, we have $y^{(i)}\left(\frac{\theta^{*\top}x^{(i)}}{\|\theta\|}\right) > \gamma$

C. There exists R such that, for every $i \in \{1, \dots, n\}$, we have $\|x^{(i)}\| \leq R$

• **Conclusion**: Then the perceptron algorithm will make at most $(R/\gamma)^2$ updates to θ . Once it goes through a pass of i without changes, the training error of its hypothesis will be 0.



Why classifiers through the origin?

- If we're clever, we don't lose any flexibility
 - Classifier with offset

$$x \in \mathbb{R}^d, \theta \in \mathbb{R}^d, \theta_0 \in \mathbb{R}$$
$$x : \theta^\top x + \theta_0 \stackrel{\leq}{=} 0$$

Classifier without offset

$$x_{\text{new}} \in \mathbb{R}^{d+1}, \theta_{\text{new}} \in \mathbb{R}^{d+1}$$

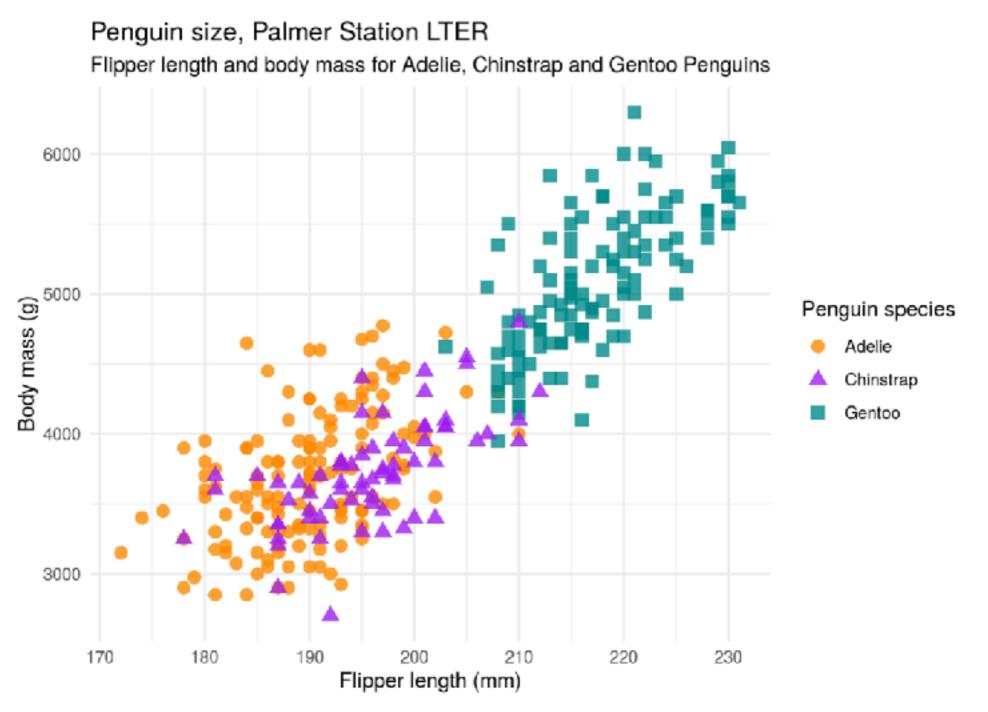
$$x_{\text{new}} = [x_1, x_2, \dots, x_d, 1]^\top, \theta_{\text{new}} = [\theta_1, \theta_2, \dots, \theta_d, \theta_0]^\top$$

$$x_{\text{new}, 1:d} : \theta_{\text{new}}^\top x_{\text{new}} \stackrel{\leq}{=} 0$$

 Can first convert to "expanded" feature space, then apply theorem

Problem: data not linearly separable

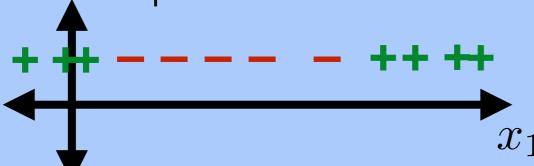
Typical real data sets aren't linearly separable [demo]



What can we do? See upcoming lectures!

Machine Learning Tasks

- Supervised learning: Learn a mapping from features to labels
- Regression: Learn a mapping to continuous values: $\mathbb{R}^d \to \mathbb{R}^k$
- Binary/two-class classification: Learn a mapping: $\mathbb{R}^d \to \{-1, +1\}$
 - Example: linear classification



- Unsupervised learning: No labels; find patterns
- Classification:

 Learn a mapping to
 a discrete set

