Generative adversarial networks (GAN)

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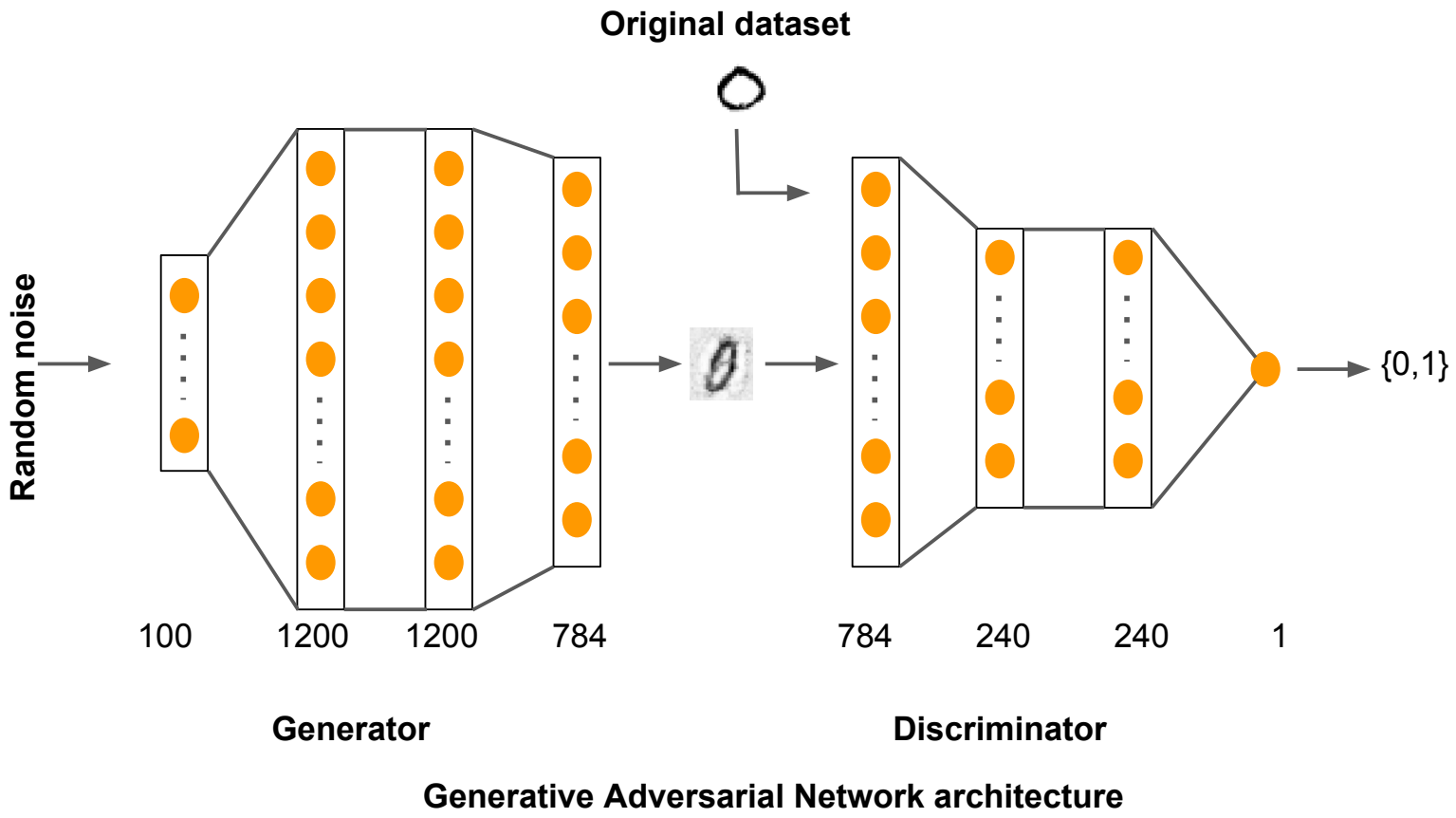
GAN architecture - Final

$\approx$ 2.75M trainable parameters



Objective for GAN

D $\rightarrow$ discriminator, G $\rightarrow$ generator
X $\rightarrow$ input data, Z $\rightarrow$ input noise

$$D\_loss = -log[D(X)] - log(1 - D(G(Z))) \quad (1)$$

$$G\_loss = -log[D(G(Z))] \quad (2)$$

At optimal, D(.) $= 0.5$, everywhere

Source: *IJ Goodfellow et. al. 2014*

Training procedure

Algorithm

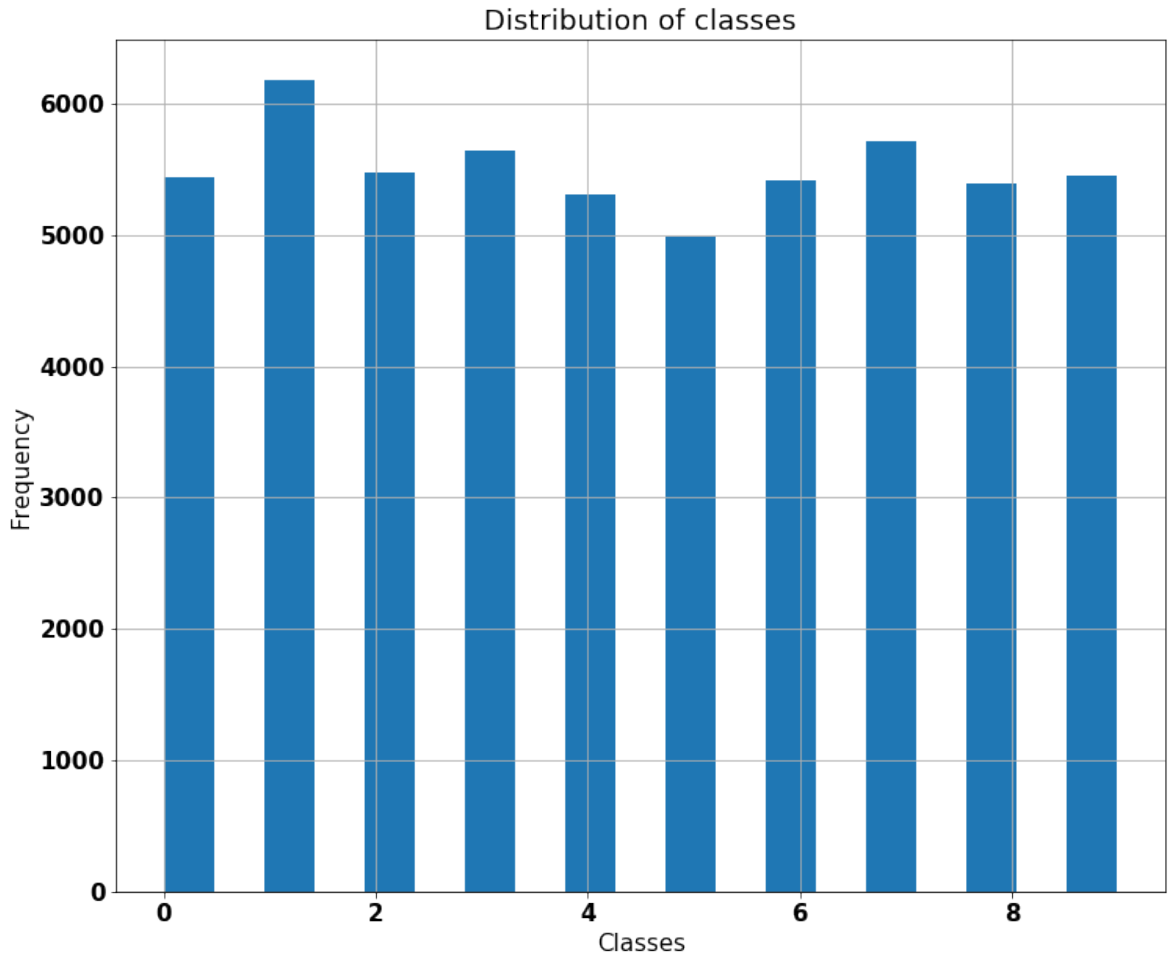
- **for** number of training iterations do:
  - **for** k steps do:
    - sample minibatch of size m of noise
    - sample minibatch of size m of images
    - Update descriminator to minimize *D_loss*
  - **end for**
  - sample minibatch of size m of noise
  - Update generator to minimize *G_loss*
- **end for**

Update rule: Momentum based gradient descent

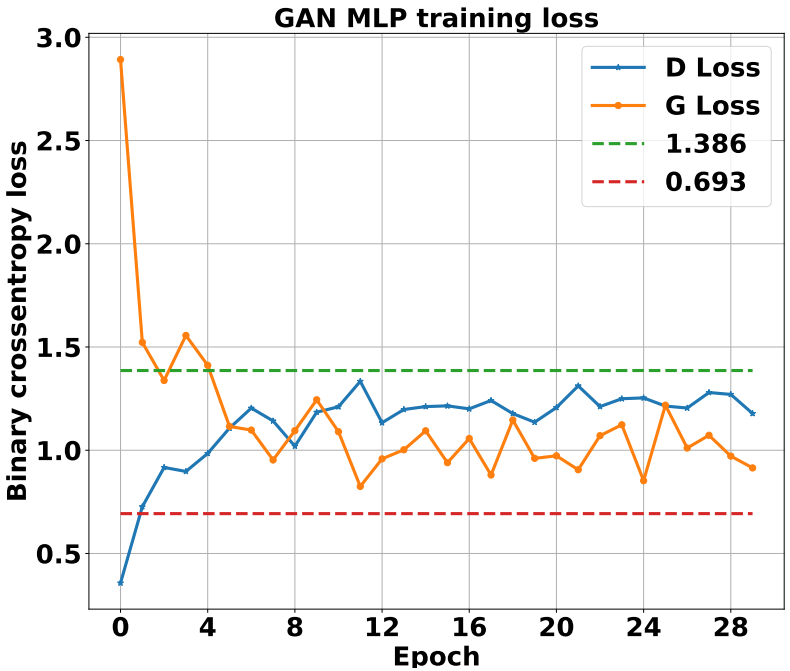
Layer normalization: Batch normalization for generator

Tools & Dataset

- Python
- Tensorflow
- numpy
- Matplotlib
- Tensorboard
- MNIST dataset
- 55K train set
- 10K test set



Results on first attempt



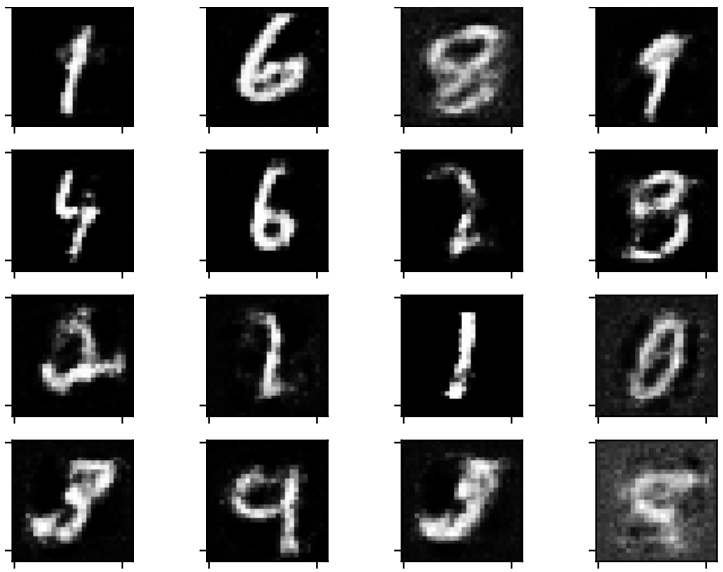
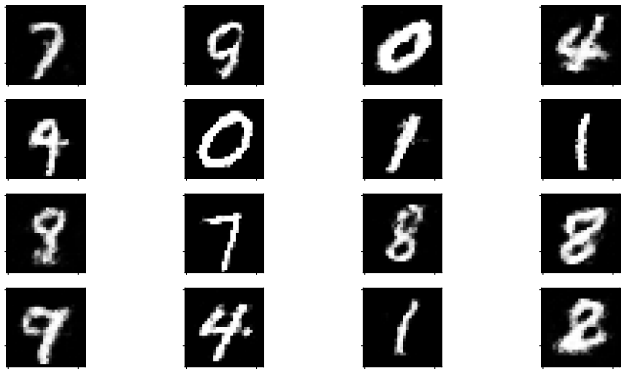
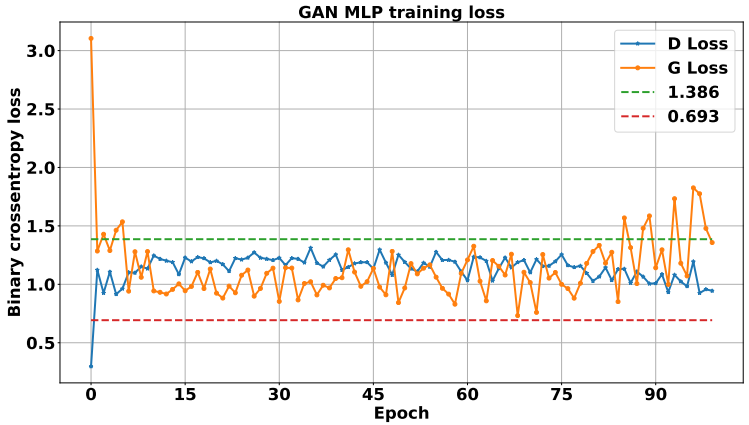


Figure: (L) G and D training loss, (R) Images generated by G at the end of 30th epoch

Extended training

Training for 100 epochs





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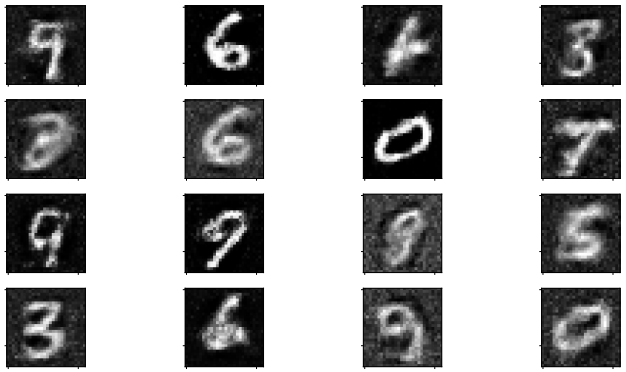
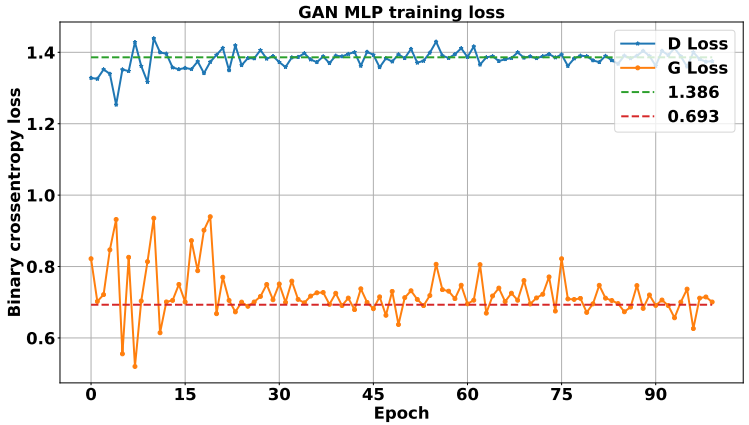
Different training techniques

PowerSign optimizer $\delta w_{new} = \delta w * \alpha^{f_n * sign(\delta w) * sign(momentum(\delta w))}$





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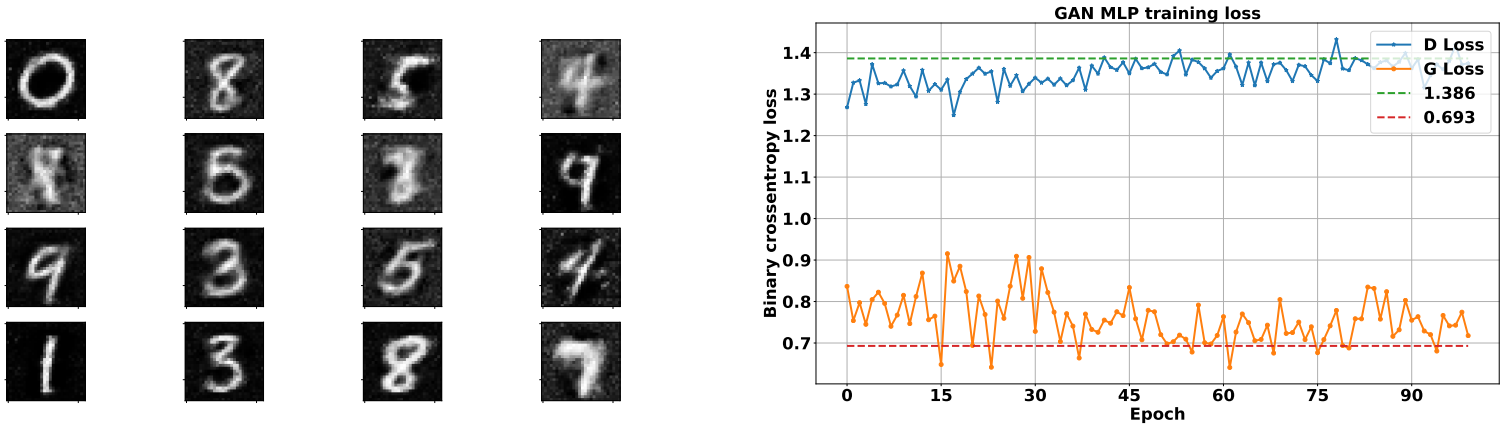
Different Activations

TanH activation in last layer of G and first layer of D



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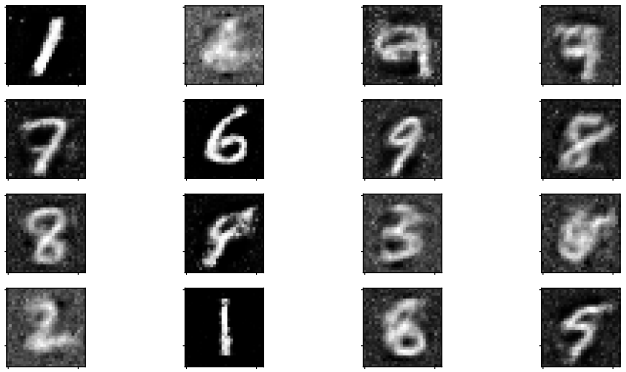
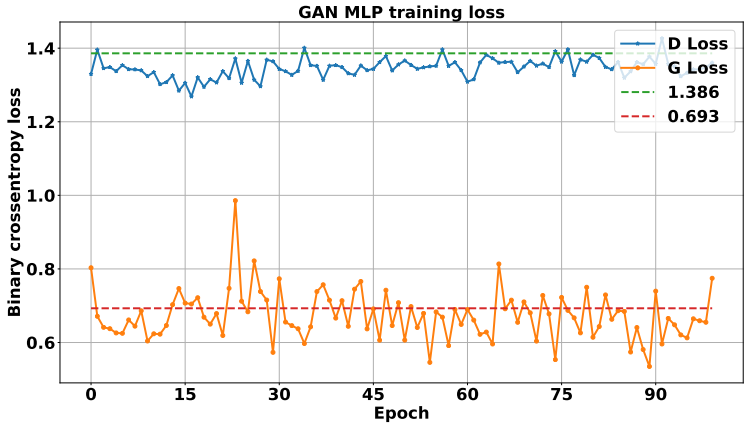
Noisy labels with Momentum optimizer

$1 \rightarrow$ U[0.7,1.2] and $0 \rightarrow$ U[0.0,0.3]





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Noisy labels with PowerSign optimizer

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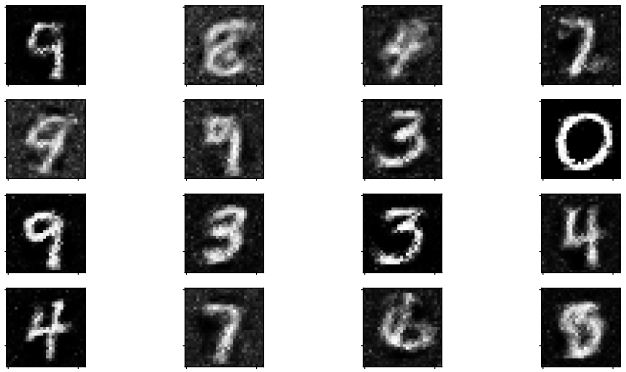

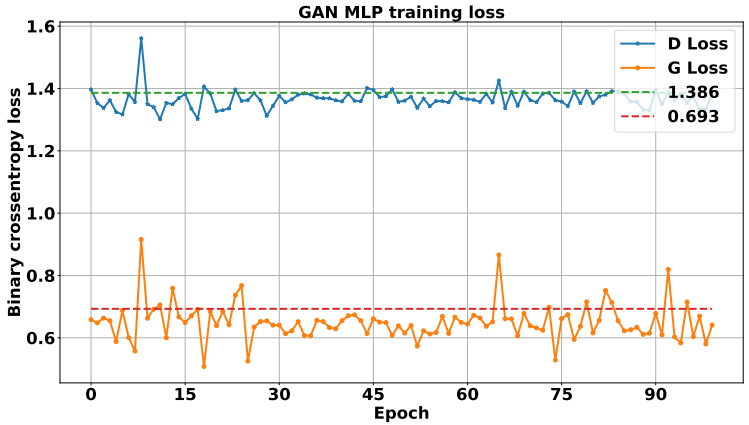

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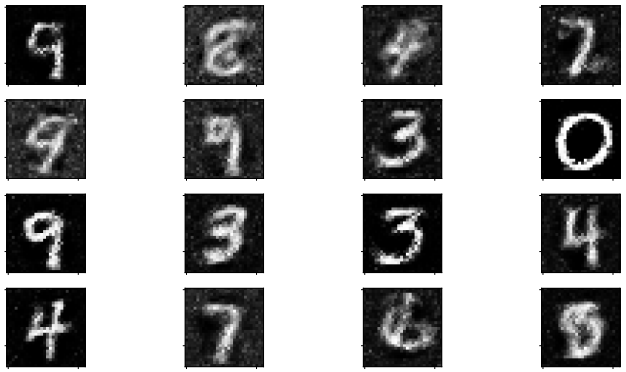

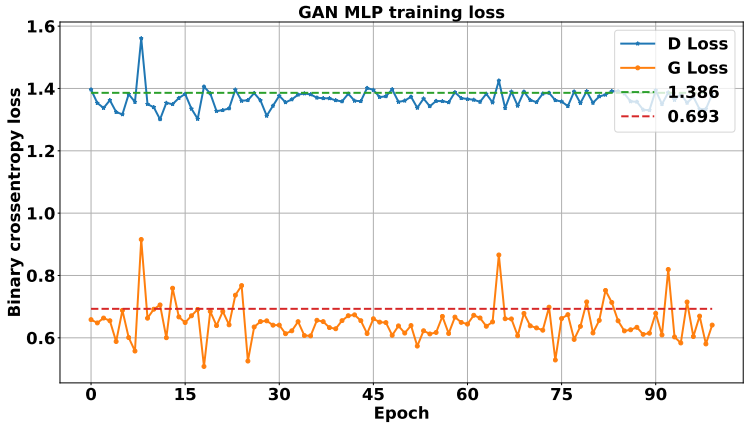

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Comparison with other techniques

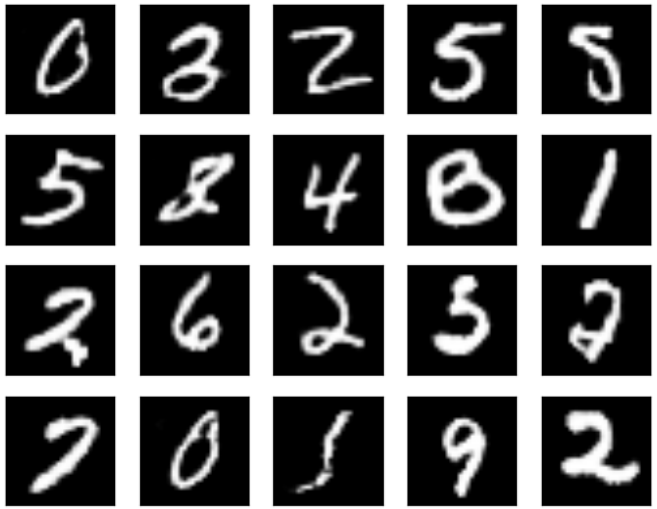

Figure: DCGAN - (https://github.com/acomets/dcgan)

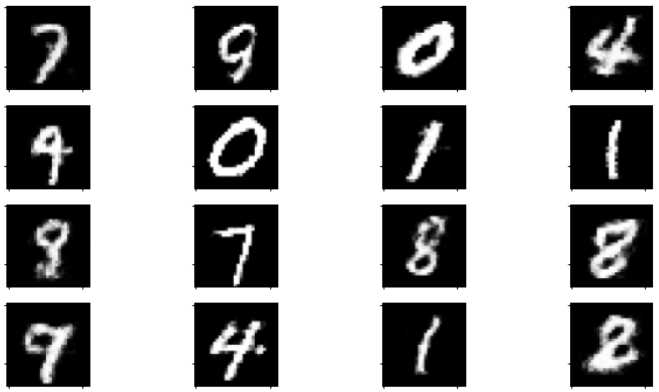

Figure: MLP-GAN