### **EDUCATION**

# Carnegie Mellon University Master

MS Electrical & Computer Engineering (Dec. 2020)

University of Michigan BSE Computer Engineering (April 2018) GPA: 3.7/4.0

## **COURSEWORK**

#### Master's Coursework

Foundations of Computer Systems | Introduction to Machine Learning (Master's) | Embedded System Software Engineering

#### Bachelor's Coursework

Autonomous Robotics Design Experience | Introduction to Machine Learning | Introduction to Operating Systems | Embedded Control Systems | Embedded System Design | Data Structures and Algorithms | Introduction to Computer Organization

## **EXPERIENCE**

## General Motors Software Engineer - AV Mapping & Localization

Warren, MI Mar. 2019 to Aug. 2019

- · Developed mapping algorithms for GM's highly advanced autonomous driving system.
- · Implemented a proof-of-concept SQLite database to store heavy volumes of complex map data in a robust, efficient schema.
- Evaluated and refined map data models to more accurately represent road signs, traffic lights, and road markings.
- Interfaced with other algorithm developers, data scientists, and system architects to achieve extremely capable self-driving vehicles.

#### **General Motors**

Software Integration Engineer

Milford, MI July 2018 to Mar. 2019

- · Integrated and tested software features for GM's Co-pilot and Supercruise active safety autonomous platforms.
- Led troubleshooting vehicle level integration issues including hardware, software, calibration, and instrumentation.
- Validated software integration functionality using a bench and/or vehicle.

#### **Goldman Sachs**

oftware Engineering Intern

New York City, NY June 2017 to Aug. 2017

- Led backend development of Java application to query financial data.
  Created RESTful API to connect Java application backend to fleet of financial data calculators to deliver to customer.
- Revised and expanded team's SQL data model to provide additional functionality to fulfill user requirements.

#### Ford Motor Company

Product Development Intern

Dearborn, MI May 2016 to Aug. 2016

- · Developed an interoperability analysis matrix to provide a roadmap for future electric vehicle testing.
- · Conducted root cause analysis of software issues from vehicle level testing for DC fast charge interoperability.

### **PROJECTS**

#### "Designated Sinkers": Beer Pong Thrower

Mar. 2018

#### Autonomous Robotics Design Project

- · Robotic arm used in conjunction with an Xbox Kinect camera to play a highly successful game of beer pong.
- · Implemented forward & reverse kinematics algorithms, as well as a torque regression model for a successful throw.
- RexArm robotic arm consisting of 5 Dynamixel motors and a 3D printed gripper.

### "Mbot": Robot Mapping and Exploration

Feb. 2018

#### Autonomous Robotics Design Project

- 2-wheeled robot capable of exploring and mapping an unknown environment using SLAM.
- · Implemented occupancy grid mapping algorithm, Monte Carlo Localization, and SLAM.
- Mbot equipped with a 2D lidar, magnetic wheel encoders, and a MEMS 3-axis IMU.

#### "BP Champs": Ping Pong Shooter

Mar. 2017

### Embedded System Design Project

- Ping Pong ball shooter using DC and servo motors controlled via a Nintendo-64 controller using an ARM Cortex M3 based prototyping board.
- Implemented DC motor and servo motor functionality, as well as LCD display interface.
- Ping pong shooter integrated with computer vision to allow simple autonomous control.

## **SKILLS**

PROGRAMMING: C++, Python, C, Java, MATLAB, Bash, SQL, HTML/CSS

APPLICATIONS: Actel Libero, Altera Quartus, INCA, Microsemi SoftConsole, Simulink, Vector CANalyzer, Vehicle Spy

**OPERATING SYSTEMS:** Linux, Ubuntu, macOS, Windows

# **LEADERSHIP**

### University of Michigan HAIL - Alumni Interviewer

2018 to Current

- Interview prospective Michigan Engineering applicants in comfortable conversational settings.
- Share personal Michigan experience and establish personal connections with applicants.

#### GM Vehicle Engineering TRACK 101 - Advisory Board Lead

2018 to 2019

- · Coordinated seminars for TRACK engineers to develop their technical knowledge ranging from vehicle systems to workplace skills.
- Facilitated networking through interaction with leadership and other TRACK engineers.