

$$a) \vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{s} \times \hat{r}}{r^2}$$



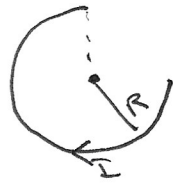
$$\vec{B}_1 = \vec{B}_2 = 0$$

$$d\vec{s} \times \hat{r} = ds \cdot r \cdot \sin(180) = 0$$



$$b) \vec{B} = \frac{\mu_0 I}{4\pi} \int \frac{d\vec{s} \times \hat{r}}{r^2}$$

$$= \frac{\mu_0 I}{4\pi r^2} \int r d\theta \cdot 1$$



$$d\vec{s} = r \cdot d\theta$$

$$= \frac{\mu_0 I}{4\pi r} \int_0^{3\pi/2} d\theta = \frac{\mu_0 I}{4\pi r} \left[ \frac{3\pi}{2} - 0 \right] = \frac{3\mu_0 I}{8r} \quad \text{T}$$

Into the page

$$c) \vec{B}_{\text{tot}} = B_{\text{straight}} + B_{\text{straight}} + B_{\text{curve}} = 0 + 0 + B_{\text{curve}}$$

$$= \frac{3\mu_0 I}{8r} \quad \text{T} \quad \text{into page}$$

$$d) F = qvB \sin \theta$$

$$= qvB \sin(90)$$

$$= qvB$$

Upward

