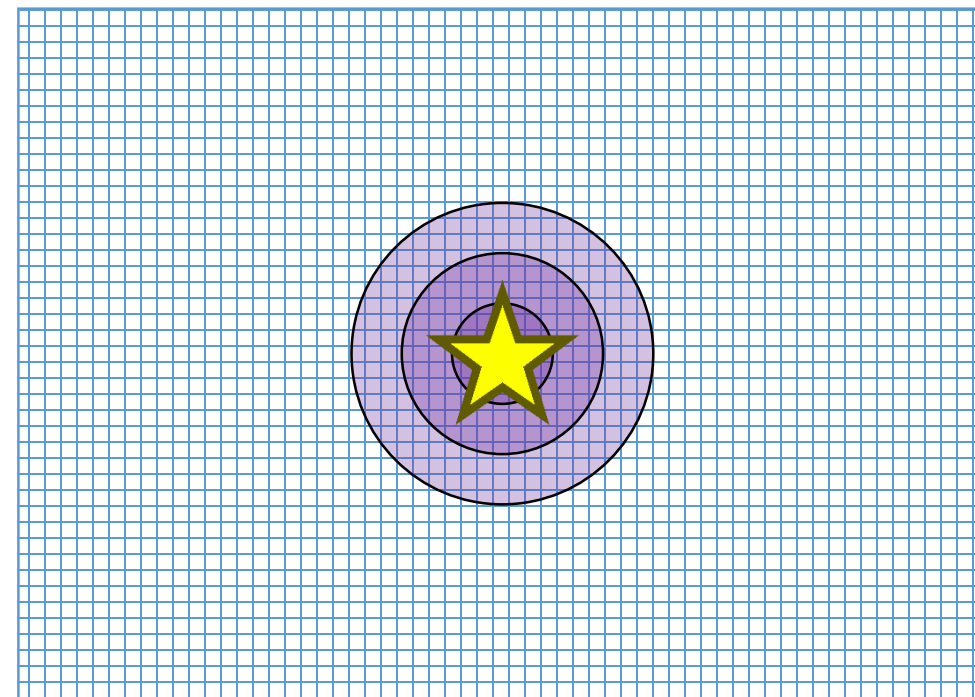
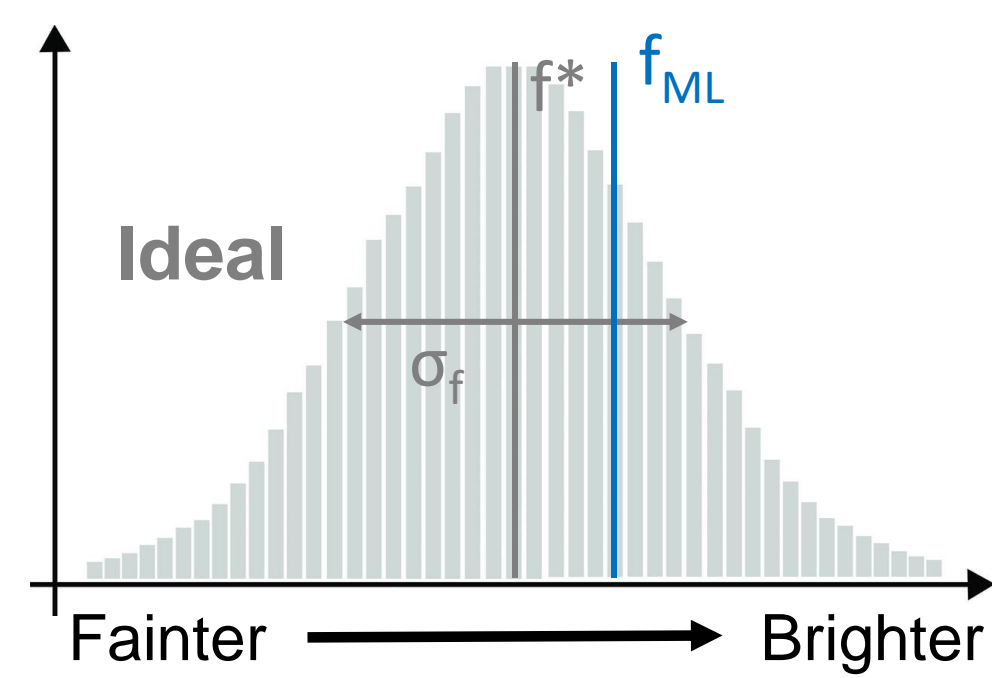


## Position **Known**

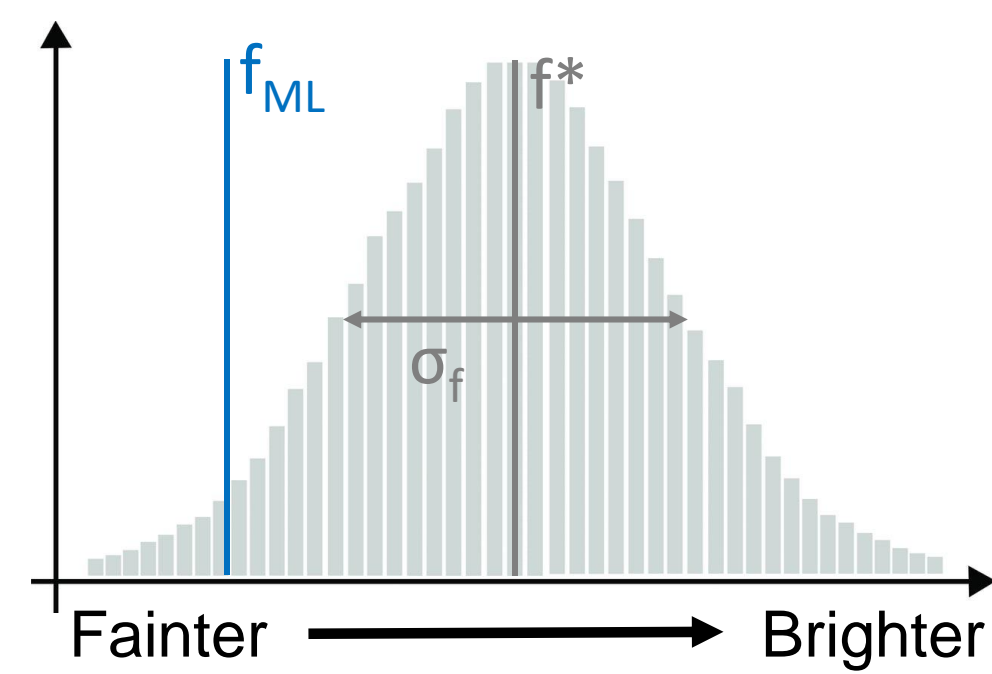
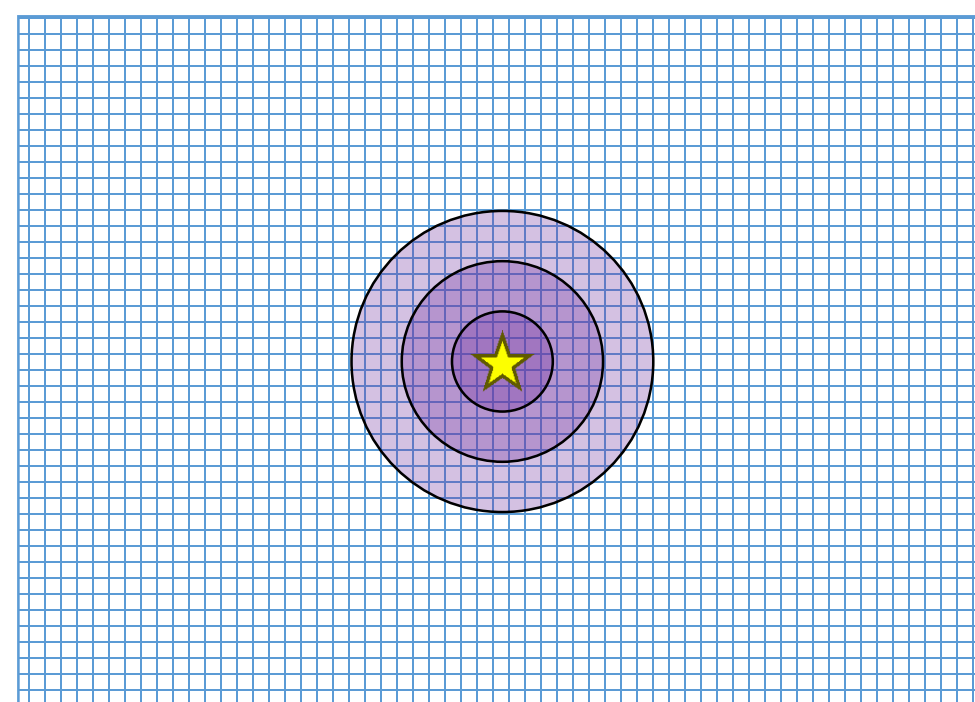
$n \times m$  footprint



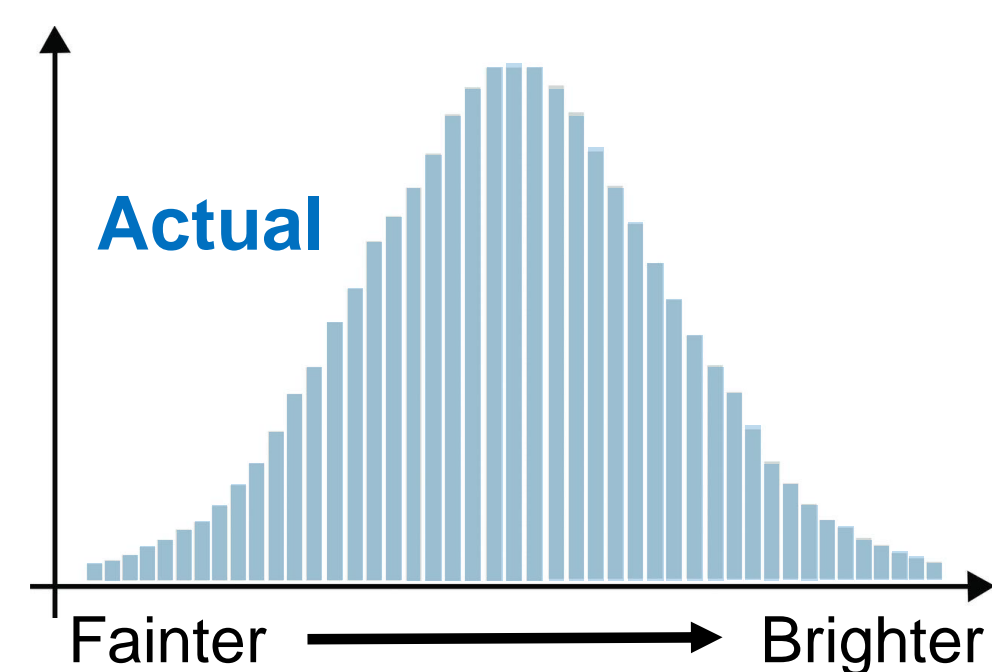
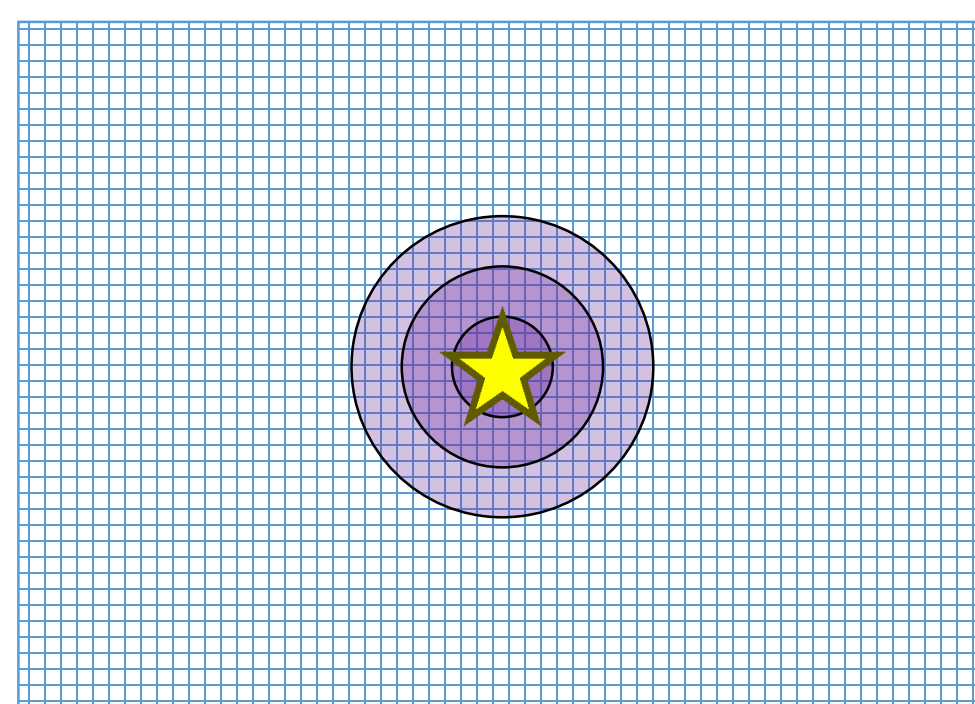
Flux Distribution



Random noise sometimes leads to high fluctuations.



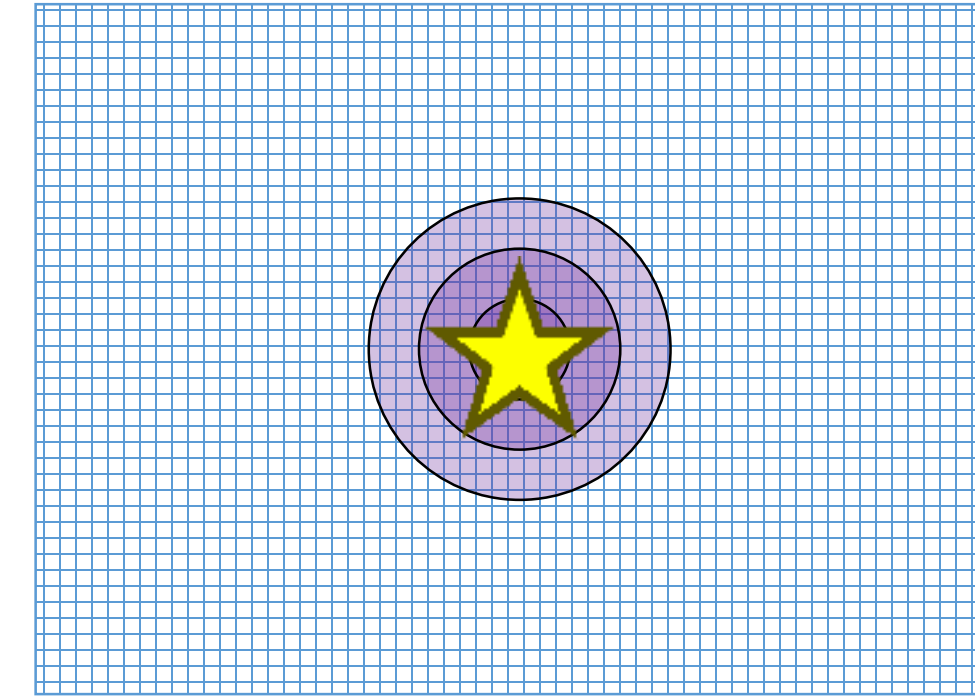
It also leads to low fluctuations with equal probability.



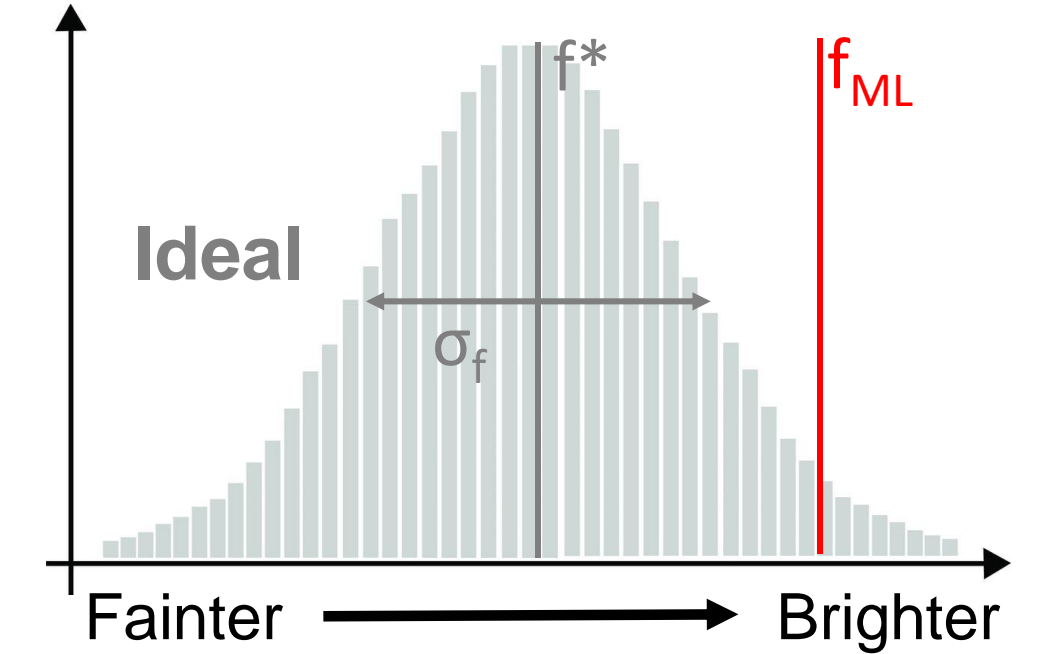
Because fluctuations are **symmetric**,  
the maximum-likelihood estimate is **unbiased**.

## Position **Unknown**

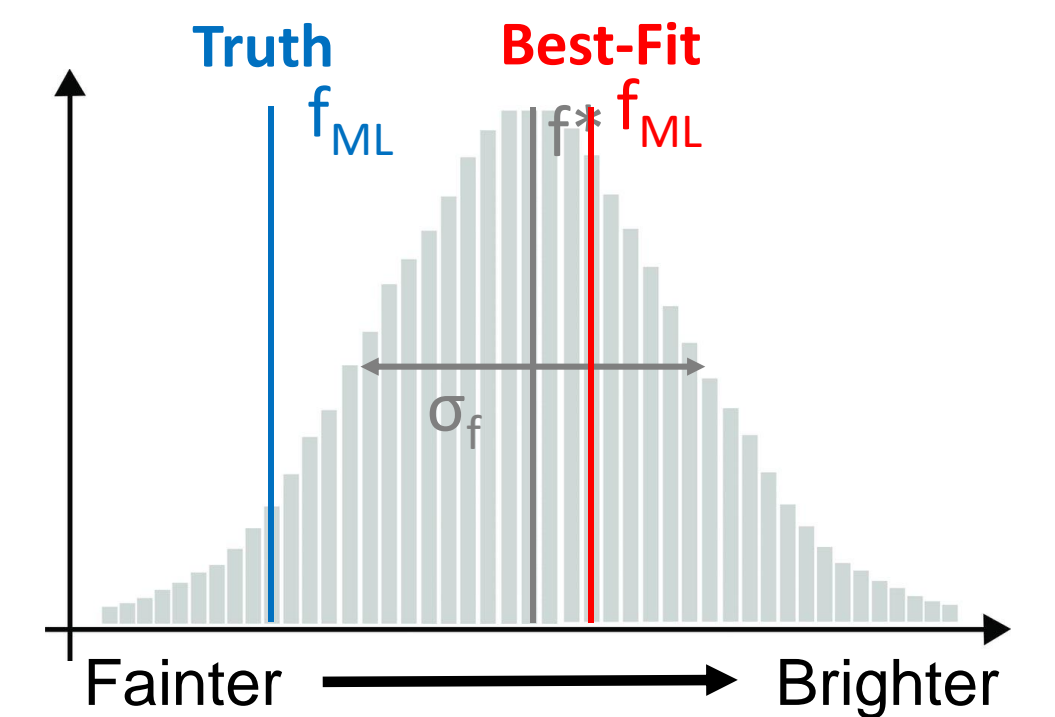
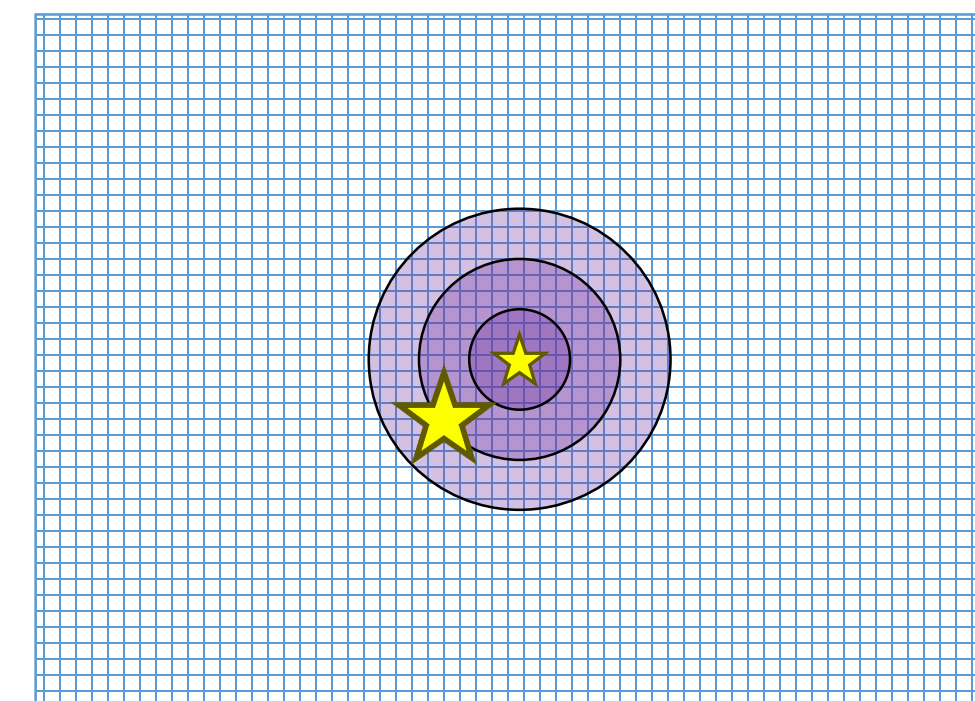
$n \times m$  footprint



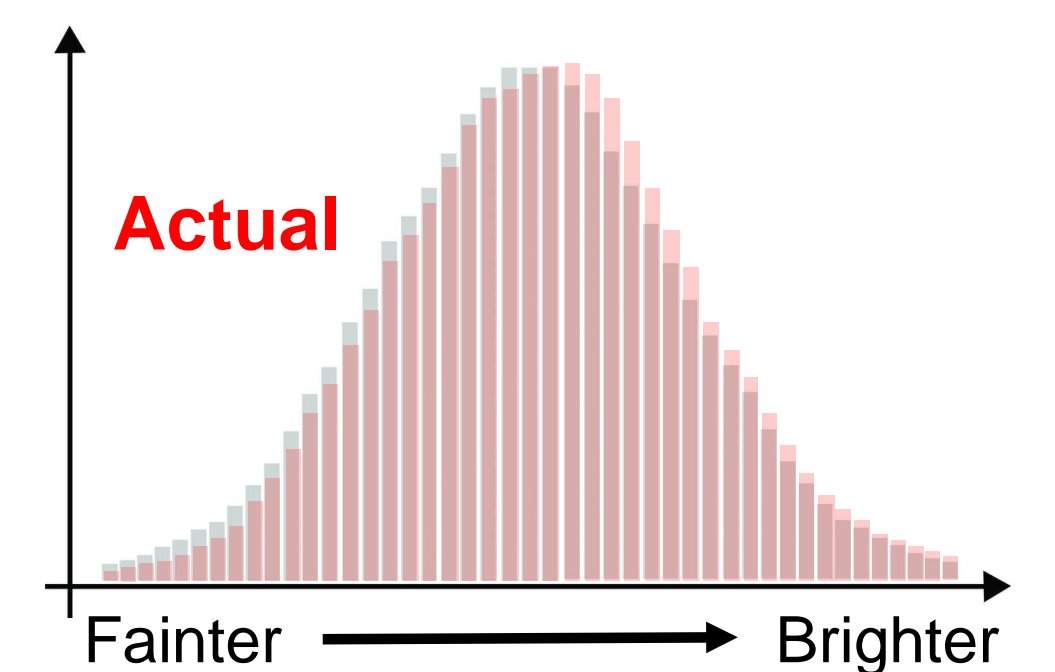
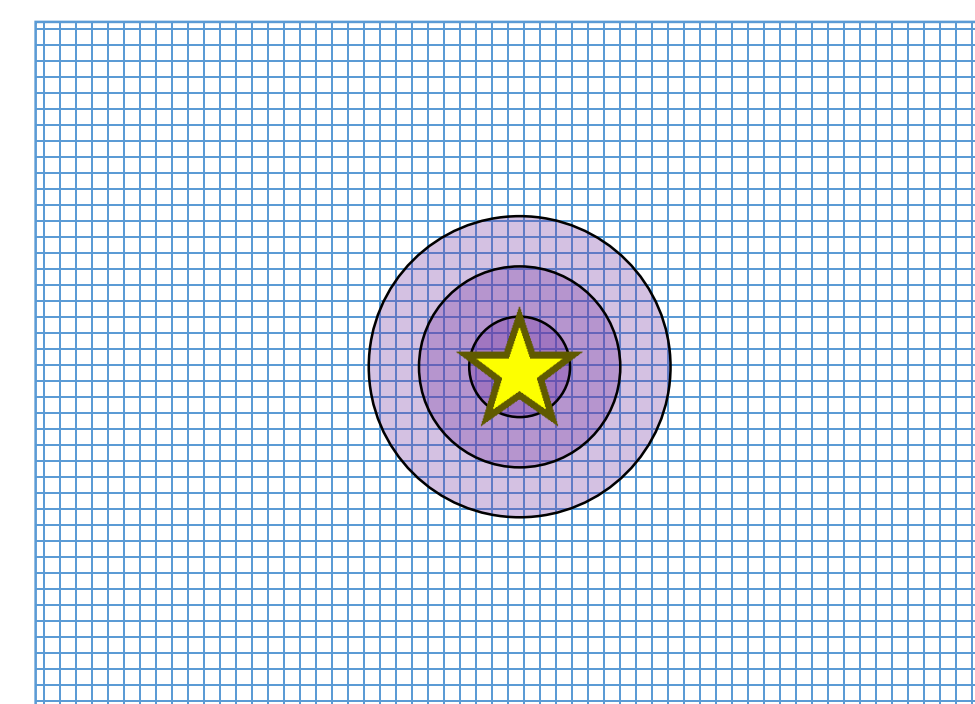
Flux Distribution



The position is centered at the true position when  
random noise generates high fluctuations...



But when there are low fluctuations at the true position, a  
better fit can be achieved at a different position.



Because fluctuations are **asymmetric**,  
the maximum-likelihood estimate is **biased**.