ARM Assembly

```
01:
       mystery2
02: CBZ
               RO, loc_C672 #compares RO to O and if equal to O branch to loc_C672 on line 8
               RO, [RO, #0x63] #Load a byte into RO from RO+0x63 (99)
03: LDRB.W
04: SUBS
               RO, #0
                              # R0 = R0-0
05: IT NE
06: MOVNE
               RO, #1
                              # R0 = 1 if R0!=0
07: BX
               LR
                              # return
08: loc_C672
09: MOVS
               RO, #1
                              \#R0 = 1
10: BX
               LR
                              #return
       ;end of function mystery2
11:
```

Mode

This codes mode is thumb mode since it has instructions ranging from 16 bits to 32 bits.

Types

RO at first is a pointer. After that, RO is used as a Boolean(0 or 1) for the return value.

Function Prototype

```
int mystery2(char * arg1)
```

C Code

```
int mystery2(void * arg1)
{
          if(arg1=='\0')
          {
                return 1;
          }
          printf("%i \n",arg1);
          arg1 = (char *)(arg1+99);
          printf("%s \n",arg1);
          if(*((char *)arg1) != '\0') { return 1;}
          return 0;
}
```

Explanation

This function is given a pointer that points to a struct that has a one byte value at 0x63. If the pointer is NULL, then the value returns true. If it is not NULL, we go to the 100th byte of the struct. If the 100th byte of the struct is 0, the function returns 0. If the last value is not 0, we return 1. The struct could be anything, so I generalized my code so it works with a void pointer. Although, I think this code was intended to check for a null terminating byte at the end of a string. In this case, the string was 100 bytes with the last byte being the null byte.