ARM Assembly

```
01:
       mystery2
               RO, loc_C672 #compares RO to O and if equal to O branch to loc_C672 on line 8
02: CBZ
               RO, [RO, #0x63] #Load a byte into RO from RO+0x63 (99)
03: LDRB.W
                              # R0 = R0-0
04: SUBS
               RO, #0
05: IT NE
06: MOVNE
               RO, #1
                              # R0 = 1 if R0!=0
07: BX
               LR
                              # return
08: loc_C672
09: MOVS
               RO, #1
                              \#R0 = 1
10: BX
               LR
                              #return
       ;end of function mystery2
11:
```

Mode

This codes mode is thumb mode since it has instructions ranging from 16 bits to 32 bits.

Types

RO at first is a pointer. After that, RO is used as a Boolean(0 or 1) for the return value.

Function Prototype

```
int mystery2(char * arg1)
```

C Code

```
int mystery2(char * arg1)
{
         if(arg1==NULL)
         {
             return 1;
         }
         arg1 = arg1+99;
         if(arg1 != 0) { return 1;}
         return 0;
}
```

Explanation

This function is given a pointer that points to a struct with a bunch of one byte values. Since the values are one byte, I'm assuming that this is an array of characters. If the pointer is NULL, then the value returns true. If it is not NULL, we go to the 100th element of the array. If the 100th element of the array is 0, the function returns 0. If the last value is not 0, we return 1.