

# PERIODIC SOLUTIONS OF SECOND-ORDER EQUATIONS

JOSHUA GEORGE

ABSTRACT.

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## 1. INTRODUCTION

**1.1. Dirac Delta Function [1].** The dirac delta function  $\delta$  is a generalized function over the real numbers where it is zero everywhere except at 0. We can construct it using a limit of the *delta*-sequence given below,

$$\delta_n(t) = \begin{cases} \frac{n}{2} & -\frac{1}{n} < t < \frac{1}{n} \\ 0 & \text{otherwise} \end{cases}$$

From the above sequence we can see that  $\delta_n(t)$  converges to a spike (as  $n \rightarrow \infty$ ) at  $t = 0$  with infinite height and zero width with the property

$$\int_{-\infty}^{\infty} \delta_n(t) dt = 1, \forall n \geq 1$$

Now assume a continuous function  $f(t)$ . We can write

$$\min_{t \in [-\frac{1}{n}, \frac{1}{n}]} f(t) \leq \int_{-\infty}^{\infty} f(t) \delta_n(t) dt \leq \max_{t \in [-\frac{1}{n}, \frac{1}{n}]} f(t)$$

Since,

$$\lim_{n \rightarrow \infty} \min_{t \in [-\frac{1}{n}, \frac{1}{n}]} f(t) = \lim_{n \rightarrow \infty} \max_{t \in [-\frac{1}{n}, \frac{1}{n}]} f(t) = f(0),$$

then by the squeeze theorem, we can write

$$\lim_{n \rightarrow \infty} \int_{-\infty}^{\infty} f(t) \delta_n(t) dt = f(0).$$

**Definition 1.** The dirac delta function can be defined by the following equality:

$$\int_{-a}^a f(t) \delta(t) dt = f(0)$$

for any  $a > 0$  and any continuous function  $f$ . This gives us the following relation,

$$\int_{s-a}^{s+a} f(t) \delta(t-s) d\tau = f(s)$$

(This is also called the Sifting property.)

## 1.2. Spectral Theory.

**Definition 2.** (pre-Hilbert) Let  $X$  be a complex vector space. A Hermitian inner product on  $X$  is a function  $\langle \cdot, \cdot \rangle : X \times X \rightarrow \mathbb{C}$ , which is :

- (1) (positive non-degenerate)  $(\forall x \in X) \langle x, x \rangle \geq 0, \langle x, x \rangle = 0$  iff  $x = 0$ .
- (2) (sesquilinear)  $(\forall \alpha, \beta \in \mathbb{C})(\forall x, y, z \in X), \langle \alpha x + \beta y, z \rangle = \alpha \langle x, z \rangle + \beta \langle y, z \rangle$
- (3) (conjugate-symmetric)  $(\forall x, y \in X) \langle y, x \rangle = \overline{\langle x, y \rangle}$

A space is complete if all cauchy sequences converge to a limit . A *Hilbert Space* is a complete inner product space. In fact every Hilbert space is a *Banach Space* but the reverse is not true.

**Definition 3.** Banach space: Let  $V$  be a vector space. A norm is a mapping  $\| \cdot \| : V \rightarrow [0, \infty)$  that satisfies:

- (1)  $\|x + y\| \leq \|x\| + \|y\|$ .
- (2)  $\|ax\| = |a| \|x\|$  for all  $a \in \mathbb{R}$ .
- (3)  $\|x\| = 0$  implies that  $x = 0$ .

A complete normed space is called a Banach space.

We can now define an inner product in function space. An inner product in the vector space of continuous functions denoted by  $C^0([a, b], \mathbb{C})$  is defined as follows, given two arbitrary functions  $u(x), v(x), x \in [a, b]$ , introduce the inner product,

$$\langle u, v \rangle = \int_a^b uv^* dx, \quad *: \text{complex conjugation.}$$

**Theorem 1. (Fredholm Alternative theorem)**

For a linear system  $Ax = b$ ,  $A^*$  which is the adjoint satisfying the property  $\langle Ax, y \rangle = \langle x, A^*y \rangle$  for all  $x, y \in \mathbb{C}^n$  exactly one is true:

- i) Solution of  $Ax = b$ , if it exists, is unique if and only if  $x = 0$  is the only solution of  $Ax = 0$ .
- ii) The equation  $Ax = b$  has a solution if and only if  $\langle b, v \rangle = 0$  for all  $v$  satisfying  $A^*v = 0$ .

*Proof:* i) Assume that  $Ax = 0$  for  $x \neq 0$  and  $Ax_0 = b$ . Then  $A(x_0 + \alpha x) = b$  for all  $\alpha$ . Therefore, the solution is not unique. Conversely, if there are two different solutions,  $x_1$  and  $x_2$ , satisfying  $Ax_1 = b$  and  $Ax_2 = b$ , then one has a nonzero solution  $x = x_1 - x_2$  such that  $Ax = A(x_1 - x_2) = 0$ .

ii) Let  $A^*v = 0$  and  $Ax_0 = b$ . Then we have

$$\langle b, v \rangle = \langle Ax_0, v \rangle = \langle x_0, A^*v \rangle = 0$$

For the second part we assume that  $\langle b, v \rangle = 0$  for all  $v$  such that  $A^*v = 0$ . Write  $b$  as the sum of a part that is in the range of  $A$  and a part that in the space orthogonal to the range of  $A$ ,  $b = b_r + b_o$ . Then,  $0 = \langle b_o, Ax \rangle = \langle A^*b, x \rangle$  for all  $x$ . Since  $\langle b, v \rangle = 0$  for all  $v$  in the nullspace of  $A^*$ , then  $\langle b, b_o \rangle = 0$ . Therefore,  $\langle b, v \rangle = 0$  implies that

$$0 = \langle b, b_o \rangle = \langle b_r + b_o, b_o \rangle = \langle b_o, b_o \rangle$$

This means that  $b_o = 0$ , giving  $b = b_r$  is in the range of  $A$ . So,  $Ax = b$  has a solution.  $\square$

The same can be said about linear operators, let  $L$  be a bounded linear operator on a Hilbert space with adjoint  $L^\dagger$ . Then exactly one of the following is true:

- i) The inhomogeneous problem

$$Lu = f$$

has a unique solution  $u$ .

- ii) The homogeneous adjoint problem

$$L^\dagger u = 0$$

has a non-trivial solution.

Fredholm Alternative theorem is established by taking the inner product of (1.1) with the adjoint null space function  $v(x)$  and we obtain,

$$\begin{aligned} \langle v, Lu \rangle &= \langle v, f \rangle \\ \langle L^\dagger v, u \rangle &= \langle v, f \rangle \end{aligned}$$

**1.3. Green's Functions.** The focus of this paper is to construct the appropriate Green's function for the following BVP (A):

$$\begin{cases} x'' + \lambda^2 x = \delta(t - s) \\ x(0) = x(\omega) \\ x'(0) = x'(\omega) \end{cases}$$

We first solve  $Ly = f$ , a differential equation with homogenous boundary conditions. The Sifting property mentioned earlier can be written as,

$$\langle f(t), \delta(t - s) \rangle = \int_0^l f(t) \delta(t - s) dt = f(s), \quad t \in [0, l]$$

Now we can consider the following problem,

$$\begin{aligned} Lu &= f \\ L^\dagger G(t, s) &= \delta(t - s) \end{aligned}$$

where  $x \in [0, l]$  and  $L^\dagger$  is the adjoint operator with its boundary conditions.  $G(t, s)$  is the Greens function. Taking the inner product of  $Lu = f$  with respect to  $G(t, s)$  we get,

$$\begin{aligned} \langle Lu, G \rangle &= \langle u, L^\dagger G \rangle = \langle f, G \rangle \\ \langle u, \delta(t - s) \rangle &= \langle f, G \rangle \\ u(t) &= \langle f, G \rangle. \end{aligned}$$

This gives us

$$u(t) = \int_0^l f(t) G(t, s) dt$$

and thus the inverse operator

$$L^{-1}[f] = \int_0^l f(t)G(t, s)ds$$

can be computed.

## 2. SOLUTION OF $x'' + \lambda^2 x = \delta(t - s)$

From the above section we can define the Greens function  $G(t, s)$  of  $\mathcal{L}$  to be the unique soltion to the problem  $\mathcal{L}G = \delta(t - s)$ , where  $\mathcal{L}$  is the general linear second order differential operator. We now construct the green function for A: From the definition of the dirac delta function, at all points  $t \neq s$ ,  $x'' + \lambda^2 x = 0$ . Solving this we get homogenous solution is  $k \cos(\lambda t) + c \sin(\lambda t)$ . Therefore our Greens function is,

$$(1) \quad G(t, s) = \begin{cases} c_1 \cos(\lambda t) + c_2 \sin(\lambda t) & 0 \leq t < s \leq \omega \\ c_3 \cos(\lambda t) + c_4 \sin(\lambda t) & 0 \leq s < t \leq \omega \end{cases}$$

To solve for  $G(t, s)$  we have to solve for  $c_1, c_2, c_3, c_4$ , we can do this by solving the following system of equations,

The periodic boundary conditions,

$$(2) \quad x(0) = x(\omega), \quad k \cos(0) + c \sin(0) = k \cos(\lambda \omega) + c \sin(\lambda \omega)$$

$$(3) \quad x'(0) = x'(\omega), \quad -k\lambda \sin(0) + c\lambda \cos(0) = -k\lambda \sin(\lambda \omega) + c\lambda \cos(\lambda \omega)$$

At  $t = s$  ( as  $G(t, s)$  is continuous ) ,

$$\lim_{t \rightarrow s^+} G(t, s) - \lim_{t \rightarrow s^-} G(t, s) = 0$$

$$(4) \quad c_3 \cos(\lambda s) + c_4 \sin(\lambda s) - c_1 \cos(\lambda s) - c_2 \sin(\lambda s) = 0$$

and the "derivative" jump of  $G(t, s)$ ,

$$\lim_{t \rightarrow s^+} G'(t, s) - \lim_{t \rightarrow s^-} G'(t, s) = 1$$

$$(5) \quad -c_3 \lambda \sin(\lambda s) + c_4 \lambda \cos(\lambda s) - (-c_1 \lambda \sin(\lambda s) + c_2 \lambda \cos(\lambda s)) = 1$$

**Remark 1.** Why  $\lim_{t \rightarrow s^+} G'(t, s) - \lim_{t \rightarrow s^-} G'(t, s) = 1$ ?

Consider  $\mathcal{L}G = \delta(t - s)$ , this is zero when  $t < s$  and  $t > s$  and  $\delta$  is infinity when  $t = s$ . Which tells us the first derivative must be discontinuous and when we take the second derivative it diverges. Now integrate the given ode from  $s - \epsilon$  to  $s + \epsilon$  and let  $\epsilon \rightarrow 0$ . We get,

$$\int_{s-\epsilon}^{s+\epsilon} \frac{\partial G}{\partial t^2} dt + \int_{s-\epsilon}^{s+\epsilon} \lambda^2 G = \int_{s-\epsilon}^{s+\epsilon} \delta(t - s) dt = 1$$

The second term on the l.h.s vanishes as  $\epsilon \rightarrow 0$  as the integrands are finite and so we get,

$$\left. \frac{\partial G}{\partial t} \right|_{t=s^+} - \left. \frac{\partial G}{\partial t} \right|_{t=s^-} = 1$$

Solving (2), (3), (4) and (5) we get our Greens Function,

$$(6) \quad G(t, s) = \begin{cases} \frac{\sin(\lambda(t - s + \omega)) + \sin(\lambda(s - t))}{2\lambda(1 - \cos(\lambda\omega))} & 0 \leq t < s \leq \omega \\ \frac{\sin(\lambda(s - t + \omega)) + \sin(\lambda(t - s))}{2\lambda(1 - \cos(\lambda\omega))} & 0 \leq s < t \leq \omega \end{cases}$$

$$(7) \quad G(t, s) = \begin{cases} G_1(t, s) & 0 \leq t < s \leq \omega \\ G_2(t, s) & 0 \leq s < t \leq \omega \end{cases}$$

We can verify this as,

$$\lim_{t \rightarrow s^+} G(t, s) - \lim_{t \rightarrow s^-} G(t, s) = 0$$

$$\lim_{t \rightarrow s^+} G'(t, s) - \lim_{t \rightarrow s^-} G'(t, s) = 1$$

$$G(t, s) = G(s, t)$$

3. SOLUTION OF  $x'' = f(t, x(t), x'(t))$ 

Consider the following B.V.P (B),

$$\begin{cases} x'' = f(t, x(t), x'(t)) \\ x(0) = x(\omega) \\ x'(0) = x'(\omega) \end{cases}$$

Notice the above ODE can be written as,

$$(8) \quad x'' + \lambda^2 x(t) = \lambda^2 x(t) + f(t, x(t), x'(t))$$

Note: The solution to the differential equation  $x'' + \lambda^2 x = \delta(t-s)$  is the Greens function we obtained above. I claim the solution to the above differential equation (20) is,

$$(9) \quad x(t) = \int_0^\omega G(t, s) \{f(s, x(s), x'(s)) + \lambda^2 x(s)\} ds$$

Why so? *Existence discussed later*

*Proof:* Need to show  $x(t)$  satisfies the BVP (B),

$$\begin{aligned} x(t) &= \int_0^\omega G(t, s) \{f(s, x(s), x'(s)) + \lambda^2 x(s)\} ds \\ x'(t) &= \frac{d}{dt} \int_0^\omega G(t, s) h(s) ds, \quad h(s) = \{f(s, x(s), x'(s)) + \lambda^2 x(s)\} \\ &= \frac{d}{dt} \int_0^{t^-} G_2(t, s) h(s) ds + \frac{d}{dt} \int_{t^+}^\omega G_1(t, s) h(s) ds \\ &= G_2(t, t^-) h(t^-) + \int_0^{t^-} \frac{\partial G_2(t, s)}{\partial t} h(s) ds - G_1(t, t^+) h(t^+) + \frac{d}{dt} \int_{t^+}^\omega \frac{\partial G_1(t, s)}{\partial t} h(s) ds \\ &= \int_0^{t^-} \frac{\partial G_2(t, s)}{\partial t} h(s) ds + \int_{t^+}^\omega \frac{\partial G_1(t, s)}{\partial t} h(s) ds \\ x''(t) &= \frac{\partial G_2(t, t^-)}{\partial t} h(t^-) + \int_0^{t^-} \frac{\partial^2 G_2(t, s)}{\partial t^2} h(s) ds - \frac{\partial G_1(t, t^+)}{\partial t} h(t^+) + \int_{t^+}^\omega \frac{\partial^2 G_1(t, s)}{\partial t^2} h(s) ds \\ &= h(t) + \int_0^{t^-} \frac{\partial^2 G_2(t, s)}{\partial t^2} h(s) ds + \int_{t^+}^\omega \frac{\partial^2 G_1(t, s)}{\partial t^2} h(s) ds \\ &= h(t) + \lambda^2 x(t) - \lambda^2 x(t) + \int_0^{t^-} \frac{\partial^2 G_2(t, s)}{\partial t^2} h(s) ds + \int_{t^+}^\omega \frac{\partial^2 G_1(t, s)}{\partial t^2} h(s) ds \\ &= h(t) + \lambda^2 x(t) + \int_0^{t^-} \frac{\partial^2 G_2(t, s)}{\partial t^2} h(s) ds + \int_{t^+}^\omega \frac{\partial^2 G_1(t, s)}{\partial t^2} h(s) ds - \lambda^2 x(t) \\ &= h(t) + \lambda^2 \left( \int_0^{t^-} G_2(t, s) h(s) ds + \int_{t^+}^\omega G_1(t, s) h(s) ds \right) + \\ &\quad \int_0^{t^-} \frac{\partial^2 G_2(t, s)}{\partial t^2} h(s) ds + \int_{t^+}^\omega \frac{\partial^2 G_1(t, s)}{\partial t^2} h(s) ds - \lambda^2 x(t) \\ &= h(t) + \int_0^{t^-} \left( \frac{\partial^2 G_2(t, s)}{\partial t^2} + \lambda^2 G_2(t, s) \right) h(s) ds + \\ &\quad \int_{t^+}^\omega \left( \frac{\partial^2 G_1(t, s)}{\partial t^2} + G_1(t, s) \right) h(s) ds - \lambda^2 x(t) \\ &= h(t) + \underbrace{\int_0^{t^-} \left( \frac{\partial^2 G_2(t, s)}{\partial t^2} + \lambda^2 G_2(t, s) \right) h(s) ds}_0 + \\ &\quad \underbrace{\int_{t^+}^\omega \left( \frac{\partial^2 G_1(t, s)}{\partial t^2} + G_1(t, s) \right) h(s) ds}_0 - \lambda^2 x(t) \\ x'' &= h(t) - \lambda^2 x(t) \end{aligned}$$

Rearranging we get,

$$x'' + \lambda^2 x(t) = \lambda^2 x(t) + f(t, x(t), x'(t)) \implies x'' = f(t, x(t), x'(t))$$

Now we have to show that the boundary conditions are satisfied, i.e

$$x(0) = x(\omega)$$

$$x'(0) = x'(\omega)$$

Consider  $x(0) = x(\omega)$ ,

$$(10) \quad \begin{aligned} x(t) &= \int_0^{t^-} G_2(t, s)h(s)ds + \int_{t^+}^{\omega} G_1(t, s)h(s)ds \\ x(0) &= \int_0^{\omega} G_1(0, s)h(s)ds \\ x(\omega) &= \int_0^{\omega} G_2(\omega, s)h(s)ds \end{aligned}$$

Well  $x(0) = x(\omega)$  as we know  $G(t, s)$  satisfies the BVP (A). Another way to verify is by just evaluating  $G_1(0, s)$  and  $G_2(\omega, s)$ .

Consider  $x'(0) = x'(\omega)$ ,

$$(11) \quad \begin{aligned} x'(t) &= \int_0^{t^-} \frac{\partial G_2(t, s)}{\partial t} h(s)ds + \int_{t^+}^{\omega} \frac{\partial G_1(t, s)}{\partial t} h(s)ds \\ x'(0) &= \int_0^{\omega} \frac{\partial G_1(0, s)}{\partial t} h(s)ds \\ x'(\omega) &= \int_0^{\omega} \frac{\partial G_2(\omega, s)}{\partial t} h(s)ds \end{aligned}$$

By a similar argument we get  $x'(0) = x'(\omega)$ .

Therefore we showed the integral satisfies the ODE.  $\square$

#### 4. DEGREE THEORY

Let  $A$  be a mapping:  $A : \bar{U} \subset \mathbb{R}^N \rightarrow \mathbb{R}^N$ , where  $U$  is an open bounded set. We defined the degree of the mapping at  $p$ ,

$$\deg(A, U, p) = \sum_{x_i \in A^{-1}(p)} \text{sign}(\det J_A(x_i))$$

as long as  $A^{-1}(p)$  are regular points. Let  $h : \mathbb{R}^N \rightarrow \mathbb{R}$  is a smooth function such that

$$\int_{\mathbb{R}^N} h(x)dx = 1,$$

and  $h(x) = 0$  outside of a ball  $B_\varepsilon(0)$  for some small  $\varepsilon > 0$ . Here  $x = (x_1, \dots, x_N)$  and  $dx = dx_1 \cdots dx_N$ .

$$\deg(A, U, 0) = \int_{\mathbb{R}^N} h(A(x)) \det J_A(x)dx$$

for  $\mathbf{x} = (x_1, \dots, x_n)$ . We show the integral is independent of  $h$ .

*Proof.* By induction. For  $n = 1$ , Let  $\eta(x)$  be another function with support in  $(-\varepsilon, \varepsilon)$  and

$$\int_{\mathbb{R}} \eta(x)dx = 1$$

Therefore,  $\omega = h(x) - \eta(x)$  has the property

$$\int_{\mathbb{R}} \omega(x)dx = 0$$

We show

$$\int_{\mathbb{R}} \{h(A(x)) - \eta(A(x))\} A'(x)dx = 0$$

For simplicity, let us denote  $h(A(x)) - \eta(A(x))\} A'(x)dx = f(x)dx$ . We show, there is  $g$  with support in  $(-\varepsilon, \varepsilon)$  such that

$$f(x)dx = d(g)(x)$$

It is enough to take  $g$  as

$$g(x) = \int_{-\infty}^x f(x)dx$$

Therefore, as  $g$  has a support in  $(-\varepsilon, \varepsilon)$ ,  $g$  vanishes outside any sufficiently large interval in  $\mathbb{R}$  by the Fundamental Theorem of Calculus,

$$\int_{\mathbb{R}} f(x)dx = \int_{\mathbb{R}} d(g)(x) = g(\infty) - g(-\infty) = 0$$

and therefore

$$\int_{\mathbb{R}} h(A(x))A'(x)dx = \int_{\mathbb{R}} \eta(A(x))A'(x)dx.$$

For  $n = 2$ , let  $h(x_1, x_2)$  and  $\eta(x_1, x_2)$  are real valued functions with support in  $B_\varepsilon(0)$  such that

$$\int_{\mathbb{R}^2} h(x_1, x_2) dx_1 dx_2 = \int_{\mathbb{R}^2} \eta(x_1, x_2) dx_1 dx_2 = 1$$

For  $\omega = h - \eta$ ,

$$\int_{\mathbb{R}^2} \omega(x) dx = 0$$

For  $f(x_1, x_2) = \{h(A(x_1, x_2)) - \eta(A(x_1, x_2))\} \det J_A(x_1, x_2)$ , we show there is an expression

$$g := g_1(x_1, x_2) dx_1 + g_2(x_1, x_2) dx_2,$$

with support in  $B_\varepsilon(0)$  such that

$$dg(x_1, x_2) = f(x_1, x_2) dx_1 dx_2$$

If we are able to show that, then

$$\int_{\mathbb{R}^2} f(x_1, x_2) dx_1 dx_2 = \int_{\mathbb{R}^2} dg(x_1, x_2) = 0.$$

as  $g, \omega$  have compact support. Define  $g$ ,

$$g(x_1, x_2) = \int_{-\infty}^{x_1} \left\{ f(t, x_2) - \left( \int_{-\infty}^{\infty} f(x_1, x_2) dx_1 \right) \tau(x_1) \right\} dt$$

where  $\tau(x_1)$  is a function with the property

$$\int_{-\infty}^{\infty} \tau(x_1) dx_1 = 1$$

It is simply seen that  $g(\infty, y) = g(x, \infty) = 0$ . We have

$$\frac{\partial g_1}{\partial x_1} + \left( \int_{-\infty}^{\infty} f(x_1, x_2) dx_1 \right) \tau(x_1) = f(x_1, x_2)$$

Let us denote  $g_3(x_2)$  by

$$g_3(x_2) = \int_{-\infty}^{\infty} f(x_1, x_2) dx_1.$$

This is a function of a single variable  $x_2$  and thus, there is  $g_4(x_2)$  such that

$$g_3(x_2) = dg_4(x_2),$$

and therefore

$$f(x_1, x_2) = \frac{\partial g_1}{\partial x_1} + \frac{\partial (g_4(x_2) \tau(x_1))}{\partial x_2}$$

Now assume for integral is independent of  $h$  for  $n = N$ . This means in  $\mathbb{R}^N$  there exists an  $\omega = f(x)dx$  such that  $\int_{\mathbb{R}^N} \omega(x)dx = 0$  with support in some  $B_\varepsilon(0)$  and there exists a  $g$  with support in  $B_\varepsilon(0)$  such that  $\omega = d(g)$ .

We show the property is true for  $n = N + 1$ . Let  $x_1 = t$ ,  $(t, x) = (t, x_2 \dots x_{N+1})$ . Consider,

$$g(t, x) = \int_{-\infty}^t (f(s, x) - \tau(s)r(x))ds$$

where  $\tau(s)$  has the property,

$$\int_{-\infty}^{\infty} \tau(t)dt = 1$$

and set

$$r(x) = \int_{-\infty}^{\infty} f(t, x)dt$$

This is a function of  $N$  dimensions. By induction hypothesis,  $\int r(x)dx = 0$  and there exist  $g_1, \dots, g_N$  such that

$$r(x) = \sum_{j=1}^N \frac{\partial g_j}{\partial x_j}$$

and each  $g_j$  are supported in  $B_\varepsilon(0)$ . Now

$$g(t, x) = \int_{-\infty}^t \left( f(s, x) - \tau(s) \sum_{j=1}^N \frac{\partial g_j}{\partial x_j} \right) ds$$

This integral vanishes in  $t$  as  $g$  has support in  $B_\varepsilon(0)$ , Thus

$$\frac{\partial g(t, x)}{\partial x_t} = f(t, x) - \tau(t)r(x)$$

which gives us

$$f(t, x) = \frac{\partial g(t, x)}{\partial x_t} + \sum_{j=1}^N \frac{\partial(g_j(x)\tau(t))}{\partial x_j}$$

□



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