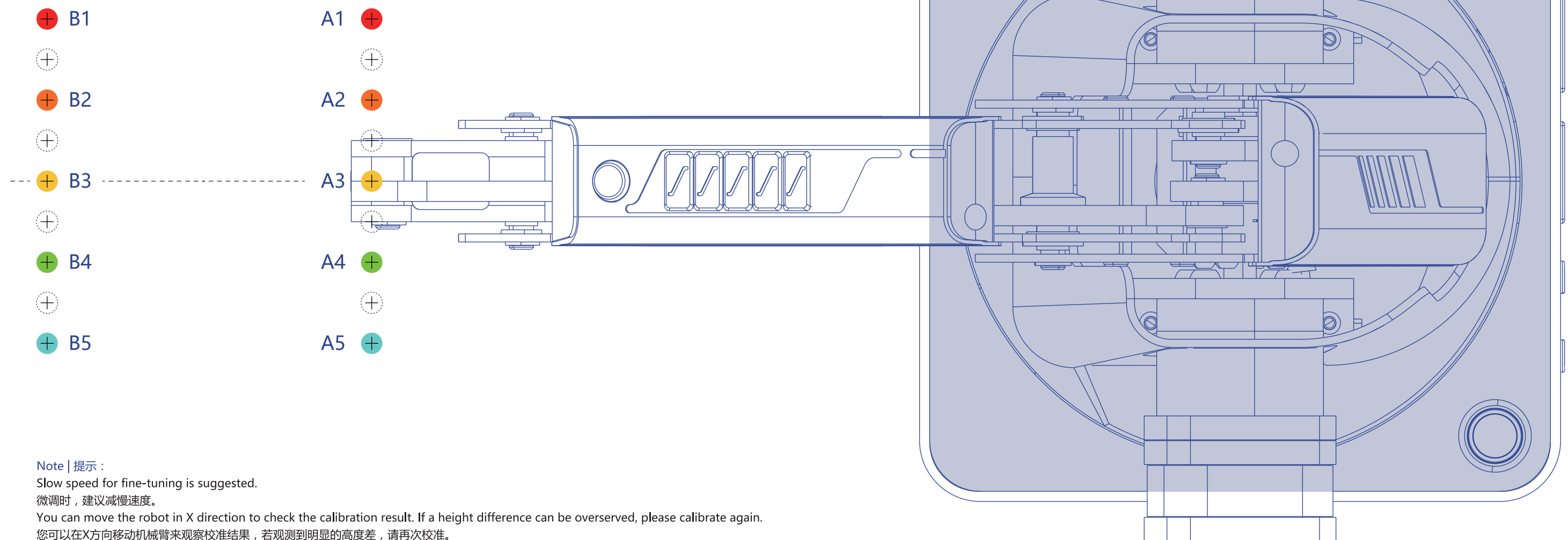


Sensor Calibration will offset the sensor error and improve the performance of Drawing, 3D printing, etc.
传感器校准能够偏置传感器误差，提高大大画画，3D打印的性能表现。

Note | 提示：
Your Dobot Magician is carefully calibrated before shipped out.
You don't need to recalibrate your robot before using it.
您的机械臂出厂前已经校准过，您在使用前无需校准。

Preparation | 准备工作：

- Install Pen& Pen Holder, and remove the cap
- Open Dobot Studio -> Tools -> Sensor Calibration Guide
- Put robot the marked place and follow the instructions to calibrate
- 安装笔和夹笔器，拔掉笔帽
- 打开Dobot Studio -> 工具->传感器校准向导
- 将机械臂放在标记的位置，并根据提示信息进行操作来完成校准



Note | 提示：
Slow speed for fine-tuning is suggested.
微调时，建议减慢速度。
You can move the robot in X direction to check the calibration result. If a height difference can be overserved, please calibrate again.
您可以在X方向移动机械臂来观察校准结果，若观测到明显的高度差，请再次校准。