Neural Networks Overview

Source:

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What are Neural Networks?

- Simple computational elements forming a large network
 - Emphasis on learning (pattern recognition)
 - Local computation (neurons)
- Definition of NNs is vague
 - Often | but not always | inspired by biological brain

History – 1 of 4

- Boots of work on NN are in:
- Neurobiological studies (more than one century ago):
 - How do nerves behave when stimulated by different magnitudes of electric current? Is there a minimal threshold needed for nerves to be activated? Given that no single nerve cell is long enough, how do different nerve cells communicate among each other?
- Psychological studies:
 - How do animals learn, forget, recognize and perform other types of tasks?
- Psycho-physical experiments helped to understand how individual neurons and groups of neurons work.
- McCulloch and Pitts introduced the first mathematical model of single neuron, widely applied in subsequent work.

History – 2 of 4

Prehistory:

 Golgi and Ramon y Cajal study the nervous system and discover neurons (end of 19th century)

History (brief):

- McCulloch and Pitts (1943): the first artificial neural network with binary neurons
- Hebb (1949): learning = neurons that are together wire together
- Minsky (1954): neural networks for reinforcement learning
- Taylor (1956): associative memory
- Rosenblatt (1958): perceptron, a single neuron for supervised learning

History – 3 of 4

- Widrow and Hoff (1960): Adaline
- Minsky and Papert (1969): limitations of single-layer perceptrons (and they erroneously claimed that the limitations hold for multi-layer perceptrons)

Stagnation in the 70's:

- Individual researchers continue laying foundations
- von der Marlsburg (1973): competitive learning and self-organization

Big neural-nets boom in the 80's

- Grossberg: adaptive resonance theory (ART)
- Hopfield: Hopfield network
- Kohonen: self-organising map (SOM)

History – 4 of 4

- Oja: neural principal component analysis (PCA)
- Ackley, Hinton and Sejnowski: Boltzmann machine
- Rumelhart, Hinton and Williams: backpropagation

Diversification during the 90's:

- Machine learning: mathematical rigor, Bayesian methods, infomation theory, support vector machines, ...
- Computational neurosciences: workings of most subsystems of the brain are understood at some level; research ranges from low-level compartmental models of individual neurons to large-scale brain models

Supervised vs Unsupervised Learning

Learning Tasks

Supervised

Data:

Labeled examples (input, desired output)

Tasks:

classification pattern recognition regression

NN models:

perceptron adaline

feed-forward NN radial basis function support vector machines

Unsupervised

Data:

Unlabeled examples (different realizations of the input)

Tasks: clustering content addressable memory

NN models: self-organizing maps (SOM) Hopfield networks

NNs: goal and design

- Knowledge about the learning task is given in the form of examples called training examples.
- A NN is specified by:
- an architecture: a set of neurons and links connecting neurons. Each link has a weight,
- a neuron model: the information processing unit of the NN,
- a learning algorithm: used for training the NN by modifying the weights in order to solve the particular learning task correctly on the training examples.

The aim is to obtain a NN that generalizes well, that is, that behaves correctly on new instances of the learning task.

Dimensions of a Neural Network

- network architectures
- types of neurons
- learning algorithms
- applications

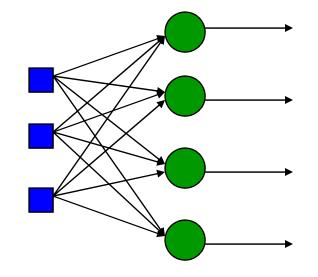
Network architectures

- Three different classes of network architectures
 - single-layer feed-forward) neurons are organized
 - multi-layer feed-forward in acyclic layers
 - recurrent

• The architecture of a neural network is linked with the learning algorithm used to train

Single Layer Feed-forward

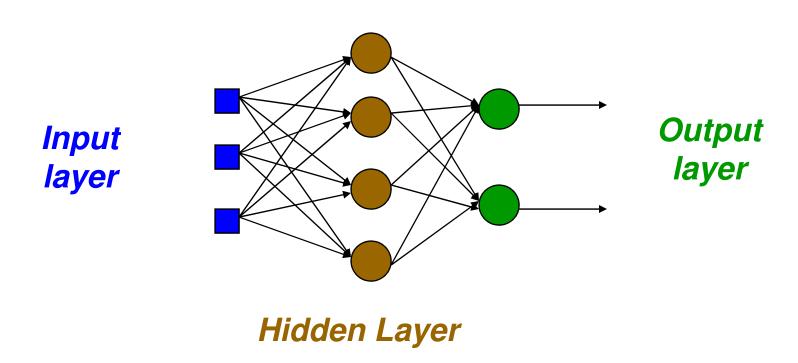
Input layer of source nodes



Output layer of neurons

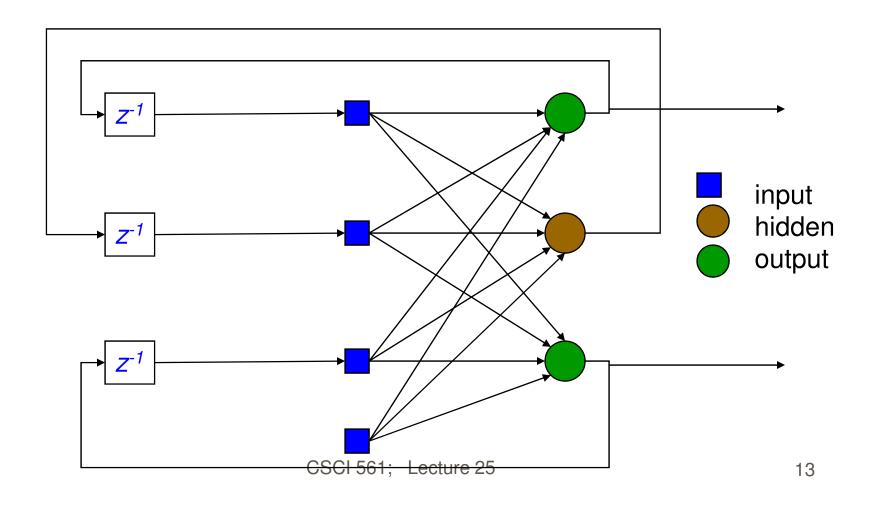
Multi layer feed-forward

3-4-2 Network

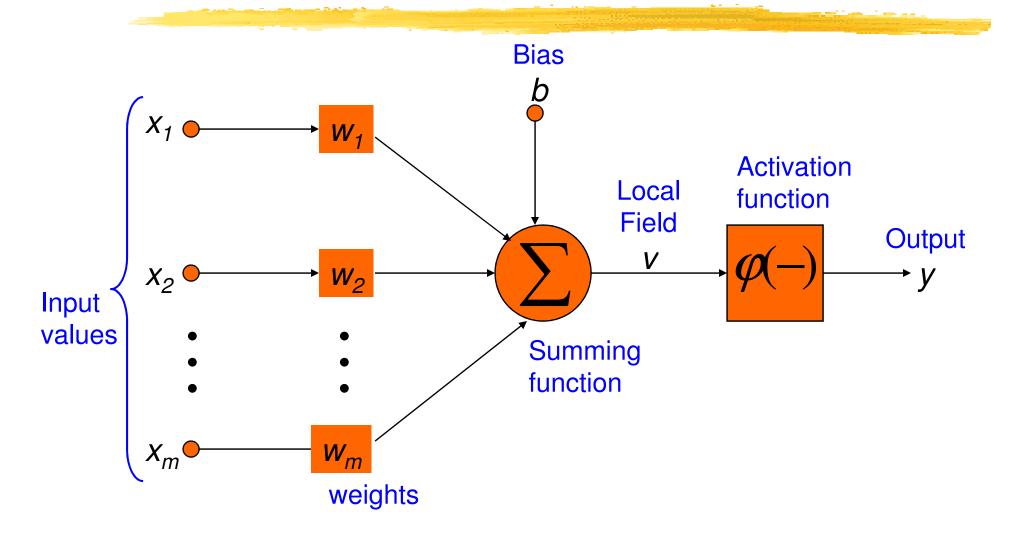


Recurrent network

Recurrent Network with *hidden neuron*: unit delay operator *z*¹ is used to model a dynamic system



The Neuron



The Neuron

- The neuron is the basic information processing unit of a NN. It consists of:
 - 1 A set of links, describing the neuron inputs, with weights W_1 , W_2 , ..., W_m
 - 2 An adder function (linear combiner) for computing the weighted sum of the inputs (real numbers):

$$\mathbf{u} = \sum_{j=1}^{m} \mathbf{w}_{j} \mathbf{x}_{j}$$

3 Activation function (squashing function) arphi for limiting the amplitude of the neuron output.

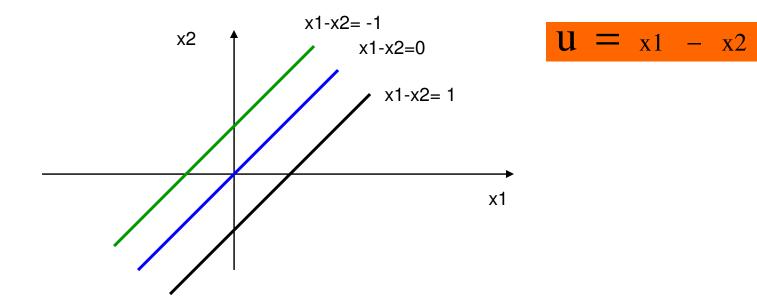
$$y = \varphi(u + b)$$

Bias of a Neuron

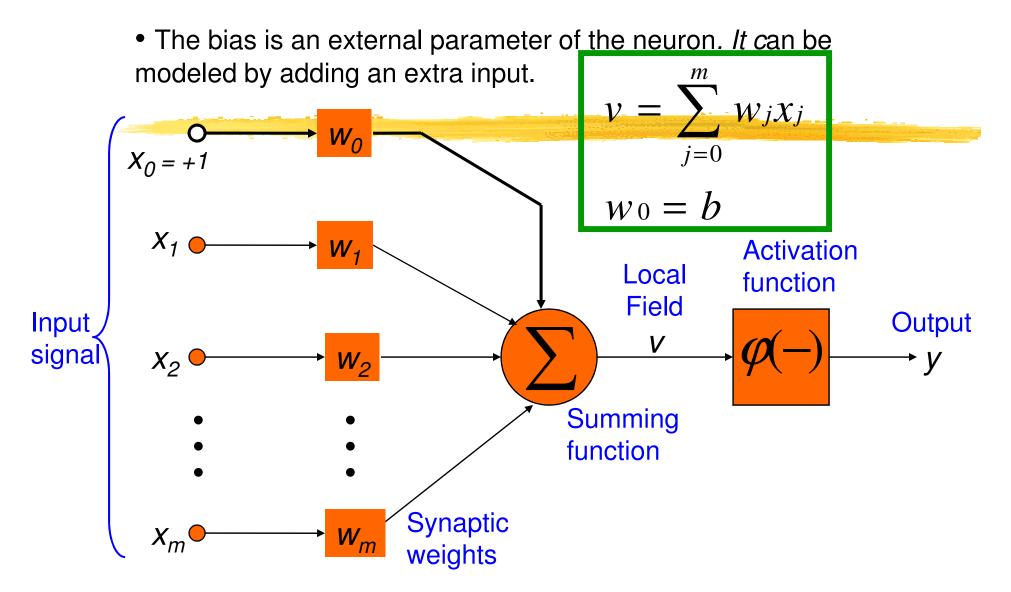
 The bias b has the effect of applying an affine transformation to the weighted sum u

$$v = u + b$$

• **v** is called **induced field** of the neuron



Bias as extra input



Neuron Models

• The choice of arphi determines the neuron model. Examples:

• step function:
$$\varphi(v) = \begin{cases} a & \text{if } v < c \\ b & \text{if } v > c \end{cases}$$

• ramp function:
$$\varphi(v) = \begin{cases} a & \text{if } v < c \\ b & \text{if } v > d \\ a + ((v-c)(b-a)/(d-c)) & \text{otherwise} \end{cases}$$

sigmoid function:with z,x,y parameters

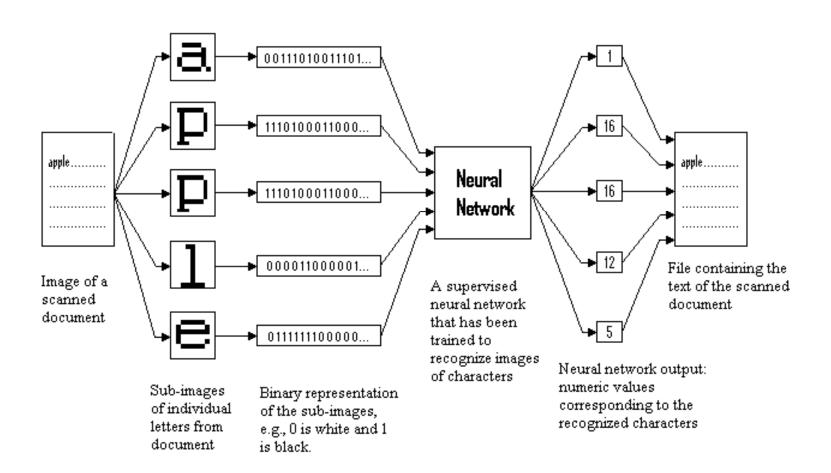
$$\varphi(v) = z + \frac{1}{1 + \exp(-xv + y)}$$

• Gaussian function: $\varphi(v) = \frac{1}{\sqrt{2\pi}\sigma} \exp\left(-\frac{1}{2}\left(\frac{v-\mu}{\sigma}\right)^2\right)$

Learning Algorithms

Depend on the network architecture:

- Error correcting learning (perceptron)
- Delta rule (AdaLine, Backprop)
- Competitive Learning (Self Organizing Maps)



Areas of Neural Network "Learning" Success

- Process Modeling and Control
- Machine Diagnostics
- Portfolio Management
- Target Recognition
- Medical Diagnosis
- Credit Rating
- Targeted Marketing
- Voice Recognition
- Financial models and forecasts
- Quality control
- Intelligent search
- Fraud Detection