

$= 1/r$ (cf . Bertrand 's theorem) and $\gamma = \cos \theta$, with the angle θ defined by

$\gamma = \frac{1}{\sqrt{1 - \beta^2}}$

and γ is the Lorentz factor . As before , we may obtain a conserved binormal vector B by taking the cross product with the conserved angular momentum vector

$B = \frac{1}{m} \mathbf{p} \times \mathbf{r}$

These two vectors may likewise be combined into a conserved dyadic tensor W ,

$W = \frac{1}{2m} (\mathbf{p} \mathbf{p} + \mathbf{r} \mathbf{r})$

In illustration , the LRL vector for a non-relativistic , isotropic harmonic oscillator can be calculated . Since the force is central ,

$\mathbf{p} \times \mathbf{r} = 0$

the angular momentum vector is conserved and the motion lies in a plane .

The conserved dyadic tensor can be written in a simple form

$W = \frac{1}{2m} (\mathbf{p} \mathbf{p} + \mathbf{r} \mathbf{r})$

although it should be noted that \mathbf{p} and \mathbf{r} are not necessarily perpendicular .

The corresponding Runge-Lenz vector is more complicated ,

$\mathbf{A} = \frac{1}{2m} (\mathbf{p} \times \mathbf{r} \times \mathbf{p}) - \frac{\mathbf{r}}{r}$

where

$\omega = \sqrt{k/m}$

is the natural oscillation frequency and

$\mathbf{L} = \mathbf{r} \times \mathbf{p}$

== Proofs that the Laplace-Runge-Lenz vector is conserved in Kepler problems ==

The following are arguments showing that the LRL vector is conserved under central forces that obey an inverse-square law .

== Direct proof of conservation ==

A central force $\mathbf{F} = -\frac{dV}{dr} \frac{\mathbf{r}}{r}$ acting on the particle is

$\mathbf{F} = -\frac{dV}{dr} \frac{\mathbf{r}}{r}$

for some function $V(r)$ of the radius r . Since the angular momentum \mathbf{L} is conserved under central forces , $\mathbf{L} \times \mathbf{r} = 0$ and

$\mathbf{L} \times \mathbf{p} = 0$

where the momentum $\mathbf{p} = m \mathbf{v}$ and where the triple cross product has been simplified using Lagrange's formula

$\mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = \mathbf{B} (\mathbf{A} \cdot \mathbf{C}) - \mathbf{C} (\mathbf{A} \cdot \mathbf{B})$

The identity

$\mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = \mathbf{B} (\mathbf{A} \cdot \mathbf{C}) - \mathbf{C} (\mathbf{A} \cdot \mathbf{B})$

yields the equation

$\frac{d\mathbf{A}}{dt} = \frac{1}{m} \mathbf{p} \times \mathbf{F}$

For the special case of an inverse-square central force $\mathbf{F} = -\frac{k}{r^2} \frac{\mathbf{r}}{r}$, this equals

$\frac{d\mathbf{A}}{dt} = \frac{1}{m} \mathbf{p} \times \mathbf{F}$

Therefore , \mathbf{A} is conserved for inverse-square central forces

$\frac{d\mathbf{A}}{dt} = 0$

A shorter proof is obtained by using the relation of angular momentum to angular velocity , $\mathbf{L} = I \boldsymbol{\omega}$, which holds for a particle traveling in a plane perpendicular to \mathbf{L} . Specifying to inverse-square central forces , the time derivative of \mathbf{A} is

$\frac{d\mathbf{A}}{dt} = \frac{1}{m} \mathbf{p} \times \mathbf{F}$

where the last equality holds because a unit vector can only change by rotation , and $\boldsymbol{\omega}$ is the orbital velocity of the rotating vector . Thus , \mathbf{A} is seen to be a difference of two vectors with equal time derivatives .

As described below , this LRL vector \mathbf{A} is a special case of a general conserved vector \mathbf{A}

that can be defined for all central forces . However , since most central forces do not produce closed orbits (see Bertrand 's theorem) , the analogous vector \mathbf{A} rarely has a simple definition and is generally a multivalued function of the angle ϕ between \mathbf{r} and \mathbf{A} .

=== Hamilton ? Jacobi equation in parabolic coordinates ===

The constancy of the LRL vector can also be derived from the Hamilton ? Jacobi equation in parabolic coordinates (ξ, η) , which are defined by the equations

$$\xi^2 = r + z$$

$$\eta^2 = r - z$$

where r represents the radius in the plane of the orbit

$$r = \sqrt{x^2 + y^2}$$

The inversion of these coordinates is

$$\xi = \sqrt{r + z}$$

$$\eta = \sqrt{r - z}$$

Separation of the Hamilton ? Jacobi equation in these coordinates yields the two equivalent equations

$$\frac{\partial S}{\partial \xi} = \frac{1}{2} \mu \dot{\xi}^2 + \frac{1}{2} \mu \dot{\eta}^2 + \frac{1}{2} \mu \dot{\phi}^2 r^2 + V(r)$$

$$\frac{\partial S}{\partial \eta} = \frac{1}{2} \mu \dot{\xi}^2 + \frac{1}{2} \mu \dot{\eta}^2 + \frac{1}{2} \mu \dot{\phi}^2 r^2 + V(r)$$

where E is a constant of motion . Substitution and re @-@ expression in terms of the Cartesian momenta p_x and p_y shows that \mathbf{A} is equivalent to the LRL vector

$$\mathbf{A} = \frac{1}{2} \mu \dot{\mathbf{r}}^2 \mathbf{r} - \frac{1}{2} \mu \dot{\mathbf{r}} \times \dot{\mathbf{r}} \times \mathbf{r}$$

=== Noether 's theorem ===

The connection between the rotational symmetry described above and the conservation of the LRL vector can be made quantitative by way of Noether 's theorem . This theorem , which is used for finding constants of motion , states that any infinitesimal variation of the generalized coordinates of a physical system

$$\delta q_i = \epsilon \eta_i(q, p, t)$$

that causes the Lagrangian to vary to first order by a total time derivative

$$\delta L = \frac{d}{dt} F(q, p, t)$$

corresponds to a conserved quantity Q

$$Q = F + \sum_i p_i \eta_i$$

In particular , the conserved LRL vector component A_z corresponds to the variation in the coordinates

$$\delta x_i = \epsilon \delta_{i3}$$

where i equals 1 , 2 and 3 , with x_i and p_i being the i th components of the position and momentum vectors \mathbf{r} and \mathbf{p} , respectively ; as usual , δ_{ij} represents the Kronecker delta . The resulting first @-@ order change in the Lagrangian is

$$\delta L = \epsilon \frac{1}{2} \mu \dot{\mathbf{r}}^2$$

Substitution into the general formula for the conserved quantity Q yields the conserved component A_z of the LRL vector ,

$$A_z = \frac{1}{2} \mu \dot{\mathbf{r}}^2 z - \frac{1}{2} \mu \dot{\mathbf{r}} \times \dot{\mathbf{r}} \times z$$

=== Lie transformation ===

The Noether theorem derivation of the conservation of the LRL vector \mathbf{A} is elegant , but has one drawback : the coordinate variation δx_i involves not only the position \mathbf{r} , but also the momentum \mathbf{p} or , equivalently , the velocity \mathbf{v} . This drawback may be eliminated by instead deriving the conservation of \mathbf{A} using an approach pioneered by Sophus Lie . Specifically , one may define a Lie transformation in which the coordinates \mathbf{r} and the time t are scaled by different powers of a parameter ϵ (Figure 9)

<formula>

This transformation changes the total angular momentum L and energy E ,

<formula>

but preserves their product EL^2 . Therefore , the eccentricity e and the magnitude A are preserved , as may be seen from the equation for A^2

<formula>

The direction of A is preserved as well , since the semiaxes are not altered by a global scaling . This transformation also preserves Kepler 's third law , namely , that the semiaxis a and the period T form a constant T^2 / a^3 .

= = Alternative scalings , symbols and formulations = =

Unlike the momentum and angular momentum vectors p and L , there is no universally accepted definition of the Laplace ? Runge ? Lenz vector ; several different scaling factors and symbols are used in the scientific literature . The most common definition is given above , but another common alternative is to divide by the constant mk to obtain a dimensionless conserved eccentricity vector

<formula>

where v is the velocity vector . This scaled vector e has the same direction as A and its magnitude equals the eccentricity of the orbit . Other scaled versions are also possible , e.g. , by dividing A by m alone

<formula>

or by p_0

<formula>

which has the same units as the angular momentum vector L . In rare cases , the sign of the LRL vector may be reversed , i.e. , scaled by -1 . Other common symbols for the LRL vector include a , R , F , J and V . However , the choice of scaling and symbol for the LRL vector do not affect its conservation .

An alternative conserved vector is the binormal vector B studied by William Rowan Hamilton

<formula>