view_frames Result

Recorded at time: 1513047737.382

base_footprint

Broadcaster: /base_footprint_to_base_link
Average rate: 99.597 Hz
Most recent transform: 1513047737.272 (0.109 sec old)
Buffer length: 4.719 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1513047737.382 sec old)
Buffer length: 0.000 sec

Broadcaster: /base_link_2_base_stabilized_link
Average rate: 30.158 Hz
Most recent transform: 1513047737.269 (0.113 sec old)
Buffer length: 4.675 sec

Broadcaster: /robot_state_publisher
Average rate: 30.213 Hz
Most recent transform: 1513047737.256 (0.126 sec old)
Buffer length: 4.700 sec

Broadcaster: /robot_state_publisher
Average rate: 30.213 Hz
Most recent transform: 1513047737.256 (0.126 sec old)
Buffer length: 4.700 sec

prism_base

base_stabilized

left_wheel

right_wheel

Broadcaster: /base_stabilized_2_base_frame
Average rate: 30.156 Hz
Most recent transform: 1513047737.276 (0.106 sec old)
Buffer length: 4.676 sec

base_frame

Broadcaster: /base_frame_2_laser_link
Average rate: 30.154 Hz
Most recent transform: 1513047737.286 (0.095 sec old)
Buffer length: 4.709 sec

Broadcaster: /base_2_nav_link
Average rate: 30.156 Hz
Most recent transform: 1513047737.292 (0.090 sec old)
Buffer length: 4.709 sec

laser

nav

prism_plate

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1513047737.382 sec old)
Buffer length: 0.000 sec

ur5_base_link

Broadcaster: /robot_state_publisher
Average rate: 30.213 Hz
Most recent transform: 1513047737.256 (0.126 sec old)
Buffer length: 4.700 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1513047737.382 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 30.213 Hz
Most recent transform: 1513047737.256 (0.126 sec old)
Buffer length: 4.700 sec

ur5_base

ur5_shoulder_link

Broadcaster: /ur_driver
Average rate: 125.217 Hz
Most recent transform: 1513047737.261 (0.121 sec old)
Buffer length: 4.720 sec

Broadcaster: /robot_state_publisher
Average rate: 30.213 Hz
Most recent transform: 1513047737.256 (0.126 sec old)
Buffer length: 4.700 sec

ur5_tool0_controller

ur5_upper_arm_link

Broadcaster: /robot_state_publisher
Average rate: 30.213 Hz
Most recent transform: 1513047737.256 (0.126 sec old)
Buffer length: 4.700 sec

ur5_forearm_link

Broadcaster: /robot_state_publisher
Average rate: 30.213 Hz
Most recent transform: 1513047737.256 (0.126 sec old)
Buffer length: 4.700 sec

ur5_wrist_1_link

Broadcaster: /robot_state_publisher
Average rate: 30.213 Hz
Most recent transform: 1513047737.256 (0.126 sec old)
Buffer length: 4.700 sec

ur5_wrist_2_link

Broadcaster: /robot_state_publisher
Average rate: 30.213 Hz
Most recent transform: 1513047737.256 (0.126 sec old)
Buffer length: 4.700 sec

ur5_wrist_3_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1513047737.382 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1513047737.382 sec old)
Buffer length: 0.000 sec

ur5_ee_link

ur5_tool0