

# Analysis II

15. Oktober 2020

## Teil I Ordinary Differential Equations

**Def.** A *differential equation* is an equation where the unknown is a function  $f$ , and the equation relates  $f(x)$  with values of derivatives  $f^{(i)}$  at the same point  $x$ .

**Def.** Ordinary  $\iff$  One variable only

**Def.** A Linear ODE is an equation of the form

$$y^{(k)} + a_{k-1}y^{(k-1)} + \dots + a_0y = D(y) = b$$

where  $y = f(x)$  is the unknown function  
 $a_{k-1}(x), \dots, a_0(x), b(x)$  are continuous functions.

**Def.** Homogenous  $\iff b(x) = 0$

**Def. (Initial Condition)** A set of equations

$$y(x_0) = y_0, y'(x_0) = y_1, \dots, y^{(k-1)}(x_0) = y_{k-1}$$

**Thm. (2.2.3)**  $I \subset \mathbb{R}$ , linear ODE of order  $k \geq 1$

(1) Let  $S_0$  be the set of solutions for  $b = 0$ . Then is  $S_0$  a vector space of dimension  $k$ .

(2) For any initial conditions, there is a unique solution  $f \in S_0$ , s.t.

$$y(x_0) = y_0, y'(x_0) = y_1, \dots, y^{(k-1)}(x_0) = y_{k-1}$$

(3) For an arbitrary  $b$ , the set of solutions is  $S_b = \{f + f_p | f \in S_0\}$ , where  $f_p$  is a particular solution

(4) For any initial value problem, there is a unique solution  $f \in S_b$

**Remark:** If  $b \neq 0$ , then  $S_b$  is not a vector space

**Remark:** If  $f_1, f_2$  are solutions for  $b_1(x), b_2(x)$ ,  
 $f_1 + f_2$  is a solution for  $b_1(x) + b_2(x)$

## 1 Linear ODEs of order 1

**Procedure:** Consider  $y' + ay = b$

1. Solve homogeneous equation  $y' + ay = 0$

$$f_0(x) = z \cdot e^{-A(x)} \text{ for } z \in \mathbb{C}$$

2. Find a solution of the inhomogeneous equation  $f_p$ , then  $S_b = f_p + S_0$ .

- Guess:  $b(x)$  should resemble  $f_p$
- Variation of Constants (Assume constants of  $S_0$  are functions)
- Formula:  $f_p(x) = \int b(x) \cdot e^{A(x)} dx \cdot e^{-A(x)}$

**Remark:** The solutions are given by  $f_0 + zf_1$ , where  $z \in \mathbb{C}$  and  $f_1$  is a basis of  $S$

**Remark:** To solve the real value problem  $f(x_0) = y_0$ , one can solve  $f_0(x_0) + zf_1(x_0) = y_0$

**Remark:** If  $a \in \mathbb{R}$ , then there exists  $f_0, f_1 \in \mathbb{R}$

## 2 Lin. ODE with constant coefs.

The equation takes the form: Let  $a_{k-1}, \dots, a_0 \in \mathbb{C}$

$$y^{(k)} + a_{k-1}y^{(k-1)} + \dots + a_0y = b(x)$$

**Intuition:** We look for solutions of the form  $f(x) = e^{\lambda x}, \lambda \in \mathbb{C}$

$$\begin{aligned} 0 &= y^{(k)} + a_{k-1}y^{(k-1)} + \dots + a_0y \\ &= e^{\lambda x}(\lambda^k + a_{k-1}\lambda^{k-1} + \dots + a_1\lambda + a_0) \\ &= e^{\lambda x}P(\lambda) \end{aligned}$$

$\implies f$  is a solution if and only if  $P(\lambda) = 0$ .

$\implies$  According to the Fundamental Theorem of Algebra, there are  $k$  roots for  $P$  in  $\mathbb{C}$ .

**Remark:**  $P(\lambda)$  is the **characteristic polynomial** and the roots are called **eigenvalues**

**Thm.** Let  $\lambda_1, \dots, \lambda_r$  be the pairwise distinct roots of  $P(\lambda)$  with corresponding multiplicity  $m_1, \dots, m_r$ . Then the functions

$$x^l e^{\lambda_j x} \quad 1 \leq j \leq r, \quad 0 \leq l < m_j$$

form a basis of the space of solutions of the homogeneous equation.

E.g. for  $k$  distinct roots we get:

$$f(x) = z_1 e^{\lambda_1 x} + \dots + z_k e^{\lambda_k x}, \text{ with } z_1, \dots, z_k \in \mathbb{C}$$

**Remark:** If we are only interested in real solutions, the solutions based on complex roots, the basis can be transformed. For  $\lambda = \beta + i\gamma$ :

$$\text{span}(e^{\lambda x}, e^{\bar{\lambda}x}) = \text{span}(e^{\beta x} \cos x, e^{\beta x} \sin x)$$

## 2.1 Solving the inhomogenous eqn.

**Procedure: (Ansatz)**

$b(x)$	Ansatz $y_p(x)$
$P_n(x)$	$Q_n(x)$
$P_n(x)e^{\mu x}$	$Q_n(x)e^{\mu x}$
$P_n(x)\sin(\nu x)$	$R_n(x)\sin(\nu x)$
$+Q_n(x)\cos(\nu x)$	$+S_n(x)\cos(\nu x)$
$P_n(x)e^{\mu x}\sin(\nu x)$	$e^{\mu x}(R_n(x)\sin(\nu x)$
$+Q_n(x)e^{\mu x}\cos(\nu x)$	$+S_n(x)\cos(\nu x))$

Insert  $y_p(x)$  in the inhomogeneous eqn. and solve for the constants.  $P_n(x), Q_n(x), \dots$  are polynomials of degree  $n$ .

**Remark:** If  $d$  is a root of  $P(\lambda)$  of multiplicity  $m$ , multiply  $y_p(x)$  by  $x^m$ .

**Procedure: (Variation of constants)**

This method can be derived from the matrix describing the problem. Assume  $n = 2$ .

Try  $y_p = z_1(x)f_1 + z_2(x)f_2$  after solving the system:

$$\begin{cases} z_1'(x)f_1 + z_2'(x)f_2 = 0 \\ z_1'(x)f_1' + z_2'(x)f_2' = b \end{cases}$$