DDENLP

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Documentation of the Toolbox DDENLP for robust steady state optimization of delayed systems.

1.1 Using this toolbox

This toolbox aids with the optimization of delayed systems using normal vector constraints for robust stability properties.

The code documentation can be found in this file.

Some common application/coding problems can be found in the Frequently Asked Questions.

Additionally, there are some example files.

1.2 Funding

The development of this toolbox was funded by Deutsche Forschungsgemeinschaft (grant MO 1086/13).

Author

Jonas Otten and Martin Moennigmann

Date

18 Jul 2017

2	Documentation of the Toolbox DDENLP for robust steady state optimization of delayed systems.

Frequently Asked Questions

2.1 Convergence of Initialization

Why does my initial value of for a (mod)Hopf converge to a (mod)fold? Check if you have specified omega $\sim=0$

2.2 DDE-BIFTOOL

Why does the calculation of eigenvalues using DDE-BIFTOOL throw the error message "Input to EIG must not contain NaN or Inf."?

The DDE-BIFTOOL-Parameter method.stability.minimal_real_part is too big. Try reducing it.

Author

Jonas Otten and Martin Moennigmann

Date

20 Sep 2017

Hierarchical Index

3.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

handle					 				 					 						36	6
DDE					 														 	13	7
DDENLP					 															2	1
EqualityConstraint .																				34	4
NVConstraint																		 		4	1
StStConstraint																		 		4	7
ManifoldSlice																				3	7
VariableVector					 		_	_									_		 	50	n

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Class Index

4.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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This class desribes the whole optimization problem for delayed systems	21
Constraint	
(abstract) class that inherits its properities to equality constraints	34
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straint	
This class describes equality constraints representing the steady state condition for the nominal	
parameters	47
Vector	
The instances of this class contain information for a VariableVector used in DDENLP	50
	This class desribes the whole optimization problem for delayed systems Constraint (abstract) class that inherits its properities to equality constraints Slice The instances of this class generate visualization data traint Instances of this class are objects representing normal vector constraints straint This class describes equality constraints representing the steady state condition for the nominal parameters Vector

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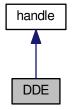
Chapter 6

Class Documentation

DDE Class Reference 6.1

The instances of this class contain information for a DDE used in DDENLP.

Inheritance diagram for DDE:



Public Member Functions

- function DDE (in rhsHandle, in delays, in xNomGuess, in uncParam, in certOptParam) Class constructor.
- function getHandles (in aDDE, in type) hands back function handles of a DDE instance

Public Attributes

- · Property foldManiHandle function handle for fold bifurcation manifold
- · Property modfoldManiHandle function handle for modified fold bifurcation manifold
- · Property hopfManiHandle

function handle for hopf bifurcation manifold

• Property modhopfManiHandle

function handle for modified hopf bifurcation manifold

• Property foldNVHandle

function handle for fold bifurcation normal vector system

• Property modfoldNVHandle

function handle for modified fold bifurcation normal vector system

• Property hopfNVHandle

function handle for hopf bifurcation normal vector system

• Property modhopfNVHandle

function handle for modified hopf bifurcation normal vector system

Protected Attributes

· Property rhs

function handle for right-hand-side of DDE

Property delays

function handle of function for delays

Property uncParam

uncertain parameters: object of class VariableVector

• Property certOptParam

certain optimization parameters: object of class Variable Vector

· Property ntau

number of delays

6.1.1 Detailed Description

The instances of this class contain information for a DDE used in DDENLP.

Those instances collect the relevant data of the DDE describing the system to be optimized

6.1.2 Constructor & Destructor Documentation

6.1.2.1 function DDE (in rhsHandle, in delays, in xNomGuess, in uncParam, in certOptParam)

Class constructor.

This function constructs instances of the class DDE

Parameters

rhsHandle	function handle for right hand side of DDE
delays	function handle for delays
xNomGuess	Guess for a nominal steady state vector of class VariableVector
uncParam	uncertain nominal paraemeter vector of class VariableVector
certOptParam	parameter vector with certain optimization variables of class VariableVector

6.1 DDE Class Reference

Returns

instance of the DDE class.

6.1.3 Member Function Documentation

6.1.3.1 function getHandles (in aDDE, in type)

hands back function handles of a DDE instance

Those function handles come in handy for the formulation of normal vector constraints

Parameters

aDDE	function handle for right hand side of DDE
type	function handle for delays

Returns

handleMani function handle with function g(.)=0 describing a critical manifold handleNV function handle with function h(.)=0 describing normal vectors on critical manifold

6.1.4 Member Data Documentation

6.1.4.1 Property certOptParam [protected]

certain optimization parameters: object of class VariableVector

6.1.4.2 Property delays [protected]

function handle of function for delays

6.1.4.3 Property foldManiHandle

function handle for fold bifurcation manifold

6.1.4.4 Property foldNVHandle

function handle for fold bifurcation normal vector system

6.1.4.5 Property hopfManiHandle

function handle for hopf bifurcation manifold

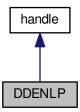
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6.1.4.6 Property hopfNVHandle
function handle for hopf bifurcation normal vector system
6.1.4.7 Property modfoldManiHandle
function handle for modified fold bifurcation manifold
6.1.4.8 Property modfoldNVHandle
function handle for modified fold bifurcation normal vector system
6.1.4.9 Property modhopfManiHandle
function handle for modified hopf bifurcation manifold
6.1.4.10 Property modhopfNVHandle
function handle for modified hopf bifurcation normal vector system
6.1.4.11 Property ntau [protected]
number of delays
6.1.4.12 Property rhs [protected]
function handle for right-hand-side of DDE
6.1.4.13 Property uncParam [protected]
uncertain parameters: object of class VariableVector
The documentation for this class was generated from the following file:
```

• @DDE/DDE.m

6.2 DDENLP Class Reference

this class desribes the whole optimization problem for delayed systems

Inheritance diagram for DDENLP:



Public Member Functions

• function DDENLP (in aCostFunction, in aDDE, in xNomGuess, in stateLB, in stateUB, in uncertParamLB, in uncertParamUB, in certOptParamLB, in certOptParamUB, in varargin)

Class constructor.

• function initializeStSt (in aDDENLP)

intialize steady state constraint within a DDENLP instance

function initializeStStRot (in aDDENLP)

intialize rotating steady state constraint within a DDENLP instance

• function addNVCon (in aDDENLP, in type, in augSysHandle, in nVSysHandle, in xGuess, in alphaGuess, in pGuess, in varargin)

add a normal vector constraint to the optimization Problem

• function initNVCons (in aDDENLP, in nVflipmode, in varargin)

initializes normal vector constraints by using a series of methods of the class NVConstraint

• function moveAwayFromManifolds (in aDDENLP, in steppingFactor, in distanceFactor, in)

moves the nominal point away from known critical manifolds methods of the class NVConstraint

• function evaluateStatus (in aDDENLP)

evaluates the status of DDENLP

• function concatConstraints (in aDDENLP, in otherEq, in otherIneq, in varargin)

concatenates the various constraints in this DDENLP instance for later optimitzation

function compareConnectionNV (in aDDENLP, in indexCrit)

compares connection and normal vector

function concatInitPoints (in aDDENLP)

concatenates the various variables in this DDENLP instance for later optimitzation

function checkConstraints (in aDDENLP)

check if constraints hold for inital point

function runOptim (in aDDENLP, in userDefinedOptions, in Aineq, in bineq, in varargin)

run optimization of DDENLP instance

• function runOptimMultipleInitPoints (in aDDENLP, in furtherInput, in varargin)

run optimization of DDENLP instance with many different initial points

function runOptimWithStabChecks (in aDDENLP, in nlterBetweenStabChecks)

run optimization of DDENLP instance with intermediate stability checks.

function runOptimAddingNewManifolds (in aDDENLP, in nIterBetweenStabChecks)

run optimization of DDENLP instance with intermediate stability checks.

· function findManifoldPointOnLine (in ignoredArg, in type, in manifoldHandle, in point1, in point2, in maxEig)

look for a manifold point between two given points

• function deconstructInit (in aDDENLP, in type, in varargin)

reconstruct inital variables from single vector

function deconstructOptimum (in aDDENLP)

reconstruct optimal variables from single vector

function checkStabilityPoint (in aDDENLP, in point)

calculate eigenvalues at a given point in parameter space

• function checkStabilityAtVertices (in aDDENLP, in indexlist, in varargin)

calculate stability an vertices of uncertianty region

• function checkStabilityAtRandom (in aDDENLP, in baseForNumberOfPoints, in seedForRandomNumbers, in varargin)

calculate stability at random points within uncertianty region

function ddesd (in aDDENLP, in point, in history, in tspan, in options)

run a simulation of the optimum.

Public Attributes

Property aCostFunction

cost function of the main steady state optimization problem

Property problemDDE

object of class DDE, contains all relevant DDE information

Property vars

structure containing the cell array of variables, find entries with ind=find(ismember...

Property algVarIndex

indexes algebraic variables

Property stStCon

steady state constraint class StStConstraint

Property lowerBoxCons

lower boundaries of box constraints

Property upperBoxCons

lower boundaries of box constraints

Property minDist

parameter uncertainty

Property maxAllowedRealPart

the highest eigenvalue real part which is allowed

· Property allowedEigsInClosedRightHP

accepted eigenvalues in the closed right halfplane (for eigenvalues on the imaginary axis)

Property NVCon

normal vector constraints, vector of objects of class NVConstraint

Property allNLEqConstraints

function handle that collects all nonlinear equality constraints

Property allNLIneqConstraints

function handle that collects all nonlinear inequality constraints

Property fixedUncertParamIndex

contains the indices of parameters that are uncertain, but fixed

Property nlcon

function handle with the nonlinear constraints (inequality and equality)

• Property optionsInitEqCons

options for initialization numerics (fsolve)

• Property optionsInitOptim

options for initialization numerics (auxiliary optimization)

Property optionsMainOptim

options for the main optimization

• Property numMinEig

real number, for DDE-BIFTOOL numerics

Property verifyStabPoints

\$\$ {verifyStabPoints}^{nAlpha} \$\$ random points are generated and evaluated

Property useLHS

flag for using latin hypercube sample for evaluating the uncertainty region

Protected Attributes

Property nX

number of states

· Property nAlpha

number of uncertain parameters

Property nP

number of optimization parameters without uncertainty

• Property occupiedVars

number of variables in whole optimization problem

Property occupiedEqs

number of equality constraints in whole optimization problem

• Property occupiedIneqs

number of inequality constraints in whole optimization problem

Property initVal

initial value, length(initVal)==occupiedVars

· Property optimVal

optimal value, should be a vector of length(optimVal)==occupiedVars

Property optJ

cost at optimum

· Property exitflag

exitflag of main optimization

• Property optimOutput

status message of main optimization

Property lambda

lagrange multiplier of main optimization

· Property grad

gradient of cost function of main optimization

Property hessian

hessian of lagrange function of main optimization

Property status

status of this optimization problem, (key in main description)

6.2.1 Detailed Description

this class desribes the whole optimization problem for delayed systems

this class is intended to for the robust stable steady state of delayed systems

status: 1: input initial guess and might not solve the equations 2: parameter is on critical manifold 3: parameter is closest critical point 4: Normal Vector at closest critical point was found 5: connection of closest critical point and nominal point by normal vector verified 6: all nonlinear constraints have been concatenated >6: values were handed back by optimization algorithm

Author

Jonas Otten

Date

18 Jul 2017

6.2.2 Constructor & Destructor Documentation

6.2.2.1 function DDENLP (in aCostFunction, in aDDE, in xNomGuess, in stateLB, in stateUB, in uncertParamLB, in uncertParamUB, in certOptParamUB, in varargin)

Class constructor.

This function constructs instances of the class DDENLP

Parameters

aCostFunction	function handle for cost function	
aDDE	underlying DDE, instance of class DDE	
xNomGuess	collection of instances of VariableVector, nominal state guess	
stateLB	lower bounds for states	
stateUB	upper bounds for states	
uncertParamLB	tParamLB lower bounds for uncertain optimization parameters	
uncertParamUB	upper bounds for uncertain optimization parameters	
certOptParamLB lower bounds for certain optimization parameters (optional input		
certOptParamUB	upper bounds for certain optimization parameters (optional input)	

Returns

instance of the DDENLP class.

6.2.3 Member Function Documentation

6.2.3.1 function addNVCon (in aDDENLP, in type, in augSysHandle, in nVSysHandle, in xGuess, in alphaGuess, in pGuess, in varargin)

add a normal vector constraint to the optimization Problem

Parameters

aDDENLP	instance of DDENLP
type	a string containing the requested manifold type
augSynVSysHandlesHandle	function handle describing the critical manifold
nVSysHandle	function handle describing the normal vectors of the critical manifold
xGuess	guess for critical state, instance of VariableVector
alphaGuess	guess for critical parameters, instance of VariableVector
pGuess	current certain parameters, instance of VariableVector

6.2.3.2 function checkConstraints (in aDDENLP)

check if constraints hold for inital point

Parameters

aDDENLP	instance of DDENLP

6.2.3.3 function checkStabilityAtRandom (in aDDENLP, in baseForNumberOfPoints, in seedForRandomNumbers, in varargin)

calculate stability at random points within uncertianty region

Parameters

aDDENLP	instance of DDENLP class
baseForNumberOfPoints	base for the number of random points
seedForRandomNumbers	(optional) seed for pseudo random number generator

Returns

maxRealPart maximal real part of all eigenvalues

6.2.3.4 function checkStabilityAtVertices (in aDDENLP, in indexlist, in varargin)

calculate stability an vertices of uncertianty region

Parameters

aDDENLP	instance of DDENLP class indexlist index list for selective stability calculation

Returns

maxRealPart maximal real part of all eigenvalues

6.2.3.5 function checkStabilityPoint (in aDDENLP, in point)

calculate eigenvalues at a given point in parameter space

Parameters

aDDENLP	instance of DDENLP class
point	string desribing at which point type the stability shall be evaluated

Returns

maxRealPart maximal real part of all eigenvalues eigs some rightmost eigenvalues

6.2.3.6 function compareConnectionNV (in aDDENLP, in indexCrit)

compares connection and normal vector

Parameters

aDDENLP	instance of DDENLP
indexCrit	index of critical point for which comparison takes place

6.2.3.7 function concatConstraints (in aDDENLP, in otherEq, in otherIneq, in varargin)

concatenates the various constraints in this DDENLP instance for later optimitzation

Parameters

aDDENLP	instance of DDENLP
otherEq	additional equality constraints
otherIneq	additional inequality constraints

6.2.3.8 function concatlnitPoints (in aDDENLP)

concatenates the various variables in this DDENLP instance for later optimitzation

Parameters

aDDENLP	instance of DDENLP

6.2.3.9 function ddesd (in aDDENLP, in point, in history, in tspan, in options)

run a simulation of the optimum.

Overloading of ddesd

Parameters

aDDENLP	instance of DDENLP class	
point	parameters to use for simulation	
history	for simulation (like inital point ODE, but for DDE)	
tspan	time spaned by simulation	
options	options for solver	

Returns

sol is solution struct as known from ode45 etc

6.2.3.10 function deconstructInit (in aDDENLP, in type, in varargin)

reconstruct inital variables from single vector

Parameters

aDDENLP	instance of DDENLP class
type	(optional) string describing which points to reconstruct

Returns

(optional) return reconstruction to external variable

6.2.3.11 function deconstructOptimum (in aDDENLP)

reconstruct optimal variables from single vector

Parameters

aDDENLP	instance of DDENLP class

Returns

(optional) return reconstruction to external variable

6.2.3.12 function evaluateStatus (in aDDENLP)

evaluates the status of **DDENLP**

Parameters

aDDENLP	instance of DDENLP
---------	--------------------

6.2.3.13 function findManifoldPointOnLine (in ignoredArg, in type, in manifoldHandle, in point1, in point2, in maxEig)

look for a manifold point between two given points

Parameters

~	(ignore first input)
type	string of expected manifold type
manifoldHandle	function handle of manifold
point1	first point
point2	second point

Returns

intermediate Point

6.2.3.14 function initializeStSt (in aDDENLP)

intialize steady state constraint within a DDENLP instance

Parameters

aDDENLP	instance of DDENLP
---------	--------------------

6.2.3.15 function initializeStStRot (in aDDENLP)

intialize rotating steady state constraint within a DDENLP instance

Parameters

aDDENLP	instance of DDENLP
~~ · · - ·	

6.2.3.16 function initNVCons (in aDDENLP, in nVflipmode, in varargin)

initializes normal vector constraints by using a series of methods of the class NVConstraint

Parameters

aDDENLP	instance of DDENLP

6.2.3.17 function moveAwayFromManifolds (in aDDENLP, in steppingFactor, in distanceFactor, in)

moves the nominal point away from known critical manifolds methods of the class NVConstraint

Parameters

aDDENLP	instance of DDENLP
steppingFactor	(optional) step width of moving nominal point. Smaller value means slower convergence but
	better numerics, default is 0.7
distanceFactor	(optional) desired final minimal distance
iterations	(optional) number of iterations. Default is 20

6.2.3.18 function runOptim (in aDDENLP, in userDefinedOptions, in Aineq, in bineq, in varargin)

run optimization of DDENLP instance

Parameters

aDDENLP	instance of DDENLP
userDefinedOptions	(optional) user defined optimization options
Aineq	(optional) user defined linear inequality constraints
bineq	(optional) user defined linear inequality constraints

6.2.3.19 function runOptimAddingNewManifolds (in aDDENLP, in nlterBetweenStabChecks)

run optimization of DDENLP instance with intermediate stability checks.

Algorithm tries to add new critical manifold if one was crossed

Parameters

aDDENLP	instance of DDENLP	
nlterBetweenStabChecks	number of iterations between stability checks and potential manifold adding	

6.2.3.20 function runOptimMultipleInitPoints (in aDDENLP, in furtherInput, in varargin)

run optimization of DDENLP instance with many different initial points

Parameters

aDDENLP	instance of DDENLP
furtherInput	(optional) set of initial points to test

6.2.3.21 function runOptimWithStabChecks (in aDDENLP, in nlterBetweenStabChecks)

run optimization of DDENLP instance with intermediate stability checks.

Less iterations between stability checks lead to slower optimization, because optimizer has to cold start more frequently

Parameters

aDDENLP	instance of DDENLP
nlterBetweenStabChecks	number of iterations between stability checks

Returns

init initial point of optimization final final point of optimization maxEig biggest eigenvalue real part after optimization eigs rightmost eigenvalues after stability loss

6.2.4 Member Data Documentation

6.2.4.1 Property aCostFunction

cost function of the main steady state optimization problem

6.2.4.2 Property algVarIndex

indexes algebraic variables

6.2.4.3 Property allNLEqConstraints

function handle that collects all nonlinear equality constraints

6.2.4.4 Property allNLIneqConstraints

function handle that collects all nonlinear inequality constraints

6.2.4.5 Property allowedEigsInClosedRightHP

accepted eigenvalues in the closed right halfplane (for eigenvalues on the imaginary axis)

6.2.4.6 Property exitflag [protected]

exitflag of main optimization

6.2.4.7 Property fixedUncertParamIndex

contains the indices of parameters that are uncertain, but fixed

```
6.2.4.8 Property grad [protected]
gradient of cost function of main optimization
6.2.4.9 Property hessian [protected]
hessian of lagrange function of main optimization
6.2.4.10 Property initVal [protected]
initial value, length(initVal)==occupiedVars
6.2.4.11 Property lambda [protected]
lagrange multiplier of main optimization
6.2.4.12 Property lowerBoxCons
lower boundaries of box constraints
6.2.4.13 Property maxAllowedRealPart
the highest eigenvalue real part which is allowed
6.2.4.14 Property minDist
parameter uncertainty
6.2.4.15 Property nAlpha [protected]
number of uncertain parameters
6.2.4.16 Property nicon
function handle with the nonlinear constraints (inequality and equality)
6.2.4.17 Property nP [protected]
number of optimization parameters without uncertainty
```

```
6.2.4.18 Property numMinEig
real number, for DDE-BIFTOOL numerics
6.2.4.19 Property NVCon
normal vector constraints, vector of objects of class NVConstraint
6.2.4.20 Property nX [protected]
number of states
6.2.4.21 Property occupiedEqs [protected]
number of equality constraints in whole optimization problem
6.2.4.22 Property occupiedIneqs [protected]
number of inequality constraints in whole optimization problem
6.2.4.23 Property occupiedVars [protected]
number of variables in whole optimization problem
6.2.4.24 Property optimOutput [protected]
status message of main optimization
6.2.4.25 Property optimVal [protected]
optimal value, should be a vector of length(optimVal)==occupiedVars
6.2.4.26 Property optionsInitEqCons
options for initialization numerics (fsolve)
6.2.4.27 Property optionsInitOptim
options for initialization numerics (auxiliary optimization)
```

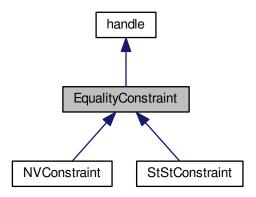
```
6.2.4.28 Property optionsMainOptim
options for the main optimization
6.2.4.29 Property optJ [protected]
cost at optimum
6.2.4.30 Property problemDDE
object of class DDE, contains all relevant DDE information
6.2.4.31 Property status [protected]
status of this optimization problem, (key in main description)
6.2.4.32 Property stStCon
steady state constraint class StStConstraint
6.2.4.33 Property upperBoxCons
lower boundaries of box constraints
6.2.4.34 Property useLHS
flag for using latin hypercube sample for evaluating the uncertainty region
6.2.4.35 Property vars
structure containing the cell array of variables, find entries with ind=find(ismember...
6.2.4.36 Property verifyStabPoints
$$ {verifyStabPoints}^{nAlpha} $$ random points are generated and evaluated
The documentation for this class was generated from the following file:
```

@DDENLP/DDENLP.m

6.3 EqualityConstraint Class Reference

(abstract) class that inherits its properities to equality constraints

Inheritance diagram for EqualityConstraint:



Public Member Functions

- function EqualityConstraint (in conFunHandle, in nEqs, in vars, in eqOffset)
 Class constructor.
- function shiftIndex (in anEqCon, in eqShift, in varShift)
 shift the index of the equations stored in this equality constraint

Public Attributes

Property vars

collection of variables of class VariableVector on which the instance of EqualityConstraint depends on

Protected Attributes

• Property conFun

function handle representin the constraint function

• Property eqIndex

indices of the equation in the superordinate constraint optimization problem

Property nEqs

number of equation in this instance of EqualityConstraint

• Property status

initialization status of this instance of EqualityConstraint

6.3.1 Detailed Description

(abstract) class that inherits its properities to equality constraints

The properties are necessary to manage mulliple classes of equality constraints

6.3.2 Constructor & Destructor Documentation

6.3.2.1 function EqualityConstraint (in conFunHandle, in nEqs, in vars, in eqOffset)

Class constructor.

This function constructs instances of the class EqualityConstraint

Parameters

conFunHandle	function handle for equality constraint
nEqs	number of equations in this equality constraint
vars	collection of instances of VariableVector
eqOffset	offset for equation indices

Returns

instance of the EqualityConstraint class.

6.3.3 Member Function Documentation

6.3.3.1 function shiftIndex (in anEqCon, in eqShift, in varShift)

shift the index of the equations stored in this equality constraint

Parameters

anEqCon	Instance of EqualityConstraint, where the variable equation will be shifted
eqShift	how far the index of equations will be shifted
varShift	how far the index of variables will be shifted

Returns

instance of the EqualityConstraint class.

6.3.4 Member Data Documentation

6.3.4.1 Property conFun [protected]

function handle representin the constraint function

6.3.4.2 Property eqindex [protected]

indices of the equation in the superordinate constraint optimization problem

6.3.4.3 Property nEqs [protected]

number of equation in this instance of EqualityConstraint

6.3.4.4 Property status [protected]

initialization status of this instance of EqualityConstraint

6.3.4.5 Property vars

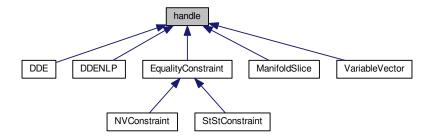
collection of variables of class VariableVector on which the instance of EqualityConstraint depends on

The documentation for this class was generated from the following file:

• @EqualityConstraint/EqualityConstraint.m

6.4 handle Class Reference

Inheritance diagram for handle:



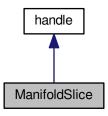
The documentation for this class was generated from the following file:

• @VariableVector/VariableVector.m

6.5 ManifoldSlice Class Reference

The instances of this class generate visualization data.

Inheritance diagram for ManifoldSlice:



Public Member Functions

- function ManifoldSlice (in aNVCon, in continParamsInd, in varargin)

 Class constructor.
- function maniContin2DbothDirections (in aManifoldSlice, in n)

runs numerical continuation in both directions

- function manifoldContinuation2D (in aManifoldSlice, in direction)
 - runs numerical continuation in one directions
- function plot (in aManifoldSlice)
 - plots results of numerical continuation of critical manifolds
- function quiver (in aManifoldSlice)

Public Attributes

- Property freeParamIndices
 - indeces for free parameters for numerical continuation
- Property nManiPoints
 - number of steps to take during numerical continuation
- Property initStepLength
 - initial step length
- Property stepLength
 - step length during numerical continuation
- · Property point
 - the manifold points resulting form numerical continuation
- Property eqAugSys
 - equations defining the manifold
- Property eqNVSys
 - normal vector system of manifold
- Property maxStepLength
 - bounds step length

Property lowerBoxCons

lower bounds to stop numerical continuation

• Property upperBoxCons

upper bounds to stop numerical continuation

Property showStepsFlag

each step is displayed in a figure, if this is set to 1

· Property debugFlag

enables warnings for debugging if set to 1

6.5.1 Detailed Description

The instances of this class generate visualization data.

Author

Jonas Otten

Date

18 Jul 2017 The instances of this class generate visualization data

This class simplyfies visualization of critical manifolds. Two dimensional numerical continuation calculates "slices" of the manifolds, which can be plotted using the methods of this class.

this class is allows easy visualization of optimization results by implementing a quasi-arclength numerical continuation of critical manifolds.

Author

Jonas Otten

Date

18 Jul 2017

6.5.2 Constructor & Destructor Documentation

6.5.2.1 function ManifoldSlice (in aNVCon, in continParamsInd, in varargin)

Class constructor.

This function constructs instances of the class ManifoldSlice

Parameters

aNVCon	an instance of the class NVConstraint. Its critical manifold will be visualized
continParamsInd	the index of the parameters used for continuation
varargin	enables to call constructor ommitting continParamsInd

Returns

instance of the ManifoldSlice class.

6.5.3 Member Function Documentation

6.5.3.1 function maniContin2DbothDirections (in a Manifold Slice, in n)

runs numerical continuation in both directions

Parameters

aManifoldSlice	instance of this class
n	number of steps to take during continuation

6.5.3.2 function manifoldContinuation2D (in aManifoldSlice, in direction)

runs numerical continuation in one directions

Parameters

aManifoldSlice	instance of this class
direction	determines direction for continuation

6.5.3.3 function plot (in aManifoldSlice)

plots results of numerical continuation of critical manifolds

Parameters

aManifoldSlice instance of this

Returns

handle vector of plot handles allowing later manipulation of plots

6.5.3.4 function quiver (in aManifoldSlice)

6.5.4 Member Data Documentation

6.5.4.1 Property debugFlag

enables warnings for debugging if set to 1

6.5.4.2 Property eqAugSys
equations defining the manifold
6.5.4.3 Property eqNVSys
normal vector system of manifold
6.5.4.4 Property freeParamIndices
indeces for free parameters for numerical continuation
6.5.4.5 Property initStepLength
initial step length
6.5.4.6 Property lowerBoxCons
lower bounds to stop numerical continuation
6.5.4.7 Property maxStepLength
bounds step length
6.5.4.8 Property nManiPoints
number of steps to take during numerical continuation
6.5.4.9 Property point
the manifold points resulting form numerical continuation
6.5.4.10 Property showStepsFlag
each step is displayed in a figure, if this is set to 1
6.5.4.11 Property stepLength
step length during numerical continuation

6.5.4.12 Property upperBoxCons

upper bounds to stop numerical continuation

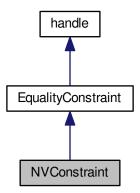
The documentation for this class was generated from the following file:

• @ManifoldSlice/ManifoldSlice.m

6.6 NVConstraint Class Reference

the instances of this class are objects representing normal vector constraints.

Inheritance diagram for NVConstraint:



Public Member Functions

- function NVConstraint (in aDDENLP, in type, in augSysHandle, in nVSysHandle, in nVvars) Class constructor.
- function prepareInitialGuess (in aNVCon, in aVarCollection)

rotates complex eigenvector to make real and imaginary part orthogonal cf.

function findManifoldPoint (in aNVCon, in aVarCollection)

find a point on the critical manifold

• function findEigVector (in aNVCon, in aVarCollection)

find an eigenvector of a critical manifold point candidate

• function findClosestCriticalPoint (in aNVCon, in alphaNom)

find closest critical point

• function findNormalVector (in aNVCon, in alphaNom, in directionMode, in varargin)

find normal vector at given closest critical point

• function findConnection (in aNVCon, in alphaNom)

initialize connection constraint

function checkSolution (in aNVCon)

checks if a solution fits the requested manifold type

function shiftIndex (in anEqCon, in eqShift, in varShift)

shift the index of the equations stored in this equality constraint

Public Attributes

· Property type

critical manifold type, string

Property eqAugSys

augmented system equations (manifold), a EqualityConstraint object

Property eqNVSys

normal vector system equations, a EqualityConstraint object

Property eqConnect

connection constraints, a EqualityConstraint object

• Property nVarAugSys

number of variables in augemented system

Property nVarNVSys

number of variables in normal vector system

· Property inequalities

function handle of inequalities

• Property optionsEqConsInit

options for numerical solver

Property optionsInitOptim

options for auxiliary optimization

Property vars

collection of variables of class VariableVector on which the instance of EqualityConstraint depends on

Protected Attributes

· Property inequalityIndex

index of the inequality constraint of this NVConstraint within all constaints

• Property problemDDE

differential equation for calculation of stability

· Property numMinEig

numerical constant for the ODE approximation of the DDE

• Property conFun

function handle representin the constraint function

• Property eqIndex

indices of the equation in the superordinate constraint optimization problem

• Property nEqs

number of equation in this instance of EqualityConstraint

Property status

initialization status of this instance of EqualityConstraint

6.6.1 Detailed Description

the instances of this class are objects representing normal vector constraints.

The procedures initialize those constraints

6.6.2 Constructor & Destructor Documentation

6.6.2.1 function NVConstraint (in aDDENLP, in type, in augSysHandle, in nVSysHandle, in nVvars)

Class constructor.

This function constructs instances of the class NVConstraint

Parameters

aDDENLP	superordinate optimization problem
type	type of critical manifold (string)
augSysHandle	function handle to critical manifold
nVSysHandle	function handle to normal vector system
nVvars	collection of instances of VariableVector

Returns

instance of the NVConstraint class.

6.6.3 Member Function Documentation

6.6.3.1 function checkSolution (in aNVCon)

checks if a solution fits the requested manifold type

Parameters

aNVCon	instance of NVConstraint
--------	--------------------------

Returns

6.6.3.2 function findClosestCriticalPoint (in aNVCon, in alphaNom)

find closest critical point

Parameters

aNVCon	instance of NVConstraint with a know point on the critical manifold
alphaNom	nominal point stored in an instance of VariableVector

Returns

instance of NVConstraint with potentially known closest critical point

6.6.3.3 function findConnection (in aNVCon, in alphaNom)

initialize connection constraint

Parameters

aNVCon	instance of NVConstraint with everything but connection constraint initialized
- I - I - A I	and the state of t
aipnainom	nominal point stored in an instance of Variable Vector
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Returns

instance of NVConstraint with potentially initialized connection constraint

6.6.3.4 function findEigVector (in aNVCon, in aVarCollection)

find an eigenvector of a critical manifold point candidate

Parameters

aNVCon	instance of NVConstraint that will initialized
aVarCollection	collection of instances of VariableVector containing numerical values for initial guess

Returns

instance of NVConstraint with potentially known

6.6.3.5 function findManifoldPoint (in aNVCon, in aVarCollection)

find a point on the critical manifold

Parameters

aNVCon	instance of NVConstraint that will initialized
aVarCollection	collection of instances of VariableVector containing numerical values for initial guess

Returns

instance of NVConstraint with potentially known critical point

6.6.3.6 function findNormalVector (in aNVCon, in alphaNom, in directionMode, in varargin)

find normal vector at given closest critical point

Parameters

aNVCon	instance of NVConstraint with known closest critical point
alphaNom	nominal point stored in an instance of VariableVector
directionMode	optional input to manipulate orientation of
varargin	

Returns

instance of NVConstraint with normal vectors etc. found

6.6.3.7 function prepareInitialGuess (in aNVCon, in aVarCollection)

rotates complex eigenvector to make real and imaginary part orthogonal cf.

Proof of Lemma 1 in [https://doi.org/10.1109/CDC.2016.7798469]

Parameters

aNVCon	instance of NVConstraint that will initialized
aVarCollection	collection of instances of VariableVector containing numerical values for initial guess

Returns

instance of NVConstraint with potentially known critical point collection of instances of VariableVector with orthogonalized real part and imaginary part of eigenvector

6.6.3.8 function shiftIndex (in anEqCon, in eqShift, in varShift) [inherited]

shift the index of the equations stored in this equality constraint

Parameters

anEqCon	Instance of EqualityConstraint, where the variable equation will be shifted
eqShift	how far the index of equations will be shifted
varShift	how far the index of variables will be shifted

Returns

instance of the EqualityConstraint class.

6.6.4 Member Data Documentation

6.6.4.1 Property conFun [protected], [inherited]

function handle representin the constraint function

6.6.4.2 Property eqAugSys

augmented system equations (manifold), a EqualityConstraint object

6.6.4.3 Property eqConnect

connection constraints, a EqualityConstraint object

```
6.6.4.4 Property eqIndex [protected], [inherited]
indices of the equation in the superordinate constraint optimization problem
6.6.4.5 Property eqNVSys
normal vector system equations, a EqualityConstraint object
6.6.4.6 Property inequalities
function handle of inequalities
6.6.4.7 Property inequalityIndex [protected]
index of the inequality constraint of this NVConstraint within all constaints
6.6.4.8 Property nEqs [protected], [inherited]
number of equation in this instance of EqualityConstraint
6.6.4.9 Property numMinEig [protected]
numerical constant for the ODE approximation of the DDE
6.6.4.10 Property nVarAugSys
number of variables in augemented system
6.6.4.11 Property nVarNVSys
number of variables in normal vector system
6.6.4.12 Property optionsEqConsInit
options for numerical solver
6.6.4.13 Property optionsInitOptim
options for auxiliary optimization
```

```
6.6.4.14 Property problemDDE [protected]
```

differential equation for calculation of stability

```
6.6.4.15 Property status [protected], [inherited]
```

initialization status of this instance of EqualityConstraint

6.6.4.16 Property type

critical manifold type, string

```
6.6.4.17 Property vars [inherited]
```

collection of variables of class VariableVector on which the instance of EqualityConstraint depends on

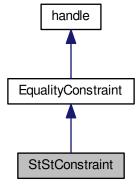
The documentation for this class was generated from the following file:

• @NVConstraint/NVConstraint.m

6.7 StStConstraint Class Reference

This class describes equality constraints representing the steady state condition for the nominal parameters.

Inheritance diagram for StStConstraint:



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Public Member Functions

function StStConstraint (in aDDE, in vars)

Class constructor.

function initStStConstraint (in aStStCon, in options)

look for a steady state as initialization of this StStConstraint instance

• function initStStConstraintRot (in aStStCon, in options)

look for a steady state as initialization of this StStConstraint instance while allowing rotating coordinates

• function shiftIndex (in anEqCon, in eqShift, in varShift)

shift the index of the equations stored in this equality constraint

Public Attributes

· Property vars

collection of variables of class VariableVector on which the instance of EqualityConstraint depends on

Protected Attributes

· Property conFun

function handle representin the constraint function

Property eqIndex

indices of the equation in the superordinate constraint optimization problem

Property nEqs

number of equation in this instance of EqualityConstraint

· Property status

initialization status of this instance of EqualityConstraint

6.7.1 Detailed Description

This class describes equality constraints representing the steady state condition for the nominal parameters.

It also contains a procedure to initialize the constraint

6.7.2 Constructor & Destructor Documentation

6.7.2.1 function StStConstraint (in aDDE, in vars)

Class constructor.

This function constructs instances of the class StStConstraint

Parameters

aDDE	instance of class DDE
vars	collection of instances of VariableVector (at least state, uncertain parameters and certain parameters)

Returns

instance of the StStConstraint class.

6.7.3 Member Function Documentation

6.7.3.1 function initStStConstraint (in aStStCon, in options)

look for a steady state as initialization of this StStConstraint instance

Parameters

aStStCon	instance of StStConstraint which will be initialized
options	options for numerical solver fsolve

Returns

initialized instance of the StStConstraint class.

6.7.3.2 function initStStConstraintRot (in aStStCon, in options)

look for a steady state as initialization of this StStConstraint instance while allowing rotating coordinates

Parameters

aStStCon	instance of StStConstraint which will be initialized
options	options for numerical solver fsolve

Returns

initialized instance of the StStConstraint class.

6.7.3.3 function shiftIndex (in an EqCon, in eqShift, in varShift) [inherited]

shift the index of the equations stored in this equality constraint

Parameters

anEqCon Instance of EqualityConstraint, where the variable equation will lead to the constraint of the	
eqShift	how far the index of equations will be shifted
varShift	how far the index of variables will be shifted

Returns

instance of the EqualityConstraint class.

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6.7.4 Member Data Documentation

6.7.4.1 Property conFun [protected], [inherited]

function handle representin the constraint function

6.7.4.2 Property eqlndex [protected], [inherited]

indices of the equation in the superordinate constraint optimization problem

6.7.4.3 Property nEqs [protected], [inherited]

number of equation in this instance of EqualityConstraint

6.7.4.4 Property status [protected], [inherited]

initialization status of this instance of EqualityConstraint

6.7.4.5 Property vars [inherited]

collection of variables of class VariableVector on which the instance of EqualityConstraint depends on

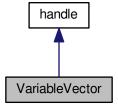
The documentation for this class was generated from the following file:

• @StStConstraint/StStConstraint.m

6.8 VariableVector Class Reference

The instances of this class contain information for a Variable Vector used in DDENLP.

Inheritance diagram for VariableVector:



Public Member Functions

• function VariableVector (in values, in offset, in nameInput)

Class constructor.

• function shiftIndex (in aVariableVec, in shift)

shift the index of the variables stored in this vector

• function copy (in aVariableVec)

this method creates a copy of an instance of VariableVector, necessary, because the superclass is the pointerlike handle-class

Public Attributes

· Property values

column vector containing the numerical values of the Variables

Protected Attributes

· Property names

column array of strings containing the description of the variables

Property index

indexes of variable within superordinate concatenation of variables

· Property nVar

number of variables

6.8.1 Detailed Description

The instances of this class contain information for a Variable Vector used in DDENLP.

Those instances collect human-readable information on the variables (their names and values) as well as the information which is used by other objects to adress those variables.

6.8.2 Constructor & Destructor Documentation

6.8.2.1 function Variable Vector (in values, in offset, in nameInput)

Class constructor.

This function constructs instances of the class Variable Vector

Parameters

values	Description of first parameter
offset	Description of the second parameter
nameInput	Description of the second parameter

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Returns

instance of the VariableVector class.

6.8.3 Member Function Documentation

6.8.3.1 function copy (in aVariableVec)

this method creates a copy of an instance of VariableVector, necessary, because the superclass is the pointerlike handle-class

Parameters

Returns

new instance of the Variable Vector class.

6.8.3.2 function shiftIndex (in aVariable Vec, in shift)

shift the index of the variables stored in this vector

Parameters

aVariableVec	Instance of VariableVector, where the variable indices will be shifted
shift	how far the index will be shifted

Returns

instance of the VariableVector class.

6.8.4 Member Data Documentation

```
6.8.4.1 Property index [protected]
```

indexes of variable within superordinate concatenation of variables

6.8.4.2 Property names [protected]

column array of strings containing the description of the variables

6.8.4.3 Property nVar [protected]

number of variables

6.8.4.4 Property values

column vector containing the numerical values of the Variables

The documentation for this class was generated from the following file:

• @VariableVector/VariableVector.m

54 Class Documentation

Chapter 7

File Documentation

7.1 @DDE/DDE.m File Reference

The instances of this class contain information for a DDE used in DDENLP.

Classes

• class DDE

The instances of this class contain information for a DDE used in DDENLP.

7.1.1 Detailed Description

The instances of this class contain information for a DDE used in DDENLP.

Author

Jonas Otten

Date

18 Jul 2017

7.2 @DDENLP/DDENLP.m File Reference

Classes

class DDENLP

this class desribes the whole optimization problem for delayed systems

7.3 @EqualityConstraint/EqualityConstraint.m File Reference

(abstract) class that inherits its properities to equality constraints

Classes

class EqualityConstraint

(abstract) class that inherits its properities to equality constraints

7.3.1 Detailed Description

(abstract) class that inherits its properities to equality constraints

Author

Jonas Otten

Date

18 Jul 2017

7.4 @ManifoldSlice/ManifoldSlice.m File Reference

Classes

· class ManifoldSlice

The instances of this class generate visualization data.

7.5 @NVConstraint/NVConstraint.m File Reference

the instances of this class are objects representing normal vector constraints.

Classes

class NVConstraint

the instances of this class are objects representing normal vector constraints.

7.5.1 Detailed Description

the instances of this class are objects representing normal vector constraints.

The procedures initialize those constraints

Author

Jonas Otten

Date

18 Jul 2017

7.6 @StStConstraint/StStConstraint.m File Reference

class that inherits its properities from EqualityConstraints.

Classes

class StStConstraint

This class describes equality constraints representing the steady state condition for the nominal parameters.

7.6.1 Detailed Description

class that inherits its properities from EqualityConstraints.

It represents steady state constraints.

Author

Jonas Otten

Date

18 Jul 2017

7.7 @ Variable Vector/Variable Vector.m File Reference

The instances of this class contain information for a Variable Vector used in DDENLP.

Classes

· class VariableVector

The instances of this class contain information for a Variable Vector used in DDENLP.

7.7.1 Detailed Description

The instances of this class contain information for a Variable Vector used in DDENLP.

Author

Jonas Otten

Date

18 Jul 2017

7.8 checkStability.m File Reference

Functions

• function checkStability (in funcs, in parameter, in x0, in numMinEig, in freeParams)

7.8.1 Function Documentation

7.8.1.1 function checkStability (in funcs, in parameter, in x0, in numMinEig, in freeParams)

7.9 circle.m File Reference

Functions

• function circle (in radius, in x, in y)

7.9.1 Function Documentation

7.9.1.1 function circle (in radius, in x, in y)

7.10 demo/optimPopulationTestManifoldSlice.m File Reference

- 7.11 demo/populationModelModFoldMani.c File Reference
- 7.12 ExampleApplications/TDS2016Population/populationModelModFoldMani.c File Reference
- 7.13 demo/populationModelModFoldNV.c File Reference
- 7.14 ExampleApplications/TDS2016Population/populationModelModFoldNV.c File Reference
- 7.15 ExampleApplications/CDC2016SupplyChain/supplyChainDelays.m File Reference

Functions

• function supplyChainDelays (in xx, in alpha, in ignoredArg)

7.15.1 Function Documentation 7.15.1.1 function supplyChainDelays (in xx, in alpha, in ignoredArg) ExampleApplications/CDC2016SupplyChain/supplyChainHopfMani.c File Reference 7.16 7.17 ExampleApplications/CDC2016SupplyChain/supplyChainHopfNV.c File Reference 7.18 ExampleApplications/CDC2016SupplyChain/supplyChainModel.m File Reference **Functions** • function supplyChainModel (in x, in xtau, in alpha, in ignoredArg) 7.18.1 Function Documentation 7.18.1.1 function supplyChainModel (in x, in xtau, in alpha, in ignoredArg) ExampleApplications/CDC2016SupplyChain/supplyChainOptim.m File Reference ExampleApplications/CDC2016SupplyChain/supplyChainOptimAcceptingTwo 7.20 EigsInRightHP.m File Reference 7.21 ExampleApplications/CoupledCSTRs/allNCSTROptim.m File Reference ExampleApplications/CoupledCSTRs/defineROIWeightingNCSTR.m File Reference

ExampleApplications/CoupledCSTRs/NCSTRdelays.m File Reference

Functions

7.23

function NCSTRdelays (in k, in ignoredArg, in p)

- 7.23.1 Function Documentation
- 7.23.1.1 function NCSTRdelays (in k, in ignoredArg, in p)
- 7.24 ExampleApplications/CoupledCSTRs/oneCSTRwithFlashSep/oneCSTRoneFlash← SepDDE.c File Reference
- 7.25 ExampleApplications/CoupledCSTRs/oneCSTRwithFlashSep/oneCSTRoneFlash← SepHopfMani.c File Reference
- 7.26 ExampleApplications/CoupledCSTRs/oneCSTRwithFlashSep/oneCSTRoneFlash
 SepHopfManiNV.c File Reference
- 7.27 ExampleApplications/CoupledCSTRs/oneCSTRwithFlashSep/oneCSTROptim.m File Reference

Functions

- · function dbstack ()
- 7.27.1 Function Documentation
- 7.27.1.1 function dbstack ()
- 7.28 ExampleApplications/CoupledCSTRs/oneCSTRwithFlashSep/returnOnInvest1.m File Reference

Functions

- function returnOnInvest1 (in x)
- 7.28.1 Function Documentation
- 7.28.1.1 function returnOnInvest1 (in x)
- 7.29 ExampleApplications/CoupledCSTRs/reactorCost.m File Reference

Functions

function reactorCost (in V)

- 7.29.1 Function Documentation
- 7.29.1.1 function reactorCost (in V)
- 7.30 ExampleApplications/CoupledCSTRs/setNCSTRBoundaries.m File Reference
- 7.31 ExampleApplications/CoupledCSTRs/threeCSTRwithFlashSep/returnOnInvest3.m File Reference

Functions

- function returnOnInvest3 (in x)
- 7.31.1 Function Documentation
- 7.31.1.1 function returnOnInvest3 (in x)
- 7.32 ExampleApplications/CoupledCSTRs/threeCSTRwithFlashSep/threeCSTRone FlashSepDDE.c File Reference
- 7.33 ExampleApplications/CoupledCSTRs/threeCSTRwithFlashSep/threeCSTRone FlashSepFoldMani.c File Reference
- 7.34 ExampleApplications/CoupledCSTRs/threeCSTRwithFlashSep/threeCSTRone FlashSepFoldManiNV.c File Reference
- 7.35 ExampleApplications/CoupledCSTRs/threeCSTRwithFlashSep/threeCSTRone ← FlashSepHopfMani.c File Reference
- 7.36 ExampleApplications/CoupledCSTRs/threeCSTRwithFlashSep/threeCSTRone FlashSepHopfManiNV.c File Reference
- 7.37 ExampleApplications/CoupledCSTRs/threeCSTRwithFlashSep/threeCSTROptim.m File Reference

Functions

function dbstack ()

7.37.1 Function Documentation

```
7.37.1.1 function dbstack ( )
```

- 7.38 ExampleApplications/CoupledCSTRs/threeCSTRwithFlashSep/threeCSTRStab.m File Reference
- 7.39 ExampleApplications/CoupledCSTRs/threeCSTRwithFlashSep/tmp.m File Reference
- 7.40 ExampleApplications/CoupledCSTRs/twoCSTRwithFlashSep/returnOnInvest2.m File Reference

Functions

- function returnOnInvest2 (in x)
- 7.40.1 Function Documentation
- 7.40.1.1 function returnOnInvest2 (in x)
- 7.41 ExampleApplications/CoupledCSTRs/twoCSTRwithFlashSep/twoCSTRoneFlash← SepDDE.c File Reference
- 7.42 ExampleApplications/CoupledCSTRs/twoCSTRwithFlashSep/twoCSTRoneFlash SepHopfMani.c File Reference
- 7.43 ExampleApplications/CoupledCSTRs/twoCSTRwithFlashSep/twoCSTRoneFlash ← SepHopfManiNV.c File Reference
- 7.44 ExampleApplications/CoupledCSTRs/twoCSTRwithFlashSep/twoCSTROptim.m File Reference

Functions

function dbstack ()

- 7.44.1 Function Documentation
- 7.44.1.1 function dbstack ()
- 7.45 ExampleApplications/CoupledLasers/10L_symm/DDE_10L_symm.c File Reference
- 7.46 ExampleApplications/CoupledLasers/10L_symm/Mod_Fold_10L_symm.c File Reference
- 7.47 ExampleApplications/CoupledLasers/10L_symm/NV_Mod_Fold_10L_symm.c File Reference
- 7.48 ExampleApplications/CoupledLasers/10L_symm/optim_10L_symm_ausnutzung_
 symm.m File Reference
- 7.49 ExampleApplications/CoupledLasers/2L_symm/Laser_DDE_2L.c File Reference
- 7.50 ExampleApplications/CoupledLasers/2L_symmOldModel/Laser_DDE_2L.c File Reference
- 7.51 ExampleApplications/CoupledLasers/2L_symmOldParam/Laser_DDE_2L.c File Reference
- 7.52 ExampleApplications/CoupledLasers/2L_symm/maniPlotter2L.m File Reference
- 7.53 ExampleApplications/CoupledLasers/2L_symmOldModel/maniPlotter2L.m File Reference
- 7.54 ExampleApplications/CoupledLasers/2L_symmOldParam/maniPlotter2L.m File Reference
- 7.55 ExampleApplications/CoupledLasers/2L symm/Mod Fold 2L.c File Reference
- 7.56 ExampleApplications/CoupledLasers/2L_symmOldModel/Mod_Fold_2L.c File Reference

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7.58	ExampleApplications/CoupledLasers/2L_symm/NV_Mod_Fold_2L.c File Referen	nce
7.59	ExampleApplications/CoupledLasers/2L_symmOldModel/NV_Mod_Fold_2L.c Reference	File
7.60	ExampleApplications/CoupledLasers/2L_symmOldParam/NV_Mod_Fold_2L.c Reference	File
7.61	ExampleApplications/CoupledLasers/2L_symm/optim2LRobSync.m File Reference	nce
7.62	ExampleApplications/CoupledLasers/2L_symmOldModel/optim2LRobSync.m Reference	File
7.63	ExampleApplications/CoupledLasers/2L_symmOldParam/optim2LRobSync.m Reference	File
7.64	ExampleApplications/CoupledLasers/2L_symm/optim2LRobSyncRobPlot.m Reference	File
7.65	ExampleApplications/CoupledLasers/2L_symmOldModel/optim2LRobSyncRobPlot.m File Reference	-
7.66	ExampleApplications/CoupledLasers/2L_symmOldParam/optim2LRobSyncRob Plot.m File Reference	\leftarrow
7.67	ExampleApplications/CoupledLasers/2L_symm/optim2LSync.m File Reference	
7.68	ExampleApplications/CoupledLasers/2L_symmOldModel/optim2LSync.m File erence	Ref-
7.69	ExampleApplications/CoupledLasers/2L_symmOldParam/optim2LSync.m File erence	Ref-

- 7.70 ExampleApplications/CoupledLasers/2L_symm/plotCostFun.m File Reference
- 7.71 ExampleApplications/CoupledLasers/2L_symmOldModel/plotCostFun.m File Reference
- 7.72 ExampleApplications/CoupledLasers/2L_symmOldParam/plotCostFun.m File Reference
- 7.73 ExampleApplications/CoupledLasers/3L_symm/plotCostFun.m File Reference
- 7.74 ExampleApplications/CoupledLasers/3L_symmOldParam/plotCostFun.m File Reference
- 7.75 ExampleApplications/CoupledLasers/2L_symm/unstab_2L_omega_in_p_2_Con.m File Reference
- 7.76 ExampleApplications/CoupledLasers/2L_symmOldModel/unstab_2L_omega_in_p

 _2_Con.m File Reference
- 7.77 ExampleApplications/CoupledLasers/2L_symmOldParam/unstab_2L_omega_in_ p_2_Con.m File Reference
- 7.78 ExampleApplications/CoupledLasers/3L_asymm/Bifurkationen_3L_asymm_fsolve
 Schnittgeraden neu.m File Reference
- 7.79 ExampleApplications/CoupledLasers/3L_asymmOldParam/Bifurkationen_3L_ asymm_fsolve_Schnittgeraden_neu.m File Reference
- 7.80 ExampleApplications/CoupledLasers/3L_asymm/createParamSpacePlots.m File Reference
- 7.81 ExampleApplications/CoupledLasers/3L_asymmOldParam/createParamSpace Plots.m File Reference
- 7.82 ExampleApplications/CoupledLasers/3L_symm/createParamSpacePlots.m File Reference

7.83 ExampleApplications/CoupledLasers/3L_symmOldParam/createParamSpace Plots.m File Reference

- 7.84 ExampleApplications/CoupledLasers/3L_asymm/DDE_3L_SETUP_1.c File Reference
- 7.85 ExampleApplications/CoupledLasers/3L_asymmOldParam/DDE_3L_SETUP_1.c File Reference
- 7.86 ExampleApplications/CoupledLasers/3L_asymm/Mod_Fold_3L_SETUP_1.c File Reference
- 7.87 ExampleApplications/CoupledLasers/3L_asymmOldParam/Mod_Fold_3L_SETUP

 _1.c File Reference
- 7.88 ExampleApplications/CoupledLasers/3L_asymm/Mod_Hopf_3L_SETUP_1.c File Reference
- 7.89 ExampleApplications/CoupledLasers/3L_asymmOldParam/Mod_Hopf_3L_SETUP← 1.c File Reference
- 7.91 ExampleApplications/CoupledLasers/3L_asymm/optim_3L_Setup1_Ausarbeitung.m File Reference
- 7.92 ExampleApplications/CoupledLasers/3L_asymmOldParam/optim_3L_Setup1_

 Ausarbeitung.m File Reference
- 7.93 ExampleApplications/CoupledLasers/3L_asymm/NV_Mod_Fold_3L_SETUP_1.c File Reference
- 7.94 ExampleApplications/CoupledLasers/3L_asymmOldParam/NV_Mod_Fold_3L_SE

 TUP 1.c File Reference

- 7.95 ExampleApplications/CoupledLasers/3L_asymm/NV_Mod_Hopf_3L_SETUP_1.c File Reference
- 7.96 ExampleApplications/CoupledLasers/3L_asymmOldParam/NV_Mod_Hopf_3L_SE

 TUP_1.c File Reference
- 7.97 ExampleApplications/CoupledLasers/3L_asymm/optim_3L_Setup1_find_Start.m File Reference
- 7.98 ExampleApplications/CoupledLasers/3L_asymmOldParam/optim_3L_Setup1_find
 __Start.m File Reference
- 7.99 ExampleApplications/CoupledLasers/3L_asymm/prepareManifoldFig.m File Reference
- 7.100 ExampleApplications/CoupledLasers/3L_asymmOldParam/prepareManifoldFig.m File Reference
- 7.101 ExampleApplications/CoupledLasers/3L_asymm/Pump_3L_fixed_K_fsolve_
 Guete.m File Reference
- 7.102 ExampleApplications/CoupledLasers/3L_asymmOldParam/Pump_3L_fixed_K_← fsolve_Guete.m File Reference
- 7.103 ExampleApplications/CoupledLasers/3L_asymm/Syncmanifold_3L_Setup1_fkt.m File Reference

Functions

- function Syncmanifold_3L_Setup1_fkt (in var, in pump, in omega)
- 7.103.1 Function Documentation
- 7.103.1.1 function Syncmanifold_3L_Setup1_fkt (in var, in pump, in omega)
- 7.104 ExampleApplications/CoupledLasers/3L_asymmOldParam/Syncmanifold_3L_
 Setup1_fkt.m File Reference

Functions

• function Syncmanifold_3L_Setup1_fkt (in var, in pump, in omega)

7.104.1	Function Documentation
7.104.1.1	function Syncmanifold_3L_Setup1_fkt (in var, in pump, in omega)
7.105	ExampleApplications/CoupledLasers/3L_asymmOldParam/optim_3L_Setup1_← Ausarbeitung_incl_plot.m File Reference
7.106	ExampleApplications/CoupledLasers/3L_symm/Bifurkationen_3L_symm_fsolve ←Schnittgeraden.m File Reference
7.107	ExampleApplications/CoupledLasers/3L_symmOldParam/Bifurkationen_3L_ symm_fsolve_Schnittgeraden.m File Reference
7.108	ExampleApplications/CoupledLasers/3L_symm/DDE_3L_symm.c File Reference
7.109	ExampleApplications/CoupledLasers/3L_symmOldParam/DDE_3L_symm.c File Reference
7.110	ExampleApplications/CoupledLasers/3L_symm/Mod_Fold_3L_symm.c File Reference
7.111	ExampleApplications/CoupledLasers/3L_symmOldParam/Mod_Fold_3L_symm.c File Reference
7.112	ExampleApplications/CoupledLasers/3L_symm/NV_Mod_Fold_3L_symm.c File Reference
7.113	ExampleApplications/CoupledLasers/3L_symmOldParam/NV_Mod_Fold_3L_ symm.c File Reference
7.114	ExampleApplications/CoupledLasers/3L_symm/optim_3L_symm.m File Reference
7.115	ExampleApplications/CoupledLasers/3L_symmOldParam/optim_3L_symm.m File Reference
7.116	ExampleApplications/CoupledLasers/3L_symm/Pump_3L_fsolve_Guete.m File

Reference

- 7.117 ExampleApplications/CoupledLasers/3L_symmOldParam/Pump_3L_fsolve_← Guete.m File Reference
- 7.118 ExampleApplications/CoupledLasers/3L_symm/Syncmanifold_3L_fkt.m File Reference

Functions

- function Syncmanifold_3L_fkt (in var, in pump)
- 7.118.1 Function Documentation
- 7.118.1.1 function Syncmanifold_3L_fkt (in var, in pump)
- 7.119 ExampleApplications/CoupledLasers/3L_symmOldParam/Syncmanifold_3L_fkt.m File Reference

Functions

- function Syncmanifold 3L fkt (in var, in pump)
- 7.119.1 Function Documentation
- 7.119.1.1 function Syncmanifold_3L_fkt (in var, in pump)
- 7.120 ExampleApplications/DiffLaser/CodeGeneration/diff11LaserDDE.c File Reference
- 7.121 ExampleApplications/DiffLaser/CodeGeneration/diff11LaserDelays.c File Reference
- 7.122 ExampleApplications/DiffLaser/CodeGeneration/diff11LaserHopfManifold.c File Reference
- 7.123 ExampleApplications/DiffLaser/CodeGeneration/diff11LaserHopfNV.c File Reference
- 7.124 ExampleApplications/DiffLaser/CodeGeneration/diff21LaserDDE.c File Reference

7.125	ExampleApplications/DiffLaser/Diff21/Backup/diff21LaserDDE.c File Reference
7.126	ExampleApplications/DiffLaser/Diff21/diff21LaserDDE.c File Reference
7.127	ExampleApplications/DiffLaser/CodeGeneration/diff21LaserDelays.c File Reference
7.128	ExampleApplications/DiffLaser/CodeGeneration/diff21LaserHopfManifold.c File Reference
7.129	ExampleApplications/DiffLaser/CodeGeneration/diff21LaserHopfNV.c File Reference
7.130	ExampleApplications/DiffLaser/CodeGeneration/diff21LaserModFoldManifold.c File Reference
7.131	ExampleApplications/DiffLaser/CodeGeneration/diff21LaserModFoldNV.c File Reference
7.132	ExampleApplications/DiffLaser/CodeGeneration/diff21LaserModHopfManifold.c File Reference
7.133	ExampleApplications/DiffLaser/CodeGeneration/diff21LaserModHopfNV.c File Reference
7.134	ExampleApplications/DiffLaser/CodeGeneration/diff31LaserDDE.c File Reference
7.135	ExampleApplications/DiffLaser/CodeGeneration/diff31LaserDelays.c File Reference
7.136	ExampleApplications/DiffLaser/CodeGeneration/diff31LaserHopfManifold.c File Reference
7.137	ExampleApplications/DiffLaser/CodeGeneration/diff31LaserHopfNV.c File Reference

- 7.138 ExampleApplications/DiffLaser/CodeGeneration/diff41LaserDDE.c File Reference
- 7.139 ExampleApplications/DiffLaser/CodeGeneration/diff41LaserDelays.c File Reference
- 7.140 ExampleApplications/DiffLaser/CodeGeneration/diff41LaserHopfManifold.c File Reference
- 7.141 ExampleApplications/DiffLaser/CodeGeneration/diff41LaserHopfNV.c File Reference
- 7.142 ExampleApplications/DiffLaser/CodeGeneration/vonJens/DDE_1L_omega_in_p.c File Reference
- 7.143 ExampleApplications/DiffLaser/CodeGeneration/vonJens/Mod_Fold_1L.c File Reference
- 7.144 ExampleApplications/DiffLaser/CodeGeneration/vonJens/NV_Mod_Fold_1L.c File Reference
- 7.145 ExampleApplications/DiffLaser/CompareDiskretisations.m File Reference
- 7.146 ExampleApplications/DiffLaser/CompareResults.m File Reference
- 7.147 ExampleApplications/DiffLaser/continueHopfDiffLaserN.m File Reference
- 7.148 ExampleApplications/DiffLaser/Diff11/backup/diff11Laser2HopfManifold.c File Reference
- 7.149 ExampleApplications/DiffLaser/Diff11/diff11Laser2HopfManifold.c File Reference
- 7.150 ExampleApplications/DiffLaser/Diff11/backup/diff11Laser2HopfNV.c File Reference
- 7.151 ExampleApplications/DiffLaser/Diff11/diff11Laser2HopfNV.c File Reference

7.152	ExampleApplications/DiffLaser/Diff11/diff11Laser2DDE.c File Reference
7.153	ExampleApplications/DiffLaser/Diff11/diff11Laser2Delays.c File Reference
7.154	ExampleApplications/DiffLaser/Diff11/findHopf.m File Reference
7.155	ExampleApplications/DiffLaser/Diff21/findHopf.m File Reference
7.156	ExampleApplications/DiffLaser/Diff31/findHopf.m File Reference
7.157	ExampleApplications/DiffLaser/Diff41/findHopf.m File Reference
7.158	ExampleApplications/DiffLaser/Diff11/findHopfFromCrit.m File Reference
7.159	ExampleApplications/DiffLaser/Diff21/findHopfFromCrit.m File Reference
7.160	ExampleApplications/DiffLaser/Diff31/findHopfFromCrit.m File Reference
7.161	ExampleApplications/DiffLaser/Diff41/findHopfFromCrit.m File Reference
7.162	ExampleApplications/DiffLaser/Diff11/optimdiff11Laser.m File Reference
7.163	ExampleApplications/DiffLaser/Diff11/optimdiff11LaserIntensity.m File Reference
7.164	ExampleApplications/DiffLaser/Diff11/optimdiffNLaser.m File Reference
7.165	ExampleApplications/DiffLaser/Diff21/Backup/diff21Laser2DDE.c File Reference
7.166	ExampleApplications/DiffLaser/Diff21/diff21Laser2DDE.c File Reference
7.167	ExampleApplications/DiffLaser/Diff21/Backup/diff21Laser2Delays.c File Reference
7.168	ExampleApplications/DiffLaser/Diff21/diff21Laser2Delays.c File Reference

- 7.169 ExampleApplications/DiffLaser/Diff21/Backup/diff21Laser2HopfEig.c File Reference
- 7.170 ExampleApplications/DiffLaser/Diff21/diff21Laser2HopfEig.c File Reference
- 7.171 ExampleApplications/DiffLaser/Diff21/Backup/diff21Laser2HopfManifold.c File Reference
- 7.172 ExampleApplications/DiffLaser/Diff21/diff21Laser2HopfManifold.c File Reference
- 7.173 ExampleApplications/DiffLaser/Diff21/Backup/diff21Laser2HopfNV.c File Reference
- 7.174 ExampleApplications/DiffLaser/Diff21/diff21Laser2HopfNV.c File Reference
- 7.175 ExampleApplications/DiffLaser/Diff21/Backup/diff21Laser2ModFoldManifold.c File Reference
- 7.176 ExampleApplications/DiffLaser/Diff21/diff21Laser2ModFoldManifold.c File Reference
- 7.177 ExampleApplications/DiffLaser/Diff21/Backup/diff21Laser2ModFoldNV.c File Reference
- 7.178 ExampleApplications/DiffLaser/Diff21/diff21Laser2ModFoldNV.c File Reference
- 7.179 ExampleApplications/DiffLaser/Diff21/Backup/diff21Laser2ModHopfManifold.c File Reference
- 7.180 ExampleApplications/DiffLaser/Diff21/diff21Laser2ModHopfManifold.c File Reference
- 7.181 ExampleApplications/DiffLaser/Diff21/Backup/diff21Laser2ModHopfNV.c File Reference

7.182	ExampleApplications/DiffLaser/Diff21/diff21Laser2ModHopfNV.c File Reference
7.183	ExampleApplications/DiffLaser/Diff21/createFigure.m File Reference
7.184	ExampleApplications/DiffLaser/Diff21/optimdiff21Laser.m File Reference
7.185	ExampleApplications/DiffLaser/Diff21/optimdiff21LaserIntensity.m File Reference
7.186	ExampleApplications/DiffLaser/Diff31/checkJacRank.m File Reference
7.187	ExampleApplications/DiffLaser/Diff31/diff31Laser2DDE.c File Reference
7.188	ExampleApplications/DiffLaser/Diff31/diff31Laser2Delays.c File Reference
7.189	ExampleApplications/DiffLaser/Diff31/diff31Laser2HopfManifold.c File Reference
7.190	ExampleApplications/DiffLaser/Diff31/diff31Laser2HopfNV.c File Reference
7.191	ExampleApplications/DiffLaser/Diff31/diff31Laser3DDE.c File Reference
7.192	ExampleApplications/DiffLaser/Diff31/initdiff31LaserIntensity.m File Reference
7.193	ExampleApplications/DiffLaser/Diff31/optimdiff31Laser.m File Reference
7.194	ExampleApplications/DiffLaser/Diff31/optimdiff31LaserIntensity.m File Reference
7.195	ExampleApplications/DiffLaser/Diff31/optimdiff31LaserIntensityNonRob.m File Reference
7.196	ExampleApplications/DiffLaser/Diff31/optimdiff31LaserIntensityUnStab.m File Reference
7.197	ExampleApplications/DiffLaser/Diff31/TestJacobianRank.m File Reference

7.198	ExampleApplications/DiffLaser/Diff41/diff41Laser2DDE.c File Reference
7.199	ExampleApplications/DiffLaser/Diff41/diff41Laser2Delays.c File Reference
7.200	ExampleApplications/DiffLaser/Diff41/diff41Laser2HopfManifold.c File Reference
7.201	ExampleApplications/DiffLaser/Diff41/diff41Laser2HopfNV.c File Reference
7.202	ExampleApplications/DiffLaser/Diff41/optimdiff41Laser.m File Reference
7.203	ExampleApplications/DiffLaser/Diff41/optimdiff41LaserIntensity.m File Reference
7.204	ExampleApplications/DiffLaser/Diff51/diff51Laser2DDE.c File Reference
7.205	ExampleApplications/DiffLaser/Diff51/diff51Laser2HopfManifold.c File Reference
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7.207	ExampleApplications/DiffLaser/Diff51/optimdiff51Laser.m File Reference
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• function findHopfDiffLaserNnoPlotFunction3 (in Ninput, in varargin)

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• function phaseCondition (in point)

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• function uniformlyDiscretizeCurve (in curve, in nPoints)

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- 7.345.1.1 function uniformlyDiscretizeCurve (in curve, in nPoints)
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• function fixedAndFreeAlpha (in yMaAlpha, in alphaIn, in contInd1, in contInd2)

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creates variable collections for different manifold types		

Functions

• function varCollection (in type, in offset, in x, in alpha, in p, in algVars) creates variable collections for different manifold types

7.416.1 Detailed Description

creates variable collections for different manifold types

Author

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Date

18 Jul 2017

7.416.2 Function Documentation

7.416.2.1 function varCollection (in type, in offset, in x, in alpha, in p, in algVars)

creates variable collections for different manifold types

the structs are allways created the same, but for some manifolds with empty entries

Parameters

type	requested manifold type	
offset index offset		
Х	state vector, instance of class VariableVector	
alpha	pha uncertain variables, instance of class VariableVector	
р	certain optimization variables, instance of class VariableVector	

Return values

vars	variables vector to return

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