

# ECE2720: Data Science for Engineers

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## **1 Numerical Optimization**

## 2 Gaussian Distribution

### 2.1 Probability Intro

Want to model uncertainty in outcomes + situations where outcomes are not known prior.

**Discrete probability**:-  $\mathcal{X}$  := set of outcomes, where  $p$  is the probability of the outcome happening

- $p(x) \geq 0$  for all  $x \in \mathcal{X}$
- $\sum_{x \in \mathcal{X}} p(x) = 1$  - the **Law of Total Probability**

**Random variable**  $X$  has outcomes  $\mathcal{X} \sim p$  when  $\mathcal{X}$  is the (apriori unknown) outcome drawn from  $p$ . An **event** is any subset of  $\mathcal{X}$  (all possible outcomes), usually denoted by  $A$  or  $E$ .

The **expectation**  $\mathbb{E}$  of a random variable  $X$  is its expected value. Note that

$$\mathbb{E}[x] = \sum_{x \in \mathcal{X}} \mathbb{P}(X = x) \times x = \sum_{x \in \mathcal{X}} p(x) \times x$$

Additionally,

- For a function  $g(x)$ ,  $\mathbb{E}[g(x)] = \sum_{x \in \mathcal{X}} p(x) \times g(x)$ .
- **Linearity of Expectation** states that for any random variables  $X_1$  and  $X_2$ ,  
 $\mathbb{E}[X_1 + X_2] = \mathbb{E}[X_1] + \mathbb{E}[X_2]$

Two random variables are **independent** if

$$\mathbb{P}(X_1 = x_1, X_2 = x_2) = \mathbb{P}(X_1 = x_1) \times \mathbb{P}(X_2 = x_2)$$

### 2.2 Discrete + Continuous Distributions

#### Discrete Distributions

$\mathcal{X}$  - a discrete set

$p$ :-

- $p(x) \geq 0$  for all  $x \in \mathbb{R}$
- $\sum_{x \in \mathcal{X}} p(x) d(x) = 1$

$$\mathbb{E}[X] = \sum_{x \in \mathcal{X}} x \times p(x)$$

For an event  $A \subseteq \mathcal{X}$ ,

$$\mathbb{P}(X \in A) = \mathbb{P}(A) = \sum_{x \in A} p(x)$$

#### Continuous Distributions

$\mathcal{X} \sim$  a continuous set of real numbers

$p$ :-

- $p(x) \geq 0$  for all  $x \in \mathbb{R}$
- $\int_{-\infty}^{\infty} p(x) \times x = 1$

$$\mathbb{E}[x] = \int_{\mathbb{R}} p(x) \times x dx$$

For an event  $A \subseteq \mathcal{X}$ ,

$$\mathbb{P}(X \in A) = \mathbb{P}(A) = \int_{x \in A} p(x) dx$$

## 2.3 Gaussian Distributions

This is the most important distribution, also known as the **bell curve** or **normal distribution**.

**Definition 2.1.** A **Gaussian distribution** with mean  $\mu$  and variance  $\sigma^2 > 0$  has the following distribution:

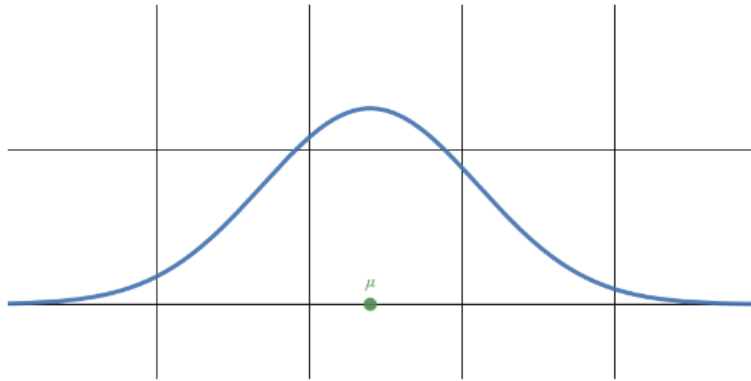
$$p(x) = \phi(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right)$$

From MATH2411 – The **normal distribution**, also called the **Gaussian distribution**, is the most important continuous probability distribution because of its ubiquity in the real world.

**Definition 2.2** (Normal Distribution). A **normal distribution** has notation:  $X \sim N(\mu, \sigma^2)$  where  $\mu \in (-\infty, \infty)$  is the *mean* and  $\sigma^2 \in (0, \infty)$  is the **variance**. A normal distribution has pdf:

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{1}{2\sigma^2}(x-\mu)^2} \text{ for all real values } x$$

A normal distribution has expectation  $E(X) = \mu$  and variance  $Var(X) = \sigma^2$ . Note that all normal distributions have a bell-shaped density curve regardless of the values of  $\mu$  and  $\sigma$ .



Observe that  $\phi_{\mu, \sigma^2}(x)$  is symmetric about  $\mu$  and that  $X \sim \phi_{\mu, \sigma^2} \rightarrow N(\mu, \sigma^2)$

**Definition 2.3.** The **central limit theorem (CLT)** states that a random quantity that is the sum of many small independent random quantities will have follow a Gaussian distribution.

By definition of **variance**:  $\mathbb{E}[(x - \mu)^2]$ , a normal distribution has

$$\mathbb{E}[x] = \mu, \text{Var}(x) = \sigma^2$$

Note that with expectation and variance, given an  $X \sim p(x)$ ,  $Y = aX + b$ ,

$$\mathbb{E}[Y] = a\mathbb{E}[X] + b, \text{Var}(Y) = a^2\text{Var}(X)$$

## 2.4 Linear Models

A large part of data science is reasoning about input/output relationships in a system. We're going to look at input which follows a Gaussian distribution.

**Theorem 2.1.** With  $X \sim N(\mu, \sigma^2)$  and  $Y = aX + b$ , then

$$Y \sim N(a\mu + b, a^2\sigma^2)$$

Note that we can standardize Gaussian distributions: From MATH2411-

**Definition 2.4** (Standard Normal Distribution). The **standard normal distribution** has mean 0 and variance 1, i.e.,  $N(0, 1)$ . The random variable following the standard normal distribution is often denoted by  $Z$  in probability and statistics. Its probability density function (pdf) is

$$\varphi(z) = \frac{1}{\sqrt{2\pi}} e^{-\frac{z^2}{2}}$$

and its distribution function (cdf) is

$$\Phi(z) = \int_{-\infty}^z f(t)dt = \int_{-\infty}^z \frac{1}{\sqrt{2\pi}} e^{-\frac{t^2}{2}} dt = \mathbb{P}(X \leq z)$$

Note that  $\lim_{x \rightarrow \infty} \Phi_{\mu, \sigma^2}(x) = 1$  and recall that  $\Phi_{\mu, \sigma^2}$  is an increasing function (cdf!).

To **standardize** a distribution, we use

$$\frac{x - \mu}{\sigma} \sim N(0, 1)$$

## 2.5 Random Vectors

Tool to analyze how different random quantities are related (e.g., current and voltage, image darkness and malignancy, etc).

**Definition 2.5.** A **random vector** is a placeholder for an unrevealed vector-valued random quantity: either thought of as a *single* random entity or a *vector* of random variables.

For any  $p$  over  $\mathbb{R} \times \mathbb{R}$ ,

$$\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} p(x_1, x_2) dx_1 dx_2 = 1$$

### 2.5.1 Bivariate Gaussian

**Definition 2.6.** The bivariate  $\mathcal{N}$  distribution with parameters  $\mu_1 \in \mathbb{R}, \mu_2 \in \mathbb{R}, \sigma_1^2 > 0, \sigma_2^2 > 0, -1 < \rho < 1$  is

$$\phi_{\mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \rho}(\vec{x}) = \frac{\exp[-\frac{1}{2(1-\rho^2)}((\frac{x_1-\mu_1}{\sigma_1})^2 - 2\rho(\frac{x_1-\mu_1}{\sigma_1})(\frac{x_2-\mu_2}{\sigma_2}) + (\frac{x_2-\mu_2}{\sigma_2})^2)]}{2\pi\sigma_1\sigma_2\sqrt{1-\rho^2}}$$

$\rho$  is the parameter that characterizes how  $X_1$  and  $X_2$  relate to each other. If

- $\rho = 0$ , then  $X_1$  and  $X_2$  are independent (Gaussian)
- $\rho > 0$ , then  $X_1$  and  $X_2$  are *positively* correlated
- $\rho < 0$ , then  $X_1$  and  $X_2$  are *negatively* correlated

If  $A \subseteq \mathbb{R} \times \mathbb{R}$ , then

$$\mathbb{P}((x_1, x_2) \in A) = \iint_{(x_1, x_2) \in A} \phi_{\mu_1, \mu_2, \sigma_1^2, \sigma_2^2, \rho}(x_1, x_2) dx_1 dx_2$$

### 2.5.2 Marginalization

$X_1$  over  $\mathcal{X}_1$ ,  $X_2$  over  $\mathcal{X}_2$ , where  $p(x_1, x_2)$  = joint distribution of  $X_1, X_2$ .