

Online Variational Bayes Inference for High-Dimensional Correlated Data Review

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1 Model specification

The model that was proposed in this paper naturally assumes image data that consist of voxels where a voxel represents a single sample, or a data point, on a regularly spaced, three-dimensional grid. This data point can consist of a single piece of data such as an opacity or multiple pieces of data, such as a color in addition to opacity. The model is as follows:

$$\mathbf{Y}_{it} = \boldsymbol{\eta}_i \boldsymbol{\mu}_{it} + \mathbf{X}_{it} \boldsymbol{\beta}_i + \boldsymbol{\epsilon}_{it} \quad (1)$$

where

$$\mathbf{Y}_{it} : K \times 1 \quad (2)$$

$$\mathbf{X}_{it} : K \times g \quad (3)$$

$$\boldsymbol{\mu}_{it} : m \times 1 \ (m < K) \quad (4)$$

$$\boldsymbol{\eta}_i : K \times m \quad (5)$$

$$\boldsymbol{\beta}_i : g \times 1. \quad (6)$$

1.1 Priors

The priors are as follows:

$$\boldsymbol{\mu}_{it} \sim \mathcal{N}(\boldsymbol{\mu}_{i,t-1}, \theta_i^{-1} \mathbf{I}_m), \ \boldsymbol{\mu}_{i0} \sim \mathcal{N}(\boldsymbol{\mu}_0, v \mathbf{I}_m) \quad (7)$$

$$\boldsymbol{\epsilon}_{it} \sim \mathcal{N}(\mathbf{0}, \sigma^{-2} \mathbf{I}_K) \quad (8)$$

$$\boldsymbol{\eta}_{ij} \sim \mathcal{N}\left(\mathbf{0}, \tau^{-1} (\mathbf{I}_K - \rho \mathbf{C})^{-1} \boldsymbol{\Omega}\right)^* \quad (9)$$

$$(\boldsymbol{\beta}_i, \theta_i) \sim G, \ G \sim \text{DP}(\alpha, \mathcal{N}(\boldsymbol{\beta}_{0r}, \boldsymbol{\Sigma}_{0r}) \text{Ga}(a_\theta, b_\theta)) \quad (10)$$

$$\sigma^2 \sim \text{Ga}(a_\sigma, b_\sigma) \quad (11)$$

$$\tau \sim \text{Ga}(a_\tau, b_\tau) \quad (12)$$

$$\rho_\ell = \frac{\ell}{M}, \ \ell = 0, 1, \dots, M-1, M-\epsilon \quad (13)$$

$$\phi_\ell = \text{P}(\rho = \rho_\ell) = \frac{1}{M+1} \quad (14)$$

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in which elements in * need clarification as below.

$$\mathbf{\Omega} = \text{Diag} \left(\frac{1}{d_{1+}}, \dots, \frac{1}{d_{K+}} \right), \quad d_{r+} = \sum_s d_{rs} \quad (15)$$

$$\mathbf{C} : K \times K, \quad c_{rs} = \frac{d_{rs}}{d_{r+}}, \quad \mathbf{D} = (d_{rs}) : \text{proximity matrix} \quad (16)$$

$$d_{rs} = \begin{cases} 0 & \text{if } r = s \\ \|\varphi_r - \varphi_s\|^{-\phi}, \quad \phi > 0 & \text{otherwise} \end{cases}. \quad (17)$$

2 Variational Bayes

Instead of directly dealing with the Dirichlet process itself, we will use the stick-breaking representation and reformulate it as follows. If we let $\Theta_i = (\beta'_i, \theta'_i)'$,

$$\Theta_i \sim G, \quad G = \sum_{r=1}^{\infty} \pi_r \delta_{\Theta_r^*}, \quad \pi_r = v_r \prod_{\ell < r} (1 - v_\ell), \quad \Theta_r^* = (\beta_r^{*'}, \theta_r^{*'})' \quad (18)$$

$$v_r \sim \text{Be}(1, \alpha), \quad \alpha \sim \text{Ga}(a_\alpha, b_\alpha), \quad \beta_r^* \sim \mathcal{N}(\beta_{0r}, \Sigma_{0r}), \quad \theta_r^* \sim \text{Ga}(a_\theta, b_\theta). \quad (19)$$

Then the parameters of interest are $\mathbf{W} = (V, \mathbf{\Theta}^*, \mathbf{z}, \boldsymbol{\eta}, \boldsymbol{\mu}, \rho, \tau, \sigma^2, \alpha)$. Then by mean-field assumption,

$$\begin{aligned} q(\mathbf{W}) &= q(\sigma^2) q(\alpha) q(\rho) q(\tau) \left(\prod_{r=1}^R q(\theta_r^*) q(\beta_r^*) q(v_r) \right) \left(\prod_{i=1}^n q(z_i) \right) \\ &\quad \times \left(\prod_{i=1}^n \prod_{t=1}^T q(\mu_{it}) \right) \left(\prod_{i=1}^n q(\boldsymbol{\eta}_i) \right) \end{aligned}$$

where R is the truncation point of the Dirichlet process.

2.1 Online Variational Bayes

Online variational Bayes only considers one data point at a time which makes it much more practical for large datasets. Sato presented a discount term for the parameters that depend on the i^{th} subject or observation. The only modification occurs here where the variational objective function embraces the discount term and also when updating the variational parameters, we do so by updating the