Cosine Basis Logistic

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1 Logistic

1.1 Model

$$y \sim \operatorname{Ber}\left(\operatorname{logit}^{-1}\left(\varphi_{J}\theta_{J}\right)\right)$$
$$\theta_{j}|\tau,\psi \sim \mathcal{N}\left(0,\tau^{2}\exp\left[-j|\psi|\right]\right)$$
$$\tau^{2} \sim \operatorname{IG}\left(\frac{r_{0,\tau}}{2},\frac{s_{0,\tau}}{2}\right)$$
$$\psi \sim \operatorname{DE}\left(0,\omega_{0}\right)$$

1.2 Likelihood

$$\begin{split} \ln p \left(y, \Theta \right) &= y^{\top} \varphi_{J} \theta_{J} - \mathbf{1}_{n}^{\top} \ln \left(\mathbf{1}_{n} + \exp \left(\varphi_{j} \theta_{J} \right) \right) \\ &- \frac{1}{2} \left\{ \sum_{j=1}^{J} \ln \left(2 \pi \tau^{2} \right) - j \left| \psi \right| + \frac{\theta_{j}^{2} e^{j \left| \psi \right|}}{\tau^{2}} \right\} \\ &+ \frac{r_{0,\tau}}{2} \ln \left(\frac{s_{0,\tau}}{2} \right) - \ln \Gamma \left(\frac{r_{0,\tau}}{2} \right) + \left(\frac{r_{0,\tau}}{2} + 1 \right) \ln \frac{1}{\tau^{2}} - \frac{s_{0,\tau}}{2} \frac{1}{\tau^{2}} \\ &- \ln \frac{\omega_{0}}{2} - \omega_{0} \left| \psi \right| \end{split}$$

1.3 Getting around the intractability

$$-\ln\left(1+e^{x}\right) = \max_{\xi \in \mathbb{R}} \left\{ \lambda\left(\xi\right) x^{2} - \frac{1}{2}x + \Psi\left(\xi\right) \right\}, \quad \forall x \in \mathbb{R}$$
$$\lambda\left(\xi\right) = -\tanh\left(\xi/2\right) / \left(4\xi\right)$$
$$\Psi\left(\xi\right) = \xi/2 - \ln\left(1+e^{\xi}\right) + \xi \tanh\left(\xi/2\right) / 4$$

then

$$\begin{aligned} -\mathbf{1}_{n}^{\top} \ln \left(\mathbf{1}_{n} + \exp \left(\varphi_{J} \theta_{J}\right)\right) &\geq \mathbf{1}_{n}^{\top} \left\{\lambda \left(\xi\right) \odot \left(\varphi_{J} \theta_{J}\right)^{2} - \frac{1}{2} \varphi_{J} \theta_{J} + \Psi \left(\xi\right)\right\} \\ &= \theta_{J}^{\top} \varphi_{J}^{\top} \operatorname{Dg} \left\{\lambda \left(\xi\right)\right\} \varphi_{J} \theta_{J} - \frac{1}{2} \mathbf{1}_{n}^{\top} \varphi_{J} \theta_{J} + \mathbf{1}_{n}^{\top} \Psi \left(\xi\right) \end{aligned}$$

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$$\ln \underline{p}(y, \Theta; \xi) = y^{\top} \varphi_{J} \theta_{J} - \frac{1}{2} \mathbf{1}_{n}^{\top} \varphi_{J} \theta_{J} + \theta_{J}^{\top} \varphi_{J}^{\top} \operatorname{Dg} \left\{ \lambda \left(\xi \right) \right\} \varphi_{J} \theta_{J} + \mathbf{1}_{n}^{\top} \Psi \left(\xi \right)$$

$$- \frac{1}{2} \left\{ \sum_{j=1}^{J} \ln \left(2\pi \tau^{2} \right) - j \left| \psi \right| + \frac{\theta_{j}^{2} e^{j \left| \psi \right|}}{\tau^{2}} \right\}$$

$$+ \frac{r_{0,\tau}}{2} \ln \left(\frac{s_{0,\tau}}{2} \right) - \ln \Gamma \left(\frac{r_{0,\tau}}{2} \right) + \left(\frac{r_{0,\tau}}{2} + 1 \right) \ln \frac{1}{\tau^{2}} - \frac{s_{0,\tau}}{2} \frac{1}{\tau^{2}}$$

$$- \ln \frac{\omega_{0}}{2} - \omega_{0} \left| \psi \right|$$

1.4 Update

1.4.1 θ_J

$$\Sigma_{\theta;\xi}^{q} = \left(-2\varphi_{J}^{\top} \operatorname{Dg} \left\{\lambda\left(\xi\right)\right\} \varphi_{J} + \frac{r_{q,\tau}}{s_{q,\tau}} \operatorname{Dg} \left(Q_{1:J}\right)\right)^{-1}$$
$$\mu_{\theta;\xi}^{q} = \Sigma_{\theta;\xi}^{q} \varphi_{J}^{\top} \left(y - \frac{1}{2} \mathbf{1}_{n}\right)$$

1.4.2 τ^2

$$r_{q,\tau} = r_{0,\tau} + J$$

$$s_{q,\tau} = s_{0,\tau} + \sum_{j=1}^{J} \left(\Sigma_{\theta;\xi,jj}^{q} + \mu_{\theta;\xi,jj}^{q^{2}} \right) Q_{j} \left(\mu_{\psi}^{q}, \sigma_{\psi}^{q^{2}} \right)$$

1.4.3 ψ

$$\sigma_{\psi}^{q^2} = -\frac{1}{2} \left\{ \frac{\partial S_1}{\partial \sigma_{\psi}^{q^2}} + \frac{\partial S_2}{\partial \sigma_{\psi}^{q^2}} \right\}^{-1}$$
$$\mu_{\psi}^q = \mu_{\psi}^q + \sigma_{\psi}^{q^2} \left\{ \frac{\partial S_1}{\partial \mu_{\psi}^q} + \frac{\partial S_2}{\partial \mu_{\psi}^q} \right\}$$

1.4.4 ξ

$$\xi^{\text{new}} = \sqrt{\operatorname{dg}\left\{\varphi_{J}\left(\Sigma_{\theta;\xi}^{q} + \mu_{\theta;\xi}^{q} \mu_{\theta;\xi}^{q^{\top}}\right)\varphi_{J}^{\top}\right\}}$$

where dg results in a vector with the diagonal entries of the argument matrix. On the other hand, Dg results in a diagonal matrix with its diagonal entries being the input vector.

1.5 LB

$$\mathcal{L} = \mu_{\theta;\xi}^{q} \, ^{\top} \varphi_{J}^{\top} \left(y - \frac{1}{2} \mathbf{1}_{n} \right) + \operatorname{Tr} \left(\varphi_{J}^{\top} \operatorname{Dg} \left\{ \lambda \left(\xi \right) \right\} \varphi_{J} \left(\Sigma_{\theta;\xi}^{q} + \mu_{\theta;\xi}^{q} \mu_{\theta;\xi}^{q} \, ^{\top} \right) \right) + \mathbf{1}_{n}^{\top} \Psi \left(\xi \right)$$

$$+ \frac{J}{2} \left(\operatorname{di} \left(\frac{r_{q,\tau}}{2} \right) - \ln \left(\frac{s_{q,\tau}}{2} \right) - \ln \left(2\pi \right) \right) + S_{1} + S_{2}$$

$$+ \frac{r_{0,\tau}}{2} \ln \left(\frac{s_{0,\tau}}{2} \right) - \ln \Gamma \left(\frac{r_{0,\tau}}{2} \right) + \frac{r_{0,\tau}}{2} \left(\operatorname{di} \left(\frac{r_{q,\tau}}{2} \right) - \ln \left(\frac{s_{q,\tau}}{2} \right) \right) - \frac{s_{0,\tau}}{2} \frac{r_{q,\tau}}{s_{q,\tau}} - \ln \frac{\omega_{0}}{2}$$

$$+ \frac{r_{q,\tau}}{2} + \ln \Gamma \left(\frac{r_{q,\tau}}{2} \right) - \frac{r_{q,\tau}}{2} \operatorname{di} \left(\frac{r_{q,\tau}}{2} \right) + \frac{J}{2} \left(1 + \ln \left(2\pi \right) \right) + \frac{1}{2} \ln \left| \Sigma_{\theta;\xi}^{q} \right|$$

$$+ \frac{1}{2} \left(\ln \left(2\pi \sigma_{\psi}^{q} \right) + 1 \right)$$