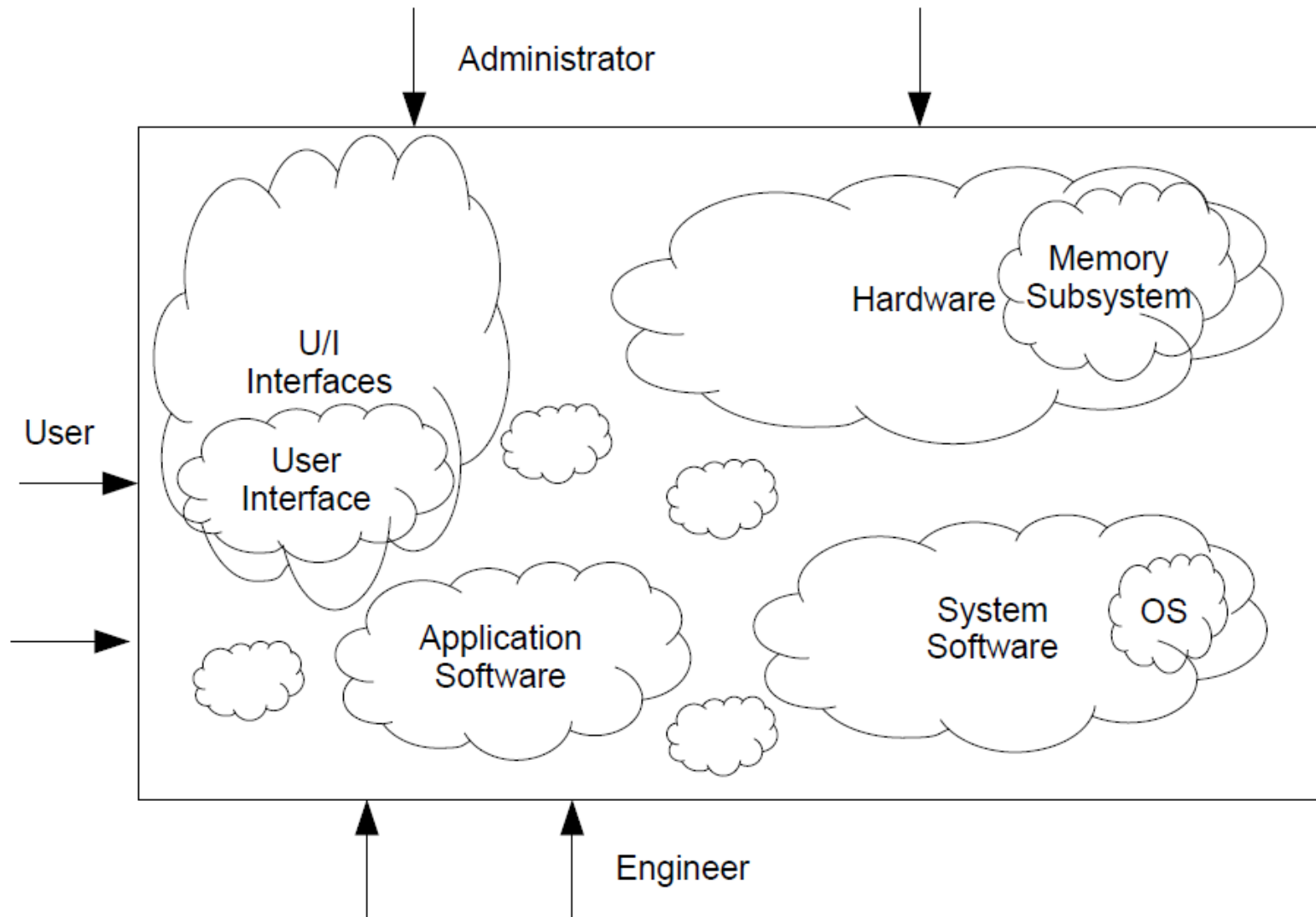


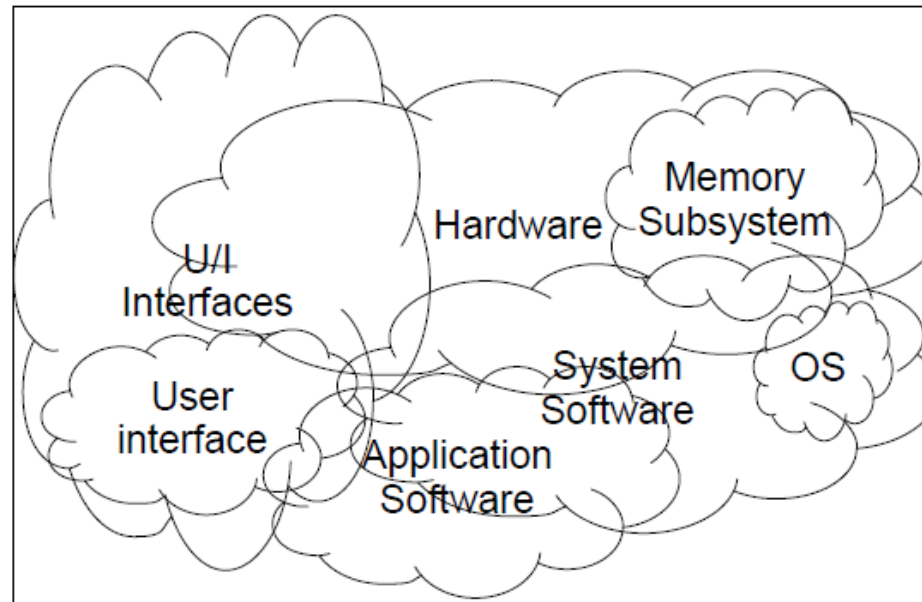
# Introduction



# Computer system



# Computer system

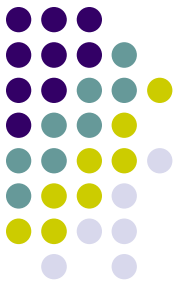


# Computer system



- Hardware - software
- Usually approached separately, but in computer engineering they are tightly connected, and when working on one you have to think about the other.
- Since mostly development of hardware starts before software development, in the common case development of software depends more on hardware than the other way.

# Computer system

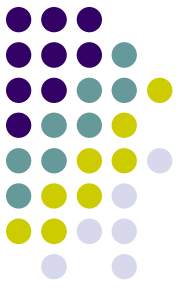


- As computer size increases, price increases.
- As computer size increases, power consumption increases.
- Computer system has to work **as good as possible**, its price to be as low as possible, and to consume power as low as possible.

# Computer system

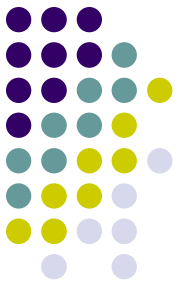


- As computer size increases, price increases.
- As computer size increases, power consumption increases.
- Computer system has to work **good enough**, its price to be as low as possible, and to consume power as low as possible.
- **What** to do good enough?
  - To run expected programs fast enough.



# Computer system

- Real time system
- **Embedded system**
- System with limited resources -> Processor with limited resources
- Special purpose systems -> Special purpose processor



# Real time systems

- Systems that work in real time.
- Key thing: tasks have a dead-line.
- When programming such systems it is almost impossible to make clear separating between “what” and “how”.

Example: Computer 1 starts text processing program in 3 minutes, computer 2 starts in 15 seconds.  
Which computer works in real time?





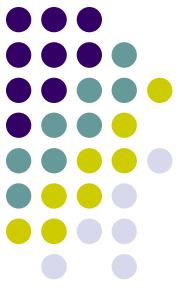
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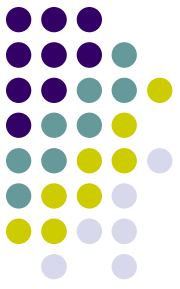
Trick question – there is no predefined dead-line.

# Embedded system



- No human-machine interface (or it is heavily reduced)
  - There is no: keyboard, screen etc.
- 99% of processors are in embedded systems
- System lifecycle: development, production, maintenance.
- For embedded systems development cost is usually under 5% of the whole cycle cost.

# System with limited resources



- Resources:

- Memory, registers
- **Speed (MIPS)**
- Energy
- ...

Example: The main computer is the most reliable spacecraft – Soyuz, is TsVM-101, with 6MHz and around 3MB of memory.

- Being limited is a relative thing

- but resources in these kind of systems are usually much smaller than in common PCs

# Special purpose systems



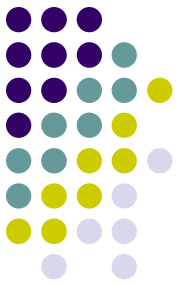
- Systems that target a specific use-case
- Special purpose processors:
  - Does every processor have an instruction for multiplication? How about for adding numbers... ?



# Processor classes

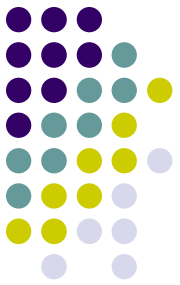
- General purpose processors
- Special purpose processors
  - DSPs
  - Microcontrollers
  - GPUs...

# General purpose processors

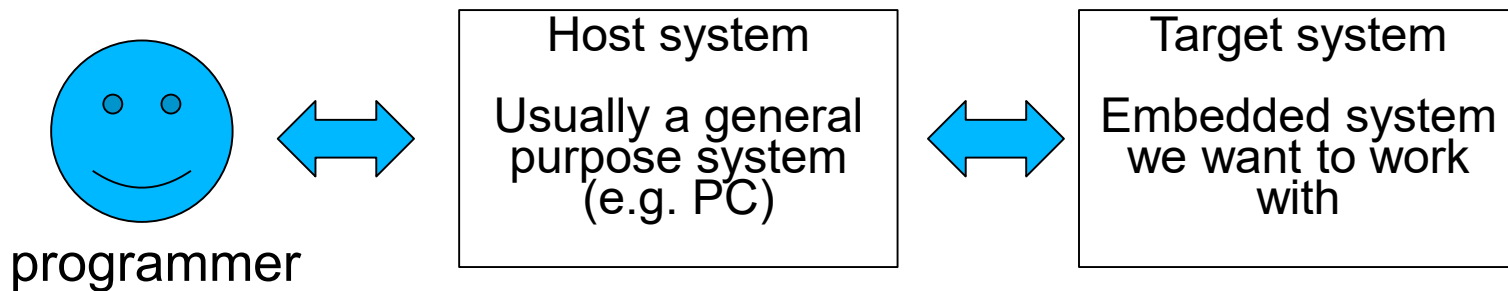


- The best performance in running all possible programs.
- Equivalent performance in running all possible programs.
- Some classes of programs run better, some worse, but in general the difference in the performance is less than one order of magnitude (10x).

# With what do we program embedded systems

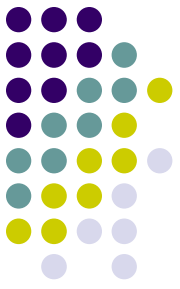


- Work with ES is usually not direct.



- Part of system software runs on the host system.
- Host is usually a system with faster and with more resources, and therefore it is easier to work on it.
- Many elements of system software could not even run on the target system (e.g. compiler, IDE, etc.).

# With what do we program embedded systems



- Tools (part of the system software):
  - Assembler
  - Compiler (for some high level language)
  - Debugger
  - Simulator (enables better execution control and insight)
  - Integrated development environment
- Operating system and libraries

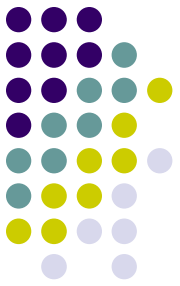


# When do we program embedded systems



- Before the hardware is finished
  - To accelerate development of the system
  - Part of the code is already available
- When the hardware architecture is locked, but it is still not produced
  - Development boards with prototype
  - Simulators
- When the hardware is finished, but system software is not (tools)
  - Development of system software usually starts before the hardware is finished
- When the hardware is ready and mature
  - For some systems this already end of their life cycle
  - For some other systems – it is a new beginning

# How do we program embedded systems

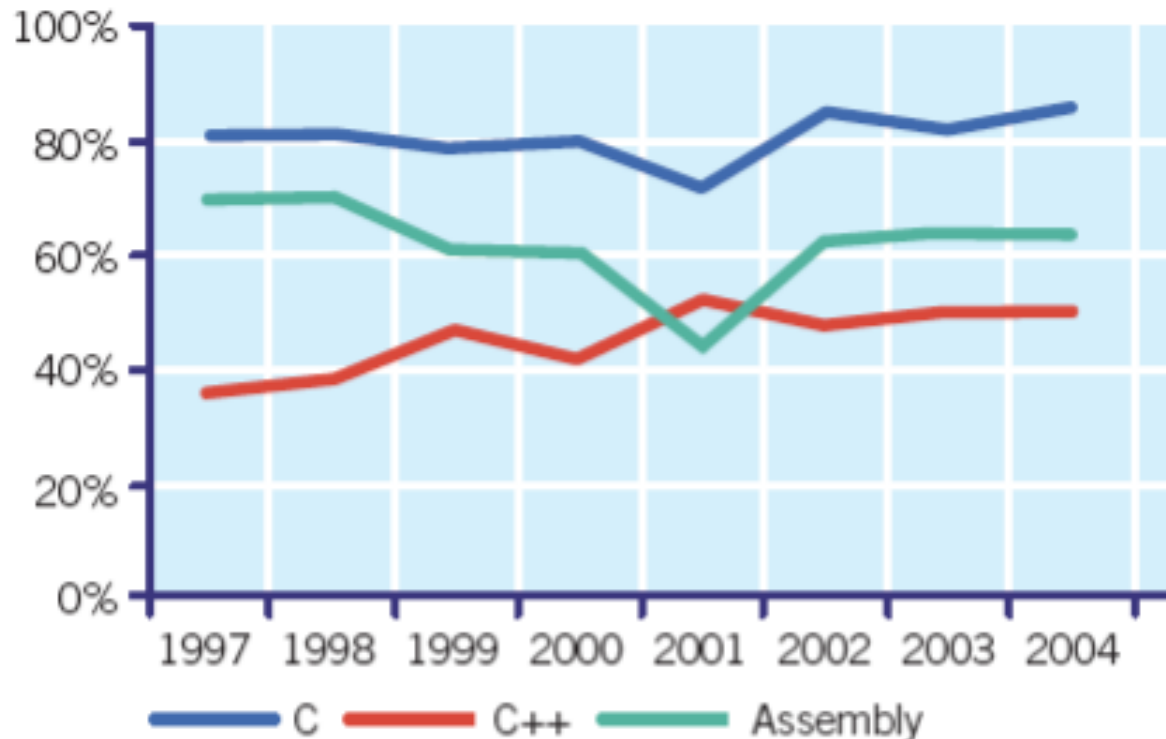


- Depends on many factors:
  - Development phase – readiness of the hardware and tools
  - Invested development effort – in the system software, mostly tools
  - Size and complexity of the particular software – small programs can be programmed even in binary code
  - Requirements of the particular software – more performance can be improved on lower abstraction level
- Assembler
  - Closer to hardware
  - Translator easier to make
  - More complicated for programming
- Higher level language
  - Farther away from hardware
  - Translator harder to make
  - Easier for programming



# C programming language

- High level programming language that is mostly used for programming embedded systems.

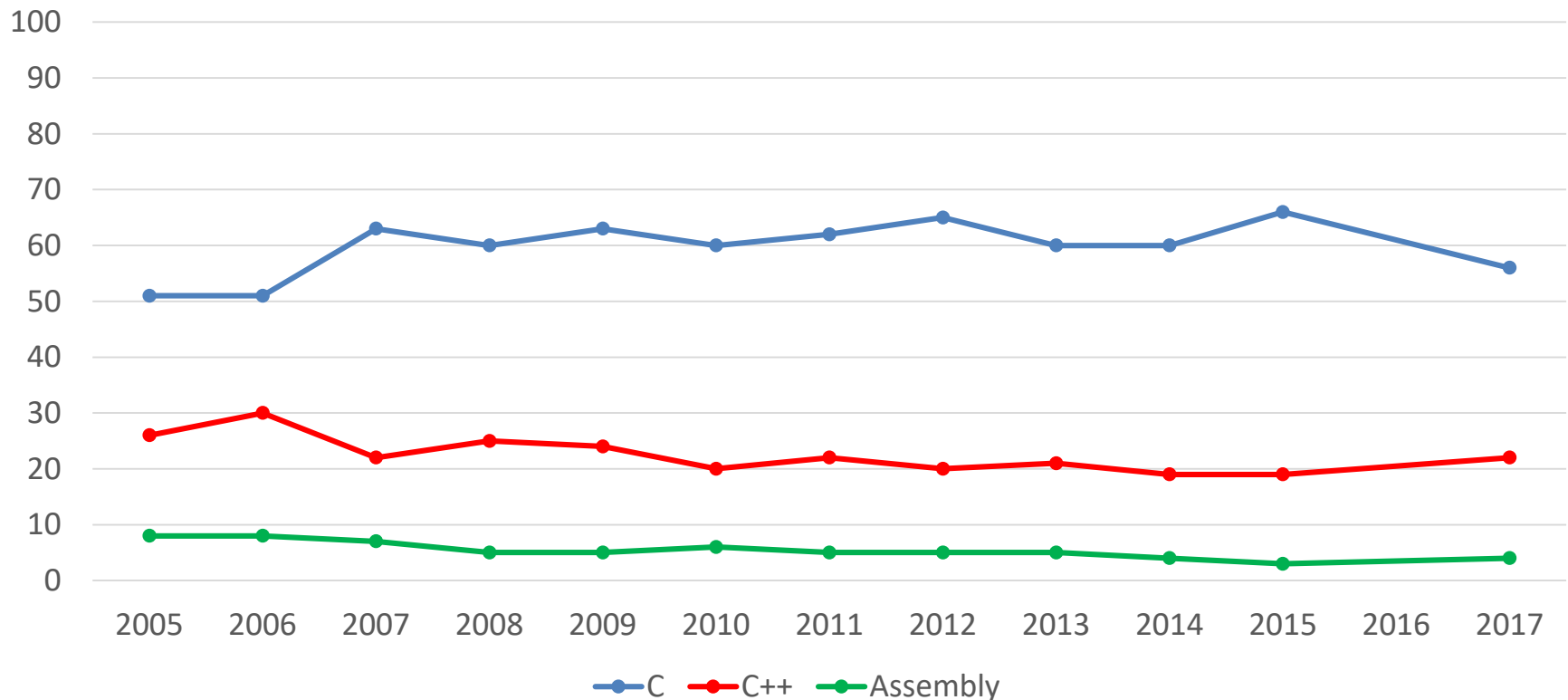


Percentage of projects in which a given language is used at least somewhere.

# C programming language

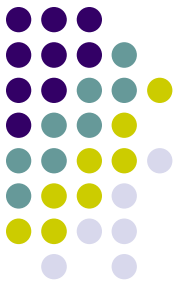


- High level programming language that is mostly used for programming embedded systems.



Percentage of projects in which a given language is predominantly used.

# C programming language

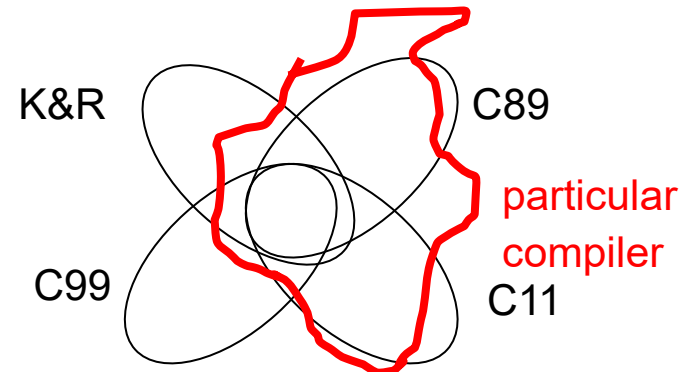
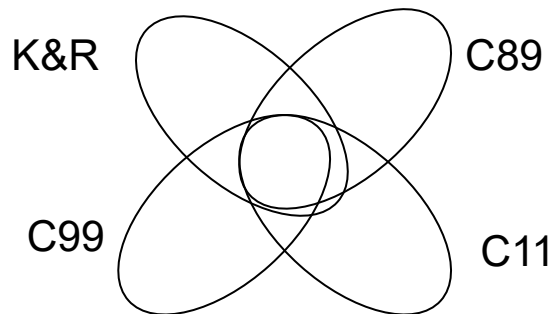


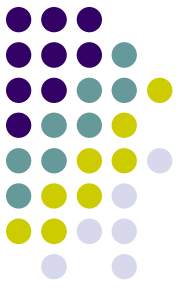
- Why C?
  - Not too high
    - Enables better performance optimization and system control
    - Relatively good mapping of its operations on hardware operations
  - Historical reasons
    - A lot of existing code
    - Large number of C programmers and experts
    - Compiler construction relatively easy (e.g. a lot of existing front-ends, etc.)

# C programming language



- Why **NOT** C?
  - Not too high
    - Higher level of abstraction would make programming easier
    - Relatively **bad** mapping of its operations on hardware operations
  - Historical reasons
    - Something better could have been invented by now?
    - Large number of C “programmers” and “experts”
    - Which standard this particular system supports?





# The goal of this course

Train students to be capable of:

- Writing new C code for embedded systems
  - Learn parts of the language which are not in focus when programming for general purpose systems and ad hoc programming, but are important when programming embedded systems
  - Learn good practice for writing nice, clear and useful code
  - Detect gray areas of the language so they would not use it unnecessarily.
- Understanding existing C code for embedded systems
  - Detect gray areas of the language so they would be able to understand them