

AA608-END Semester Exam
(Spring Semester)

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problem :-

1(a) $\alpha = \frac{-(1-\alpha)}{S_0^{1-\alpha}} = \frac{\alpha-1}{S_0^{1-\alpha}}$

The model probability distribution for s^i is

$$p(s) ds = (\alpha-1) S_0^{\alpha-1} s^\alpha ds$$

So where -

The factor $\alpha-1$ in front of the terms arises from the normalization requirement

$$\int_{S_0}^{\infty} ds p(s) = 1$$

Now the Likelihood function L for n observed sources is →

$$L = \prod_{i=1}^n (\alpha-1) S_0^{\alpha-1} s_i^{-\alpha}$$

$$L(\alpha | s) = \prod_{i=1}^n (\alpha-1) \left(\frac{s_i}{S_0} \right)^{-\alpha} \frac{1}{S_0}$$

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taking the log both sides -

$$\ln L(d) = \ln \left(\prod_{i=1}^n (\alpha-1) \left(\frac{s_i}{s_0} \right)^{-d} \frac{1}{s_0} \right)$$

$$\ln L(d) = \sum_{i=1}^n [\ln(\alpha-1) + (\alpha-1) \ln s_0 - d \ln s_i]$$

then find maximum value of d differenting with respect to d

$$\frac{d \ln L(d)}{d \alpha} = \sum_{i=1}^n \left(\frac{1}{\alpha-1} + \ln s_0 - \ln s_i \right) = 0$$

$$\frac{\cancel{\alpha}}{\cancel{\alpha-1}} = \sum_{i=1}^n \frac{\ln s_i}{s_0} = 0$$

$$\frac{\alpha-1}{n} = \frac{\sum_{i=1}^n \ln \frac{s_i}{s_0}}{n}$$

$$d = 1 + \frac{\sum_{i=1}^n \ln \frac{s_i}{s_0}}{n}$$

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1(b)

Suppose we only observe one source
with flux twice the cut-off. ($n=1$)

$S_1 = 2S_0$ then -

$$\alpha = 1 + \frac{1}{\ln \frac{2S_0}{S_0}} = 1 + \frac{1}{\ln 2}$$

$$\boxed{\alpha = 2.44}$$

1(c)

To get a rough estimate at the width
at the credibility interval for α , we can
compute

$$\sigma_{\alpha}^{+2} = - \left(\frac{\partial^2 \ln L}{\partial \alpha^2} \right)^{-1}$$

$$\sigma_{\alpha}^{-2} = - \left(\sum_{i=1}^n \cdot \frac{1}{(\alpha-1)^2} \right)^{-1}$$

$$\sigma_{\alpha}^2 = - \left(\frac{n}{(\alpha-1)^2} \right)^{-1} = - \left[\frac{(\alpha-1)^2}{n} \right]$$

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$$\bar{\sigma}^2(\alpha) = \frac{(\alpha-1)^2}{n}$$

~~Q~~ From part (b) $\alpha = 2.44 \Rightarrow$

and $n = 10$

$$\bar{\sigma}_\alpha^2 = \frac{(2.44-1)^2}{10-1} = (1.44)^2$$

$$\bar{\sigma}_\alpha = 1.44$$

=

problem: 2 \rightarrow (a)

2(a)

The distribution of emission M

Poisson distribution \rightarrow Count of photons emits
in time ~~t~~ $\cdot \lambda = dt$

\rightarrow probability of emitting m photons \rightarrow

$$\phi(m) = \frac{(\lambda)^m}{m!} e^{-\lambda}$$

$$\phi(m) \underset{\sim}{=} \frac{(dt)^m}{m!} e^{-dt}$$

The detection of photon by telescope is ~~an~~
independent event so the consider it as a
Binomial distribution.

\rightarrow probability of detecting N out of M photons.

$$\phi(m) = \frac{M!}{m! (N-m)!} p^N (1-p)^{M-N}$$

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The joint probability M -

$$P(M, N) = \frac{(dt)^M}{M!} \frac{e^{-dt}}{N! (N-M)!} p^N (1-p)^{M-N}$$

$$[\therefore P(M, N) = P(M) P(N)].$$

2(b)

$$P(N) = \sum_M P(M, N)$$

$$\therefore \text{for continuous } P(N) = \int dy P(N, y)$$

$$P(N) = \sum_M \frac{(dt)^M}{M!} \frac{e^{-dt}}{N! (M-N)!} p^N ((1-p)^{M-N})$$

$$P(N) = \frac{(1-p)^N p^N}{N!} \sum_M \frac{e^{-dt} (1-p)^M (dt)^M}{(M-N)!}$$

$$P(N) = \frac{p^N (1-p)^N}{N!} e^{-dt} \sum_{M=2N}^{\infty} \frac{((1-p)(dt))^M}{(M-N)!}$$

$\therefore M < N$ is not defined

$$P(n) = \frac{P^N Q^{n-N} e^{-\lambda}}{N!} \cdot \sum_{M=N}^{\infty} \frac{(q\mu)^M}{(M-N)!}$$

= A

where $\lambda = dt$, $Q = 1 - P$

2(c)

in this series \rightarrow

$$\sum_{M=N}^{\infty} \frac{(\lambda q)^M}{(M-N)!}$$

$$= \sum_{k=0}^{\infty} \frac{(\lambda q)^{k+N}}{k!}$$

$$\therefore M - N = k$$

$$= (\lambda q)^N \sum_{k=0}^{\infty} \frac{(\lambda q)^k}{k!}$$

$$= (\lambda q)^N e^{\lambda q} \quad \longrightarrow \quad \text{B}$$

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from equation (A) & B \rightarrow

$$P(N) = \frac{e^{-M} q^N p^N}{N!} (\lambda q)^N e^{\lambda q}$$

$$P(N) = \frac{\left(\frac{p \cdot \lambda q}{q}\right)^N e^{\lambda(2-1)}}{N!} \quad \therefore q-1 = -p$$

$$\boxed{P(N) = \frac{(\lambda H)^N e^{-\lambda H}}{N!}}$$

where - where H is a
 λH \doteq poisson distribution

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Problem: 3 →

3(a)

Bayes' Theorem :-

$$P(O/D) = \frac{P(D/O) P(O)}{P(D)}$$

where $P(D/O)$ = likelihood probability

$P(O)$ = ~~prior~~ prior probability

$P(O/D)$ = posterior probability

$P(D)$ → Evidence

The use $P(D)$ → the evidence under
Bayes theorem relates to the probability
of finding evidence in relation to
allured. When Bayes' theorem concerns
the probability of an event and its
inverse.

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3(b) If ~~M~~ independent variables y_i are normally distributed such that mean μ_i and variance σ_i^2 then the quantity χ^2 M

$$\chi^2 = \frac{(y_1 - \mu_1)^2}{\sigma_1^2} + \frac{(y_2 - \mu_2)^2}{\sigma_2^2} + \dots + \frac{(y_m - \mu_m)^2}{\sigma_m^2}$$

$$\boxed{\chi^2 = \sum_{i=1}^m \frac{(y_i - \mu_i)^2}{\sigma_i^2}}$$

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3(c)

The goodness of fit test is a statistical hypothesis test to see ~~whether~~ how well sample data fit a distribution from a population with a normal distribution put differently this test shows if ~~our~~ our sample data respects the data we would expect to find in the actual population. so

The flow-chart below shows how chi-square can be used to test goodness of fit

choose a function/model

↓
calculate expectation values
for each n_i

find out m (number of data points)

calculate χ^2 using
$$\chi^2 = \sum_{i=1}^m \frac{(y_i - \bar{y}_i)^2}{\sigma_i^2}$$

Calculate χ^2/M

Choose cut value
of significance

~~Calculate χ^2~~

~~Cheek~~

Determine corresponding values of
 $\chi^2_{M, \alpha/2}$, $\chi^2_{M, 1-\alpha}$

Compare χ^2/M , $\alpha/2$ with χ^2/M

$$\frac{\chi^2}{M} < \chi^2_{M, 1-\alpha}$$

$$\frac{\chi^2}{M} > \chi^2_{M, \alpha/2}$$

$\chi^2 > \chi^2_{M, \alpha/2}$

Model is
good fit

Overestimated
or
underestimated
data

Model can be
rejected with
[(1-d)100]%.
confidence

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Problem #6 :-

		<u>predicted</u> <u>No</u>	<u>predicted</u> <u>Yes</u>
<u>Actual</u> <u>No</u>	<u>Actual</u> <u>No</u>	50 (a)	10 (b)
	<u>Actual</u> <u>Yes</u>	5 (c)	100 (d)

given - $n=165$ data points or examples

$\Rightarrow 50 = \text{True No.} \cdot (\text{correct rejections})$

$\Rightarrow 10 = \text{False Yes} \cdot (\text{false alarms})$

$\Rightarrow 5 = \text{False No mistakes} \cdot (\text{over leased demand})$

$\Rightarrow 100 = \text{True Yes hits}$

we have $k=2$ classes here

So the accuracy w/ the percent of correct classifications

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for this model

$$\text{accuracy} = \frac{a+d}{a+b+c+d}$$

$$\text{accuracy} = \frac{TN + TY}{\text{total}}$$

$$= \frac{50 + 100}{165}$$

$$\text{accuracy} = \frac{150}{165} \approx 0.9090 \dots$$

$$\boxed{\text{accuracy} = 0.90}$$

\Rightarrow recall or True yes rate or sensitivity

$$= \frac{TY}{\text{actual Yes}} = \frac{d}{c+d} = \frac{100}{5+100}$$

$$= \frac{100}{105} = 0.952380952$$

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⇒ Precision or predicted Yes value \rightarrow

$$= \frac{\text{Ty}}{\text{predicted } \text{yu}}$$

$$= \frac{d}{b+d} = \frac{100}{10+100} = \frac{100}{110} = 0.9090\ldots$$

$$= 0.\overline{90}$$

⇒ None False alarm or false Yes rate \rightarrow

$$= \frac{Fy}{\text{actual No}} = \frac{b}{(a+b)} = \frac{10}{50+10}$$

$$= \frac{10}{60} \approx 0.16666 = 0.17$$

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Problem: 7 →

The major advantages or disadvantages →

k-Means Advantages →

- ① If variables are here, then k-means most of the times computationally faster than hierarchical clustering, if we keep k smalls.
- ② k-means produce tighter clusters than hierarchical clustering, especially if the clusters are globular.

k-means Disadvantages →

- ① difficult to predict k-value
- ② with global cluster, it did not work well
- ③ different initial partitions can result in different final clusters
- ④ it does not work well with clusters of different size and different density.

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Problem: 8 \Rightarrow

The Naive Bayes classification probability

$$P\left(\frac{\text{yes}}{\text{today or feature}}\right) = \frac{P\left(\frac{\text{Feature}}{\text{yes}}\right) \times P(\text{yes})}{P\left(\frac{\text{Feature}}{\text{yes}}\right) \times P(\text{yes}) + P(\text{Feature}) \times P(\text{no})}$$

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Now this question, future values for the given data point are outlook = sunny

Temperature = Hot

Humidity = Normal

windy = False

then since all the features are independent

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We can use Multiplication theorem of probability to

get $P(\text{Feature/yes})$ and $P(\text{Feature/no})$

$$\textcircled{B} \quad P(\text{Feature/yes}) = P(\text{yes}) \times P(\text{sunny}) \times P(\text{Hot})$$

$$P(\text{Feature/yes}) = P\left(\frac{\text{sunny}}{\text{yes}}\right) \times P\left(\frac{\text{Hot}}{\text{yes}}\right) \times P\left(\frac{\text{normal}}{\text{yes}}\right) \times P\left(\frac{\text{False}}{\text{yes}}\right)$$

$$\boxed{P(\text{Feature/yes}) = \frac{3}{9} \times \frac{2}{9} \times \frac{6}{9} \times \frac{6}{9}} \rightarrow \textcircled{B}$$

In the same way →

$$P\left(\frac{\text{Feature}}{\text{no}}\right) = \frac{2}{5} \times \frac{2}{5} \times \frac{1}{5} \times \frac{2}{5} \rightarrow \textcircled{C}$$

$$\text{Now; } P(\text{yes}) = \frac{9}{14} \rightarrow \textcircled{D}$$

$$P(\text{no}) = \frac{5}{14} \rightarrow \textcircled{E}$$

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In event A putting equation B, C, D, E -

$$P\left(\frac{4v}{\text{Feature}}\right) = \frac{\left(\frac{3}{9} \times \frac{2}{9} \times \frac{6}{9} \times \frac{6}{9}\right) \times \frac{9}{14}}{\left(\frac{3}{9}\right) \times \frac{2}{9} \times \frac{6}{9} \times \frac{6}{9} \times \frac{9}{14} + \left(\frac{2}{5} \times \frac{2}{5} \times \frac{1}{5} \times \frac{2}{5}\right) \times \frac{5}{14}}$$

$$= \frac{0.021164}{0.021164 + 0.004571428}$$

$$= \frac{0.021164}{0.025735428}$$

$$P\left(\frac{4v}{\text{Return}}\right) = 0.822368293$$