

12/03/21 End Semester Examination

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2003421005~~Ques~~ Given:

$$\begin{aligned} p(s|\alpha) &\propto s^{-\alpha} \\ p(s|\alpha) &= \alpha s^{-\alpha} \end{aligned}$$

~~where 'a' is a constant of proportionality~~

Ques 1 → ~~The model probability~~(a) The model probability distribution for  $s$  is

$$p(s) ds = (\alpha-1) S_0^{\alpha-1} s^{-\alpha} ds$$

where the factor  $\alpha-1$  in front of the terms arises from the normalization requirement.

$$\int_{S_0}^{\infty} ds p(s) = 1$$

So the likelihood function  $L$  for  $n$  observed sources is:-

$$L = \prod_{i=1}^n (\alpha-1) S_0^{\alpha-1} s_i^{-\alpha}$$

~~Taking natural log both sides:-~~

$$\ln L = \sum_{i=1}^n [\ln(\alpha-1) + (\alpha-1)\ln S_0 - \alpha \ln s_i]$$

Maximizing  $\ln L$  w.r.t.  $\alpha$  :-

$$\frac{\partial}{\partial \alpha} \ln L = \sum_{i=1}^n \left[ \frac{1}{\alpha-1} + \ln S_0 - \ln s_i \right] = 0$$

We find the minimum when

$$\alpha = 1 + \frac{1}{\sum_{i=1}^n \ln (S_i/S_0)}$$

- (b) Suppose we only observe one source with flux twice the cut-off,  $S_1 = 2S_0$ , then

$$\alpha = 1 + \frac{1}{1+2} = 2.44$$

but with a large uncertainty.

- (c) To get a rough estimate of width of the credibility interval for  $\alpha$ ; we can compute:

$$\sigma_\alpha^{-2} \approx -\frac{\delta^2 \ln L}{\delta \alpha^2} = \sum_{i=1}^n \frac{1}{(\alpha-1)^2}$$

For single source,  $\alpha = 2.44$  and  $n=1$ , so the estimate of the error is

$$\sigma_\alpha = 1.44$$

Ques 2 →

(a)

Detection of photons by telescope is an independent event than the previous one.

The probability of detecting  $N$  out of  $M$  photons is :-

$$P(N) = \frac{M!}{N!(M-N)!} p^N (1-p)^{M-N}$$

Since these 2 are independent events ~~so the~~ so the joint probability is :-

$$P(M, N) = \frac{\mu^M}{M!} e^{-\mu} \frac{M!}{N!(M-N)!} p^N q^{(M-N)} \quad \text{--- (1)}$$

$$\mu = \lambda t \rightarrow, \quad q = 1 - p$$

(b)

From the previous expression (1)

$$P(M, N) = \frac{\mu^M}{M!} e^{-\mu} \frac{M!}{N!(M-N)!} p^N q^{(M-N)}$$

Marginalization over M

$$P(N) = \frac{p^N q^{-N} e^{-\mu}}{N!} \sum_{M=N}^{\infty} \frac{\mu^M \times q^M}{(M-N)!} \quad \text{--- (2)}$$

The sum starts from  $M=N$  as ~~for~~  $M$  less than  $N$  is not possible. Hence meaning that number of detected photons cannot be greater than number of emitted photon in absence of any ~~any~~ ~~any~~ Systemic error.

(c) The series is

$$\sum_{M=N}^{\infty} \frac{(mq)^M}{(M-N)!}$$

$$= \sum_{K=0}^{\infty} \frac{(mq)^{K+N}}{K!} \quad (\text{Putting } M-N=K)$$

~~$$= \alpha (mq)^N \sum_{K=0}^{\infty} \frac{(mq)^K}{K!}$$~~

~~$$= \alpha (mq)^N e^{mq}$$~~ - ③

From ② and ③, we get

$$p(N) = \frac{p^n q^{-n} e^{-n}}{N!} (mq)^N e^{mq}$$

$$= \frac{\left(\frac{p \cdot mq}{q}\right)^N \times e^{n(q-1)}}{N!}$$

$$= \frac{(pq)^N e^{-pn}}{N!} \quad (\because q-1=p)$$

Ques 3 →

(a) Baye's theorem is given by

$$P(\theta|D) = \frac{P(D|\theta) P(\theta)}{P(D)}$$

where

 $P(\theta|D)$  → Posterior $P(D|\theta)$  → likelihood $P(\theta)$  → Prior $P(D)$  → Evidence

\*  $P(D)$  or Evidence essentially represents the probability of the data, given a model. It is usually neglected if only one model is assumed.

However, in ~~most~~ cases where multiple models are involved, the evidence can no longer be ~~be~~ ignored and must be explicitly calculated along with the other terms.

(b). When we fit a set of data points to some hypothesized function, a sample value of  $\chi^2$  becomes available if we happen to have made independent estimates of the  $y$  variables  $\sim \sigma_y^{-2}$ . The sum of the squares of residuals is equal to  $K^2$  and its value can be used to test whether or not our data points are well described by the hypothesized function.

If  $M$  independent ~~not~~ variables  $x_i$  are normally distributed, each with mean  $m_i$  and variance  $\sigma_i^2$ , then

the quantity  $\chi^2$  is defined by :-

$$\chi^2 = \frac{(y_1 - m_1)^2}{\sigma_1^2} + \frac{(y_2 - m_2)^2}{\sigma_2^2} + \dots + \frac{(y_M - m_M)^2}{\sigma_M^2}$$

$$\Rightarrow \chi^2 = M \sum_{i=1}^M \frac{(y_i - m_i)^2}{\sigma_i^2}$$

$$\chi^2 = \sum_{i=1}^M \frac{(y_i - m_i)^2}{\sigma_i^2}$$

Where  $M$  is the degree of freedom, or simply the number of data points.

- (c) Goodness of fit of a statistical model describes how well the model fits the set of observations. The flow chart below shows how chi-square can be used to test goodness of fit: (Assuming that  $\sigma_i^2$  are given)

Choose a function / model

Calculate expectation values  $m_i$  for each  $x_i$

Find out  $n$  (number of data points)

Calculate  $\chi^2$  using  $\chi^2 = \sum_{k=1}^M \frac{(y_k - m_k)^2}{\sigma_k^2}$

Calculate  $\chi^2/n$

Choose a value of significance

Determine corresponding values of  $\chi^2_{n,\alpha}/n$

Compare  $\chi^2_{n,\alpha}/n$  with  $\chi^2/n$

$\chi^2 > \chi^2_{n,\alpha}$

$\chi^2/n \sim 1$

$\chi^2 < \chi^2_{n,\alpha}$

Over-estimated

$\chi^2$  or Fraudulent data

Model can be ~~good~~

Rejected with  $[(1-\alpha) \times 100] \%$

confidence

Model is a  
good fit

(d). We find the weighted mean  $\bar{M}_2$  and its standard error  $s_{M_2}$  using

$$\bar{x} = \frac{\sum w_k x_k}{\sum w_k}$$

$$\text{For } w_k = \frac{1}{\sigma_k^2} \quad (\text{Weight})$$

$$\text{and } s^2 = \left[ \frac{\sum w_k}{(\sum w_k)^2 - (\sum w_k^2)} \right] \sum w_k (x_k - \bar{x})^2$$

$$\bar{M}_2 \pm s_{M_2} = 91.177 \pm 0.06 \text{ GeV}/c^2$$

We then calculate our sample value of  $\chi^2$  using the equation in part (b); -

$$\chi^2 = \sum_{k=1}^3 \frac{(M_k - \bar{M}_2)^2}{\sigma_k^2} \approx 2.78$$

We expect this value of  $\chi^2$  to be drawn from a Chi-Square distribution with 3 degrees of freedom. The number is 3 because we have used up one degree of freedom to calculate  $M_2$ , the true mass of  $Z^0$  boson.

$$\therefore \chi^2/3 = 2.78/3 \approx 0.93$$

Now from the graph of  $\alpha$  vs  $\chi^2/3$ , we find that for 3 degrees of freedom,  $\alpha \approx 0.42$ , meaning that if the experiment was to be repeated, we won't have a 42% chance of finding a  $\chi^2$  larger than

2.78 , assuming our hypothesis to be correct . ~~the~~

We therefore have no good reason to reject the hypothesis and conclude that the four measurements of the  $Z^*$  boson mass are consistent with each other .

Que 5 →

(a)

(b)

The linear fit plot the functional form of the best fit line is:

$$y = 3.404x + 40.3105$$

This function is chosen because the deviations of the observed points from the ~~is the~~ line in the least

(c).

A polynomial function would be a better fit as given in Sc (image).

(d).

The given data is Heteroskedastic. This is because as we can see from plot g 5 b, the variance of the observed data pts are not ~~same~~ same with  $x$ .

Ques 6 →

		Predicted		
n=165		-ve	+ve	
Actual	+	50	10	
	-	(a)	(b)	
	+	5	100	
	-	(c)	100 (d)	

There are  $n=165$  data points or examples. Out of which 50 are correct rejections (True Negative); 10 are False alarms (False positive), type 1 error; 5 are False negative misses (over looked danger), type 2 error; 100 are ~~True~~ True positive hits. We ~~have~~ have  $K=2$  classes here.

Now accuracy is the percent of correct classifications.

For this model,

$$\text{accuracy} = \frac{a+d}{a+b+c+d} = \frac{TN+TP}{\text{Total}}$$

$$= \frac{50+100}{165} = 0.909$$

$$\text{accuracy} = 0.909 \approx 91\%$$

Recall or True positive Rate or Sensitivity

$$= \frac{TP}{\text{actual positive}} = \frac{d}{c+d} = \frac{100}{5+100} = 0.9523$$

Precision or predicted positive value = TP

$$= \frac{d}{b+d} = \frac{100}{10+100} = 0.91$$

False alarm or False positive rate = FP

$$= \frac{b}{a+b} = \frac{10}{50+10} = \frac{\cancel{0.1666}}{\cancel{60}} = \underline{\underline{0.17}}$$

Ques 7 → K-Means Algorithm advantages :-

- ① If variables are huge, then ~~Does~~ K-Means does most of the times computationally faster than hierarchical clustering if we keep K small.
- ② K-Means produce tighter clusters than hierarchical clustering, especially if the clusters are globular.

K-Means Algorithm disadvantages :-

- ① Difficult to predict K-value
- ② With globular cluster, it did not work well.
- ③ Different initial partitions can result in ~~different~~ different final clusters
- ④ It does not work very well with clusters (in the original data) of different size and different density.

K-Means Algorithm ~~Is~~ is a clustering algorithm.

Ques 8 → Naive Bayes Classification probability,

$$P(\text{Yes} \mid \text{today or feature}) = \frac{P(\text{Feature} \mid \text{Yes}) \times P(\text{Yes})}{P(\text{Feature} \mid \text{Yes}) \times P(\text{Yes}) + P(\text{Feature} \mid \text{No}) \times P(\text{No})}$$

- ①

~~Given Data~~

Feature values for the given ~~data~~ point are:-

Outlook = Sunny , Temperature = Hot

Humidity = Normal , Windy = False

Now since all the features are independent, we can use Multiplication Theorem of probability to get

$P(\text{Feature} \mid \text{Yes})$  and  $P(\text{Feature} \mid \text{No})$

$$\text{i.e. } P(\text{Feature} \mid \text{Yes}) = P(\text{Sunny} \mid \text{Yes}) \times P(\text{Hot} \mid \text{Yes}) \\ \times P(\text{Normal} \mid \text{Yes}) \times P(\text{False} \mid \text{Yes})$$

$$= \frac{3}{9} \times \frac{2}{9} \times \frac{6}{9} \times \frac{6}{9} - (1) . \textcircled{2}$$

In the same way

$$P(\text{Feature} \mid \text{No}) = \frac{2}{9} \times \frac{2}{9} \times \frac{1}{9} \times \frac{2}{9} - (2) . \textcircled{3}$$

$$\text{Now, } P(\text{Yes}) = \frac{9}{14} - \textcircled{4}$$

$$P(\text{No}) = \frac{5}{14} - \textcircled{5}$$

Putting all of these values in eq ①, we get :

$$P(\text{Yes} | \text{Feature}) = \frac{\left( \frac{3}{9} \times \frac{2}{9} \times \frac{6}{9} \times \frac{6}{9} \right) \times \frac{9}{14}}{\left( \frac{3}{9} \times \frac{2}{9} \times \frac{6}{9} \times \frac{6}{9} \right) \times \frac{9}{14} + \left( \frac{2}{5} \times \frac{2}{5} \times \frac{1}{5} \times \frac{3}{5} \right) \times \frac{5}{14}}$$

$$= \frac{1944}{91854} = 0.8223$$

$$\frac{1944}{91854} + \frac{40}{8750}$$

$$P(\text{Yes} | \text{Feature}) = 0.82$$