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# Supplementary material for: Multiresolution dictionary learning for conditional distributions

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## 1 Full conditionals

Introduce the latent variable  $S_i \in \{1, \dots, k\}$ , for  $i = 1, \dots, n$ , denoting the multiscale level used by the  $i$ th subject. Assuming data are normalized prior to analysis, we let  $\mu \sim \mathcal{N}(0, I)$  and  $\sigma = \mathcal{IG}(a, b)$  for the means and variances of the dictionary densities. Let  $n_{B_j}$  be the number of observations allocated to node  $B_j$ . Each Gibbs sampler iteration can be summarized in the following steps.

1. Update  $S_i$  by sampling from the multinomial full conditional with

$$\Pr(S_i = j | -) = \frac{\pi_{B_j(x_i)} f_{B_j(x_i)}(y_i)}{\sum_{h=1}^k \pi_{B_h(x_i)} f_{B_h(x_i)}(y_i)}$$

2. Update stick-breaking random variable  $V_{B_j(x_i)}$ , for  $j = 1, \dots, k$  and  $i = 1, \dots, n$ , from  $\text{Beta}(\beta_p, \alpha_p)$  with  $\beta_p = 1 + n_{B_j}$  and  $\alpha_p = \alpha + \sum_{B_h(x_i) \in de\{B_j(x_i)\}} n_{B_h(x_i)}$ .

3. Update  $(\mu_{B_j(x_i)}, \sigma_{B_j(x_i)})$  by sampling from

$$\begin{aligned} \mu_{B_j} &\sim \mathcal{N}(\bar{y}_{B_j} n_{B_j} / \sigma_{B_j}, (1 + n_{B_j} / \sigma_{B_j})^{-1}) \\ \sigma_{B_j} &\sim \mathcal{IG}\left(a_\sigma, b + 0.5 \sum_{\{i: S_i=j, x_i \in B_j\}} (y_i - \mu_{B_j})^2\right) \end{aligned}$$

with  $a_\sigma = a + n_{B_j}/2$ ,  $\bar{y}_{B_j}$  being the average of the observation  $\{y_i\}$  allocated to node  $B_j$ .

## 2 Predictions

Consider the case we want to predict the response  $y_{n+1}$  for a future subject based on the predictors  $x_{n+1}$  and  $(y_1, \dots, y_n)$ . For each tree level, the new vector of predictors  $x_n$  is allocated to subsets having closer centers with respect some metric. We will consider the euclidean metric. Then, for a new observation the predictive density is defined as

$$p(y_{n+1} | x_{n+1}, y_1, \dots, y_n) = \int f(y_{n+1} | x_{n+1}, \Omega) dp(\Omega | y_1, \dots, y_n) \quad (1)$$

with  $f(y_{n+1} | x_{n+1}, \Omega)$  defined as in (1) and  $\Omega$  being the set of all parameters involved, i.e. weights, location and scale parameters. In order to make inference on the predictive density of  $y_{n+1}$ , at the  $s$ th Gibbs sampler iteration, we will first sample parameters involved in ?? from its posterior, i.e.  $\Omega^{(s)} \sim p(\Omega | y_1, \dots, y_n)$  and then we will sample  $y_{n+1}^{(s)}$  from  $p(y_{n+1} | x_{n+1}, \Omega^{(s)})$ . Let us assume the number of iterations is  $S$  and a burn-in of  $b$  is considered. Then, given the sequence  $(y_{n+1}^{(b+1)}, \dots, y_{n+1}^{(S)})$ , summaries of the predictive density such as mean, variance and quantiles can be computed.

Table 1: Linear manifold example 1: Mean and standard deviations of squared errors under multi-scale stick-breaking (MSB), CART and Lasso for sample size 50 and 100 for different simulation scenarios.

| $p$       | $n$ |      | MSB   | $r = 5$ |       |      | $r = 10$ |       |  |
|-----------|-----|------|-------|---------|-------|------|----------|-------|--|
|           |     |      |       | CART    | LASSO | MSB  | CART     | LASSO |  |
| $1e + 04$ | 50  | MSE  | 0.18  | 0.31    | 0.25  | 0.22 | 0.58     | 0.22  |  |
|           |     | STD  | 0.32  | 0.30    | 0.42  | 0.24 | 0.54     | 0.30  |  |
|           |     | TIME | 3     | 2       | 1     | 3    | 3        | 1     |  |
| $1e + 04$ | 100 | MSE  | 0.18  | 0.27    | 0.26  | 0.20 | 0.41     | 0.52  |  |
|           |     | STD  | 0.26  | 0.42    | 0.46  | 0.23 | 0.46     | 0.78  |  |
|           |     | TIME | 5     | 5       | 2     | 5    | 5        | 1     |  |
| $1e + 05$ | 50  | MSE  | 0.35  | 0.45    | 0.89  | 0.16 | 0.33     | 0.20  |  |
|           |     | STD  | 0.53  | 0.77    | 1.04  | 0.21 | 0.46     | 0.31  |  |
|           |     | TIME | 3     | 25      | 2     | 3    | 27       | 2     |  |
| $1e + 05$ | 100 | MSE  | 0.43  | 0.88    | 0.52  | 0.17 | 0.50     | 0.31  |  |
|           |     | STD  | 0.59  | 1.29    | 0.70  | 0.24 | 0.75     | 0.49  |  |
|           |     | TIME | 7     | 50      | 5     | 7    | 51       | 5     |  |
| $5e + 05$ | 50  | MSE  | 0.11  | 0.16    | 0.15  | 0.83 | 2.26     | 0.92  |  |
|           |     | STD  | 0.15  | 0.24    | 0.19  | 1.01 | 2.60     | 3.69  |  |
|           |     | TIME | 5     | 90      | 11    | 5    | 121      | 10    |  |
| $5e + 05$ | 100 | MSE  | 0.003 | 0.17    | 0.08  | 0.13 | 1.37     | 1.06  |  |
|           |     | STD  | 0.16  | 0.23    | 0.13  | 1.12 | 1.81     | 1.50  |  |
|           |     | TIME | 10    | 214     | 43    | 8    | 227      | 42    |  |
| $7e + 05$ | 50  | MSE  | 1.70  | 1.48    | 1.47  | 0.66 | 1.65     | 1.07  |  |
|           |     | STD  | 2.18  | 2.47    | 1.63  | 0.87 | 1.49     | 0.95  |  |
|           |     | TIME | 6     | 121     | 12    | 7    | 151      | 13    |  |
| $5e + 05$ | 100 | MSE  | 0.69  | 1.36    | 0.82  | 0.78 | 1.52     | 1.43  |  |
|           |     | STD  | 0.94  | 1.47    | 1.28  | 1.03 | 1.34     | 2.11  |  |
|           |     | TIME | 13    | 321     | 41    | 12   | 325      | 44    |  |

Table 2: Linear manifold example 2: Mean and standard deviations of squared errors under multi-scale stick-breaking (MSB), CART and Lasso for different sample sizes

| $p$        | $n$ |     | $r = 2$ |      |       | $r = 5$ |      |       |
|------------|-----|-----|---------|------|-------|---------|------|-------|
|            |     |     | MSB     | CART | LASSO | MSB     | CART | LASSO |
| $10e + 03$ | 100 | MSE | 1.54    | 1.78 | 2.37  | 0.84    | 1.25 | 1.62  |
|            |     | STD | 1.70    | 1.72 | 0.89  | 1.38    | 1.35 | 1.47  |
| $50e + 03$ | 100 | MSE | 0.76    | 0.97 | 1.77  | 0.88    | 1.53 | 1.43  |
|            |     | STD | 1.04    | 1.21 | 3.13  | 1.00    | 1.59 | 2.73  |
| $10e + 04$ | 100 | MSE | 0.77    | 1.01 | 1.61  | 0.67    | 0.46 | 0.97  |
|            |     | STD | 0.94    | 1.13 | 1.85  | 0.82    | 0.61 | 1.16  |
| $20e + 04$ | 100 | MSE | 0.86    | 0.90 | 1.41  | 0.74    | 1.09 | 0.78  |
|            |     | STD | 1.30    | 1.35 | 1.41  | 0.95    | 1.98 | 0.95  |

### 3 Synthetic examples

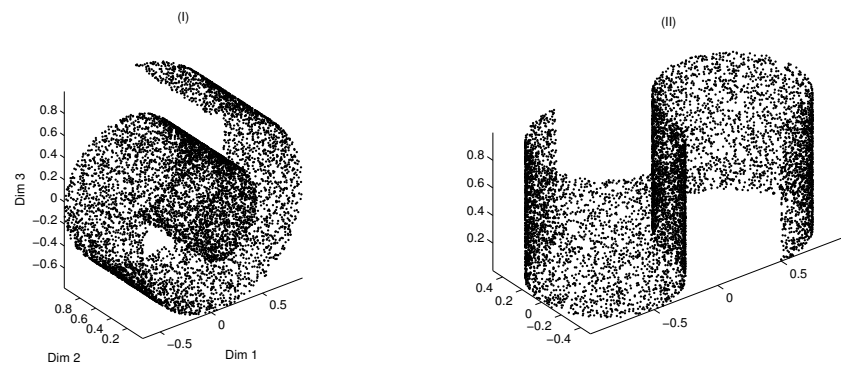


Figure 1: Non-linear manifolds: Swissroll (I) and S-Manifold (II) embedded in  $\mathcal{R}^3$