

# Covert and Reliable Short-Packet Communications against A Proactive Warden

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**Abstract**—Wireless short-packet communications pose challenges to the security and reliability of the transmissions. Besides, the proactive warden compounds these challenges, who detects and interferes with the potential transmission. An eavesdropping channel is introduced by the proactive warden compared with the passive one, resulting in the inapplicability of analytical methods and rendering existing works difficult to use. Thus, effective system design schemes are required for short-packet communications against the proactive wardens. To address this issue, we consider the analysis and design of covert and reliable transmissions for above systems. Specifically, we investigate the reliable and covert performance of the system, detection error probability at the warden and decoding error probability at the receiver are derived, which is affected by both the transmit power and the jamming power. Furthermore, the maximizing the effective throughput optimization framework is proposed under reliability and covertness constraints. Numerical results verify the accuracy of analytical results and the feasibility of the optimization framework. It is shown that the tradeoff between transmission reliability and covertness is changed by the proactive warden compared with the passive one. Besides, it is shown that longer blocklength is always beneficial to improve the throughput for systems with optimized transmission power. But when the transmission rates are fixed, the blocklength should be carefully designed since the maximum one is not optimal in this case since the maximum one is not optimal in this case. **Terms**—covert and reliable transmission, short-packet communications, proactive warden, effective throughput

## I. INTRODUCTION

### A. Introduction

Time-sensitive and mission-critical Internet of Things (IoT) applications have aroused great attention in the fifth-generation (5G) communications systems [1]. The use of short packets meets the stringent low-latency requirements, but it also brings the coding gain loss with short packets, posing challenges to transmission reliability. Besides, massive confidential messages are transmitted in wireless channels in IoT scenarios, which pose unprecedented challenges to transmission security. The exposure of transmission behaviors may bring unpredictable risks and challenges to the transmission. Notably, covert communication offers a solution for this issue, which prevents the transmission behaviors from being detected [2].

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covert and reliable communications with short packets, [2] investigated the effective throughput of the system in additive white Gaussian noise (AWGN) channels. Similarly, [3] considered the achievable bounds on the maximal channel coding rate at given blocklength and the probability of error in AWGN channels system in addition to [2]. [4] then investigated the AWGN channels system in addition to [2]. [5] then investigated the AWGN channels system in addition to [2]. [6] then investigated the AWGN channels system in addition to [2]. [7] then investigated the AWGN channels system in addition to [2]. [8] then investigated the AWGN channels system in addition to [2]. [9] then investigated the AWGN channels system in addition to [2]. [10] then investigated the AWGN channels system in addition to [2]. [11] then investigated the AWGN channels system in addition to [2]. [12] then investigated the AWGN channels system in addition to [2]. 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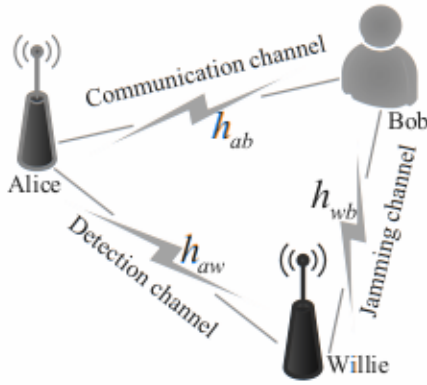


Fig. 1. Covert and reliable communication system against proactive eavesdropper.

communications. To guarantee the reliability requirement, the analysis and design of reliable and covert transmissions against a proactive eavesdropper. Specifically, to guarantee the system covertness requirement, the average detection error probability of the eavesdropper is derived. Furthermore, an optimization problem is formulated and an optimization framework is proposed to maximize the effective throughput of the system with reliability and covertness constraints by jointly designing the transmit power, transmission rate, and blocklength. Numerical simulations verify the tightness of the proposed approximations and the feasibility of the proposed optimization framework for the system.

**Notation:**  $|\cdot|$  denotes the absolute value operator,  $\mathbb{E}(\cdot)$  denotes the average decoding error probability at the receiver is derived. Furthermore,  $\mathcal{CN}(0, \sigma^2)$  denotes the complex Gaussian distribution with zero mean and variance  $\sigma^2$ ,  $\Pr(\cdot)$  denotes the probability of an event,  $Q(x) = \frac{1}{\sqrt{2\pi}} \int_x^\infty \exp(-t^2/2) dt$  denotes the Q-function,  $\Gamma(n) = (n-1)!$  denotes the Gamma function, and  $\gamma(n, x) = \int_0^x t^{n-1} e^{-t} dt$  denotes the lower incomplete Gamma function,  $\psi_0(x) = \frac{d}{dx} \ln \Gamma(x)$  denotes the digamma function while  $\psi^{(n)}(x)$  denotes its  $n$ -th derivative,  $E_1(x) = \int_x^\infty \frac{e^{-t}}{t} dt$  denotes the exponential integral function.

**Notation:**  $|\cdot|$  denotes the absolute value operator.

**A. Signal and Channel Models**

As shown in Fig. 1, a covert wireless communication of an event is considered, where the transmitter (Alice) desires to deliver messages to the receiver (Bob) while keeping a full-duplex eavesdropper (Willie) unaware of the transmission. Willie operates in full-duplex receiving signals from Alice and transmitting jamming signals to Bob simultaneously. Alice and Bob are assumed to be equipped with a single antenna, while Willie is assumed to be equipped with two antennas to support full-duplex functionality (detecting and jamming) [?].

In one transmission round, Alice transmits  $n$  covert signals  $x_a[i]$ ,  $i \in \{1, \dots, n\}$  to Bob, while Willie sends  $n$  jamming signals  $x_w[i]$  to Bob. Besides, Willie also receives signals to detect whether or not Alice has transmitted signals. The transmit power of Alice (Bob) while using full-duplex is denoted as  $P_a$  ( $P_b$ ). Similarly, the jamming power of Willie is denoted as  $P_w$ . We denote the AWGN at Bob and Willie signals as  $n_b$  and  $n_w$ , respectively. Alice and Bob are assumed to be equipped with two antennas, while Willie is assumed to be equipped with two

antennas to support full-duplex functionality (detecting and jamming). Alice to Willie (detection channel,  $h_{aw}$ ) and Willie to Bob (jamming channel,  $h_{wb}$ ) are subject to the quasi-static Rayleigh fading [?]. Specifically,  $h_{aw} \sim \mathcal{CN}(0, \lambda_{aw})$  and  $h_{wb} \sim \mathcal{CN}(0, \lambda_{wb})$ . Besides, the channel coefficients received signals during one transmission round are independently and identically distributed (i.i.d.) among different rounds. The instantaneous channel state information (CSI) is unavailable for Alice since Willie does not cooperate with Alice as an adversarial node while the statistical CSI is able to be estimated through the jamming signal [?]. Besides, the instantaneous CSI is available for Willie from a worst case perspective for covert communication.

**B. Binary Hypothesis Testing at Willie**

In order to detect the presence of covert communications, Willie must distinguish between the following two hypotheses in each transmission round. Specifically,  $h_{ab} \sim \mathcal{CN}(0, \lambda_{ab})$ ,  $h_{aw} \sim \mathcal{CN}(0, \lambda_{aw})$  and  $h_{wb} \sim \mathcal{CN}(0, \lambda_{wb})$ . The channel coefficients remain constant during one transmission round, and are independently and identically distributed (i.i.d.) among different rounds. The instantaneous channel state information (CSI)  $h_{aw}$  is unavailable for Alice since Willie does not cooperate with Alice as an adversarial node while the statistical CSI is able to be estimated through the jamming signal [?]. Besides, the instantaneous CSI is available for Willie from a worst case perspective for covert communication.

$$T = \frac{1}{n} \sum_{i=1}^n |y_w[i]|^2 \stackrel{H_0}{\leq} \tau, \quad (2)$$

**B. Binary Hypothesis Testing at Willie**

where  $T$  is the average power of each received signal at Willie,  $\tau$  denotes the detection threshold,  $D_0$  and  $D_1$  denote the binary decisions that infer whether Alice transmits or not.

Suppose there is no prior knowledge for Willie about when Alice will transmit, the prior probability of either hypothesis is equal. Mathematically, the detection error probability  $\xi$  at Willie is defined as follows [?], [?], [?], [?]

where  $\mathcal{H}_0$  denotes the null hypothesis where Alice has not transmitted,  $\mathcal{H}_1$  denotes the alternative hypothesis where Alice has transmitted.  $y_w[i]$  is the received signal at Willie, and  $\varphi \in [0, 1]$  is the self-interference cancellation coefficient [?], [?].

With a radiometer [?], Willie makes a binary decision as the presence of Alice's transmission with the minimum detection error probability  $\xi^*$ , which is achieved by using the optimal detection threshold  $\tau^*$  that minimizes  $\xi$ .

**C. Effective Throughput with Finite Blocklength**

where  $T$  is the average power of each received signal at Willie,  $\tau$  denotes the detection threshold,  $D_0$  and  $D_1$  denote the binary decisions that infer whether Alice transmits or not.

Suppose there is no prior knowledge for Willie about when Alice will transmit, the prior probability of either hypothesis is equal. Mathematically, the detection error probability  $\xi$  at Willie is defined as follows [?], [?], [?], [?]

$$\xi(\tau) \in \Pr(D_1 | H_0) + \Pr(D_0 | H_1), \quad (5)$$

$$= \Pr(T > \tau | H_0) + \Pr(T < \tau | H_1), \quad (3)$$



where  $\gamma = P_r(D_b | H_0) / (P_r(D_b | H_1) + P_r(D_b | H_0))$  denotes the received signal to noise ratio (SNR) at Bob and  $P_r$  is the probability of correct detection. Willie's ultimate goal is to detect the presence of Alice's transmission [7].

Since the presence of Alice's transmission [7] is affected by fading channels, probability  $\gamma$ , which is achieved by using the optimal detection threshold  $\tau^*$  that minimizes performance. And the effective throughput of the system is given by [2]

$$\eta = nR(1 - \delta), \quad (6)$$

When Alice transmits, the received signal at Bob can be expressed as the expected number of information bits that can be reliably transmitted from Alice to Bob.

$$y_b[i] = h_{ab}x_a[i] + h_{wb}x_w[i] + n_b[i]. \quad (4)$$

### III. COVERTNESS PERFORMANCE ANALYSIS

Based on the received signal (4), Bob can decode the messages. The decoding error cannot be ignored in short-packet communications, which is given by [7]

With detection threshold  $\tau$ , the detection error probability is expressed as [2]

$$\delta = Q\left(\frac{\ln 2\sqrt{n}(\log_2(1 + \gamma_b) - R)}{\gamma(n, \frac{\pi}{2}) - (\gamma_b + 1)^{\frac{n\tau}{\sigma^2 + P_a|h_{aw}|^2}}}\right), \quad (5)$$

$$\xi(\tau) = 1 - \frac{\gamma(n, \frac{\pi}{2}) - (\gamma_b + 1)^{\frac{n\tau}{\sigma^2 + P_a|h_{aw}|^2}}}{\Gamma(n)}, \quad (7)$$

where  $\gamma = P_r(D_b | H_0) / (P_r(D_b | H_1) + P_r(D_b | H_0))$  denotes the received signal to noise ratio (SNR) at Bob and  $P_r$  is the probability of correct detection.

Since Willie knows  $h_{aw}$  in each round, Willie can adjust the optimal threshold  $\tau$  to minimize the detection error probability for each round, which is given by [7]. Since the decoding error probability [7] is affected by fading channels  $h_{ab}$  and  $h_{wb}$ , the average decoding error probability  $\delta$  is adopted to evaluate the reliability performance. And the effective throughput of the system is given by [2]

Notably, from the perspective of Alice, only statistical CSI is available. Therefore, the average detection error probability is derived as the covertness metric [7].

**Theorem 1.** The average detection error probability at Willie with optimal detection threshold under Rayleigh fading channels can be derived as

In this section, to analyze the covertness performance of the system, the average detection error probability is derived as

$$\xi(\tau) = 1 - \frac{\gamma(n, \frac{\pi}{2}) - (\gamma_b + 1)^{\frac{n\tau}{\sigma^2 + P_a|h_{aw}|^2}}}{\Gamma(n)}, \quad (6)$$

where  $B$  is the parameter of Gaussian-Chebyshev Quadrature, and  $\theta_i = \frac{\pi}{4} \left(1 + \cos \frac{(2i-1)\pi}{2B}\right)$  for expression simplification.

Since Willie knows  $h_{aw}$  in each round, Willie can adjust the optimal threshold  $\tau$  to minimize the detection error probability for each round, which is given by [7]. The average detection error probability can be expressed as

$$\xi(\tau^*) = 1 - \frac{\sigma^2 + P_a|h_{aw}|^2}{P_a|h_{aw}|^2} \ln \left( \frac{\sigma^2 + P_a|h_{aw}|^2}{\sigma^2} \right). \quad (8)$$

Notably, from the perspective of Alice, only statistical CSI is available. Therefore, the average detection error probability is derived as the covertness metric [7].

The above integral expression (8) can be obtained, and the proof is completed.  $\square$

Due to the complicated form of (8), it is intractable to further guide the system design. Thus, a tractable lower approximation of the detection error probability in one transmission round is derived first, and then a lower approximation of the average detection error probability is derived.

**Theorem 2.** A lower approximation of the minimum detection error probability in one transmission round is given by

$$\xi(\tau^*) = 1 - \frac{P_a|h_{aw}|^2}{\sigma^2} \ln \left( \frac{\sigma^2 + P_a|h_{aw}|^2}{\sigma^2} \right), \quad (9)$$

where  $B$  is the parameter of Gaussian-Chebyshev Quadrature, and  $\theta_i = \frac{\pi}{4} \left(1 + \cos \frac{(2i-1)\pi}{2B}\right)$ . Proof. By substituting (8) into (7) and considering the probability density function (PDF) of Rayleigh fading channels, the detection error probability can be expressed as

The lower approximation of the minimum detection error probability of (9) is tighter than the approximation based on KL divergence (i.e.,  $\xi^{KL} = 1 - \frac{1}{2}D(P_0||P_1)$ , see Appendix ?? for the detailed definition), which is widely used to evaluate the covertness performance in the existing works [7], [8]. The detailed proof is given in Appendix ??.

The above concise approximation facilitates the performance analysis and optimization design for the covert communication system. It can be used as a metric for the system with AWGN channels [7] or the fading channels when only considering one transmission round [2]. Besides, it can also be adopted to analyze the average detection error probability in fading channels and the system design. Thus, a tractable lower approximation of the average detection error probability at Willie is derived as follows.

**Theorem 2.** A lower approximation of the minimum detection error probability in one transmission round is given by

$$\xi(\tau^*) = 1 - \frac{P_a|h_{aw}|^2}{\sigma^2} \ln \left( \frac{\sigma^2 + P_a|h_{aw}|^2}{\sigma^2} \right), \quad (10)$$

The expression of average detection error probability (9) and its approximation (10) can be extended to the covert communication scenario with a passive warder by setting  $P_w = 0$ . Besides, the lower approximation of the detection error probability in one transmission round given in (9) can also be extended to the scenario with a passive warder by setting  $P_w = 0$ , which can replace the KL divergence based on KL divergence (i.e.,  $\xi^{KL} = 1 - \frac{1}{2}D(P_0||P_1)$ , see Appendix ?? for the detailed definition), which is widely used to evaluate the covertness performance in the existing works [7], [8]. The detailed proof is given in Appendix ??.

**IV. RELIABILITY PERFORMANCE ANALYSIS AND SYSTEM DESIGN**  
In this section, we analyze the reliability performance, the decoding error probability, under the fading channels through jointly optimizing the system parameters.

Notably, from the perspective of Alice, only statistical CSI is available. Therefore, the average detection error probability is derived as the covertness metric [7].







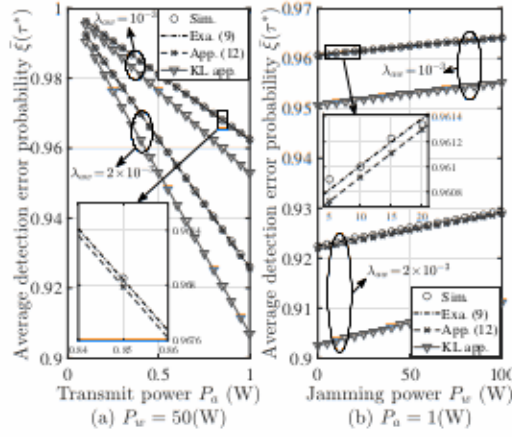


Fig. 2. The detection error probability versus the transmit/jamming power.

In this section, we provide numerical results to show the covert and reliable performance of the short-packet communication system against a proactive warden. The parameter settings are as follows, unless specified otherwise: the fading parameters  $\lambda_{ab} = 5 \times 10^{-3}$ ,  $\lambda_{aw} = \lambda_{wb} = 10^{-3}$ , the AWGN variances  $\sigma_b^2 = \sigma_w^2 = 10^{-1}$  (W), the self-interference cancellation coefficient  $\phi = 10^{-4}$ , the blocklength  $n = 100$ , the minimum blocklength  $n_{\min} = 50$ , the maximum blocklength  $n_{\max} = 200$ , the maximum transmit power  $P_a^{\max} = 5(W)$  the covertness requirement  $\varepsilon = 10^{-1}$  and the reliability requirement  $\kappa = 10^{-1}$ . All the simulation results shown in this paper are obtained by averaging over  $10^4$  channel realizations.

In Fig. 2, the impact of the transmit (jamming) power on the average detection error probability is investigated. The curves with “Sim.”, “Exa. (9)”, “App. (12)”, and “KL app.” denote the results obtained by numerical simulations, the exact widely used KL divergence metric, due to its conciseness and tightness, and the numerical integration combined with the KL divergence metric, respectively.

In Fig. 3, the relationship among the achievable covertness requirement with numerical simulation, reliability requirement is investigated. It can be seen from the figure, larger the tolerance with small  $\kappa$  can be achieved. Conversely, larger simulation results, smaller, can be achieved. Besides, it can be seen that the system performance (covertness and reliability performance) is degraded by the proactive warden. Comparing 50, 100 (W) compared with the passive one ( $P_w = 0$ ). The results show that the tradeoff between transmission covertness and reliability is changed by the proactive warden and the proposed performance evaluations in Sections III and IV can be adopted to guide the system design in the covert channels.

Fig. 4 shows the impact of blocklength on the effective throughput. The curves with marked solid lines have marked dotted lines denote the system performance in the system with passive warden and that with a passive warden, respectively.

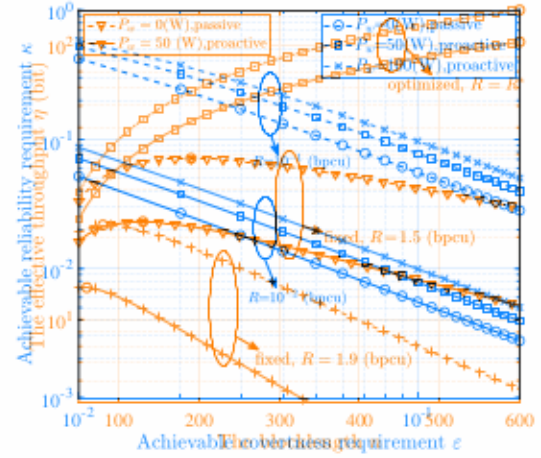


Fig. 3. The achievable reliability with optimized/fixed transmit variables versus the blocklength.

The red dots in the figure indicate the optimal blocklength that maximizes the throughput. It can be seen that in the system with fixed transmission rates, the effective throughput first increases and then decreases with  $n$ . This is because when  $n$  is too small,  $\eta$  is directly limited by the blocklength. On the contrary, when  $n$  is too large, the transmit power is limited by the covertness constraint and the decoding error is too large, resulting in the reduction of effective throughput. In addition, the effective throughput with an optimized transmission rate is always higher than that with a fixed transmission rate, which demonstrates the feasibility of the proposed optimization framework. These results imply that for the system with optimized rates, a longer blocklength is always beneficial to improve the effective throughput. However, for the system with a fixed rate, the optimal blocklength is not necessarily the maximum one, which is critical for the system design.

Fig. 4. The effective throughput with optimized/fixed transmission rates versus the blocklength.

## VI. CONCLUSION

In this paper, we investigated the reliable and covert performance of short-packet communication systems degraded by a proactive warden. Specifically, 50, 100 (W) average detection error probability and its approximation were derived. The tradeoff between the covertness performance and the reliability was derived. The proposed performance evaluation framework was derived to propose the reliability performance in Section III and the analysis can be adopted to optimize the framework was proposed to maximize the effective throughput. Numerical results in Fig. 4 show the blocklength of the proposed approximations and the optimization framework. The performance of the system with a proactive warden was investigated and compared with the passive one and the optimal blocklength system maximize the effective throughput that elaborated with different systems. The red dots in the figure indicate the optimal blocklength that maximizes the throughput. It can be seen that in the system with fixed transmission rates, the effective throughput first increases and then decreases with  $n$ . This is because when  $n$  is too small,  $\eta$  is directly limited by the blocklength. On the contrary, when  $n$  is too large, the transmit power is limited by the covertness constraint and the decoding error is too large, resulting in the reduction of effective throughput. In addition, the effective throughput with an optimized transmission rate is always higher than that with a fixed transmission rate, which demonstrates the feasibility of the proposed optimization framework. These results imply that for the system with optimized rates, a longer blocklength is always beneficial to improve the effective throughput. However, for the system with a fixed rate, the optimal blocklength is not necessarily the maximum one, which is critical for the system design.

## APPENDIX A

### PROOF OF THEOREM 2

We denote  $f_u(x) = \ln\left(\frac{1}{1+x}\right) + 1$  and  $f_l(x) = \frac{x}{1+x}$ . This is because when  $n$  is too small,  $\eta$  is directly limited by the blocklength. On the contrary,

high covertness scenario, the transmission approach is limited by the covertness requirement, and the decoding error is not large, resulting in the reduction of the effective throughput. In addition, the effect of the approximation (20) is obtained. Below, we prove (??) is a lower bound of (??).

When  $x \geq e^{-\frac{\Gamma(n)}{e^{-n}n^{2n-1}}} - 1$ , it holds that  $\xi^l(\tau^*) = 0 < 1 - \frac{\Gamma(n)}{e^{-n}n^{2n-1}}$ . When  $0 \leq x < e^{-\frac{\Gamma(n)}{e^{-n}n^{2n-1}}} - 1$ , we define the function  $f_1(x)$  (is always beneficial to improve the effective throughput). However, for the system with a fixed rate, the optimal blocklength is not necessarily the maximum one, which is critical for the system design. and  $\frac{df_2(x)}{dx} = \frac{(\log(x+1)-x)((x+1)\log(x+1)-x)}{(x+1)^{1/x+1}x^3} < 0$ . Thus, the first-order derivative of  $f_1(x)$  is small than 0, and  $f_1(x) \leq f_1(0) = 0$ .

Thus, for  $0 \leq x < e^{-\frac{\Gamma(n)}{e^{-n}n^{2n-1}}} - 1$ , we can obtain  $\xi^l(\tau^*) = 1 - \frac{\Gamma(n)}{e^{-n}n^{2n-1}} \ln(1+x) < 1 - \frac{\Gamma(n)}{e^{-n}n^{2n-1}}$ , and Theorem 2 is proved.

Against a proactive warder. Specifically, the average detection error probability with the approximation is derived to evaluate the covertness performance. In addition, the

By adopting the Pinsker's inequality, a lower bound of the average decoding error probability is derived to evaluate the reliability performance. Based on the analysis above, an optimization framework was proposed to maximize the effective throughput. Numerical results verified the feasibility of the proposed approximations and the optimization framework. The performance loss brought by a proactive warder was investigated compared with the passive one, and the optimal blocklength to maximize the effective throughput was elaborated with different systems.

Then, we prove that (??) is tighter than the KL divergence approximation, i.e.,  $\xi(\tau^*) > \xi^l(\tau^*) > \xi^{KL}$ .

We denote  $f_3(x) = -2e^{-2n}n^{2n-1}(\Gamma(n))^{-2} \ln^2 x + \ln x + \frac{1}{x} - 1$  with  $\frac{df_3(x)}{dx} = \frac{1}{x}(-2e^{-2n}n^{2n-1}(\Gamma(n))^{-2} \ln x + 1 - \frac{1}{x})$ . In addition, we denote  $f_4(x) = -2e^{-2n}n^{2n-1}(\Gamma(n))^{-2} \ln x + 1 - \frac{1}{x}$  with  $\frac{df_4(x)}{dx} = x^{-2} - 2e^{-2n}n^{2n-1}(\Gamma(n))^{-2}x^{-1}$ , where  $2e^{-2n}n^{2n-1}(\Gamma(n))^{-2} < 1$ , proved as follows.

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