
Tradutor de linguagem NAG para Jason

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O problema

Necessidade de tradução entre as linguagens

Funcionamento da tradução em ferramentas
padrões do Jason

Solução

- BNF
- Analisador Léxico - Flex
- Analisador Sintático - Bison
- Estruturas de dados
- Implementações



1. BNF Base

$\langle \text{programa} \rangle ::= \langle \text{Lagentes} \rangle$

$\langle \text{Lagentes} \rangle ::= (\langle \text{agente} \rangle \text{ “\%” })^+$

$\langle \text{agente} \rangle ::= \text{ “\#” NAME crencas: } \langle \text{Lcrencas} \rangle \text{ objetivos: } \langle \text{Lobjetivos} \rangle \text{ planos: } \langle \text{Lplanos} \rangle$

$\langle \text{Lcrencas} \rangle ::= (\text{ “\{” } \langle \text{nomeCrenca} \rangle \text{ “;”}^* \text{ “\}” })$

$\langle \text{nomeCrenca} \rangle ::= \text{NAME}$

$\langle \text{Lobjetivos} \rangle ::= (\text{ “\{” } \langle \text{nomeObjetivo} \rangle \text{ “;”}^* \text{ “\}” })$

$\langle \text{nomeObjetivo} \rangle ::= \text{NAME}$

$\langle \text{Lplanos} \rangle ::= (\text{ “\{” } \langle \text{nomePlano} \rangle \text{ “;”}^* \text{ “\}” })$

$\langle \text{nomePlano} \rangle ::= \text{NAME } \langle \text{tuplaPlano} \rangle$

$\langle \text{tuplaPlano} \rangle ::= \text{ “(” } \langle \text{eventoGatilho} \rangle \text{ “;” } \langle \text{contexto} \rangle \text{ “;” } \langle \text{corpo} \rangle \text{ “)”}$

$\langle \text{eventoGatilho} \rangle ::= \text{NAME}$

$\langle \text{contexto} \rangle ::= \langle \text{expressaoLogica} \rangle \mid \text{NAME} \mid \varepsilon$

$\langle \text{expressaoLogica} \rangle ::= \text{NAME “E” NAME} \mid \text{NAME “OU” NAME} \mid \text{ “NAO” NAME}$

$\langle \text{corpo} \rangle ::= \text{ “\{” } \langle \text{formulasCorpo} \rangle \text{ “;”}^* \text{ “\}”}$

$\langle \text{formulasCorpo} \rangle ::= \text{NAME}$



2. BNF Final

```
<program> ::= <agents>
<agents> ::= ε
           | <agent> '%' <agents>
<agent> ::= '#' NAME BELIEFS ':' <beliefs> GOALS ':' <goals> PLANS ':' '{' <plans> '}'
<beliefs> ::= '{' <beliefsName> '}'
<beliefsName> ::= ε
               | NAME ';' <beliefsName>
<goals> ::= '{' <goalsName> '}'
<goalsName> ::= ε
              | NAME ';' <goalsName>
<plans> ::= ε
          | <plan> ';' <plans>
<plan> ::= ε
         | NAME <plansTuple>
<plansTuple> ::= '(' <triggerEvent> ';' <context> ';' <body> ')'
<triggerEvent> ::= NAME
<context> ::= ε
            | <logExp>
            | NAME
<logExp> ::= NAME AND NAME
           | NAME OR NAME
           | NOT NAME
<body> ::= '{' <bodysFormula> '}'
<bodysFormula> ::= ε
                | NAME ';' <bodysFormula>
```

3. FLEX



```
%option noyywrap nodefault yylineno
```

```
%{  
    #include "header.h"  
    #include "analise-sintatica.tab.h"  
}%
```

```
%%
```

```
":" |  
";" |  
"{" |  
"}" |  
"(" |  
"%" |  
"#" |  
")" | { return yytext[0]; }  
"E" | { return AND; }  
"OU" | { return OR; }  
"NAO" | { return NOT; }  
"crencas" | { return BELIEFS; }  
"objetivos" | { return GOALS; }  
"planos" | { return PLANS; }  
[a-z][a-zA-Z0-9]* | { yylval.s = strdup(yytext); return NAME; }  
[ \t\r]+ | { }  
[\n] | { }  
[\\n] | { }  
.| { }
```

```
%%
```

4. Bison



```
%{  
    #include<stdio.h>  
    #include<stdlib.h>  
    #include "header.h"  
%}  
  
%union {  
    struct agents *a;  
    struct believes *b;  
    struct goals *g;  
    struct plans *p;  
    struct body *bo;  
    struct planContent *pc;  
    void *v;  
    char *s;  
}  
  
%token <s> NAME BELIEFS GOALS PLANS  
%token <s> OR NOT AND  
  
%type <a> agent agents  
%type <s> triggerEvent context logExp  
%type <b> beliefs beliefsName  
%type <g> goals goalsName  
%type <p> plans plan  
%type <pc> plansTuple  
%type <bo> body bodysFormula  
%type <v> initial;  
  
%start initial  
  
%%
```

4. Bison



```
initial: agents { printList($1); }
;
agents: { $$ = NULL; }
| agent '%' agents { $$ = prependAgent($3, $1); }
;
agent: '#' NAME BELIEFS ':' beliefs GOALS ':' goals PLANS ':' '{' plans '}' { $$ = createAgent($2, $5, $8, $12); }
;
beliefs: '{' beliefsName '}' { $$ = $2; }
;
beliefsName: { $$ = NULL; }
| NAME ';' beliefsName { $$ = prependBelieve($3, $1); }
;
goals: '{' goalsName '}' { $$ = $2; }
;
goalsName: { $$ = NULL; }
| NAME ';' goalsName { $$ = prependGoal($3, $1); }
;
plans: { $$ = NULL; }
| plan ';' plans { $$ = prependPlan($3, $1); }
;
plan: { $$ = NULL; }
| NAME plansTuple { $$ = createPlan($1, $2); }
;
plansTuple: '(' triggerEvent ';' context ';' body ')' { $$ = createContent($2, $4, $6); }
;
triggerEvent: NAME { $$ = $1; }
;
context: { $$ = NULL; }
| logExp { $$ = $1; }
| NAME { $$ = $1; }
;
logExp: NAME AND NAME { $$ = newExp($1, $3, "E"); }
| NAME OR NAME { $$ = newExp($1, $3, "OU"); }
| NOT NAME { $$ = newExp(NULL, $2, "NAO"); }
;
body: '{' bodysFormula '}' { $$ = $2; }
;
bodysFormula: { $$ = NULL; } |
NAME ';' bodysFormula { $$ = prependBody($3, $1); }
;
%%
```


Estrutura de dados

- Estrutura de listas
 - Maior facilidade
- Estrutura dividida
- Junção da lista no final

5. Estrutura de dados



```
struct believes
{
    char *believes;
    struct believes *next;
};
```

```
struct goals
{
    char *goals;
    struct goals *next;
};
```

```
struct body
{
    char *body;
    struct body *next;
};
```

```
struct planContent
{
    char *triggerEvent;
    char *context;
    struct body *body;
};

struct plans
{
    char *name;
    struct planContent *planContent;
    struct plans *next;
};

struct agents
{
    char *name;
    struct believes *believes;
    struct goals *goals;
    struct plans *plans;
    struct agents *next;
};
```

Implementação

- Inserção no início
- Armazenamento primeiro, depois escrita
- Múltiplos agentes escritos em arquivos diferentes de saída

6. Implementações



```
// believes
struct believes *prependBelieve(struct believes *believes, char *newBelieve);
// goals
struct goals *prependGoal(struct goals *goals, char *newGoal);
// planContent
struct planContent *createPlanContent(char *triggerEvent, char *context, struct body *body);

struct body *prependBody(struct body *body, char *newBody);
// plans
struct plans *createPlan(char *name, struct planContent *planContent);

struct plans *prependPlan(struct plans *plans, struct plans *newPlan);

struct planContent *createContent(char *triggerEvent, char *context, struct body *body);
struct agents *createAgent(char *name, struct believes *believes, struct goals *goals, struct plans *plans);
struct agents *prependAgent(struct agents *agents, struct agents *newAgent);
void printAgent(struct agents *agents);
void printList(struct agents *list);
void printAgentInFile(struct agents *agent);
// exp
char *newExp(char *leftSide, char *rightSide, char *operator);
```

6. Implementações

```
struct believes *prependBelieve(struct believes *believes, char *newBelieve)
{
    if (newBelieve == NULL)
    {
        return believes;
    }

    struct believes *new = (struct believes *)malloc(sizeof(struct believes));

    new->believes = (char *)malloc(sizeof(char) * strlen(newBelieve) + 2);

    new->believes = newBelieve;

    strcat(new->believes, ".");
    new->next = believes;

    return new;
}
```

```
struct goals *prependGoal(struct goals *goals, char *newGoal)
{
    if (newGoal == NULL)
    {
        return goals;
    }

    struct goals *new = (struct goals *)malloc(sizeof(struct goals));

    char *formattedGoal = (char *)malloc(sizeof(char) * strlen(newGoal) + 4);
    strcat(formattedGoal, "!");
    strcat(formattedGoal, newGoal);
    strcat(formattedGoal, ".");

    new->goals = formattedGoal;
    new->next = goals;

    return new;
}
```

```
struct body *prependBody(struct body *body, char *newBody)
{
    if (newBody == NULL)
    {
        return body;
    }
    if (body == NULL)
    {
        struct body *new = (struct body *)malloc(sizeof(struct body));

        new->body = (char *)malloc(sizeof(char) * strlen(newBody) + 100);

        strcat(new->body, " .printf(\"");
        strcat(new->body, newBody);
        strcat(new->body, "\\").");
        new->next = body;

        return new;
    }

    struct body *aux = body;

    struct body *new = (struct body *)malloc(sizeof(struct body));

    new->body = (char *)malloc(sizeof(char) * strlen(newBody) + 100);

    strcat(new->body, " .printf(\"");
    strcat(new->body, newBody);
    strcat(new->body, "\\").");
    new->next = body;

    return new;
}
```

6. Implementações

```
struct planContent *createContent(char *triggerEvent, char *context, struct body *body)
{
    struct planContent *new = (struct planContent *)malloc(sizeof(struct planContent));

    if (new == NULL)
    {
        yyerror("out of memory");
        exit(0);
    }

    new->triggerEvent = (char *)malloc(sizeof(char) * strlen(triggerEvent) + 4);
    strcat(new->triggerEvent, "?!");
    strcat(new->triggerEvent, triggerEvent);
    strcat(new->triggerEvent, ":");
    new->context = (char *)malloc(sizeof(char) * strlen(context) + 3);
    strcat(new->context, context);
    strcat(new->context, " ←");
    new->body = body;

    return new;
}
```

```
struct plans *createPlan(char *name, struct planContent *planContent)
{
    struct plans *new = (struct plans *)malloc(sizeof(struct plans));

    if (new == NULL)
    {
        yyerror("out of memory");
        exit(0);
    }

    new->name = name;
    new->planContent = planContent;
    new->next = NULL;

    return new;
}

struct plans *prependPlan(struct plans *plans, struct plans *newPlan)
{
    if (newPlan == NULL)
    {
        return plans;
    }

    newPlan->next = plans;

    return newPlan;
}
```

```
char *newExp(char *leftSide, char *rightSide, char *operator)
{
    char *new = (char *)malloc(1000);
    if (!strcmp(operator, "E"))
    {
        strcpy(new, leftSide);
        strcat(new, " & ");
        strcat(new, rightSide);
    }
    else if (!strcmp(operator, "OU"))
    {
        strcpy(new, leftSide);
        strcat(new, " | ");
        strcat(new, rightSide);
    }
    else if (!strcmp(operator, "NAO") && leftSide == NULL)
    {
        strcpy(new, "not ");
        strcat(new, rightSide);
    }
    else if (!strcmp(operator, "NAO") && rightSide == NULL)
    {
        strcpy(new, "not ");
        strcat(new, leftSide);
    }

    return new;
}
```

6. Implementações

```
struct agents *createAgent(char *name, struct believes *believes, struct goals *goals, struct plans *plans)
{
    struct agents *new = (struct agents *)malloc(sizeof(struct agents));

    if (new == NULL)
    {
        yyerror("out of memory");
        exit(0);
    }

    new->name = name;
    new->believes = believes;
    new->goals = goals;
    new->plans = plans;
    new->next = NULL;

    return new;
}
```

```
struct agents *prependAgent(struct agents *agents, struct agents *newAgent)
{
    if (newAgent == NULL)
    {
        return agents;
    }

    newAgent->next = agents;

    agents = newAgent;

    return agents;
}
```

```
void printAgentInFile(struct agents *agent)
{
    struct stat st = {0};

    if (stat("output", &st) == -1)
    {
        mkdir("output", 0700);
    }

    char *agentName = (char *)malloc(sizeof(char) * strlen(agent->name) + 16);
    strcpy(agentName, "output/");
    strcat(agentName, agent->name);
    strcat(agentName, ".asl");
    FILE *f = fopen(agentName, "w");
    struct believes *auxBelieves = agent->believes;
    while (auxBelieves != NULL)
    {
        fprintf(f, "%s\n", auxBelieves->believes);
        auxBelieves = auxBelieves->next;
    }
    fprintf(f, "\n\n");

    struct goals *auxGoals = agent->goals;
    while (auxGoals != NULL)
    {
        fprintf(f, "%s\n", auxGoals->goals);
        auxGoals = auxGoals->next;
    }

    fprintf(f, "\n\n");

    struct plans *auxPlans = agent->plans;
    while (auxPlans != NULL)
    {
        fprintf(f, "%s", auxPlans->planContent->triggerEvent);
        fprintf(f, " %s", auxPlans->planContent->context);

        struct body *aux = auxPlans->planContent->body;

        while (aux != NULL)
        {
            fprintf(f, " %s\n", aux->body);
            aux = aux->next;
        }

        auxPlans = auxPlans->next;
    }

    fprintf(f, "\n\n");
    free(agentName);
    agentName = NULL;
    fclose(f);
}
```

Obrigado!

