

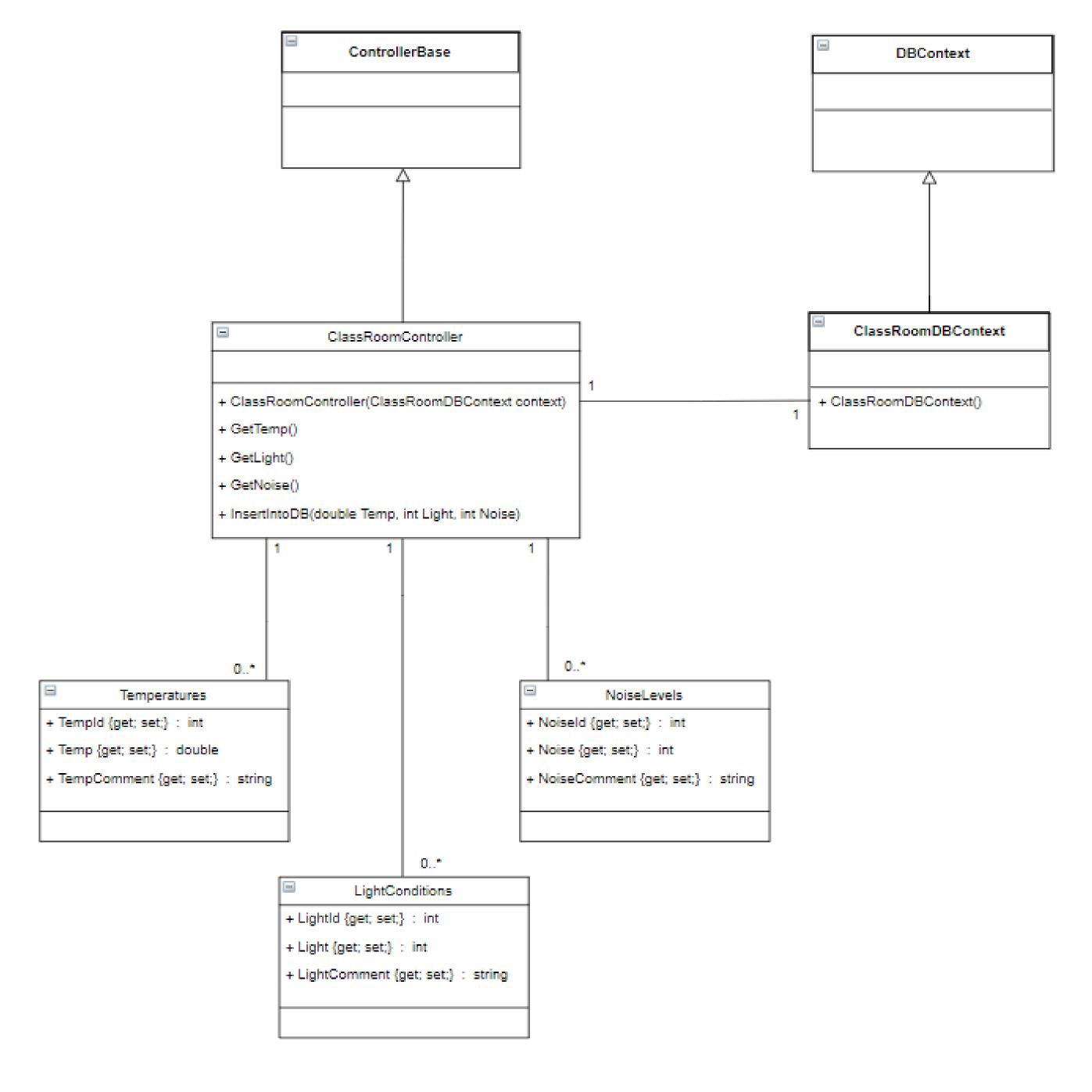
#### Udarbejdet af: Gruppe 1, 4108h3dakp

#### **Indholdsfortegnelse:**

Klassediagram	3
RDS	4
Flowchart	5
Arduino design	6
Arduino kode	7
Arduino til API (connecting & sending data)	11
Database ClassRoomDB	12
API til Angular (skærmprint)	13

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Figur 1 illustrerer projektets Klassediagram:



3

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Figur 2 illustrerer projektets RDS:

### Temperatures

Templd	Temp	TempComment

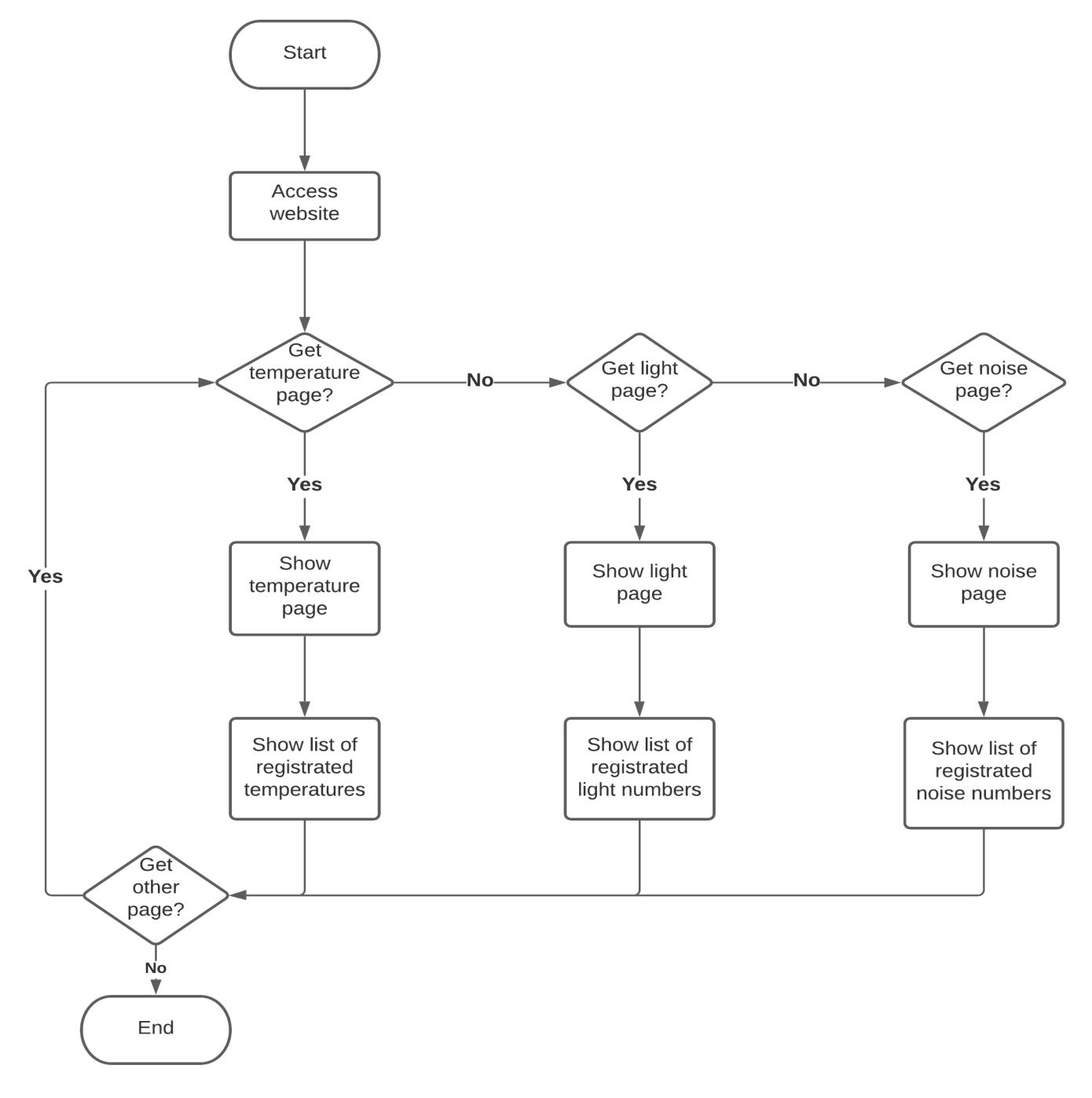
### LightConditions

LightId	Light	LightComment

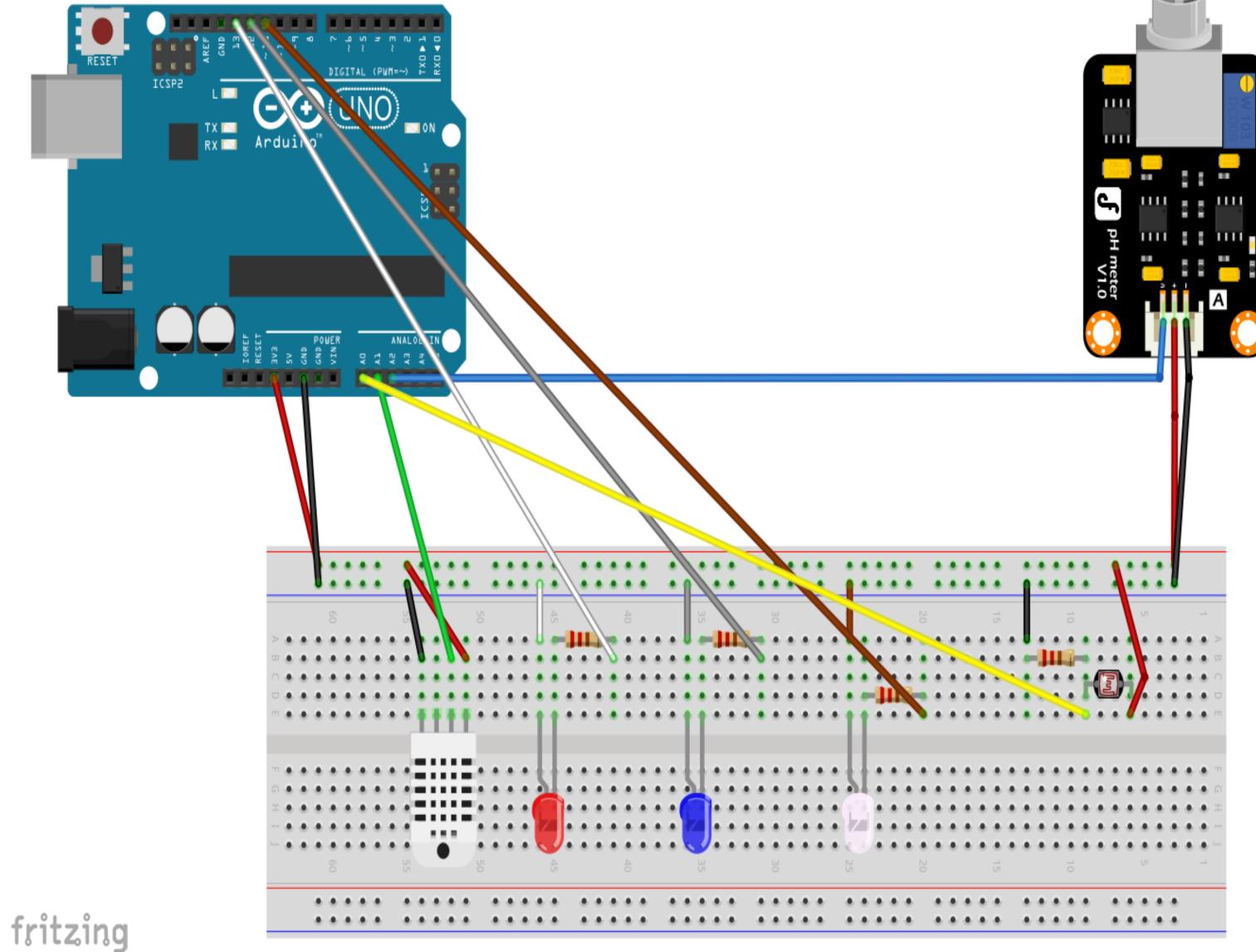
### NoiseLevels

Noiseld	Noise	NoiseComment

Figur 3 illustrerer projektets Flowchart:



Figur 4 illustrerer projektets Arduino design:



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#### Figur 5 illustrerer projektets Arduino kode del 1 af 4:

```
#include <SPI.h>
#include <Ethernet.h>
#include < HttpClient.h >
byte mac[] = { 0xDE, 0xAD, 0xBE, 0xEF, 0xFE, 0xED };
// Set the static IP address to use if the DHCP fails to assign!
// Arduino IP!
IPAddress ip(192, 168, 1, 120);
// PC IP!
IPAddress server(192, 168, 1, 121);
// Initialize the Ethernet client library!
EthernetClient client;
// Variables to measure the speed!
unsigned long beginMicros, endMicros;
unsigned long byteCount = 0;
// set to false for better speed measurement!
bool printWebData = true;
// Create sensors values!
int ThermistorPin = 0;
int Vo;
float R1 = 10000;
float logR2, R2, T;
float c1 = 1.009249522e-03, c2 = 2.378405444e-04, c3 = 2.019202697e-07;
int val1;
int val2;
void setup() {
 // You can use Ethernet.init(pin) to configure the CS pin!
 Ethernet.init(10); // Most Arduino shields
  // initialize digital pin LED_BUILTIN as an output!
 pinMode(LED_BUILTIN, OUTPUT);
 // Open serial communications and wait for port to open!
 Serial.begin(9600);
 while (!Serial) {
 // wait for serial port to connect. Needed for native USB port only!
```

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#### Figur 6 illustrerer projektets Arduino kode del 2 af 4:

```
// start the Ethernet connection!
 Serial.println("Initialize Ethernet with DHCP:");
 if (Ethernet.begin(mac) == 0) {
  Serial.println("Failed to configure Ethernet using DHCP");
  // Check for Ethernet hardware present!
  if (Ethernet.hardwareStatus() == EthernetNoHardware) {
   Serial.println("Ethernet shield was not found. Sorry, can't run without hardware. :(");
   while (true) {
    // do nothing, no point running without Ethernet hardware!
    delay(1);
  if (Ethernet.linkStatus() == LinkOFF) {
   Serial.println("Ethernet cable is not connected.");
  // try to congifure using IP address instead of DHCP!
  Ethernet.begin(mac, ip);
 } else {
  Serial.print(" DHCP assigned IP ");
  Serial.println(Ethernet.localIP());
 // give the Ethernet shield a second to initialize!
 delay(1000);
 Serial.print("connecting to ");
 Serial.print(server);
 Serial.println("...");
 // Calculate temperature and statements!
 Vo = analogRead(A1);
 R2 = R1 * (1023.0 / (float)Vo - 1.0);
 logR2 = log(R2);
T = (1.0 / (c1 + c2*logR2 + c3*logR2*logR2*logR2));
T = T - 293,15;
T = (T * 9.0) / 5.0 + 32.0;
T = (T - 32)/1.8;
 if ( T < 18 )
  // turn the temperture LED off!
  digitalWrite(13, LOW);
 else
```

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#### Figur 7 illustrerer projektets Arduino kode del 3 af 4:

```
// turn the temperture LED on!
  digitalWrite(13, HIGH);
 if ( val1 < 10 )
  // turn the noise-level LED off!
  digitalWrite(12, LOW);
  // turn the noise-level LED on!
  digitalWrite(12, HIGH);
 if ( val2 < 50 )
  // turn the light-condition LED off!
  digitalWrite(11, LOW);
  // turn the light-condition LED on!
  digitalWrite(11, HIGH);
 // Output in monitor!
 Serial.print("Temperature: ");
 Serial.println(T);
 delay(2000);
 val1 = analogRead(A2);
 Serial.print("Noise-Level: ");
 Serial.println(val1);
 delay(2000);
 val2 = analogRead(A0);
 Serial.print("Light-Condition: ");
 Serial.println(val2);
 delay(2000);
 String PostData ="Vi sender data";
 // if you get a connection, report back via serial!
 if (client.connect(server, 44889)) {
  Serial.print("connected to ");
  Serial.println(client.remoteIP());
```

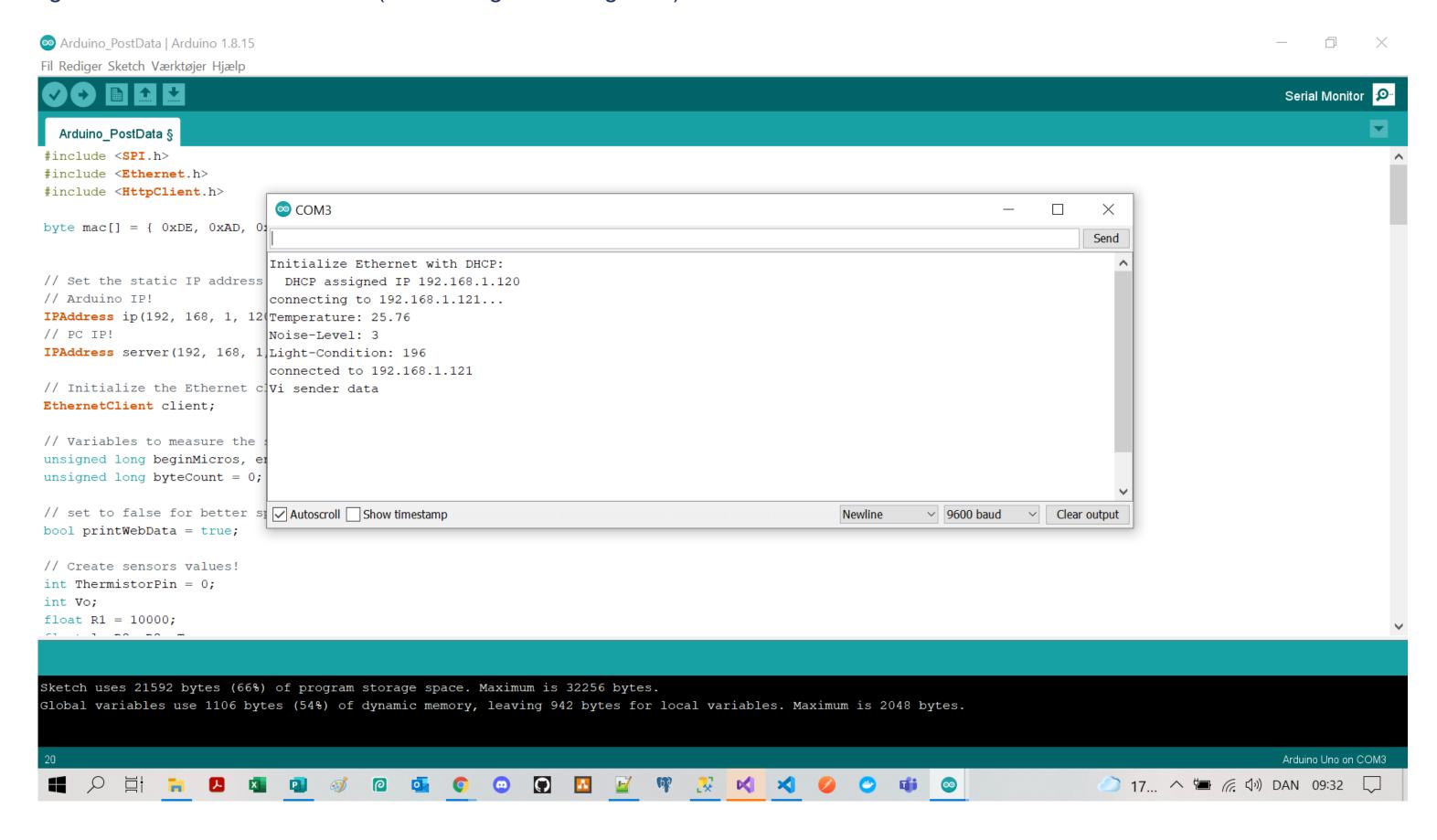
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#### Figur 8 illustrerer projektets Arduino kode del 4 af 4:

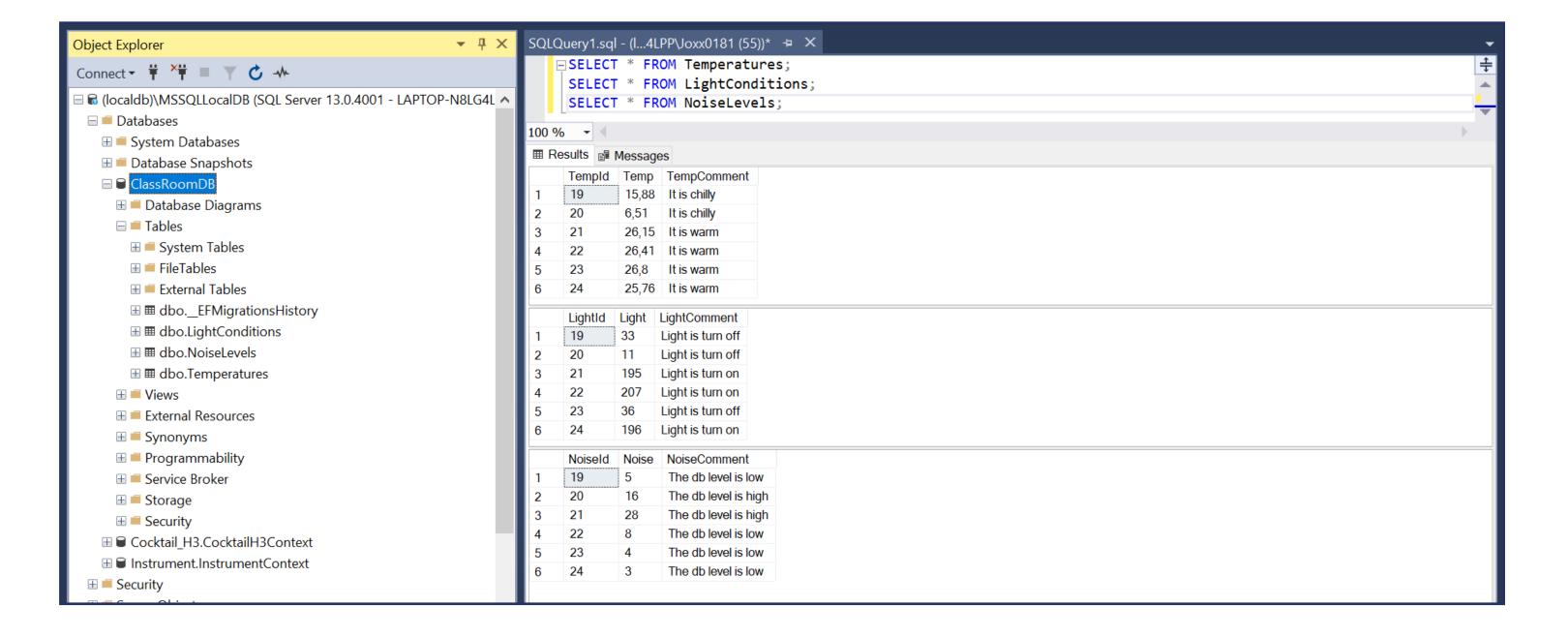
```
// Make a HTTP POST with values from temperature-, light- and noisesesensor request!
  client.println("POST /api/ClassRoom/AllPosts?Temp=" + String(T) + "&Light=" + String(val2) + "&Noise=" + String(val1) + " HTTP/1.1");
  client.println("HOST: 192.168.1.121:44889");
  client.println("User.Agent: Arduino/1.0");
  client.println("Connection: close");
  client.print("Content-length: ");
  client.println(PostData.length());
  client.println();
  Serial.println(PostData);
 // if you didn't get a connection to the server!
  Serial.println("connection failed");
 beginMicros = micros();
void loop() {
 // if there are incoming bytes available rom the server, read them and print them!
 int len = client.available();
 if (len > 0) {
  byte buffer[80];
  if (len > 80) len = 80;
  client.read(buffer, len);
  if (printWebData) {
   // show in the serial monitor (slows some boards)!
   Serial.write(buffer, len);
  byteCount = byteCount + len;
 // if the server's disconnected, stop the client!
 if (!client.connected()) {
  endMicros = micros();
  Serial.println();
  Serial.println("disconnecting.");
  client.stop();
  Serial.print("Received ");
  Serial.print(byteCount);
  Serial.print(" bytes in ");
  float seconds = (float)(endMicros - beginMicros) / 1000000.0;
  Serial.print(seconds, 4);
  float rate = (float)byteCount / seconds / 1000.0;
  Serial.print(", rate = ");
  Serial.print(rate);
  Serial.print(" kbytes/second");
  Serial.println();
  // do nothing forevermore!
  while (true) {
   delay(1);
```

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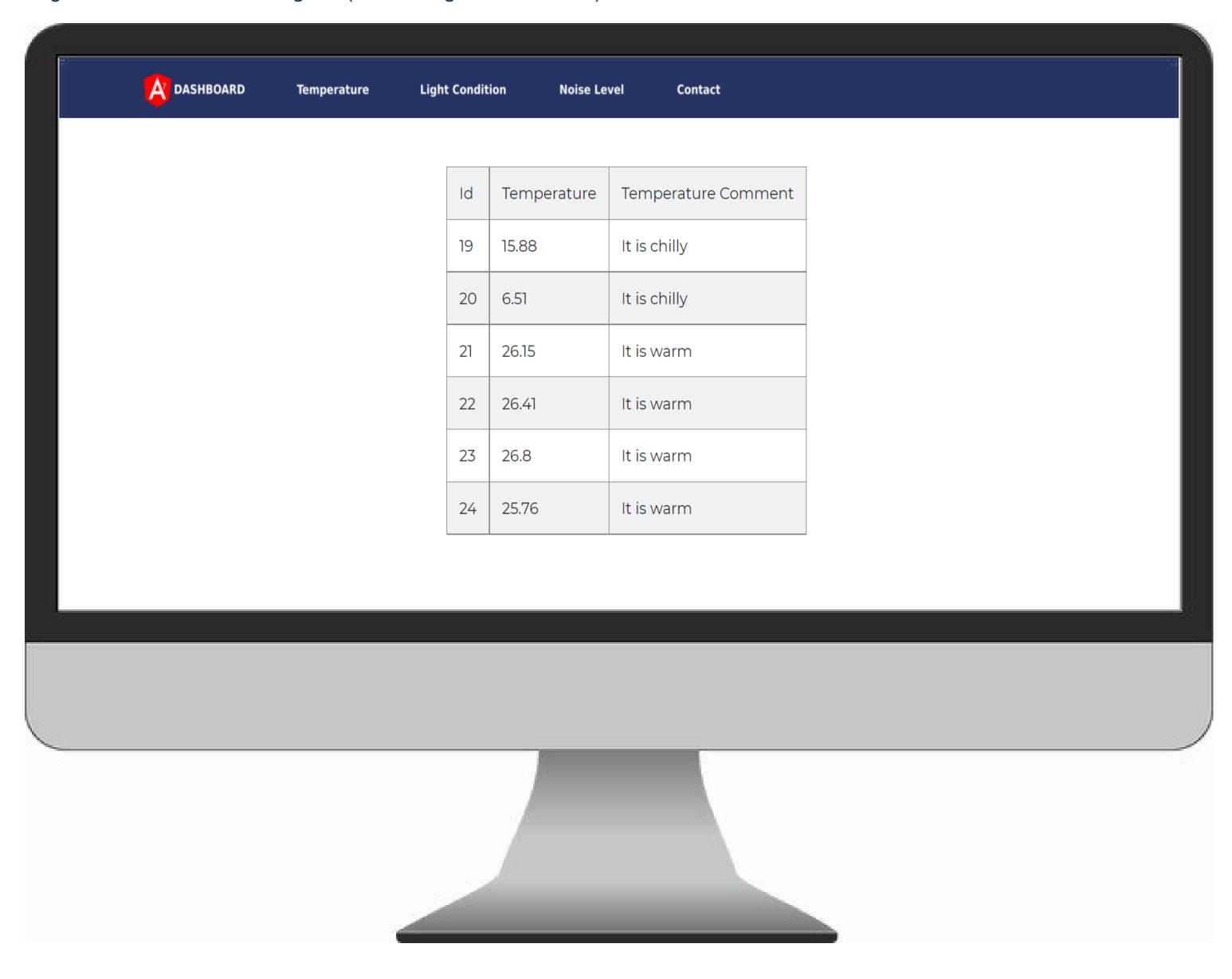
Figur 9 illustrerer Arduino til API (connecting & sending data):



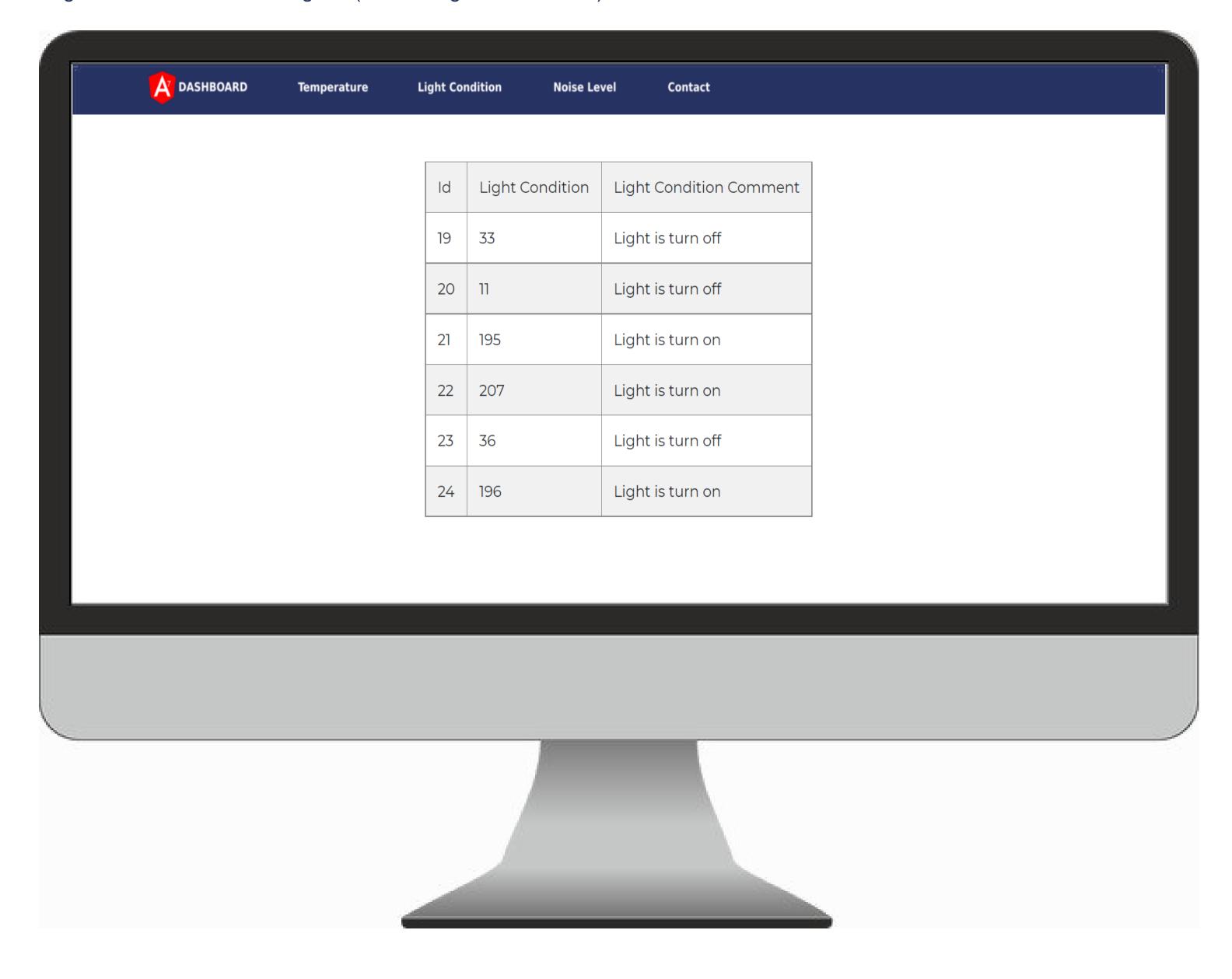
Figur 10 illustrerer Databasen ClassRoomDB:



Figur 11 illustrerer API til Angular (connecting & receive data):



Figur 12 illustrerer API til Angular (connecting & receive data):



Figur 13 illustrerer API til Angular (connecting & receive data):

