Lecture 26 – Type Inference (2)

COSE212: Programming Languages

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 Type inference is the process of automatically inferring the types of expressions.



- Type inference is the process of automatically inferring the types of expressions.
- We have seen three examples to learn how the type inference works.

```
/* RFAE */ def sum(x) = if (x < 1) 0 else x + sum(x - 1); sum
```

```
/* FAE */ val app = n => f => f(n); app(42)(x => x)
```

```
/* FAE */ val id = x => x; val n = id(42); val b = id(true); b
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/* FAE */ val id = x => x; val n = id(42); val b = id(true); b
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/* FAE */ val app = n => f => f(n); app(42)(x => x)
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/* FAE */ val id = x => x; val n = id(42); val b = id(true); b
```

- In this lecture, let's learn the details of the type inference algorithm.
- TIFAE TRFAE with type inference.
 - Type Checker and Typing Rules with Type Inference
 - Interpreter and Natural Semantics

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Type Checker and Typing Rules



Let's **1** design **typing rules** of TIFAE to define when an expression is well-typed in the form of:

$$\Gamma \vdash e : \tau$$

and 2 implement a type checker in Scala according to typing rules:

```
def typeCheck(expr: Expr, tenv: TypeEnv): Type = ???
```

The type checker returns the **type** of e if it is well-typed, or rejects it and throws a **type error** otherwise.

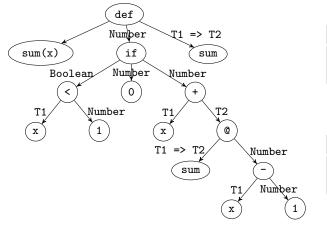
We will keep track of the **variable types** using a **type environment** Γ as a mapping from variable names to their types.

Type Environments
$$\Gamma \in \mathbb{F} = \mathbb{X} \xrightarrow{\mathsf{fin}} \mathbb{T}$$
 (TypeEnv)

Recall: Example 1 - sum



In addition, we need to keep track of the **solution** for **type constraints** over **type variables** to infer the types of expressions.



Type Environment

Type Lilvironinent		
X	\mathbb{T}	
х	T1	
sum	T1 => T2	

Solution

\mathbb{X}_{α}	\mathbb{T}
T1	Number
T2	Number

Solutions for Type Constraints



A **solution** is a mapping from **type variables** to **types** or •.

Types
$$\mathbb{T}\ni\tau::=\operatorname{num}\mid\operatorname{bool}\mid\tau\to\tau\mid\alpha\quad\text{(Type)}$$
 Solutions
$$\psi\ \in\Psi=\mathbb{X}_\alpha\xrightarrow{\operatorname{fin}}(\mathbb{T}\uplus\{\bullet\})\quad\text{(Solution)}$$
 Type Variables
$$\alpha\ \in\mathbb{X}_\alpha\quad\text{(Int)}$$

```
type Solution = Map[Int, Option[Type]]
```

Note that ● (None) represents a **not yet solved** (**free**) type variable.

Solutions for Type Constraints



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Types
$$\mathbb{T}\ni\tau::=\operatorname{num}\mid\operatorname{bool}\mid\tau\to\tau\mid\alpha\quad\text{(Type)}$$
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 Type Variables
$$\alpha\ \in\mathbb{X}_{\alpha}\quad\text{(Int)}$$

```
type Solution = Map[Int, Option[Type]]
```

Note that ● (None) represents a **not yet solved** (free) type variable.

Now, we have new forms of type checker and typing rules.

```
def typeCheck(expr: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = ????
```

$$\Gamma, \psi \vdash e : \tau, \psi$$

Similar to the memory passing in MFAE for mutation, we will pass the solution ψ and update it during type checking.

Numbers



```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
    ...
    case Num(n) => (NumT, sol)
```

$$\boxed{\Gamma, \psi \vdash e : \tau, \psi}$$

$$\tau\text{-Num }\overline{\Gamma,\psi \vdash n:\mathtt{num},\psi}$$

Additions



```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
    ...
    case Add(1, r) =>
        val (lty, sol1) = typeCheck(1, tenv, sol)
        val (rty, sol2) = typeCheck(r, tenv, sol1)
        val sol3 = unify(lty, NumT, sol2)
        val sol4 = unify(rty, NumT, sol3)
        (ty, sol4)
```

$$\Gamma, \psi \vdash e : \tau, \psi$$

The unify function that takes two types must be the same and updates the given solution. We will see how it works later.

Conditionals



```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
...
case If(c, t, e) =>
  val (cty, sol1) = typeCheck(c, tenv, sol)
  val (tty, sol2) = typeCheck(t, tenv, sol1)
  val (ety, sol3) = typeCheck(e, tenv, sol2)
  val sol4 = unify(cty, BoolT, sol3)
  val sol5 = unify(tty, ety, sol4)
  (tty, sol5)
```

$$\Gamma, \psi \vdash e : \tau, \psi$$

$$\tau - \texttt{If} \ \frac{\Gamma, \psi \vdash e_c : \tau_c, \psi_c \qquad \Gamma, \psi_c \vdash e_t : \tau_t, \psi_t \qquad \Gamma, \psi_t \vdash e_e : \tau_e, \psi_e}{\Gamma, \psi \vdash \texttt{if} \ (e_c) \ e_t \ \texttt{else} \ e_e : \tau_t, \psi''}$$





```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
    ...

    case Val(x, e, b) =>
      val (ety, sol1) = typeCheck(e, tenv, sol)
      typeCheck(b, tenv + (x -> ety), sol1)

    case Id(x) => tenv.getOrElse(x, error(s"free identifier: $x"))
```

$$\boxed{\Gamma, \psi \vdash e : \tau, \psi}$$

$$\tau-\mathrm{Val}\ \frac{\Gamma,\psi_0\vdash e_1:\tau_1,\psi_1\qquad \Gamma[x:\tau_1],\psi_1\vdash e_2:\tau_2,\psi_2}{\Gamma,\psi_0\vdash \mathrm{val}\ x=e_1;\ e_2:\tau_2,\psi_2}$$

$$\tau\mathrm{-Id}\;\frac{x\in\mathsf{Domain}(\Gamma)}{\Gamma,\psi\vdash x:\Gamma(x),\psi}$$

Function Definitions



```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
...
  case Fun(p, b) =>
    val (pty, sol1) = newTypeVar(sol)
    val (rty, sol2) = typeCheck(b, tenv + (p -> pty), sol1)
    (ArrowT(pty, rty), sol2)
```

$$\Gamma, \psi \vdash e : \tau, \psi$$

$$\tau-\operatorname{Fun}\,\frac{\alpha_p\notin\psi\quad\quad\Gamma[x:\alpha_p],\psi[\alpha_p\mapsto\bullet]\vdash e:\tau,\psi'}{\Gamma,\psi\vdash\lambda x.e:\alpha_p\to\tau,\psi'}$$

We need to introduce a **new type variable** α_p for the parameter x.





```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
...
case Rec(f, p, b, s) =>
  val (pty, sol1) = newTypeVar(sol)
  val (rty, sol2) = newTypeVar(sol1)
  val fty = ArrowT(pty, rty)
  val tenv1 = tenv + (f -> fty)
  val tenv2 = tenv1 + (p -> pty)
  val (bty, sol3) = typeCheck(b, tenv2, sol2)
  val sol4 = unify(bty, rty, sol3)
  typeCheck(s, tenv1, sol4)
```

$$\Gamma, \psi \vdash e : \tau, \psi$$

$$\tau-\text{Rec} \begin{array}{c} \alpha_p,\alpha_r\notin\psi \quad \alpha_p\neq\alpha_r \quad \Gamma_1=\Gamma[x_f:(\alpha_p\to\alpha_r)]\\ \Gamma_2=\Gamma_1[x_p:\alpha_p] \quad \Gamma_2,\psi[\alpha_p\mapsto\bullet,\alpha_r\mapsto\bullet]\vdash e_b:\tau_b,\psi_b\\ \frac{\text{unify}(\tau_b,\alpha_r,\psi_b)=\psi_r \quad \Gamma_1,\psi_r\vdash e_s:\tau_s,\psi_s}{\Gamma,\psi\vdash \text{def }x_f(x_p)=e_b;\ e_s:\tau_s,\psi_s} \end{array}$$

Function Applications



```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
...
    case App(f, a) =>
        val (fty, sol1) = typeCheck(f, tenv, sol)
        val (aty, sol2) = typeCheck(a, tenv, sol1)
        val (rty, sol3) = newTypeVar(sol2)
        val sol4 = unify(ArrowT(aty, rty), fty, sol3)
        (rty, sol4)
```

$$\Gamma, \psi \vdash e : \tau, \psi$$

$$\tau-\texttt{App} \ \frac{\alpha_r \notin \psi_a \quad \ \ \, \inf \texttt{y}(\tau_a \to \alpha_r, \tau_f, \psi_a[\alpha_r \mapsto \bullet]) = \psi'}{\Gamma, \psi \vdash e_f(e_a) : \alpha_r, \psi'}$$

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Definition (Type Unification)

Type unification is the process of updating a solution to make two types equal. If the types are not unifiable, then this process fails and throws an exception.

$$\mathtt{unify}: (\mathbb{T} \times \mathbb{T} \times \Psi) \rightharpoonup \Psi$$

For example, if we unify a type variable α and the number type num, the solution $[\alpha \mapsto \bullet]$ is updated to $[\alpha \mapsto \text{num}]$.

$$\mathtt{unify}(\alpha,\mathtt{num},\varnothing) = [\alpha \mapsto \mathtt{num}]$$



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$$\mathtt{unify}(\alpha,\mathtt{num},\varnothing) = [\alpha \mapsto \mathtt{num}]$$

Before, we define the type unification, we need to define the **type resolving** and **occurrence checking** functions.

- **1** Type resolving is the process of recursively resolving a type variable to its representative type to deal with the **type aliasing**.
- Occurrence checking is the process of checking whether a type variable occurs in a type to detect recursive types.



To understand why we need the **type resolving** function, let's consider the following example:

$$\mathtt{unify}(\alpha_1,\mathtt{num},\psi_1)=\psi_2$$

Solution

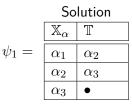
	\mathbb{X}_{α}	\mathbb{T}
$\psi_1 =$	α_1	α_2
	α_2	α_3
	α_3	•

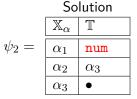
$$\psi_2 =$$



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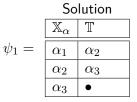






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	Solution	
	\mathbb{X}_{α}	\mathbb{T}
$\psi_2 =$	α_1	num
	α_2	α_3
	α_3	•

If we update α_1 to num in the solution ψ_2 , it misses the information that α_2 and α_3 are also num.



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	Solution	
	\mathbb{X}_{α}	\mathbb{T}
$\psi_1 =$	α_1	α_2
	α_2	α_3
	α_3	•

	Solution	
	\mathbb{X}_{α}	\mathbb{T}
$\psi_2 =$	α_1	α_2
	α_2	α_3
	α_3	num

If we directly update α_1 to num in the solution ψ_2 , it misses the information that α_2 and α_3 are also num.

Instead, we need to **resolve** the type variable α_1 to find its **representative type** (i.e., α_3) and unify it with num to deal with the **type aliasing**.





We can define the **type resolving** function as follows:

$$\mathtt{resolve}: (\mathbb{T} \times \Psi) \to \mathbb{T}$$

$$\mathtt{resolve}(\tau,\psi) = \left\{ \begin{array}{ll} \mathtt{resolve}(\tau',\psi) & \mathrm{if} \ \tau = \alpha \wedge \psi(\alpha) = \tau' \\ \tau & \mathrm{otherwise} \end{array} \right.$$

and implement it in Scala as follows:

```
def resolve(ty: Type, sol: Solution): Type = ty match
  case VarT(k) => sol(k) match
  case Some(ty) => resolve(ty, sol)
  case None => ty
  case _ => ty
```



Let's understand why we need the **occurrence checking** function:

$$\mathtt{unify}(\alpha_1,\mathtt{num} o \alpha_1,\psi) = \psi'$$

Can we unify α_1 and num $\rightarrow \alpha_1$?



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$$\mathtt{unify}(\alpha_1,\mathtt{num} o \alpha_1,\psi) = \psi'$$

Can we unify α_1 and num $\to \alpha_1$? **No!** because it requires **recursive types** not supported in our type system.



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Can we unify α_1 and num $\to \alpha_1$? **No!** because it requires **recursive types** not supported in our type system.

Let's define the **occurrence checking** function to detect type constraints that require recursive types

$$\mathtt{occur}(\alpha,\tau,\psi) = \left\{ \begin{array}{ll} \mathtt{true} & \mathsf{if} \ \tau = \alpha \\ \mathtt{occur}(\alpha,\tau_p,\psi) \lor \mathtt{occur}(\alpha,\tau_r,\psi) & \mathsf{if} \ \tau = (\tau_p \to \tau_r) \\ \mathtt{false} & \mathsf{otherwise} \end{array} \right.$$



Let's understand why we need the occurrence checking function:

$$\mathtt{unify}(\alpha_1,\mathtt{num} o \alpha_1,\psi) = \psi'$$

Can we unify α_1 and num $\to \alpha_1$? **No!** because it requires **recursive types** not supported in our type system.

Let's define the **occurrence checking** function to detect type constraints that require recursive types

$$\mathtt{occur}: (\mathbb{X}_\alpha \times \mathbb{T} \times \Psi) \to \mathtt{bool} \\ \mathtt{occur}(\alpha, \tau, \psi) = \left\{ \begin{array}{ll} \mathtt{true} & \mathsf{if} \ \tau = \alpha \\ \mathtt{occur}(\alpha, \tau_p, \psi) \vee \mathtt{occur}(\alpha, \tau_r, \psi) & \mathsf{if} \ \tau = (\tau_p \to \tau_r) \\ \mathtt{false} & \mathsf{otherwise} \end{array} \right.$$

and implement it in Scala as follows:

```
def occurs(k: Int, ty: Type, sol: Solution): Boolean = resolve(ty, sol) match
  case VarT(1) => k == 1
  case ArrowT(pty, rty) => occurs(k, pty, sol) || occurs(k, rty, sol)
  case _ => false
```



Using the **type resolving** and **occurrence checking** functions, we could define the **type unification** as a partial function:

$$\boxed{\mathtt{unify}: (\mathbb{T} \times \mathbb{T} \times \Psi) \rightharpoonup \Psi}$$

•

- 1
- 2
- 3



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$$\boxed{\mathtt{unify}: (\mathbb{T} \times \mathbb{T} \times \Psi) \rightharpoonup \Psi}$$

where $\tau_1' = \mathtt{resolve}(\tau_1, \psi)$ and $\tau_2' = \mathtt{resolve}(\tau_2, \psi)$.

- First, it resolves the types τ_1 and τ_2 with the current solution ψ into τ_1' and τ_2' using the **type resolving** function resolve.
- 2
- 3



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$$\boxed{\mathtt{unify}: (\mathbb{T} \times \mathbb{T} \times \Psi) \rightharpoonup \Psi}$$

$$\begin{cases} \psi[\alpha \mapsto \tau_2'] & \text{if } \tau_1' = \alpha \wedge \neg \mathsf{occur}(\alpha, \tau_2') \\ \psi[\alpha \mapsto \tau_1'] & \text{if } \tau_2' = \alpha \wedge \neg \mathsf{occur}(\alpha, \tau_1') \end{cases}$$

where $\tau_1' = \mathtt{resolve}(\tau_1, \psi)$ and $\tau_2' = \mathtt{resolve}(\tau_2, \psi)$.

- First, it resolves the types τ_1 and τ_2 with the current solution ψ into τ_1' and τ_2' using the **type resolving** function resolve.
- 2 If one of τ'_1 or τ'_2 is a type variable, it checks recursive types using the **occurrence checking** and updates the solution of the type variable.





Using the **type resolving** and **occurrence checking** functions, we could define the **type unification** as a partial function:

$$\boxed{\mathtt{unify}: (\mathbb{T} \times \mathbb{T} \times \Psi) \rightharpoonup \Psi}$$

$$\begin{aligned} & \text{unify}(\tau_1,\tau_2,\psi) = \\ & \begin{cases} \psi & \text{if } \tau_1' = \text{num} \wedge \tau_2' = \text{num} \\ \psi & \text{if } \tau_1' = \text{bool} \wedge \tau_2' = \text{bool} \\ \text{unify}(\tau_{1,r},\tau_{2,r}, \text{unify}(\tau_{1,p},\tau_{2,p},\psi)) & \text{if } \tau_1' = (\tau_{1,p} \to \tau_{1,r}) \wedge \tau_2' = (\tau_{2,p} \to \tau_{2,r}) \\ \psi & \text{if } \tau_1' = \alpha = \tau_2' \\ \psi[\alpha \mapsto \tau_2'] & \text{if } \tau_1' = \alpha \wedge \neg \text{occur}(\alpha,\tau_2') \\ \psi[\alpha \mapsto \tau_1'] & \text{if } \tau_2' = \alpha \wedge \neg \text{occur}(\alpha,\tau_1') \end{cases} \end{aligned}$$

where $\tau_1' = \mathtt{resolve}(\tau_1, \psi)$ and $\tau_2' = \mathtt{resolve}(\tau_2, \psi)$.

- **1** First, it resolves the types τ_1 and τ_2 with the current solution ψ into τ_1' and τ_2' using the **type resolving** function resolve.
- 2 If one of τ_1' or τ_2' is a type variable, it checks recursive types using the **occurrence checking** and updates the solution of the type variable.
- **3** Otherwise, it checks au_1' and au_2' are equal or recursively unifies them.





```
\begin{aligned} & \text{unify}(\tau_1,\tau_2,\psi) = \\ & \begin{cases} \psi & \text{if } \tau_1' = \text{num} \wedge \tau_2' = \text{num} \\ \psi & \text{if } \tau_1' = \text{bool} \wedge \tau_2' = \text{bool} \\ \text{unify}(\tau_{1,r},\tau_{2,r},\text{unify}(\tau_{1,p},\tau_{2,p},\psi)) & \text{if } \tau_1' = (\tau_{1,p} \to \tau_{1,r}) \wedge \tau_2' = (\tau_{2,p} \to \tau_{2,r}) \\ \psi & \text{if } \tau_1' = \alpha = \tau_2' \\ \psi[\alpha \mapsto \tau_2'] & \text{if } \tau_1' = \alpha \wedge \neg \text{occur}(\alpha,\tau_2') \\ \psi[\alpha \mapsto \tau_1'] & \text{if } \tau_2' = \alpha \wedge \neg \text{occur}(\alpha,\tau_1') \end{cases} \end{aligned}
```

where $\tau_1' = \mathtt{resolve}(\tau_1, \psi)$ and $\tau_2' = \mathtt{resolve}(\tau_2, \psi)$.

And, we can implement the **type unification** function in Scala as follows:

```
def unify(lty: Type, rty: Type, sol: Solution): Solution =
  (resolve(lty, sol), resolve(rty, sol)) match
  case (NumT, NumT) => sol
  case (BoolT, BoolT) => sol
  case (ArrowT(lpty, lrty), ArrowT(rpty, rrty)) =>
    unify(lrty, rrty, unify(lpty, rpty, sol))
  case (VarT(k), VarT(l)) if k == l => sol
  case (VarT(k), rty) if !occurs(k, rty, sol) => sol + (k -> Some(rty))
  case (lty, VarT(k)) if !occurs(k, lty, sol) => sol + (k -> Some(lty))
  case _ => error(s"Cannot unify ${lty.str} and ${rty.str}")
```

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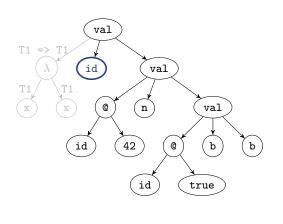
3. Type Inference with Let-Polymorphism

Type Generalization

Type Instantiation

Recall: Example 3 – id





Type Environment		
\mathbb{X}	\mathbb{T}	
id	[T1] { T1 => T1 }	

		Solution
\mathbb{X}_{α}	T	
T1	_	

Let's **generalize** the type T1 => T1 into a **polymorphic type** for id with **type variable** T1 as a **type parameter**.

We call this **let-polymorphism** because it only introduces polymorphism for the let-binding (e.g., val).

Type Environment with Type Schemes



We need to extend the **type environment** with **type schemes**, restricted forms of polymorphic types.

Type Environments
$$\Gamma \ \in \ \mathbb{\Gamma} = \mathbb{X} \xrightarrow{\operatorname{fin}} \mathbb{T}^{\forall}$$
 Type Schemes
$$\forall (\alpha^*).\tau = \tau^{\forall} \ \in \ \mathbb{T}^{\forall} = \mathbb{X}_{\alpha}^* \times \mathbb{T}$$
 Types
$$\mathbb{T} \ni \ \tau ::= \operatorname{num} \mid \operatorname{bool} \mid \tau \to \tau \mid \alpha$$

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$$\mathbb{T} \ni \ \tau ::= \mathrm{num} \mid \mathrm{bool} \mid \tau \to \tau \mid \alpha$$

Note that polymorphic types are not types in TIFAE, and **type schemes** are restricted forms of polymorphic types used in type environments.





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Note that polymorphic types are not types in TIFAE, and **type schemes** are restricted forms of polymorphic types used in type environments.

We can define the **type environment** and **type schemes** in Scala:

```
// type environments
type TypeEnv = Map[String, TypeScheme]
// type schemes
case class TypeScheme(ks: List[Int], ty: Type)
```

```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
    ...

case Val(x, e, b) =>
    val (ety, sol1) = typeCheck(e, tenv, sol)
    val polyty = gen(ety, tenv, sol1)
    typeCheck(b, tenv + (x -> polyty), sol1)
```

$$\Gamma, \psi \vdash e : \tau, \psi$$

$$\tau\text{-Val}\ \frac{ \begin{array}{ccc} \Gamma, \psi_0 \vdash e_1 : \tau_1, \psi_1 \\ \hline \tau\text{-Val}\ \frac{\text{gen}(\tau_1, \Gamma, \psi_1) = \tau_1^{\forall} & \Gamma[x : \tau_1^{\forall}], \psi_1 \vdash e_2 : \tau_2, \psi_2 \\ \hline \Gamma, \psi_0 \vdash \text{val}\ x = e_1;\ e_2 : \tau_2, \psi_2 \end{array} }$$

We need to **generalize** the type τ_1 of the expression e_1 into a **type** scheme τ_1^{\forall} using the **type generalization** function gen.

```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
    ...

case Val(x, e, b) =>
    val (ety, sol1) = typeCheck(e, tenv, sol)
    val polyty = gen(ety, tenv, sol1)
    typeCheck(b, tenv + (x -> polyty), sol1)
```

$$\Gamma, \psi \vdash e : \tau, \psi$$

$$\tau\text{-Val}\ \frac{ \begin{array}{cccc} \Gamma, \psi_0 \vdash e_1 : \tau_1, \psi_1 \\ \hline \tau\text{-Val}\ & \Gamma[x:\tau_1^{\forall}], \psi_1 \vdash e_2 : \tau_2, \psi_2 \\ \hline \Gamma, \psi_0 \vdash \text{val}\ & x = e_1;\ e_2 : \tau_2, \psi_2 \\ \end{array}}$$

We need to **generalize** the type τ_1 of the expression e_1 into a **type** scheme τ_1^{\forall} using the **type generalization** function gen. For example,

$$gen(\alpha \to \alpha, \varnothing, [\alpha \mapsto \bullet]) = \forall \alpha. (\alpha \to \alpha)$$



We can define the **type generalization** function gen as follows:

$$\gcd(\tau,\Gamma,\psi) = \forall (\alpha_1,\dots,\alpha_m).\tau \qquad \text{where} \qquad \gcd(\tau,\psi) \setminus \gcd(\Gamma,\psi) = \{\alpha_1,\dots,\alpha_m\}$$



We can define the type generalization function gen as follows:

$$\boxed{ \begin{split} & \text{gen}: (\mathbb{T} \times \mathbb{F} \times \Psi) \to \mathbb{T}^{\forall} \\ \text{gen}(\tau, \Gamma, \psi) &= \forall (\alpha_1, \dots, \alpha_m). \tau \end{split} } \quad \text{where} \quad \text{free}_{\tau}(\tau, \psi) \setminus \text{free}_{\Gamma}(\Gamma, \psi) = \{\alpha_1, \dots, \alpha_m\}$$

with the following definitions of free type variables in each component:

$$\mathtt{free}_{\tau}: (\mathbb{T} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \bigg] \\ \mathtt{free}_{\tau}: (\mathbb{T} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \bigg] \\ \mathtt{free}_{\tau}(\tau, \psi) = \begin{cases} \{\alpha\} & \text{if } \tau = \alpha \wedge \psi(\alpha) = \bullet \\ \mathtt{free}_{\tau}(\tau', \psi) & \text{if } \tau = \alpha \wedge \psi(\alpha) = \tau' \\ \mathtt{free}_{\tau}(\tau_p, \psi) \cup \mathtt{free}_{\tau}(\tau_r, \psi) & \text{if } \tau = (\tau_p \to \tau_r) \\ \varnothing & \text{otherwise} \end{cases}$$



We can define the **type generalization** function gen as follows:

$$\boxed{ \begin{split} \operatorname{\mathsf{gen}} : (\mathbb{T} \times \mathbb{\Gamma} \times \Psi) \to \mathbb{T}^{\forall} \\ \operatorname{\mathsf{gen}}(\tau, \Gamma, \psi) &= \forall (\alpha_1, \dots, \alpha_m).\tau \end{split} \quad \text{where} \quad \operatorname{\mathsf{free}}_{\tau}(\tau, \psi) \setminus \operatorname{\mathsf{free}}_{\Gamma}(\Gamma, \psi) = \{\alpha_1, \dots, \alpha_m\} \end{split}}$$

with the following definitions of free type variables in each component:

$$\mathtt{free}_{\tau}: (\mathbb{T} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \bigg| \\ \mathtt{free}_{\tau}: (\mathbb{T} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \bigg| \\ \mathtt{free}_{\tau}(\tau, \psi) & \text{if } \tau = \alpha \wedge \psi(\alpha) = \bullet \\ \mathtt{free}_{\tau}(\tau', \psi) & \text{if } \tau = \alpha \wedge \psi(\alpha) = \tau' \\ \mathtt{free}_{\tau}(\tau_p, \psi) \cup \mathtt{free}_{\tau}(\tau_r, \psi) & \text{if } \tau = (\tau_p \to \tau_r) \\ \varnothing & \text{otherwise} \\ \end{matrix}$$

$$\boxed{ \begin{split} \operatorname{free}_{\tau^{\forall}} : (\mathbb{T}^{\forall} \times \Psi) &\rightarrow \mathcal{P}(\mathbb{X}_{\alpha}) \\ \operatorname{free}_{\tau^{\forall}} (\forall (\alpha_{1}, \dots, \alpha_{m}).\tau, \psi) &= \operatorname{free}_{\tau} (\tau, \psi) \setminus \{\alpha_{1}, \dots, \alpha_{m}\} \end{split}}$$



We can define the **type generalization** function gen as follows:

$$\boxed{ \begin{split} \operatorname{\mathsf{gen}} : (\mathbb{T} \times \mathbb{\Gamma} \times \Psi) \to \mathbb{T}^{\forall} \\ \operatorname{\mathsf{gen}}(\tau, \Gamma, \psi) &= \forall (\alpha_1, \dots, \alpha_m).\tau \end{split} \quad \text{where} \quad \operatorname{\mathsf{free}}_{\tau}(\tau, \psi) \setminus \operatorname{\mathsf{free}}_{\Gamma}(\Gamma, \psi) = \{\alpha_1, \dots, \alpha_m\} \end{split}}$$

with the following definitions of free type variables in each component:

$$\begin{split} & \boxed{ \mathbf{free}_{\tau} : (\mathbb{T} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) } \\ \mathbf{free}_{\tau} (\tau, \psi) = \begin{cases} & \{\alpha\} & \text{if } \tau = \alpha \wedge \psi(\alpha) = \bullet \\ & \mathbf{free}_{\tau} (\tau', \psi) & \text{if } \tau = \alpha \wedge \psi(\alpha) = \tau' \\ & \mathbf{free}_{\tau} (\tau_p, \psi) \cup \mathbf{free}_{\tau} (\tau_r, \psi) & \text{if } \tau = (\tau_p \to \tau_r) \\ \varnothing & \text{otherwise} \end{cases} \\ & \boxed{ \begin{aligned} & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\ & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \end{aligned} } \\ & \boxed{ \begin{aligned} & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\ & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \end{aligned} } \\ & \boxed{ \begin{aligned} & \mathbf{free}_{\tau} &: (\mathbb{T} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\ & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \end{aligned} } \\ & \boxed{ \begin{aligned} & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\ & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \end{aligned} } \end{cases} } \\ & \boxed{ \begin{aligned} & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\ & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \end{aligned} } \\ & \boxed{ \begin{aligned} & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\ & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \end{aligned} } \\ & \boxed{ \end{aligned} } \end{aligned} } \\ & \boxed{ \begin{aligned} & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\ & \boxed{ \end{aligned} } \end{aligned} } \\ & \boxed{ \begin{aligned} & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\ & \boxed{ \end{aligned} } \end{aligned} } \\ & \boxed{ \end{aligned} } \end{aligned} } \\ & \boxed{ \begin{aligned} & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\ & \boxed{ \end{aligned} } \end{aligned} } \end{aligned} } \\ & \boxed{ \end{aligned} } \end{aligned} } \\ & \boxed{ \begin{aligned} & \mathbf{free}_{\tau} &: (\mathbb{T}^{\forall} \times \Psi) \to \mathcal{P}(\mathbb{X}_{\alpha}) \\ & \boxed{ \end{aligned} } \end{aligned} } \end{aligned} } \\ & \boxed{ \end{aligned} } \end{aligned} } \\ & \boxed{ \end{aligned} } \end{aligned} } \end{aligned} } \\ & \boxed{ \end{aligned} } \end{aligned} } \end{aligned} } \end{aligned}$$



We can define the **type generalization** function gen as follows:

$$\boxed{ \texttt{gen}: (\mathbb{T} \times \mathbb{F} \times \Psi) \to \mathbb{T}^{\forall} }$$

$$\texttt{gen}(\tau, \Gamma, \psi) = \forall (\alpha_1, \dots, \alpha_m).\tau \qquad \text{where} \qquad \texttt{free}_{\tau}(\tau, \psi) \setminus \texttt{free}_{\Gamma}(\Gamma, \psi) = \{\alpha_1, \dots, \alpha_m\}$$

Why do we need to subtract the free type variables $\mathtt{free}_{\Gamma}(\Gamma,\psi)$ in the type environment Γ when generalizing the type τ ?



We can define the **type generalization** function gen as follows:

$$\gcd(\tau,\Gamma,\psi) = \forall (\alpha_1,\dots,\alpha_m).\tau \qquad \text{where} \qquad \gcd(\tau,\psi) \setminus \gcd_\Gamma(\Gamma,\psi) = \{\alpha_1,\dots,\alpha_m\}$$

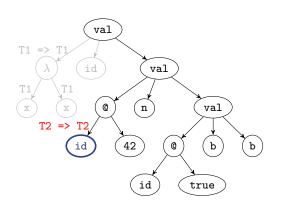
Why do we need to subtract the free type variables ${\tt free}_{\Gamma}(\Gamma,\psi)$ in the type environment Γ when generalizing the type τ ?

Consider the following example:

If we generalize the type T1 to [T1] $\{ T1 => T1 \}$ for z, the types of x and z will be different even though they have exactly the same value.

Recall: Example 3 - id





Type Environment		
\mathbb{X}	T	
id	[T1] { T1 => T1 }	

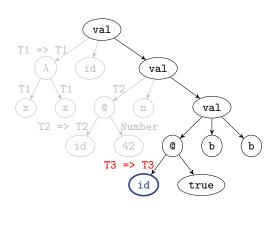
Solution		
\mathbb{X}_{α}	\mathbb{T}	
T1	_	
T2	-	

Calution

Let's define a new **type variable T2** to **instantiate** the **type variable T1**. And, **substitute T1** with **T2**.

Recall: Example 3 - id





Type Environment		
\mathbb{X}	T	
id	[T1] { T1 => T1 }	
n	T2	

Solution		
\mathbb{X}_{α}	T	
T1	-	
T2	Number	
ТЗ	_	

Let's define a new **type variable T3** to **instantiate** the **type variable T1**. And, **substitute T1** with **T3**.





```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
...

case Id(x) =>
  val ty = tenv.getOrElse(x, error(s"free identifier: $x"))
  inst(ty, sol)
```

$$\begin{array}{c|c} \boxed{\Gamma,\psi \vdash e : \tau,\psi} \\\\ \tau\text{-Id} \ \frac{\Gamma(x) = \tau^\forall}{\Gamma,\psi \vdash x : \tau,\psi'} \end{array}$$

We need to **instantiate** the type scheme τ^{\forall} with new type variables using the **type instantiation** function inst.





```
def typeCheck(e: Expr, tenv: TypeEnv, sol: Solution): (Type, Solution) = e match
...

case Id(x) =>
  val ty = tenv.getOrElse(x, error(s"free identifier: $x"))
  inst(ty, sol)
```

$$\Gamma, \psi \vdash e : \tau, \psi$$

$$\tau - \mathrm{Id} \ \frac{\Gamma(x) = \tau^\forall \qquad \mathrm{inst}(\tau^\forall, \psi) = (\tau, \psi')}{\Gamma, \psi \vdash x : \tau, \psi'}$$

We need to **instantiate** the type scheme τ^{\forall} with new type variables using the **type instantiation** function inst. For example,

$$\operatorname{inst}(\forall \alpha.(\alpha \to \alpha), \varnothing) = (\beta \to \beta, [\beta \mapsto \bullet])$$

Type Instantiation



We can define the **type instantiation** function inst as follows:

$$\begin{bmatrix} \operatorname{inst} : (\mathbb{T}^{\forall} \times \Psi) \to (\mathbb{T} \times \Psi) \end{bmatrix}$$

$$\operatorname{inst}(\forall (\alpha_1, \dots, \alpha_m).\tau, \psi) = ($$

$$\operatorname{subst}(\tau, \psi[\alpha_1 \mapsto \alpha_1', \dots, \alpha_m \mapsto \alpha_m']),$$

$$\psi[\alpha_1' \mapsto \bullet, \dots, \alpha_m' \mapsto \bullet]$$

$$)$$
 where
$$\alpha_1', \dots, \alpha_m' \notin \psi \wedge \forall 1 \leq i < j \leq m. \ \alpha_i' \neq \alpha_j'$$

Type Instantiation



We can define the **type instantiation** function inst as follows:

$$\begin{split} & \text{inst}: (\mathbb{T}^\forall \times \Psi) \to (\mathbb{T} \times \Psi) \\ & \text{inst}(\forall (\alpha_1, \dots, \alpha_m).\tau, \psi) = (\\ & \text{subst}(\tau, \psi[\alpha_1 \mapsto \alpha_1', \dots, \alpha_m \mapsto \alpha_m']), \\ & \psi[\alpha_1' \mapsto \bullet, \dots, \alpha_m' \mapsto \bullet] \\) \\ & \text{where} \qquad \alpha_1', \dots, \alpha_m' \notin \psi \land \forall 1 \leq i < j \leq m. \ \alpha_i' \neq \alpha_j' \end{split}$$

with the following **type substitution** function subst:

$$\mathtt{subst}: (\mathbb{T} \times \Psi) \to \mathbb{T}$$

$$\mathtt{subst}(\tau,\psi) = \left\{ \begin{array}{ll} \mathtt{subst}(\tau',\psi) & \text{if } \tau = \alpha \wedge \psi(\alpha) = \tau' \\ \mathtt{subst}(\tau_p,\psi) \to \mathtt{subst}(\tau_r,\psi) & \text{if } \tau = (\tau_p \to \tau_r) \\ \tau & \text{otherwise} \end{array} \right.$$

Summary



1. Type Checker and Typing Rules with Type Inference

Solutions for Type Constraints

Numbers

Additions

Conditionals

Immutable Variable Definitions and Identifier Lookup

Function Definitions

Recursive Function Definitions

Function Applications

2. Type Unification

Type Resolving

Occurrence Checking

Type Unification

3. Type Inference with Let-Polymorphism

Type Generalization

Type Instantiation

Exercise #16



https://github.com/ku-plrg-classroom/docs/tree/main/cose212/tifae

- Please see above document on GitHub:
 - Implement typeCheck function.
 - Implement interp function.
- It is just an exercise, and you don't need to submit anything.
- However, some exam questions might be related to this exercise.

Final Exam



- Date: 18:30 21:00 (150 min.), December 18 (Wed.).
- Location: 205, Woojung Hall of Informatics (우정정보관)
- Coverage: Lectures 14 26
- Format: closed book and closed notes
 - Fill-in-the-blank questions about the PL concepts.
 - Write the evaluation results of given expressions.
 - Draw derivation trees of given expressions.
 - Define the syntax or semantics of extended language features.
 - Define typing rules for the given language features.
 - etc.
- Note that there is no class on December 16 (Mon.).

Next Lecture



Course Review

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