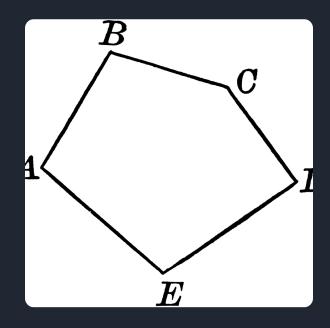


Computational Geometry Project: Minimum Weight Triangulation of a Simple Polygon

An in-depth look at the dynamic programming algorithm implementation to find the minimum weight triangulation of a simple polygon.

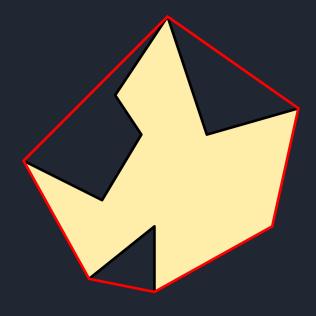
Input Polygon

A simple polygon can be defined as a closed path formed by the straight line segments in the plane, which encloses a region on one side. Our algorithm takes as input a simple polygon defined by its vertices, which can be taken as an ordered set of points that lie on the boundary of the polygon.



Convex Polygon

A polygon where no interior angle is greater than or equal to 180 degrees is a convex polygon.



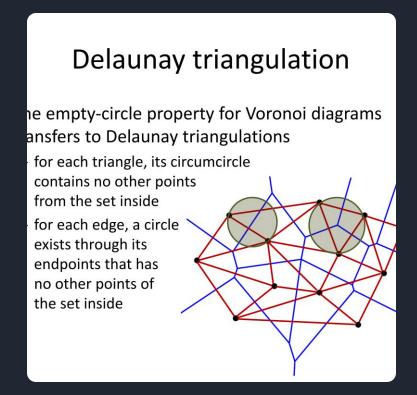
Concave Polygon

A polygon where at least one interior angle is greater than or equal to 180 degrees is a concave polygon.

Minimum Weight Triangulation

A minimum weight triangulation of a simple polygon P is a triangulation with a minimum sum of weights of its diagonals.

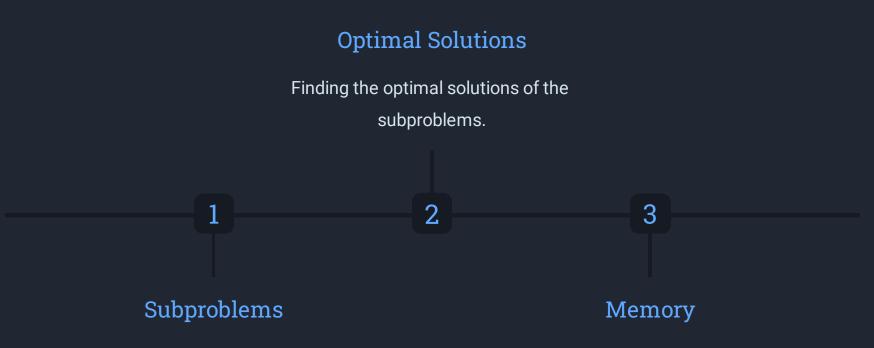
The weight of a diagonal is simply the Euclidean distance between the vertices determining it.



A Delaunay triangulation is the "nicest" triangulation, not necessarily the minimum weight one

Dynamic Programming

Dynamic programming is a technique used to solve problems in computer science, mathematics, economics and more. It's often applied to optimization problems, such as the minimum weight triangulation of a simple polygon.



Break the problem into smaller subproblems.

Store the solutions to the subproblems in memory to avoid redundant calculations.

Dynamic Programming Approach

- 1. Let **MWT(i, j)** be the weight of the minimum-weight triangulation of the polygon for an edge ij, and assume we want to compute MWT(1, n), i.e. the minimum weight triangulation of the entire polygon.
- 2. Consider a chord between vertices i and j. This chord divides the polygon into two smaller polygons: Pi..j and Pj..k..i.
- 3. The weight of the triangulation that uses this chord is W(i,j,k) = weight(i,j,k) + MWT(i,j) + MWT(j,k). Here, weight(i,j,k) is the weight of the triangle formed by vertices i, j, and k.
- 4. We can then compute MWT(i, j) as the minimum of all possible chords:
 - a. $MWT(i, j) = min \{ weight(i, k, j) + MWT(i, k) + MWT(k, j) \}, if j > i + 1, where i < j < k \}$
 - b. MWT(i, j) = 0, otherwise
- 5. We start with the base case MWT(i, i+1) = 0 for all i, since a line segment does not need to be triangulated. The final solution is then MWT(1, n).

Time Complexity and Optimization

The time complexity of the above solution is exponential. On drawing a recursion tree, we can easily see that each subproblem gets repeated several times. The problem satisfies both **optimal substructure** and **overlapping subproblems** properties of dynamic programming, so the subproblem solutions can be derived using memoization or in a bottom-up manner.

The time complexity of the dynamic programming algorithm is $O(n^3)$, which could make it unsuitable for large polygons. There are other techniques as well, such as triangulation based on ear clipping or Delaunay triangulations, which reduces the time complexity to $O(n^2)$, which doesn't give such an optimized answer, however.

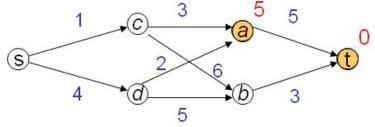
Note - My solution uses the iterative dynamic programming version of the recursive algorithm mentioned, just to make the solution more obvious.

namic Programming – Simple Exam

nortest path in a directed graph

$$cost(i) = min_k \{ d_{ik} + cost(k) \}$$

imple:



cost(v) =
of shortes
from v to
destinatic
vertex

$$cost(s) = min(1+cost(c), 4+cost(d))$$

 $cost(c) = min(3+cost(a), 6+cost(b))$
 $cost(d) = min(2+cost(a), 5+cost(b))$
 $cost(a) = 5+cost(t)$
 $cost(b) = 3+cost(t)$

Conclusion

Minimum weight triangulation is a classical problem in the field of computational geometry with a variety of applications. The dynamic programming approach used here is quite analogous to the Bellman Ford approach in determining all pairs shortest paths in a graph.

Demonstration

