

Artificial Intelligence Project 3

Neural Networks

Class 1, Team 6

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2 Problem Description

The dataset (including the training set and the test set) contains clean data generated from 8×8 images of handwritten digits. Each record contains the sampled data of size $8 \times 8 = 64$ (each point ranging in $[0, 16]$) and its label (range $[0, 9]$).

Given this dataset, the goal is to build a neural network with the training set and evaluate its precision by classifying the records in the test set (that is, to predict its label based on its sampled data).

3 Algorithm and Implementation

For this project we implemented a multilayer perceptron(MLP) with the logistic function

$$y(v_i) = (1 + e^{-v_i})^{-1}$$

as the activation function.

3.1 Building the Neural Network

First we initialize the neural network with random weights ranging between $[-0.25, 0.25]$ (it is just an empirical value). Then, we use back propagation for training the network. Here instead of running the backpropagation on the training data sequentially, we randomly choose records from the training data to propagate. The algorithm is described in Algorithm 1.

The back propagation, as shown in Algorithm 2, will be run until a certain number of epochs is reached.

Algorithm 1 Training the Network

```
1: function TRAINING(examples, epochs)
2:   Initialize network with random weights between  $[-0.25, 0.25]$ 
3:   for  $k = 1 \rightarrow \text{epochs}$  do
4:     Randomly choose a record ( $\mathbf{x}$ ,  $\mathbf{y}$ ) from examples
5:     BACK-PROPAGATE( $\mathbf{x}$ ,  $\mathbf{y}$ , network)
6:   end for
7: end function
```

Algorithm 2 Back Propagation

```
1: function BACK-PROPAGATE( $\mathbf{x}$ ,  $\mathbf{y}$ , network) ▷  $\mathbf{x}$  is the input
2:    $w \leftarrow \text{network.weights}$  ▷  $\mathbf{y}$  is the vector transformed from the label
3:   for each node  $i$  in the input layer do
4:      $a_i \leftarrow x_i$ 
5:   end for
6:   for  $l = 2 \rightarrow L$  do ▷  $L$  is the number of layers in the network
7:     for each node  $j$  in layer  $l$  do
8:        $in_j \leftarrow \sum_i w_{i,j} a_i$ 
9:        $a_j \leftarrow g(in_j)$  ▷  $g$  is the activation function
10:    end for
11:  end for
12:  for each node  $j$  in the output layer do
13:     $\Delta[j] \leftarrow g'(in_j) \times (y_j - a_j)$  ▷  $\Delta$  is a local vector of erros indexed by network node
14:  end for
15:  for  $l = L - 1 \rightarrow 1$  do
16:    for each node  $i$  in layer  $l$  do
17:       $\Delta[i] \leftarrow g'(in_i) \sum_j w_{i,j} \Delta[j]$  ▷ propagate backwards
18:    end for
19:  end for
20:  for each weight  $w_{i,j}$  do
21:     $w_{i,j} \leftarrow w_{i,j} + \alpha \times a_i \times \Delta[j]$  ▷ gradient descent rule,  $\alpha$  is the learning rate
22:  end for
23:   $\text{network.weights} \leftarrow w$ 
24: end function
```

3.2 Classification

The algorithm for classifying an observation is described in Algorithm 3. Note that the output is a vector, its value needs to be further interpreted.

Algorithm 3 Classification

```
1: function CLASSIFY(network, observation)
2:    $w \leftarrow \text{network.weights}$ 
3:    $a \leftarrow \text{observation}$ 
4:   for  $l = 2 \rightarrow L$  do ▷  $L$  is the number of layers in the network
5:     for each node  $j$  in layer  $l$  do
6:        $in_j \leftarrow \sum_i w_{i,j} a_i$ 
7:        $a_j \leftarrow g(in_j)$  ▷  $g$  is the activation function
8:     end for
9:   end for
10:  return  $a$ 
11: end function
```

4 Experiment Result

For this project, we set the number of layers in the neural network to 3 (i.e. one input layer, one hidden layer, one output layer), and the learning rate α is set to 0.2. Before building the neural network, we first transform the labels into vectors. Every elements in the vector is first set to 0, then the element

with the same index as the label will be set to 1. For example, when the label is 0, we transform it into a vector:

$$[1, 0, 0, 0, 0, 0, 0, 0, 0, 0]$$

Then, the input layer consists of vectors of size 64, and the output layer consists of vectors of size 10. The output vectors contains the probabilities for each label, here we choose the label with the largest probability as the final result.

We evaluate the implementation from two different perspectives. First, we examine the relationship between its precision and the size of the training data (i.e. the learning curve), as shown in Figure 1. The number of hidden units is set to 50, and we stop the iteration after 50,000 epochs. When the size of training data is larger than 1000, the precision stays higher than 90%. Generally the precision increases with the size of training data, but there are signs of overfitting.

Then, we examine the relationship between the total errors produced by the neural network and the number of epochs. Here we use the full training data set and set the number of hidden units to 50. As shown in Figure 2, The number of errors decreases significantly when the epochs grows large enough. When the number of epochs becomes larger than 20,000, the number of errors stays at about 100 (given that the size of the test set is about 1,700, this implies that the precision stays over 90%).

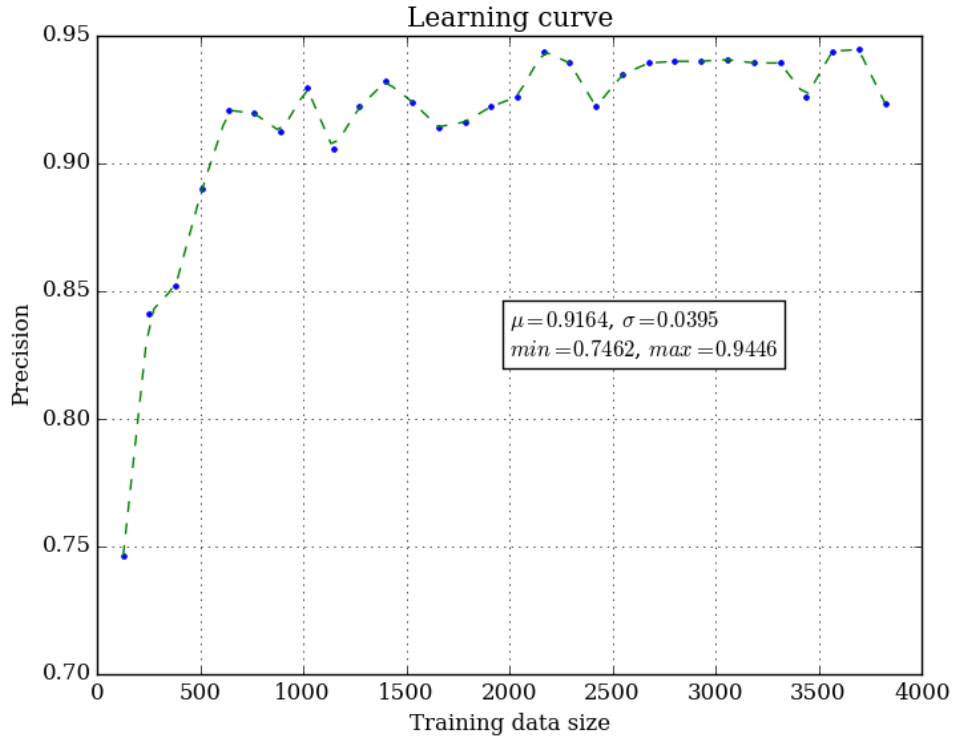


Figure 1: Learning Curve

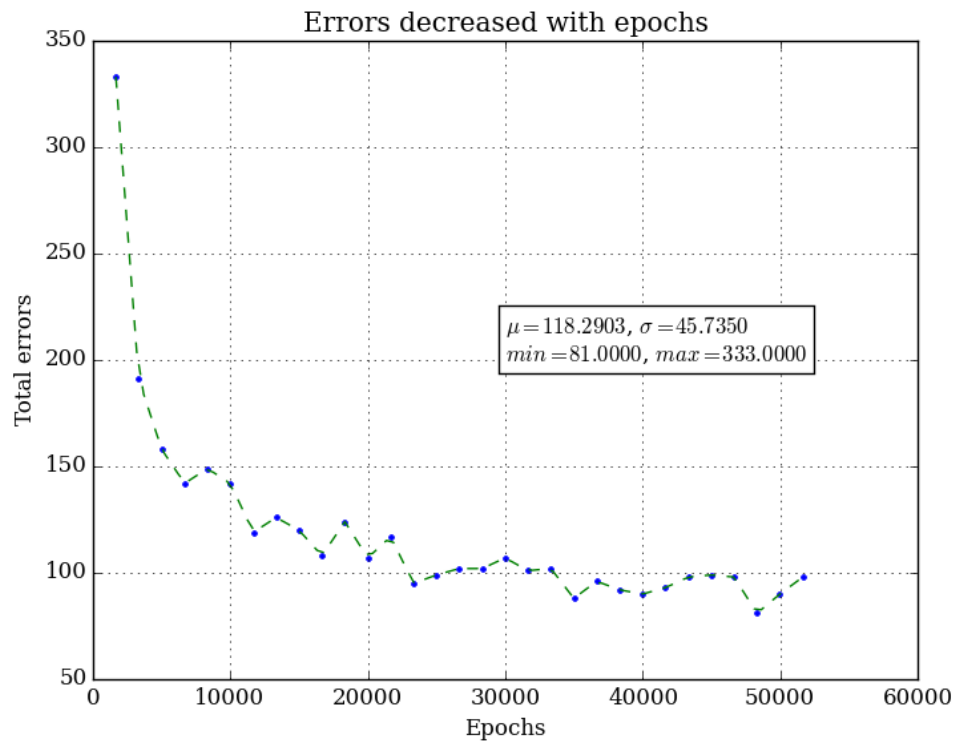


Figure 2: Relationship between total errors and epochs