

Code for prediction of Multiphase flow

```
# -*- coding: utf-8 -*-
```

```
"""MultiphaseFlowPrediction.ipynb
```

Automatically generated by Colaboratory.

Original file is located at

```
https://colab.research.google.com/drive/1jTWMIJxdXatFkoiNhcMMRX\_ZCHQDhR-q
"""
```

```
import pandas as pd
import tensorflow as tf
import numpy as np
import matplotlib.pyplot as plt
from tensorflow.keras.models import Model
from tensorflow.keras.layers import Dense, Input
from sklearn.model_selection import train_test_split
```

```
from google.colab import files
import io
data = files.upload()
```

```
df = pd.read_csv(io.StringIO(data['MULTIPHASE_V2.csv'].decode('utf-8')))
```

```
df.head()
```

```
df.shape
```

```
"""## *Split Data into train and test sets*
```

```
"""
```

```
train, test = train_test_split(df, test_size=0.2, random_state=1)
```

```
train, val = train_test_split(train, test_size=0.2, random_state=1)
```

```
"""## *Data Normalization and structuring*"""
```

```
def norm(x):
```

```
    return (x - train_stats['mean']) / train_stats['std']
```

```
def format_output(data):
```

```
    y1 = data.pop('water_kg_min')
```

```
    y1 = np.array(y1)
```

```
    y2 = data.pop('oil_kg_min')
```

```
    y2 = np.array(y2)
```

```
    y3 = data.pop('air_kg_min')
```

```
    y3 = np.array(y3)
```

```
    return y1, y2, y3
```

```
"""# *Format Water, Oil and air data as numpy array*"""
```

```
train_stats = train.describe()
```

```
train_stats.pop('water_kg_min')
```

```
train_stats.pop('oil_kg_min')
```

```
train_stats.pop('air_kg_min')
```

```
train_stats = train_stats.transpose()
```

```
train_Y = format_output(train)
```

```
test_Y = format_output(test)
```

```
val_Y = format_output(val)
```

```
print(train_stats)
```

```
normalized_train_X = np.array(norm(train))
```

```
normalized_test_X = np.array(norm(test))
```

```
normalized_val_X = np.array(norm(val))
```

```
def build_model():
```

```

# Model layers.
input_layer = Input(shape=(len(train.columns),))
first_dense_layer = Dense(units='128', activation='relu')(input_layer)
# Y1 output wfrom first dense
y1_out = Dense(units='1', name='water_kg_min')(first_dense_layer)

second_dense_layer = Dense(units='128', activation='relu')(first_dense_layer)
# Y2 output from second dense
y2_out = Dense(units='1', name='oil_kg_min')(second_dense_layer)

third_dense_layer = Dense(units='128', activation='relu')(second_dense_layer)
# Y3 output from third dense
y3_out = Dense(units='1', name='air_kg_min')(third_dense_layer)

# Model with input and output layers
model = tf.keras.Model(inputs=input_layer, outputs=[y1_out, y2_out, y3_out])

return model

"""# *Model, Optimizer, loss and metrics*"""

model = build_model()

optimizer = tf.keras.optimizers.SGD(lr=0.001)
model.compile(optimizer=optimizer,
              loss={'water_kg_min': 'mse', 'oil_kg_min': 'mse', 'air_kg_min': 'mse'},
              metrics={'water_kg_min': tf.keras.metrics.RootMeanSquaredError(),
                       'oil_kg_min': tf.keras.metrics.RootMeanSquaredError(),
                       'air_kg_min': tf.keras.metrics.RootMeanSquaredError()})

history = model.fit(normalized_train_X, train_Y,
                    epochs=100, batch_size=10, validation_data=(normalized_test_X, test_Y))

```

```
loss, Y1_loss, Y2_loss, Y3_loss, Y1_rmse, Y2_rmse, Y3_rmse =  
model.evaluate(x=normalized_val_X, y=val_Y)
```

```
print()  
print(f'loss: {loss}')
```

```
print(f'water_kg_min: {Y1_loss}')
```

```
print(f'oil_kg_min: {Y2_loss}')
```

```
print(f'air_kg_min: {Y3_loss}')
```

```
print(f'water_kg_min: {Y1_rmse}')
```

```
print(f'oil_kg_min: {Y2_rmse}')
```

```
print(f'air_kg_min: {Y3_rmse}')
```

```
def plot_diff(y_true, y_pred, title=""):  
    plt.plot(y_true, label="True Values")  
    plt.plot(y_pred, label="Predicted Values")  
    plt.title(title)  
    plt.legend()  
    plt.show()
```

```
def plot_metrics(metric_name, title, ylim=5):  
    plt.title(title)  
    plt.ylim(0, ylim)  
    plt.plot(history.history[metric_name], color='blue', label=metric_name)  
    plt.plot(history.history['val_' + metric_name], color='green', label='val_' + metric_name)  
    plt.legend()  
    plt.show()
```

```
Y_pred = model.predict(normalized_test_X)  
water_kg_min = Y_pred[0]  
oil_kg_min = Y_pred[1]  
air_kg_min = Y_pred[2]
```

```
plot_diff(test_Y[0], Y_pred[0], title='water_kg_min')  
plot_diff(test_Y[1], Y_pred[1], title='oil_kg_min')
```

```
plot_diff(test_Y[2], Y_pred[2], title='air_kg_min')
```

```
# Plot RMSE
```

```
plot_metrics(metric_name='water_kg_min_root_mean_squared_error', title='Water Flow  
RMSE', ylim=50)
```

```
plot_metrics(metric_name='oil_kg_min_root_mean_squared_error', title='Oil Flow RMSE',  
ylim=50)
```

```
plot_metrics(metric_name='air_kg_min_root_mean_squared_error', title='Air Flow RMSE',  
ylim=7)
```