

## A TECHNICAL DETAILS FOR HANDLING DUPLICATE EDGES

In this section, we discuss the intuition and detailed analysis of Algorithm 7.

Given a butterfly or wedge  $P$ , we consider a subgraph  $S$  constructed by choosing exactly one edge  $(u, v, t)$  for each  $(u, v) \in E(P)$ . We denote the set of all possible  $S$ s by  $\mathcal{S}$ . Due to duplicate edges,  $|\mathcal{S}| > 1$ . For each  $S \in \mathcal{S}$ , its active timestamp is  $[l_S, r_S]$  where  $l_S = \min_{(u,v,t) \in S} t$  and  $r_S = \max_{(u,v,t) \in S} t$ . For a time-window  $[t_s, t_e]$ ,  $P \in G_{[t_s, t_e]}$  if and only if there exists an  $S \in \mathcal{S}$  satisfying  $t_s \leq l_S \leq r_S \leq t_e$ . Therefore, for  $S_1, S_2 \in \mathcal{S}$ , if  $l_{S_1} \leq l_{S_2} \leq r_{S_2} \leq r_{S_1}$ , then  $S_1$  is not necessary to be considered for any query time-window. In this way, we manage to reduce the number of  $S$ s to be stored to answer historical queries concerning  $P$ .

We still need to resolve the issue of overcounting. For a time-window  $[t_s, t_e]$ , if there are multiple  $S$ s such that their timestamps are all included in  $[t_s, t_e]$ , we should not count  $P$  as multiple wedges or butterflies (Definition 3.4). This is the reason we consider the redefined active timestamp in Definition 4.3. Let the reduced set of  $S$ s be  $\{[l_1, r_1], [l_2, r_2], \dots, [l_k, r_k]\}$  satisfying  $l_i < l_{i+1}, r_i \leq r_{i+1}$  for each  $1 \leq i < k$ . We create a redefined timestamp  $[l_i, r_i, r_{i+1}]$  for each  $1 \leq i < k$  and a redefined timestamp  $[l_k, r_k, \infty]$  for the last timestamp  $[l_k, r_k]$ . We can see that exactly one of the redefined timestamps becomes active when  $P \in G_{[t_s, t_e]}$ : If there exists  $1 \leq i < k$  such that  $r_i \leq t_e < r_{i+1}$ , only  $[l_i, r_i, r_{i+1}]$  is active. Otherwise, we have  $t_e \geq r_k$ . In such case,  $[l_k, r_k, \infty]$  is active. In addition, if  $P \notin G_{[t_s, t_e]}$ , no redefined timestamps becomes active. For any timestamp  $[l_i, r_i]$ ,  $[t_s, t_e]$  does not include  $[l_i, r_i]$ . This implies that the redefined timestamp  $[l_i, r_i, r_{i+1}]$  (or  $[l_k, r_k, \infty]$  when  $i = k$ ) is not active.

Algorithm 7 computes the active intervals for a wedge  $\langle x \rightsquigarrow y \rightsquigarrow z \rangle$ . Given the two timestamp sets  $L_{x,y}$  and  $L_{y,z}$ , we will produce all necessary  $S \in \mathcal{S}$  and store the redefined timestamps in  $A$ . We can safely assume that there is no duplicate timestamp in either  $L_{x,y}$  or  $L_{y,z}$ . To begin with, we initialize  $S$  to be  $\emptyset$  (Line 3). We sort  $L_{x,y}$  and  $L_{y,z}$  from small to large (Line 2). We also insert an  $\infty$  timestamp to both timestamp sets (Line 1) to avoid boundary cases. We will enumerate every element in these sets, and we denote them as  $L_{x,y}[i]$  ( $1 \leq i \leq |L_{x,y}|$ ) and  $L_{y,z}[j]$  ( $1 \leq j \leq |L_{y,z}|$ ). Consider a pair  $(i, j)$ . When  $L_{x,y}[i] \leq L_{y,z}[j]$ , we will adjust  $i$  to  $i'$  such that  $L_{x,y}[i'] > L_{y,z}[j]$ . That is to say, we will adjust the smaller side as much as possible without breaking the inequality  $L_{x,y}[i] \leq L_{y,z}[j]$  (Line 5, Line 14, Line 7, and Line 17). We do the same for the case which  $L_{x,y}[i] > L_{y,z}[j]$  (adjusting  $j$  instead). For the current enumerated pair  $(i, j)$ , the corresponding redefined timestamp of the wedge formed by  $(x, y, L_{x,y}[i])$  and  $(y, z, L_{y,z}[j])$  is  $[l, r, \max(L_{x,y}[i], L_{y,z}[j])]$ , where  $l$  and  $r$  are the minima and maxima of the two timestamps  $L_{x,y}[i]$ s and  $L_{y,z}[j]$ s in the previous iteration (Line 10 and Line 11). We insert it into  $A$  (Line 11). After inserting, we move to the next pair by increasing one of the indices  $i$  or  $j$ . When  $L_{x,y}[i] \leq L_{y,z}[j]$ , by setting  $i$  to  $i + 1$ , we will have  $L_{x,y}[i] > L_{y,z}[j]$  (Line 12 to Line 14). Then we adjust  $j$  again to the largest possible value satisfying  $L_{y,z}[j] \leq L_{x,y}[i]$  (Line 14). If  $L_{x,y}[i] > L_{y,z}[j]$ , we increase  $j$  and adjust  $i$  instead (Line 13 and Line 17). The whole process will terminate when no more feasible pair needs to be enumerated (Line 9). Then, all the

---

### Algorithm 7: COMPUTING $\langle x \rightsquigarrow y \rightsquigarrow z \rangle$ 'S ACTIVE TIMESTAMPS

---

**Input:** A list of unique timestamps on the duplicate edges between  $x$  and  $y$ :  $L_{x,y}$ ; A list of unique timestamps on the duplicate edges between  $y$  and  $z$ :  $L_{y,z}$ ;  
**Output:** The active intervals  $A = \{[l_i, r_{1,i}, r_{2,i}]\}$  for  $\langle x \rightsquigarrow y \rightsquigarrow z \rangle$

```

1  $L_{x,y} \leftarrow L_{x,y} \cup \{\infty\}, L_{y,z} \leftarrow L_{y,z} \cup \{\infty\}$ ;
2 Sort  $L_{x,y}$  and  $L_{y,z}$  in ascending order;
3  $S \leftarrow \emptyset, i \leftarrow 1, j \leftarrow 1$ ;
4 if  $L_{x,y}[1] \leq L_{y,z}[1]$  then
5    $i \leftarrow$  the maximum  $k$  such that  $L_{x,y}[k] \leq L_{y,z}[1]$ ;
6 else
7    $j \leftarrow$  the maximum  $k$  such that  $L_{y,z}[k] \leq L_{x,y}[1]$ ;
8  $l \leftarrow \infty, r \leftarrow \infty$ ;
9 while  $i < |L_{x,y}|$  and  $j < |L_{y,z}|$  do
10    $l' \leftarrow \min(L_{x,y}[i], L_{y,z}[j]), r' \leftarrow \max(L_{x,y}[i], L_{y,z}[j])$ ;
11   if  $r \neq \infty$  then  $A = A \cup \{[l, r, r']\}$ ;
12   if  $L_{x,y}[i] \leq L_{y,z}[j]$  then
13      $i \leftarrow i + 1$ ;
14      $j \leftarrow$  the maximum  $k$  such that  $L_{y,z}[k] \leq L_{x,y}[i]$ ;
15   else
16      $j \leftarrow j + 1$ ;
17      $i \leftarrow$  the maximum  $k$  such that  $L_{x,y}[k] \leq L_{y,z}[j]$ ;
18    $l \leftarrow l', r \leftarrow r'$ ;
19 if  $r \neq \infty$  then
20    $A = A \cup \{[l, r, \infty]\}$ 
21 return  $S$ ;
```

---

redefined timestamps are stored in  $A$ . We return  $A$  as the output (Line 21).

Lastly, we prove that counting the number of activated redefined timestamps can be converted to computing the difference between two 2D-range counting queries.

Previously, we regarded the active timestamp as a single point in the 2-D plane and inserted it into the 2D-counting data structure. For any time-window, the answer is computed by a single query on the data structure. Under the current definition of the active timestamp, we can still efficiently answer the query using two 2D-range counting data structures  $T$  and  $\bar{T}$  instead. That is to say, after construction, we will be able to answer the number of redefined timestamps  $[l, r_1, r_2]$  satisfying  $t_s \leq l$  and  $r_1 \leq t_e < r_2$ . Specifically, for  $[l, r_1, r_2]$ , we insert  $(l, r_1)$  and  $(l, r_2)$  into  $T$  and  $\bar{T}$  respectively. To count the number of active timestamps of a time-window  $[t_s, t_e]$ , we first query  $[t_s, \infty] \times [-\infty, t_e]$  on both  $T$  and  $\bar{T}$ , denoted as  $num$  and  $\overline{num}$  respectively. Then, we return  $num - \overline{num}$  as the answer.

The formal proof is as follows.

$$\begin{aligned}
& \sum_{P \in G} \sum_{[l_i, r_{1,i}, r_{2,i}] \in \tilde{\mathcal{T}}(P)} \mathbb{1}\{l_i \geq t_s \wedge t_e \in [r_{1,i}, r_{2,i}]\} = \\
& \sum_{P \in G} \sum_{[l_i, r_{1,i}, r_{2,i}] \in \tilde{\mathcal{T}}(P)} \mathbb{1}\{l_i \geq t_s \wedge t_e \geq r_{1,i}\} - \mathbb{1}\{l_i \geq t_s \wedge t_e \geq r_{2,i}\} = \\
& \left( \sum_{P \in G} \sum_{[l_i, r_{1,i}] \in \tilde{\mathcal{T}}(P)} \mathbb{1}\{l_i \geq t_s \wedge t_e \geq r_{1,i}\} \right) - \\
& \left( \sum_{P \in G} \sum_{[l_i, r_{2,i}] \in \tilde{\mathcal{T}}(P)} \mathbb{1}\{l_i \geq t_s \wedge t_e \geq r_{2,i}\} \right) = \\
& T.query([t_s, \infty] \times [-\infty, t_e]) - \bar{T}.query([t_s, \infty] \times [-\infty, t_e])
\end{aligned}$$

PROOF OF LEMMA 4.6. WLOG, we assume  $cnt_{x,y} \leq cnt_{y,z}$ . It is easy to see the time complexity of Algorithm 7 is  $O(|S| \log m)$ , and we will then show  $|S| \leq 3cnt_{x,y}$ .

For each wedge  $\langle x \rightsquigarrow y \rightsquigarrow z \rangle [l_i, r_{1,i}, r_{2,i}] \in S$ , we have at least one of  $l_i$  or  $r_{1,i}$  comes from a timestamp of  $L_{x,y}$ . In other words, for each pair  $(l, r)$  in lines 9 to 18 of Algorithm 7, there exists an  $i \in [1, cnt_{x,y}]$  such that at least one of  $l$  or  $r$  equals to  $L_{x,y}[i]$ . We consider these cases as follows:

- $l = L_{x,y}[i], r \neq L_{x,y}[i]$ : We move  $i \leftarrow i + 1$  in the next iteration, which implies this case will only occur for at most  $cnt_{x,y}$  times.
- $l \neq L_{x,y}[i], r = L_{x,y}[i]$ : let  $\hat{l}$  and  $\hat{r}$  be the values of  $l$  and  $r$  in the next iteration, respectively. We have  $\hat{r} \geq \hat{l} \geq r$ , which implies this case will only occur for at most  $cnt_{x,y}$  times.
- $l = L_{x,y}[i], r = L_{x,y}[i]$ : let  $\hat{l}$  and  $\hat{r}$  be the value of  $l$  and  $r$  in the next iteration, respectively. We have either  $r' \geq \hat{l} > r$  or  $\hat{r} > \hat{l} \geq r$ , which implies this case will only occur for at most  $cnt_{x,y}$  times.

Since each wedge belongs to one of the three cases above, we prove that  $|S| \leq 3cnt_{x,y}$ .  $\square$

## B OMITTED PROOF FOR POWER-LAW GRAPHS

PROOF FOR THEOREM 5.1 AND THEOREM 5.2. For completeness, we include the proof sketch.

By Theorem 4.5, we know that the query time for GSI is nearly linear in the number of keys  $(x, z)$  in  $T_C$ . The space usage for GSI is bounded by the number of butterflies not maintained by  $T_C[(x, z)]$ , plus the total number of wedges in each  $W[(x, z)]$  for  $(x, z) \in T_C.keys()$ .

To bound the query time and space usage, let  $k$  be a parameter between 1 and  $\Delta = \max(\Delta_1, \Delta_2)$ . Let  $P_{\geq k}$  be the set of unordered pairs  $(x, z)$  such that  $x, z$  are on the same side of the bipartite graph  $G$ , and that  $d_x, d_z \geq k$ . Let  $\# \bowtie_{\geq k}$  be the number of butterflies  $B$  such that  $\exists \{x, z\} \in P_{\geq k}, \{x, z\} \subseteq B$ . Here we abuse notation and use  $B$  to mean the vertices of a butterfly  $B$ .

In Line 11 of Algorithm 5, we construct  $T_C[(x, z)]$ s for pairs  $(x, z)$  with the largest  $W[(x, z)]$ s until the total number of butterflies in these largest  $W[(x, z)]$ s exceeds  $(1 - \alpha)numB$ . The rest of the butterflies will be maintained by  $T_E$ .

Intuitively, for proving the efficiency of GSI, we would like to show that a small number of  $\{x, z\}$  (those in  $P_{\geq k}$ ) covers a large fraction ( $\# \bowtie_{\geq k} / numB$ ) of the total number of butterflies. Formally, we can prove that for some  $k$ , GSI has query complexity  $\tilde{O}(|P_{\geq k}|)$  and expected space complexity.

$O(\# \bowtie_{\geq 1} - \# \bowtie_{\geq k} + \sum_{(x,z) \in P_{\geq k}} |T_C[(x, z)]|)$ . To show this, let's consider an algorithm similar to Algorithm 5. The modified algorithm changes the condition on Line 12 from " $num \geq \alpha \cdot numB$ " to " $\{x, z\} \in P_{\geq k}$ ". Then  $T_C$  contains  $|P_{\geq k}|$  elements (one for each  $(x, z) \in P_{\geq k}$ ), and  $T_E$  contains  $\# \bowtie_{\geq 1} - \# \bowtie_{\geq k}$  butterflies. The time complexity of the modified algorithm is  $\tilde{O}(|P_{\geq k}|)$  and that the expected space usage of it is

$$O(\# \bowtie_{\geq 1} - \# \bowtie_{\geq k} + \sum_{(x,z) \in P_{\geq k}} |T_C[(x, z)]|).$$

In the original GSI (Algorithm 5), for a fixed choice of  $k$ , we can choose  $\alpha$  properly such that the condition on Line 12 evaluates to true for the first  $|P_{\geq k}|$  iterations, i.e., after the first  $|P_{\geq k}|$  iterations of the loop,  $num$  is no more than  $\alpha \cdot numB$ . The query time of GSI is bounded by  $\tilde{O}(|P_{\geq k}|)$ . The space usage of GSI is bounded above by that of the modified algorithm, because the sets in  $W$  are sorted with decreasing order of sizes. Each set  $W[(x, z)]$  costs  $|W[(x, z)]|$  space if it is maintained in  $T_C$  and  $\binom{|W[(x, z)]|}{2}$  space if it is maintained in  $T_E$ . GSI costs less space because it maintains larger sets in  $T_C$ , compared to the modified algorithm. These will automatically translates to the same bounds for GSI.

For simplicity, we use  $V_1, V_2$  to denote  $U, L$ . We first calculate the expected number of edges,  $m$ , of  $G$ .  $m$  can be calculated by  $\Delta_i, \gamma_i, n_i$  for either  $i = 1$  or  $i = 2$ . For the model to be consistent, we require that the  $m$ 's calculated by  $i = 1$  and  $i = 2$  are equal.

LEMMA B.1. For any  $i \in \{1, 2\}$ , if  $\gamma_i \in (2, 3)$ ,

$$m = \left(1 + O\left(\Delta_i^{2-\gamma_i}\right)\right) \frac{n_i}{s_i(\gamma_i - 2)}.$$

PROOF. Let  $x$  be a fixed vertex in  $V_i$ .

$$\begin{aligned}
m &= n_i \mathbb{E} [\deg_x] && \text{(by linearity of expectation)} \\
&= n_i \mathbb{E} [d_x] \\
&= n_i \frac{1}{s_i} \sum_{i=1}^{\Delta_i} i^{1-\gamma_i} \\
&= \left(1 + O\left(\Delta_i^{2-\gamma_i}\right)\right) \frac{n_i}{s_i(\gamma_i - 2)}.
\end{aligned}$$

$\square$

Next, we estimate the expectation of  $|P_{\geq k}|$  for bounding the query time.

$$\text{LEMMA B.2. } \mathbb{E} [|P_{\geq k}|] = \left(1 + O\left(\frac{1}{n_1} + \frac{1}{n_2}\right)\right) \left(\frac{n_1^2 s_{1,k}^2}{2s_1^2} + \frac{n_2^2 s_{2,k}^2}{2s_2^2}\right).$$

PROOF. Recall that for any pair of vertices  $x, z$ ,  $(x, z) \in P_{\geq k}$  if  $x, z \in V_i$  and  $d_x, d_z \geq k$ . The expected number of such pairs for a

fixed  $i \in \{1, 2\}$  is

$$\begin{aligned} & \binom{n_i}{2} \mathbb{P}[d_x \geq k] \mathbb{P}[d_z \geq k] \\ &= \binom{n_i}{2} \left( \frac{\sum_{d=k}^{\Delta_d} d^{-\gamma_i}}{s_i} \right)^2 \\ &= \left( 1 + O\left(\frac{1}{n_i}\right) \right) \frac{n_i^2 s_{i,k}^2}{2s_i^2}. \end{aligned}$$

Summing over  $i = \{1, 2\}$  gives

$$\mathbb{E}[|P_{\geq k}|] = \left( 1 + O\left(\frac{1}{n_1} + \frac{1}{n_2}\right) \right) \left( \frac{n_1^2 s_{1,k}^2}{2s_1^2} + \frac{n_2^2 s_{2,k}^2}{2s_2^2} \right).$$

□

Lastly, we calculate  $\mathbb{E}[\# \bowtie_{\geq k}]$ , and  $\mathbb{E}[\# \bowtie_{\geq 1}]$ . The difference of these two numbers will bound the space usage.

LEMMA B.3.

$$\begin{aligned} & \mathbb{E}[\# \bowtie_{\geq k}] \\ & \geq \left( 1 + O\left(\Delta_1^{\gamma_1-3} + \Delta_2^{\gamma_2-3}\right) \right) \frac{n_1^2 n_2^2}{4m^4} \\ & \quad \frac{\left(\Delta_1^{3-\gamma_1} - k^{3-\gamma_1}\right) \left(\Delta_2^{3-\gamma_2} - k^{3-\gamma_2}\right)}{s_1 s_2 (3 - \gamma_1)(3 - \gamma_2)}. \end{aligned}$$

PROOF. To get a lower bound for  $\mathbb{E}[\# \bowtie_{\geq k}]$ , we use the quantity  $\# \bowtie_{both \geq k}$  be the number of butterflies  $B = (x, y, z, w)$  such that both  $(x, z)$  and  $(y, w)$  are from  $P_{\geq k}$ .

$\# \bowtie_{both \geq k}$  is no more than  $\# \bowtie_{\geq k}$  which is the number of butterflies such that at least one of  $(x, z)$  and  $(y, w)$  are from  $P_{\geq k}$ .

We sum up the probability that  $x, y, z, w$  form a butterfly for  $x, z \in V_1, y, w \in V_2$ .

$$\begin{aligned} & \mathbb{E}[\# \bowtie_{both \geq k}] \\ &= \binom{n_1}{2} \binom{n_2}{2} \sum_{d_1, d_3 \in [k, \Delta_1], d_2, d_4 \in [k, \Delta_2]} \mathbb{P}[d_x = d_1] \mathbb{P}[d_y = d_2] \\ & \quad \mathbb{P}[d_z = d_3] \mathbb{P}[d_w = d_4] \frac{d_x d_y}{m} \frac{d_x d_w}{m} \frac{d_z d_y}{m} \frac{d_z d_w}{m} \\ &= \binom{n_1}{2} \binom{n_2}{2} \sum_{d_1, d_3 \in [k, \Delta_1], d_2, d_4 \in [k, \Delta_2]} \mathbb{P}[d_x = d_1] \mathbb{P}[d_y = d_2] \\ & \quad \mathbb{P}[d_z = d_3] \mathbb{P}[d_w = d_4] \frac{d_x^2 d_y^2 d_z^2 d_w^2}{m^4} \\ &= \binom{n_1}{2} \binom{n_2}{2} \frac{1}{m^4} \left( \sum_{d_1, d_3 \in [k, \Delta_1]} \mathbb{P}[d_x = d_1] \mathbb{P}[d_z = d_3] d_x^2 d_z^2 \right) \\ & \quad \left( \sum_{d_2, d_4 \in [k, \Delta_2]} \mathbb{P}[d_y = d_2] \mathbb{P}[d_w = d_4] d_y^2 d_w^2 \right) \\ &= \binom{n_1}{2} \binom{n_2}{2} \frac{1}{m^4} \left( \sum_{d_1 \in [k, \Delta_1]} \mathbb{P}[d_x = d_1] d_x^2 \right)^2 \\ & \quad \left( \sum_{d_2 \in [k, \Delta_2]} \mathbb{P}[d_y = d_2] d_y^2 \right)^2 \\ &= \binom{n_1}{2} \binom{n_2}{2} \frac{1}{m^4} \mathbb{E}^2[\mathbf{1}_{d_{v_1} \geq k} d_{v_1}^2] \mathbb{E}^2[\mathbf{1}_{d_{v_2} \geq k} d_{v_2}^2] \end{aligned}$$

where  $v_1$  ( $v_2$ ) is an arbitrary vertex from  $V_1$  ( $V_2$ ). We next calculate the expectations in the equation above. For any  $i \in \{1, 2\}$ ,

$$\begin{aligned} & \mathbb{E}[\mathbf{1}_{d_{v_i} \geq k} d_{v_i}^2] \\ &= \sum_{d=k}^{\Delta_i} \mathbb{P}[d_{v_i} = d] d^2 \\ &= \frac{1}{s_i} \sum_{d=k}^{\Delta_i} d^{2-\gamma_i} \\ &= \left( 1 + O\left(\Delta_i^{\gamma_i-3}\right) \right) \frac{\Delta_i^{3-\gamma_i} - k^{3-\gamma_i}}{s_i(3 - \gamma_i)}. \end{aligned}$$

Thus, we have

$$\begin{aligned} & \mathbb{E}[\# \bowtie_{both \geq k}] \\ &= \binom{n_1}{2} \binom{n_2}{2} \frac{1}{m^4} \mathbb{E}^2[\mathbf{1}_{d_{v_1} \geq k} d_{v_1}^2] \mathbb{E}^2[\mathbf{1}_{d_{v_2} \geq k} d_{v_2}^2] \\ &= \binom{n_1}{2} \binom{n_2}{2} \frac{1}{m^4} \Pi_{i=1}^2 \left( 1 + O\left(\Delta_i^{\gamma_i-3}\right) \right) \frac{\Delta_i^{3-\gamma_i} - k^{3-\gamma_i}}{s_i(3 - \gamma_i)} \\ &= \left( 1 + O\left(\Delta_1^{\gamma_1-3} + \Delta_2^{\gamma_2-3}\right) \right) \frac{n_1^2 n_2^2}{4m^4} \\ & \quad \frac{\left(\Delta_1^{3-\gamma_1} - k^{3-\gamma_1}\right) \left(\Delta_2^{3-\gamma_2} - k^{3-\gamma_2}\right)}{s_1 s_2 (3 - \gamma_1)(3 - \gamma_2)}. \end{aligned}$$

□

Similar to Lemma B.3, we can estimate the expectation of  $\text{num}B = \# \bowtie_{\geq k}$ .

LEMMA B.4.

$$\begin{aligned} & \mathbb{E} [\# \bowtie_{\geq 1}] \\ &= \left(1 + O\left(\Delta_1^{\gamma_1-3} + \Delta_2^{\gamma_2-3}\right)\right) \frac{n_1^2 n_2^2}{4m^4} \\ & \quad \frac{\Delta_1^{3-\gamma_1} \Delta_2^{3-\gamma_2}}{s_1 s_2 (3-\gamma_1)(3-\gamma_2)}. \end{aligned}$$

PROOF. The proof is identical to that of Lemma B.3 with  $k = 1$ . We may replace the  $\geq$  to  $=$  because when  $k = 1$ ,  $\# \bowtie_{\text{both} \geq k}$  is equal to  $\# \bowtie_{\geq k}$ .  $\square$

*Double-sided power-law bipartite graphs.* In the double-sided power-law model, both  $\gamma_1$  and  $\gamma_2$  are in the range  $(2, 3)$ . In this case, we have that  $s_i$  is a constant for  $i = 1, 2$ . We also have that  $m = O(n)$ .

We define  $n = \max(n_1, n_2)$ ,  $\Delta = \max(\Delta_1, \Delta_2)$ , and  $\gamma = \min(\gamma_1, \gamma_2)$ .

We may calculate

$\mathbb{E} [\# \bowtie_{\geq 1} - \# \bowtie_{\geq k}]$  by Lemma B.4 and Lemma B.3.

$$\begin{aligned} & \mathbb{E} [\# \bowtie_{\geq 1} - \# \bowtie_{\geq k}] \\ &= O\left(\left(\Delta_1^{\gamma_1-3} + \Delta_2^{\gamma_2-3}\right) \frac{n_1^2 n_2^2}{m^4} \left(k^{3-\gamma_1} \Delta_2^{3-\gamma_2} + k^{3-\gamma_2} \Delta_1^{3-\gamma_1}\right)\right) \\ &= O\left(\frac{n_1^2 n_2^2}{m^4} \left(\left(\frac{k}{\Delta_1}\right)^{3-\gamma_1} \Delta_2^{3-\gamma_2} + \left(\frac{k}{\Delta_2}\right)^{3-\gamma_2} \Delta_1^{3-\gamma_1} + k^{3-\gamma_1} + k^{3-\gamma_2}\right)\right) \\ &= O\left(\Delta^{6-2\gamma}\right) \end{aligned}$$

for  $k \leq \Delta$ . When  $k$  is no more than the smaller of  $\Delta_1$  and  $\Delta_2$ , we have a sharper bound.

$$\begin{aligned} & \mathbb{E} [\# \bowtie_{\geq 1} - \# \bowtie_{\geq k}] \\ &= O\left(\frac{n_1^2 n_2^2}{m^4} \left(\Delta_2^{3-\gamma_2} + \Delta_1^{3-\gamma_1} + k^{3-\gamma_1} + k^{3-\gamma_2}\right)\right) \quad (k \leq \Delta_1, k \leq \Delta_2) \\ &= O\left(\frac{n^4}{m^4} \Delta^{3-\gamma}\right) \\ &= O\left(\Delta^{3-\gamma}\right) \end{aligned}$$

for  $k \leq \min(\Delta_1, \Delta_2)$ . By Lemma B.2,

$$\begin{aligned} & \mathbb{E} [|P_{\geq k}|] \\ &= O\left(n^2 k^{2-2\gamma}\right). \end{aligned}$$

Note that the two bounds above on space usage do not depend on  $k$ . Thus, we may choose the largest possible  $k$  to reduce the query time in each case.

- We may choose  $k = \Delta$  so that all butterflies are maintained by  $T_E$ . The query time is  $\tilde{O}(1)$  and the expected space usage is  $\mathbb{E} [\# \bowtie_{\geq 1}] = O(\Delta^{6-2\gamma})$ .
- We may also choose  $k = \min(\Delta_1, \Delta_2)$  so that the expected query time is  $\tilde{O}(\mathbb{E} [|P_{\geq k}|]) = \tilde{O}(n^2 \min(\Delta_1, \Delta_2)^{2-2\gamma})$  and the expected

space usage for  $T_E$  is  $O(\Delta^{3-\gamma})$ . Note that we need to consider the space usage of  $T_C$ . This can be bounded by

$$\begin{aligned} & \sum_{i=1}^2 n_i \mathbb{E} [\deg_{x_i}^2] \\ &= \sum_{i=1}^2 n_i \frac{\sum_{d=1}^{\Delta_i} d^{2-\gamma_i}}{s_i} \\ &= O\left(\sum_{i=1}^2 n_i \Delta_i^{3-\gamma_i}\right) \\ &= O\left(n \Delta^{3-\gamma}\right) \end{aligned}$$

where  $x_i \in V_i$  for  $i = 1, 2$ . The total expected space usage is  $O(n \Delta^{3-\gamma})$ .

*Single-sided power-law bipartite graphs.* In the single-sided power-law model, we have  $\gamma_1 \in (2, 3)$ ,  $\gamma_2 = 0$ , and  $\Delta_1 > \Delta_2$ . In this case,  $s_1$  is a constant and  $s_2 = \Delta_2$ . We also have that  $m = \Theta(n_1) = \Theta(n_2 \Delta_2)$ .

We define  $n = \max(n_1, n_2)$ ,  $\Delta = \max(\Delta_1, \Delta_2)$ . We choose  $\Delta_2 < k \leq \Delta_1$ . We may calculate  $\mathbb{E} [\# \bowtie_{\geq 1} - \# \bowtie_{\geq k}]$  by Lemma B.4 and Lemma B.3.

$$\begin{aligned} & \mathbb{E} [\# \bowtie_{\geq 1} - \# \bowtie_{\geq k}] \tag{1} \\ &= O\left(\left(\Delta_1^{\gamma_1-3} + \Delta_2^{\gamma_2-3}\right) \frac{n_1^2 n_2^2}{m^4} \left(k^{3-\gamma_1} \Delta_2^{3-\gamma_2} + k^{3-\gamma_2} \Delta_1^{3-\gamma_1}\right)\right) \tag{2} \\ &= O\left(\frac{n_1^2 n_2^2}{m^4} \left(\left(\frac{k}{\Delta_1}\right)^{3-\gamma_1} \Delta_2^{3-\gamma_2} + \left(\frac{k}{\Delta_2}\right)^{3-\gamma_2} \Delta_1^{3-\gamma_1} + k^{3-\gamma_1} + k^{3-\gamma_2}\right)\right) \tag{3} \\ &= O\left(\frac{n_2^2}{m^2} \left(\frac{\Delta_1^{6-\gamma_1}}{\Delta_2^3} + \Delta_2^3\right)\right) \quad (k \leq \Delta_1, \Delta_1 > \Delta_2) \\ &= O\left(\Delta_2 + \left(\frac{\Delta_1^{6-\gamma_1}}{\Delta_2^5}\right)\right). \quad \left(\frac{n_2}{m} = \Theta\left(\frac{1}{\Delta_2}\right)\right) \end{aligned}$$

Note that the bound above does not depend on  $k$ . Thus, it is an upper bound of  $\mathbb{E} [\# \bowtie_{\geq 1}]$ . We may set  $\alpha > 1$  so that GSI maintain all butterflies in  $T_E$ . This results in an expected query time of  $\tilde{O}(1)$ .  $\square$