view_frames Result

Recorded at time: 1534693212.038

odom

Broadcaster: /virtual_joint_broadcaster_0
Average rate: 10.170 Hz
Most recent transform: 1534693212.111 (-0.073 sec old)
Buffer length: 4.916 sec

base_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1534693212.038 sec old)
Buffer length: 0.000 sec

footprint_x

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

footprint_y

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

footprint_z

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1534693212.038 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1534693212.038 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

arm_link_0

plate_link

caster_link_bl

caster_link_br

caster_link_fl

caster_link_fr

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

arm_link_1

wheel_link_bl

wheel_link_br

wheel_link_fl

wheel_link_fr

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

arm_link_2

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

arm_link_3

Broadcaster: /robot_state_publisher
Average rate: 10.203 Hz
Most recent transform: 1534693212.000 (0.038 sec old)
Buffer length: 4.901 sec

arm_link_4

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1534693212.038 sec old)
Buffer length: 0.000 sec

arm_link_5

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1534693212.038 sec old)
Buffer length: 0.000 sec

arm_link_ee